# STAT GU4221/GR5221 Homework 2 [100 pts] Due: Thursday, March 2nd at 11:59pm (ET)

## Problem 1

Let  $\{X_t : t \in \mathbb{Z}\}$  be a time series defined by the First-Order Autoregressive Model (AR(1)):

$$(1) X_t = \phi X_{t-1} + Z_t, \quad t \in \mathbb{Z},$$

where  $Z_t \sim WN(0, \sigma^2)$ .

- 1.i Derive the unique stationary solution of the above AR(1) for  $|\phi| > 1$ , i.e., derive the linear process that satisfies equation (1) for  $|\phi| > 1$ . Uniqueness will be established in part 1.iii.
- 1.ii Briefly describe (in one or two sentences) why the solution obtained in part 1.i is not very useful in practice.
- 1.iii Show that the stationary solution derived in part 1.i is unique. To solve this problem, suppose that  $\{Y_t\}$  is another stationary solution that satisfies (1), and show that the solution in (i), which can be written as an infinite sum, converges in mean square to  $Y_t$ . See the lecture notes for more guidance.

#### Problem 2

Let  $\{Y_t: t \in \mathbb{Z}\}$  be a time series defined by the First-Order Autoregressive Model with Non-zero Mean:

(2) 
$$Y_t - \mu = \phi(Y_{t-1} - \mu) + Z_t, \quad t \in \mathbb{Z},$$

where  $Z_t \sim WN(0, \sigma^2)$  and  $|\phi| < 1$ . Note that  $E[Y_t] = \mu$  and hence,  $E[Y_t - \mu] = 0$ .

2.i Using properties of the prediction operator  $P(\cdot|Y_n, Y_{n-1}, \dots, Y_1)$ , derive the h-step ahead forecast, i.e., derive

$$P(Y_{n+h}|Y_n, Y_{n-1}, \dots, Y_1), h > 0.$$

**Note:** you don't have to solve the matrix inverse  $\Gamma \mathbf{a} = \gamma$  for this problem. Simply use properties of the prediction operator P.

2.ii Compute the mean square prediction error using the formula

$$E[(Y_{n+h} - P(Y_{n+h}|Y_n, Y_{n-1}, \dots, Y_1))^2] = \gamma(0) - \mathbf{a}^T \gamma.$$

#### Problem 3

Let  $\{X_t: t \in \mathbb{Z}\}$  be a time series defined by the First-Order Moving Average Model (MA(1)):

$$(3) X_t = Z_t + \theta Z_{t-1}, \quad t \in \mathbb{Z},$$

where  $Z_t \sim WN(0, \sigma^2)$ .

- 3.i Derive the one-step ahead forecast  $X_3$ , based on  $X_2, X_1$ . More specifically, derive  $P(X_3|X_2, X_1)$ , assuming the MA(1) process (3). To solve this problem, find coefficients **a** that satisfy  $\Gamma \mathbf{a} = \gamma$ . See lecture notes for more details.
- 3.ii Derive the expected prediction error of  $P(X_3|X_2,X_1)$ .

#### Problem 4

Let  $\{X_t : t \in \mathbb{Z}\}$  be a time series defined by:

$$(4) X_t = Z_t + 0.5Z_{t-1}, \quad t \in \mathbb{Z},$$

where  $Z_t \sim WN(0, 2^2)$ .

- 4.i Consider using n = 10 cases  $\{X_1, \ldots, X_{10}\}$  to perform a one-step ahead forecast  $P(X_{11}|X_{10}, \ldots, X_1)$ . Find the coefficients **a** that satisfy  $\Gamma \mathbf{a} = \gamma$ . For full credit:
  - 4.i.a. Display the  $(10 \times 10)$  matrix  $\Gamma$  and the  $(10 \times 1)$  vector  $\gamma$ . You will have to write down each entry manually based on the true ACVF of the MA(1) process (4).
  - 4.i.b. Solve the problem numerically, i.e., use R or similar to solve  $\mathbf{a} = (\Gamma)^{-1} \gamma$ .
- 4.ii Compute the expected prediction error of  $P(X_{11}|X_{10},\ldots,X_1)$ . This will be a numeric answer.
- 4.iii Run a simulation to check if the theoretical expected prediction error from part 4.ii matches the empirical prediction error. To solve this problem, write a loop using 10000 iterations:

for k in 1:10000 {

- ullet simulate time series  $X_t$  (MA(1)) with n=11 observations
- ullet forecast the 11th observation using  $X_{10}, X_9, \dots, X_1$ , i.e., compute  $P(X_{11}|X_{10}, X_9, \dots, X_1)$
- ullet store both the forecasted 11th case and the simulated  $X_{11}$  for each iteration k

Use the stored values to compute the *empirical prediction error* and compare this result with the *expected prediction error* from 4.ii.

