

# Investigate Small Vision Encoders in Multimodal <u>Transformers</u>

**CSE641 Computer Vision: Modern Methods And Application** 

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#### **Problem Statement**

- Multimodal transformers like CLIP rely heavily on large vision encoders, leading to high computational costs and memory usage
- This project investigates the use of small vision encoders to reduce model complexity while maintaining competitive performance in image-text tasks.

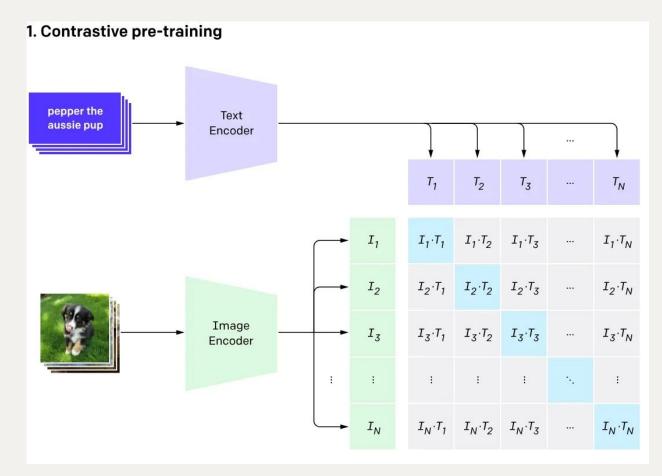


Fig. 1 : CLIP architecture



# Literature Survey

Question	Pros	Cons	References
How does natural language supervision improve visual models?	CLIP demonstrates that natural language supervision enables robust, transferable visual representations for multimodal tasks.	Requires large-scale datasets and computational resources for pretraining effectively.	Learning Transferable Visual Models From Natural Language Supervision. https://arxiv.org/pdf/2103.00020
How can EfficientNet improve Model Scaling for CNN's?	Balances network width, depth, and resolution using a compound coefficient, leading to better accuracy and efficiency.	Scaling might not always translate directly to improved performance in all multimodal tasks.	EfficientNet: Rethinking Model Scaling for Convolutional Neural Networks <a href="https://arxiv.org/pdf/1905.11946v5">https://arxiv.org/pdf/1905.11946v5</a>
How does MobileNetV2 achieve efficiency?	Utilizes inverted residuals and linear bottlenecks to significantly reduce the number of parameters and computational cost.	May have limitations in capturing very fine-grained details due to information bottlenecking.	MobileNetV2: Inverted Residuals and Linear Bottlenecks. https://arxiv.org/pdf/1801.04381
How does the Inception architecture contribute to efficient visual encoding?	Multi-scale feature extraction within a single layer, potentially reducing depth and parameters.	Increased complexity in layer design and potential for vanishing gradients in deeper networks.	Going deeper with convolutions.  https://arxiv.org/pdf/1409.4842



## **Dataset Discussion**

- **Total Images:** 31,783
- **Total Captions:** 158,915 (5 captions per image)
- **Source**: Flickr (real-world photographs)
- Caption Format: Short descriptive English sentences
- Common Caption Themes: Human activities, sports, nature scenes, animals, vehicles, objects, and urban settings.



















Fig. 2 : Dataset Example



# Methodology

Used CLIP (Contrastive Language-Image Pretraining) model.

Trained the model on different variants of vision encoders within the CLIP model.

