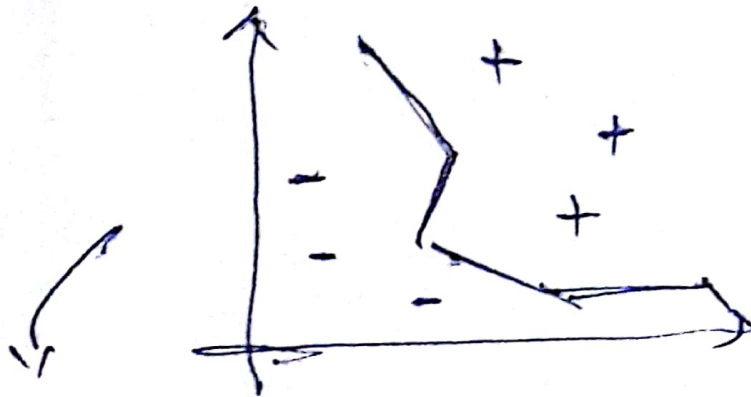


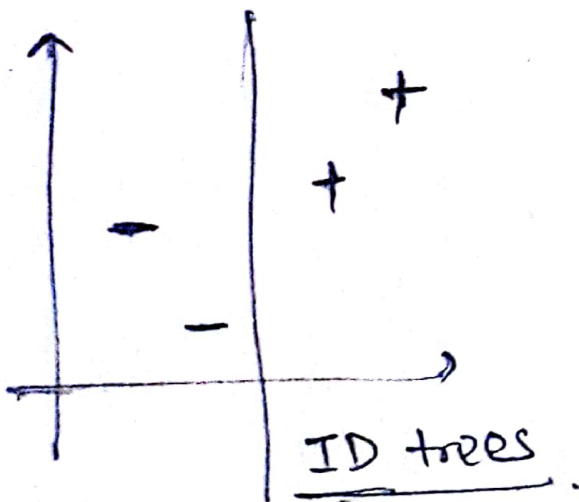
Support Vector machines

(1)

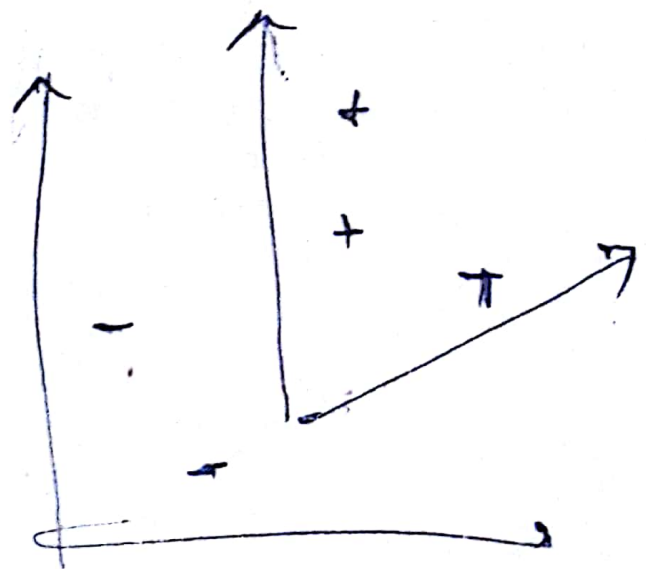
Suppose we have a dataset like below and we wish to obtain a decision boundary separating the two samples.



