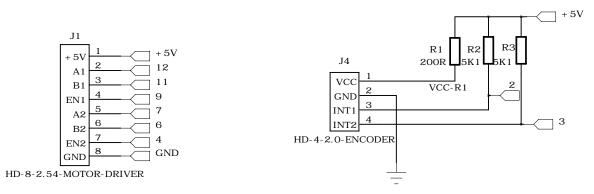
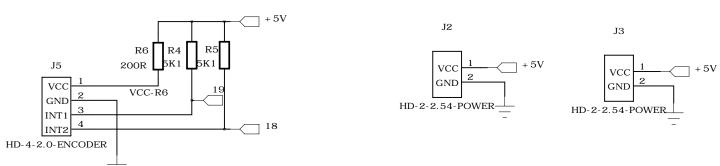


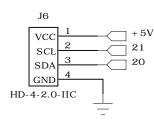
## Right-motor



## Left-motor







## UART2