- **EfficientNet:** High accuracy with efficiency
- **MobileNet:** Lightweight and fast
- Inception: Multi-scale feature extraction

#### TABLE I HYPERPARAMETERS USED IN TRAINING

Hyperparameter	Value	
Debug Mode	False	
Batch Size	16	
Number of Workers	4	
Head Learning Rate	$1 \times 10^{-3}$	
Image Encoder LR	$1 \times 10^{-4}$	
Text Encoder LR	$1 \times 10^{-5}$	
Weight Decay	$1 \times 10^{-3}$	
Patience	1	
Factor	0.8	
Epochs	2	
Text Encoder Model	DistilBERT (base, uncased)	
Text Tokenizer	DistilBERT (base, uncased)	
Max Token Length	200	
Pretrained Models	True	
Trainable Models	True	
Temperature Parameter	1.0	
Image Size	224x224	
Projection Layers	1	
Projection Dimension	256	
Dropout	0.1	



# Methodology

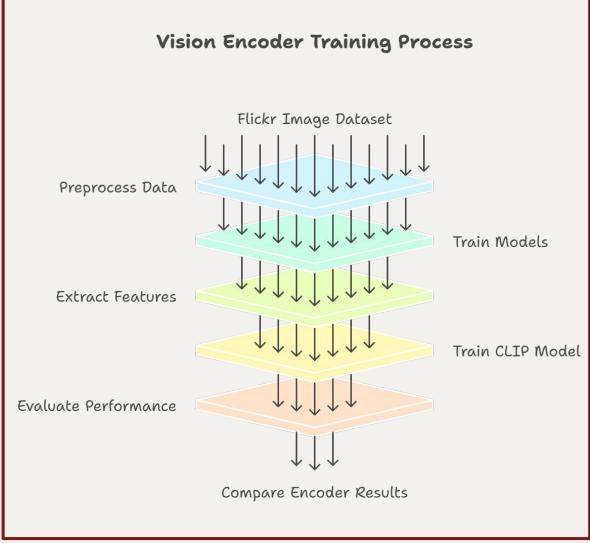




Fig. 3: Methodology

### Results

TABLE II
TRAINING AND VALIDATION PERFORMANCE OF DIFFERENT VISION
ENCODERS

Model	Train Loss	Val Loss	Train Time (min)	Val Time (min)
ResNet50	1.99	2.37	36:05	3:09
MobileNet	2.3	2.48	23:40	2:34
EfficientNet	0.745	2.41	34:14	3:00
Inception	2.05	2.35	45:40	3:54

#### TABLE III RETRIEVAL MATRICES

Model	Rank@1	Rank@5	Rank@10
MobileNet	0.0148	0.0726	0.1171
EfficientNet	0.0107	0.0493	0.0867



### **Future Work**

- Assess the computational cost and resource efficiency of each vision encoder variant.
- Evaluate the performance of each variant in terms of accuracy and relevance for text-based person search tasks.
- Compare the trade-offs between model efficiency and performance, identifying the most efficient vision encoder variant that still performs well for the text-to-image matching task.



### References

1] Radford, A., Kim, J. W., Hallacy, C., Ramesh, A., Goh, G., Agarwal, S., Sastry, G., Askell, A., Mishkin, P., Clark, J., Krueger, G., & Sutskever, I. (2021a, February 26). *Learning transferable visual models from Natural Language Supervision*. arXiv.org. <a href="https://arxiv.org/abs/2103.00020">https://arxiv.org/abs/2103.00020</a>

[2] Tan, M., & Le, Q. V. (2020, September 11). *EfficientNet: Rethinking model scaling for Convolutional Neural Networks*. arXiv.org. <a href="https://arxiv.org/abs/1905.11946v5">https://arxiv.org/abs/1905.11946v5</a>

[3] Sandler, M., Howard, A., Zhu, M., Zhmoginov, A., & Chen, L.-C. (2019, March 21). *MobileNetV2: Inverted residuals and linear bottlenecks*. arXiv.org. <a href="https://arxiv.org/abs/1801.04381">https://arxiv.org/abs/1801.04381</a>

[4] Szegedy, C., Liu, W., Jia, Y., Sermanet, P., Reed, S., Anguelov, D., Erhan, D., Vanhoucke, V., & Rabinovich, A. (2014, September 17). *Going deeper with convolutions*. arXiv.org. <a href="https://arxiv.org/abs/1409.4842">https://arxiv.org/abs/1409.4842</a>

