

# E14 BP Algorithm (C++/Python)

---

17341015 Hongzheng Chen

December 12, 2019

## Contents

<b>1</b>	<b>Horse Colic Data Set</b>	<b>2</b>
<b>2</b>	<b>Reference Materials</b>	<b>2</b>
<b>3</b>	<b>Tasks</b>	<b>5</b>
<b>4</b>	<b>Codes and Results</b>	<b>6</b>

# 1 Horse Colic Data Set

The description of the horse colic data set (<http://archive.ics.uci.edu/ml/datasets/Horse+Colic>) is as follows:

Data Set Characteristics:	Multivariate	Number of Instances:	368	Area:	Life
Attribute Characteristics:	Categorical, Integer, Real	Number of Attributes:	27	Date Donated	1989-08-06
Associated Tasks:	Classification	Missing Values?	Yes	Number of Web Hits:	108569

We aim at trying to predict if a horse with colic will live or die.

Note that we should deal with missing values in the data! Here are some options:

- Use the features mean value from all the available data.
- Fill in the unknown with a special value like -1.
- Ignore the instance.
- Use a mean value from similar items.
- Use another machine learning algorithm to predict the value.

## 2 Reference Materials

1. Stanford: **CS231n: Convolutional Neural Networks for Visual Recognition** by Fei-Fei Li, etc.
  - Course website: <http://cs231n.stanford.edu/2017/syllabus.html>
  - Video website: [https://www.bilibili.com/video/av17204303/?p=9&tdsourcetag=s\\_pctim\\_aiomsg](https://www.bilibili.com/video/av17204303/?p=9&tdsourcetag=s_pctim_aiomsg)
2. **Machine Learning** by Hung-yi Lee
  - Course website: <http://speech.ee.ntu.edu.tw/~tlkagk/index.html>
  - Video website: <https://www.bilibili.com/video/av9770302/from=search>
3. A Simple neural network code template

```
# -*- coding: utf-8 -*-
import random
import math

# Shorthand:
# "pd_" as a variable prefix means "partial derivative"
# "d_" as a variable prefix means "derivative"
# "_wrt_" is shorthand for "with respect to"
# "w_ho" and "w_ih" are the index of weights from hidden to output layer neurons and
  ↳ input to hidden layer neurons respectively

class NeuralNetwork:
    LEARNING_RATE = 0.5
    def __init__(self, num_inputs, num_hidden, num_outputs, hidden_layer_weights =
        ↳ None, hidden_layer_bias = None, output_layer_weights = None,
        ↳ output_layer_bias = None):
        #Your Code Here

    def init_weights_from_inputs_to_hidden_layer_neurons(self, hidden_layer_weights):
        #Your Code Here

    def init_weights_from_hidden_layer_neurons_to_output_layer_neurons(self,
        ↳ output_layer_weights):
```

```

#Your Code Here

def inspect(self):
    print('-----')
    print('* Inputs: {}'.format(self.num_inputs))
    print('-----')
    print('Hidden Layer')
    self.hidden_layer.inspect()
    print('-----')
    print('* Output Layer')
    self.output_layer.inspect()
    print('-----')

def feed_forward(self, inputs):
    #Your Code Here

# Uses online learning, ie updating the weights after each training case
def train(self, training_inputs, training_outputs):
    self.feed_forward(training_inputs)

    # 1. Output neuron deltas
    #Your Code Here
    #  $E / z$ 

    # 2. Hidden neuron deltas
    # We need to calculate the derivative of the error with respect to the output
    #  $\rightarrow$  of each hidden layer neuron
    #  $dE / dy = E / z * z / y = E / z * w$ 
    #  $E / z = dE / dy * z / w$ 
    #Your Code Here

    # 3. Update output neuron weights
    #  $E / w = E / z * z / w$ 
    #  $w = * E / w$ 
    #Your Code Here

    # 4. Update hidden neuron weights
    #  $E / w = E / z * z / w$ 
    #  $w = * E / w$ 
    #Your Code Here

def calculate_total_error(self, training_sets):
    #Your Code Here
    return total_error

class NeuronLayer:
    def __init__(self, num_neurons, bias):

        # Every neuron in a layer shares the same bias
        self.bias = bias if bias else random.random()

        self.neurons = []
        for i in range(num_neurons):
            self.neurons.append(Neuron(self.bias))

def inspect(self):