decision boundary obtained by using KNN



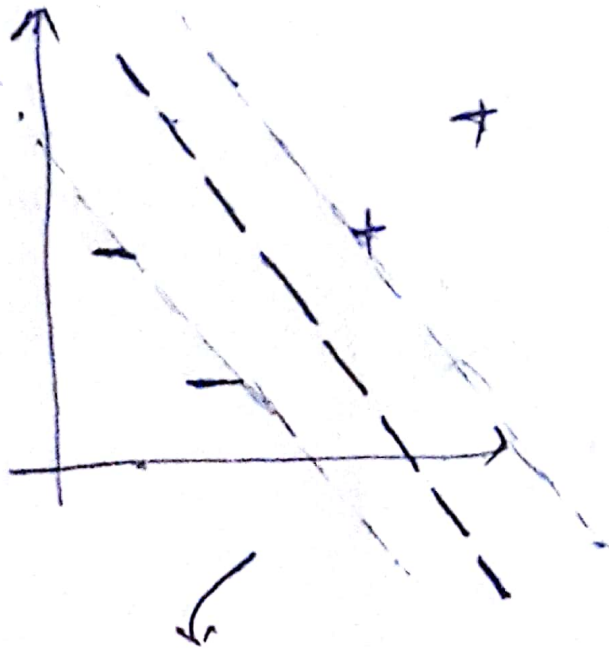
ID trees



Neural Nets

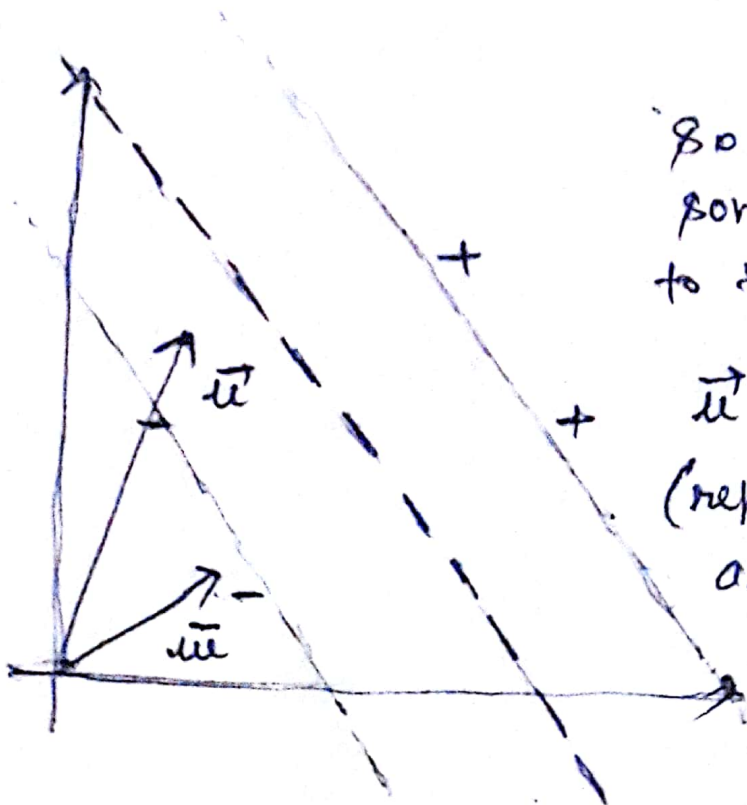
But how would a SVM work with such a dataset?

②



Vladimir Vapnik, introduced SVM's by saying that we draw a line which is farthest from each of the class.

It tries to put a line in between so that the separation b/w the line and the street is as wide as possible.



So, \vec{u} is vector of some length perpendicular to the street.

\vec{u} is some vector (represents a vector to an unknown in the space).

Now we will try and take projection of \vec{u} on the vector \vec{w} , and its length will tell us if the point \vec{u} is in the class or +ve class. (3)

$$\vec{w} \cdot \vec{u} \geq c$$

$$b = -c$$

$$\vec{w} \cdot \vec{u} + b \geq 0 \quad \text{Then +ve (1)}$$

DECISION RULE

↓ but right now we don't know what \vec{w} to use or which b to use. (there are many \vec{w} possible right now).

* So what we are going to do now is lay down enough constraints so that we'll eventually be able to figure out \vec{w} and b .

Now we are going to start out laying some constraints.

(4)

$$\overline{w} \cdot \overline{x}_+ + b \geq 1$$

We are going to insist that if a sample is a positive sample then our decision function is

going to give a value of 1 or greater than 1.

$$\overline{w} \cdot \overline{x}_- + b \leq -1$$

Similarly, if some sample is a negative sample, we are

going to insist that

Now above we have two equations but, carrying around these equations is kinda pain. So I'll try to introduce a variable (y_i) to make life little easier.

$$y_i = \begin{cases} +1 & \text{for +ve samples} \\ -1 & \text{for -ve samples} \end{cases}$$

Multiplying y_i to both the equations.

