#### Practical Work No.1- Documentation

The class called Graph represents a directed graph and contains the following methods:

• The Constructor(\_\_init\_\_(self)):

The graph is represented using 3 dictionaries, named as it follows:

- dIn: dictionary in
- dOut: dictionary out
- dCost: dictionary of costs of edges
- noVertices: the current number of vertices in the graph
- noEdges: the current number of edges in the graph
- vertexList: the list of vertices in the graph

Complexity: O(1)

• loadFromFileInit(self, file\_name):

Loads the data of a directed graph from a text file (initial read so the isolated vertices are not taken into account)

:param: file\_name -the name of the file we want to read the data from

Complexity: O(number of edges) -linear complexity for reading a list of edges

• loadFromFile(self, file\_name):

Loads the data of a directed graph from a text file (normal read so the isolated vertices are taken into account)- since, at this point, the graph may not contain all its vertices, we also list at the beginning the list of current vertices, beginning on the 2<sup>nd</sup> row of the file. (see Page 6 for example)

:param: file\_name -the name of the file we want to read the data from

Complexity: O(number of edges + number of isolated vertices) -linear complexity for reading a list of edges and the isolated vertices, if any

• writeToFile(self, file\_name):

Save a graph's data to a file with a given name :param: file\_name -the name of the file we save the data to

Complexity: O(edge number + isolated vertex number)

• addVertex(self, vertex):

Add a new vertex to the graph by creating its corresponding successors and predecessors lists, incrementing the vertex number and adding it to the vertices list

Precondition: the vertex must not exist in the graph beforehand :param vertex: the given vertex that we must add to the graph :return: 0 if the vertex already exists and cannot be added, else 1

Complexity: O(1)

• removeVertex(self, vertex):

Remove a vertex from the graph (and the edges containing it)
Precondition: the vertex must exist in the graph
:param vertex: the given vertex that we must remove from the graph
:return: Raise a ValueError if the vertex does not exist in the graph

Complexity: O(number\_of\_edges) - we parse through the list of edges to see which ones contain the vertex we have just removed

• addEdge(self, StartVertex, EndVertex, edgeCost):

Adds an edge (StartVertex, EndVertex) of cost edgeCost
Preconditions: Both the source and the target must exist
The edge must not exist in the graph beforehand
:param StartVertex: the source vertex of the edge
:param EndVertex: the target vertex of the edge
:param edgeCost: the edge's cost
:return: Paises ValueErrors if the preconditions are not fulfilled

:return: Raises ValueErrors if the preconditions are not fulfilled

Complexity: O(1)

• removeEdge(self, SourceVertex, TargetVertex):

Remove an edge identified by its target and source vertices Preconditions: both vertices must exist in the graph The edge must exist in the graph :param SourceVertex: the source vertex of the edge :param TargetVertex: the target vertex of the edge :return: Raises ValueErrors if the preconditions are not fulfilled Complexity: O(1)

• EmptyGraphInit(self, id):

Initialises an empty graph with the given number of vertices/ given list of vertices

:param id: 0 when loading the graph from the initial file, 1 when loading the graph with isolated vertices :return:

Complexity: O(number\_of\_vertices)

• checkifEdgeExists(self, StartVertex, EndVertex):

Checks if an edge already exists in the graph :param StartVertex: the source vertex of the edge :param EndVertex: the target vertex of the edge :return: 1 if the edge already exists, else 0 """

Complexity: O(n), where n is length(\_dIn.keys)+length(\_dOut.keys)+length(\_dIn[EndVertex])

• checkifVertexExists(self, vertex):

Checks if a given vertex exists in the graph :param vertex: the given vertex :return: 1 if the vertex exists, else 0, or a ValueError if the precondition is not fulfilled

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Complexity:

O(n), where n is the length of the vertex list

• numberOfVertices(self):

Returns the number of vertices in the graph

• inDegree(self, vertex):

Gets the in degree of a given vertex

Precondition: the vertex must exist in the graph beforehand

:param vertex: given vertex

:return: the in-degree of the vertex, or a ValueError if the precondition

is not fulfilled

Complexity: O(1)

## • outDegree(self, vertex):

**(())** 

Gets the out degree of a given vertex

Precondition: the vertex must exist in the graph beforehand

:param vertex: given vertex

:return: the out-degree of the vertex

Complexity: O(1)

#### • retrieveCost(self, edge):

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Retrieve the information(cost) associated to an edge

Precondition: the edge must exist in the graph beforehand

:param edge: the edge we want to retrieve the cost of

:return: the cost of the edge, or a ValueError if the precondition is not

fulfilled

Complexity: O(1)

modifyCost(self, edge, value):

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Modify the information(cost) associated to an edge

Precondition: the edge must exist in the graph beforehand

:param edge: the edge

:param value: the new cost of the edge

:return: raise a ValueError if the condition is not fulfilled

Complexity: O(1)

#### • checkIsolatedVertex(self, vertex):

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Checks if a vertex is an isolated one

Precondition: the vertex must exist in the graph beforehand

:param vertex: the vertex

:return: 1 if the vertex is isolated (both its in-degree and out-degreeare

0), else 0. Raises a ValueError if the precondition is not fulfilled

Complexity: O(1)

#### parseVertices(self):

Parse through the set of vertices in the graph

Return: an iterator for the set of vertices

Complexity: O(n), where n is the length of VertexList

## parseInbound(self, vertex):

Parse the set of inbound edges of a specified vertex and provide the source vertex for each edge

Precondition: the given vertex must exist in the graph

:param vertex: the given vertex

:return: an iterator for the set of source vertices

Complexity: O(n), where n is the in-degree of the given vertex

## parseOutbound(self, vertex):

Parse the set of qoutbound edges of a specified vertex and provide the target vertex for each edge

Precondition: the given vertex must exist in the graph

:param vertex: the given vertex

:return: an iterator for the set of target vertices

Complexity: O(n), where n is the out-degree of the given vertex

#### Copy(self):

Returns a copy of the graph

Complexity: O(1)

The UI class acts as a link between the directed graph implementation and the user interface (it is, in fact, the user interface), and, besides the command menu, it also contains a random graph generator functions, defined as follows:

# randomGraphGenerator(vertexNumber, edgeNumber, fileName):

Generate a random graph with a specified number of vertices and edges and write it to a file whose name is given from the user input

Precondition: number of edges can be maximum the square of the number of vertices

:param vertexNumber: the number of vertices

:param edgeNumber: the number of edges

:param fileName: the name of the file the graph will be saved to

:return: -

Complexity: O(n), where n is the number of edges

---- Saving graph to file----

#### Initial file:

```
5 6
0 0 1
0 1 7
1 2 2
2 1 -1
1 3 8
2 3 5
```

Operation: remove vertex 2 Save graph to file

# Output file:

```
43
0
1
3
4
0 0 1
0 1 7
1 3 8
```

4 3-4 vertices and 3 edges

0, 1,3,4 -the vertices contained in the graph

(0,0,1), (0,1,7), (1,3,8) -edges contained in the graph

4 -isolated vertex