```

```

        print('Neurons:', len(self.neurons))
        for n in range(len(self.neurons)):
            print(' Neuron', n)
            for w in range(len(self.neurons[n].weights)):
                print(' Weight:', self.neurons[n].weights[w])
            print(' Bias:', self.bias)

    def feed_forward(self, inputs):
        outputs = []
        for neuron in self.neurons:
            outputs.append(neuron.calculate_output(inputs))
        return outputs

    def get_outputs(self):
        outputs = []
        for neuron in self.neurons:
            outputs.append(neuron.output)
        return outputs

class Neuron:
    def __init__(self, bias):
        self.bias = bias
        self.weights = []

    def calculate_output(self, inputs):
        #Your Code Here

    def calculate_total_net_input(self):
        #Your Code Here

    # Apply the logistic function to squash the output of the neuron
    # The result is sometimes referred to as 'net' [2] or 'net' [1]
    def squash(self, total_net_input):
        #Your Code Here

    # Determine how much the neuron's total input has to change to move closer to the
    #     ↪ expected output
    #
    # Now that we have the partial derivative of the error with respect to the output
    #     ↪ (E/y) and
    # the derivative of the output with respect to the total net input (dy/dz) we can
    #     ↪ calculate
    # the partial derivative of the error with respect to the total net input.
    # This value is also known as the delta () [1]
    #     = E / z     = E / y * dy / dz
    #
    def calculate_pd_error_wrt_total_net_input(self, target_output):
        #Your Code Here

    # The error for each neuron is calculated by the Mean Square Error method:
    def calculate_error(self, target_output):
        #Your Code Here

    # The partial derivate of the error with respect to actual output then is
    #     ↪ calculated by:
    # = 2 * 0.5 * (target output - actual output) ^ (2 - 1) * -1

```

```

# = -(target output - actual output)
#
# The Wikipedia article on backpropagation [1] simplifies to the following, but
    ↪ most other learning material does not [2]
# = actual output - target output
#
# Alternative, you can use (target - output), but then need to add it during
    ↪ backpropagation [3]
#
# Note that the actual output of the output neuron is often written as y and
    ↪ target output as t so:
# = E / y = -(t - y)
def calculate_pd_error_wrt_output(self, target_output):
#Your Code Here

# The total net input into the neuron is squashed using logistic function to
    ↪ calculate the neuron's output:
# y = 1 / (1 + e^(-z))
# Note that where represents the output of the neurons in whatever layer we're
    ↪ looking at and represents the layer below it
#
# The derivative (not partial derivative since there is only one variable) of the
    ↪ output then is:
# dy / dz = y * (1 - y)
def calculate_pd_total_net_input_wrt_input(self):
#Your Code Here

# The total net input is the weighted sum of all the inputs to the neuron and
    ↪ their respective weights:
# z = net = xw + xw ...
#
# The partial derivative of the total net input with respect to a given weight
    ↪ (with everything else held constant) then is:
# z / w = some constant + 1 * xw^(1-0) + some constant ... = x
def calculate_pd_total_net_input_wrt_weight(self, index):
#Your Code Here

# An example:

nn = NeuralNetwork(2, 2, 2, hidden_layer_weights=[0.15, 0.2, 0.25, 0.3],
    ↪ hidden_layer_bias=0.35, output_layer_weights=[0.4, 0.45, 0.5, 0.55],
    ↪ output_layer_bias=0.6)
for i in range(10000):
    nn.train([0.05, 0.1], [0.01, 0.99])
    print(i, round(nn.calculate_total_error([[0.05, 0.1], [0.01, 0.99]]), 9))

```

### 3 Tasks

- Given the training set `horse-colic.data` and the testing set `horse-colic.test`, implement the BP algorithm and establish a neural network to predict if horses with colic will live or die. In addition, you should calculate the accuracy rate.
- Please submit a file named `E14.YourNumber.pdf` and send it to `ai_201901@foxmail.com`

## 4 Codes and Results