(5)

$$y_i (\bar{x}_i \cdot \bar{w} + b) \geq 1 \cdot y_i \Rightarrow \text{here } y_i = +1$$

$$\therefore \boxed{y_i (\bar{x}_i \cdot \bar{w} + b) \geq 1}$$

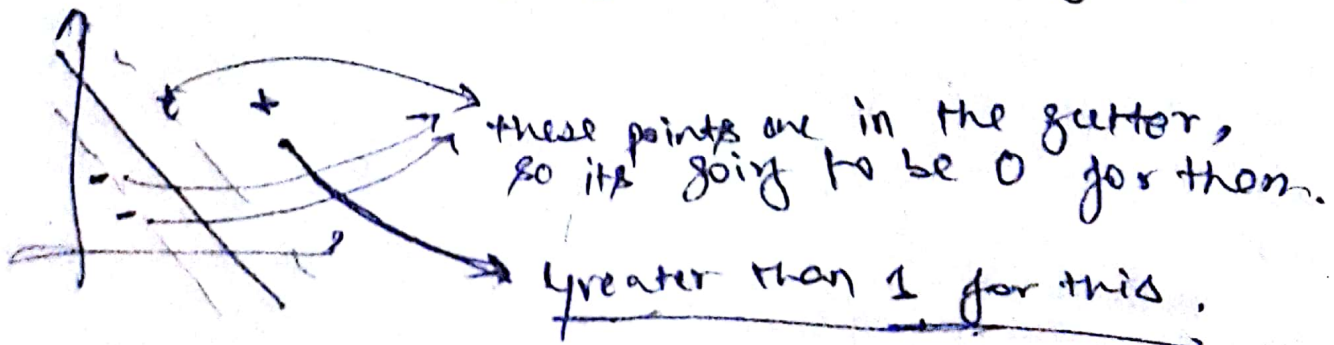
$$y_i (\bar{x}_i \cdot \bar{w} + b) \leq -1 \cdot y_i \Rightarrow \text{here } y_i = -1$$

$$\therefore \boxed{y_i (\bar{x}_i \cdot \bar{w} + b) \geq 1}$$

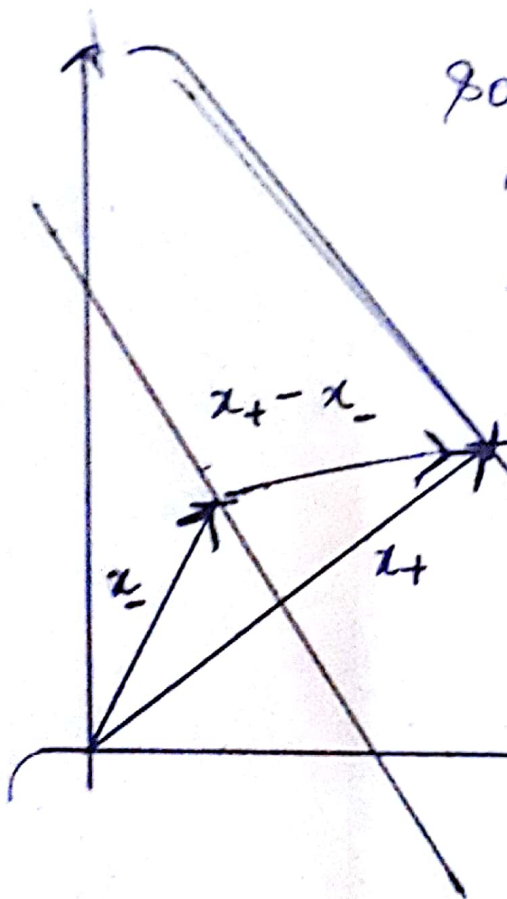
Now, our purpose of introducing this new variable y_i has been fulfilled, both of our equations are now same.

$$\boxed{y_i (\bar{x}_i \cdot \bar{w} + b) - 1 \geq 0} \quad (2)$$

It's always going to be greater than 0, but for \bar{x}_i in the gutter, it's going to be exactly 0.



(6)



So we draw a few vectors,

x_+ and x_- vector and then we subtracted those vectors and draw a $(x_+ - x_-)$ vector.