## Problem 5

}

Let  $\{Y_t : t \in \mathbb{Z}\}$  be a time series defined by the Second-Order Moving Average Model with Non-zero Mean:

(5) 
$$Y_t - \mu = Z_t + \theta_1 Z_{t-1} + \theta_2 Z_{t-2}, \quad t \in \mathbb{Z},$$

where  $Z_t \sim WN(0, \sigma^2)$ . Also assume that  $\{Y_t\}$  is invertible.

5.i Show that  $\{Y_t\}$  is a linear process of the form

$$Y_t = \mu + \sum_{j=-\infty}^{\infty} \psi_j Z_{t-j},$$

i.e., identify the coefficients  $\psi_i$ . Hint: this is very easy.. don't overcomplicate this problem!

- 5.ii Is the process  $\{Y_t\}$  causal? Explain your reasoning in one or two sentences.
- 5.iii Derive the covariance function  $\gamma_Y(h)$ . Note that you can use the following formula which computes the covariance function  $\gamma(h)$  for a generic MA(q) model:

$$\gamma(h) = \begin{cases} \sigma^2 \sum_{j=0}^{q-|h|} \theta_j \theta_{j+|h|}, & \text{if } |h| \le q, \\ \\ 0, & \text{if } |h| > q \end{cases}$$

5.iv Compute the Long-Run Variance of  $\{Y_t\}$ . Simplify the result as much as possible.

5.v Consider the sample average

$$\bar{Y}_n = \frac{1}{n} \sum_{t=1}^n Y_t,$$

where the  $Y_t$ 's come from the MA(2) model defined in equation (5). Further, assume that the noise structure is IID, i.e.,  $Z_t \sim IID(0, \sigma^2)$ . Identify the limiting distribution of

$$\sqrt{n}(\bar{Y}_n - \mu).$$

Note that you don't have to prove this result, you can simply reference the appropriate theorem and compute the limiting distribution's mean and variance.

## Problem 6

In this problem students will prove property (4) of the Second-order Prediction Operator  $P(\cdot|\mathbf{W})$ .

**Statement:** Suppose that U and V are random variables such that  $E[U^2] < \infty$  and  $E[V^2] < \infty$ . Also suppose that  $\Gamma = cov(\mathbf{W}, \mathbf{W})$  and that  $\beta, \alpha_1, \alpha_2$  are constants. Prove that

$$P(\alpha_1 U + \alpha_2 V + \beta | \mathbf{W}) = \alpha_1 P(U | \mathbf{W}) + \alpha_2 P(V | \mathbf{W}) + \beta.$$

To prove this result, follow the steps shown below

• Assume the defining properties of the projection operator for  $P(U|\mathbf{W})$  and  $P(V|\mathbf{W})$ . More specifically, you can assume

$$P(U|\mathbf{W}) = E[U] + \mathbf{a}_1^T(\mathbf{W} - E\mathbf{W}), \text{ where } \mathbf{\Gamma}\mathbf{a}_1 = cov(U, \mathbf{W}),$$

and

$$P(V|\mathbf{W}) = E[V] + \mathbf{a}_2^T(\mathbf{W} - E\mathbf{W}), \text{ where } \mathbf{\Gamma}\mathbf{a}_2 = cov(V, \mathbf{W}).$$

- Note that  $\mathbf{a}_1 = \mathbf{\Gamma}^{-1} cov(U, \mathbf{W})$  and  $\mathbf{a}_2 = \mathbf{\Gamma}^{-1} cov(V, \mathbf{W})$ , which can be substituted in the above expressions  $P(U|\mathbf{W})$  and  $P(V|\mathbf{W})$ .
- Use the defining formula of the projection operator to simplify  $P(\alpha_1 U + \alpha_2 V + \beta | \mathbf{W})$ . The first step follows:

$$P(\alpha_1 U + \alpha_2 V + \beta | \mathbf{W}) = E[\alpha_1 U + \alpha_2 V + \beta] + \mathbf{a}^T (\mathbf{W} - E\mathbf{W}),$$

where  $\Gamma \mathbf{a} = cov(\alpha_1 U + \alpha_2 V + \beta, \mathbf{W}).$ 

- Solve for **a** and apply linearity of covariance  $cov(\alpha_1 U + \alpha_2 V + \beta, \mathbf{W})$ .
- Put everything together, i.e.,

$$P(\alpha_1 U + \alpha_2 V + \beta | \mathbf{W}) = E[\alpha_1 U + \alpha_2 V + \beta] + \mathbf{a}^T (\mathbf{W} - E\mathbf{W})$$

 $=\cdots$  fill in missing gaps  $\cdots$ 

$$= \alpha_1 P(U|\mathbf{W}) + \alpha_2 P(V|\mathbf{W}) + \beta.$$

• QED