Now we'll take projection of this vector on a unit vector in a direction \perp to the street i.e. in the direction of vector \vec{u} .

$$\text{WIDTH} = (\bar{x}_+ - \bar{x}_-) \cdot \left(\frac{\vec{u}}{\|\vec{u}\|} \right)$$

Now, let's look at the equation (2),

$$y_i (\bar{x}_i \cdot \vec{u} + b) - 1 = 0$$

for a +ve sample, $\vec{u} \cdot \bar{x}_i = 1 - b$

for a -ve sample, $-\vec{u} \cdot \bar{x}_i = 1 + b$

Putting these back into the above equation,

(7)

$$\text{WIDTH} = \frac{(\bar{x}_+ \cdot \bar{w}) - (\bar{x}_- \cdot \bar{w})}{\|\bar{w}\|} = \frac{(1-b) + (1+b)}{\|\bar{w}\|}$$

$$\boxed{\text{WIDTH} = \frac{2}{\|\bar{w}\|}} \quad (8)$$

So, Now what we're trying to do is, we are trying to maximize the width of the street.

∴ what we'll like to do is $\boxed{\text{MINIMIZE } \|\bar{w}\|}$

And to minimize $\|\bar{w}\|$, we can also say that, we'll like to

$$\boxed{\text{MINIMIZE } \left(\frac{1}{2} \|\bar{w}\|^2 \right)}$$

⊛ And we did that because it's mathematically convenient.

Now if we want to find minimum, extremum of something and we have some constraints that we'd like to honour, we'll use Lagrange's Multiplier

Now, we are going to use Lagrang multipliers to find the extremum of our function.

⑧

$$L = \frac{1}{2} \|w\|^2 - \sum \alpha_i [y_i (\bar{w} \cdot \bar{x}_i + b) - 1]$$

And to find the extremum i.e. minimum/maximum we'll find its partial derivatives and set them to 0.

$$\frac{\partial L}{\partial \bar{w}} = \bar{w} - \sum \alpha_i y_i x_i = 0$$

$$\Rightarrow \boxed{\bar{w} = \sum_i \alpha_i y_i x_i}$$

$$\frac{\partial L}{\partial b} = - \sum_i \alpha_i y_i = 0$$

③

$$\Rightarrow \boxed{\sum \alpha_i y_i = 0}$$

So we found the derivatives of L w.r.t to whatever might vary. i.e. w and b and equaled it to 0.

And then we obtain these above two relations.

Now we have obtained the value of \bar{w} and b which will give us the extremum, so we'll plug those values of \bar{w} and b into the Lagrangian. (9)

$$L = \frac{1}{2} \|\bar{w}\|^2 - \sum \alpha_i [y_i (\bar{w} \cdot \bar{x}_i + b) - 1]$$

$$L = \frac{1}{2} \left(\sum_i \alpha_i y_i \bar{x}_i \right) \left(\sum_j \alpha_j y_j \bar{x}_j \right) - \sum \alpha_i y_i b + \sum \alpha_i - \sum_i \alpha_i y_i \bar{x}_i \left(\sum_j \alpha_j y_j \bar{x}_j \right)$$

$$\textcircled{2} - \sum \alpha_i y_i b = -b \sum \alpha_i y_i = 0$$

Adding $\textcircled{1}$ and $\textcircled{4}$

$$L = -\frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j (\bar{x}_i \cdot \bar{x}_j) + \sum_i \alpha_i$$

$$L = \sum \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j (\bar{x}_i \cdot \bar{x}_j) \quad \textcircled{4}$$

We went through all this trouble to realize that (10)
what's the dependence of this width.

As it turns out, it depends on the sample vectors \bar{x}_i and \bar{x}_j and the optimization depends only on the dot product of the pairs of samples, $(\bar{x}_i \cdot \bar{x}_j)$.

Now as we plugged the \bar{u} into the Lagrangian, we are also going to plug into the decision rule, (1) to see what happens.

$$\bar{u} \cdot \bar{u} + b \geq 0 \rightarrow \text{then the}$$

$$\sum_i \alpha_i y_i \bar{x}_i \cdot \bar{u} + b \geq 0$$

$$\boxed{\sum_i \alpha_i y_i (\bar{x}_i \cdot \bar{u}) + b \geq 0} \rightarrow \text{then the}$$

So all the math is being dependent on the dot product of (\bar{x}_i) and (\bar{u}) .