ENX 10 EASY/QUAD

Encoder Ø10 mm, 1...1024 CPT

Capitalize Integrated



Key Data	E/	ASY Incremental Differential	QUAD Increme	ental
Number of channels	3		2	
Max. counts per turn	10	24	1	
Encoder length L4	mm 8.	5	8.5	
Ambient temperature	°C -4	0 +100	-40 +100	
Weight	a <5		<5	

Selection criteria	EASY Incremental Differential	QUAD Incremental	
Speed and rotation direction detection			
Speed and position control		▲	
Compact and robust design			
High resolution		•	
Cost effective			
■ suitable suitable to a limited extent ●	not suitable		

Specifications		EASY Incremental Differential		QUAD Incremental
Supply voltage Vcc		5 ±0.5		5 ±0.5
Typical current draw	mΑ	22		5.5
Max. operating frequency	kHz	500		2
Max. Speed	rpm	30000		30000
Connector		10-pin 1.27 mm multipoint connector ⁵		10-pin 2.54 mm multipoint connector ³
		e.g. Samtec FFSD series		(IEC/EN 60603-1-DIN41651)
		Pin 1 Do not connect ¹ (BiSS-C Data)		Pin 1 Not connected
		Pin 2 V _{cc}		Pin 2 V _{CC}
		Pin 3 GND		Pin 3 Channel A
		Pin 4 Do not connect1 (BiSS-C CLK)		Pin 4 Channel B
		Pin 5 Channel A		Pin 5 GND
		Pin 6 Channel A	1	Pin 6 Not connected
		Pin 7 Channel B	9	Pin 7 Not connected 9
		Pin 8 Channel B		Pin 8 Not connected 2
		Pin 9 Channel Ī	10	Pin 9 Not connected
		Pin 10 Channel I		Pin 10 Not connected
		Output signal: EIA-Standard RS 422		Output signal: TTL compatible
		Output current per channel: ± 20 mA		Output current per channel: + 10 mA
		The second secon		
Configuration		EASY Incremental Differential		QUAD Incremental
Counts per turn ²		1 1024		1
Cable length	mm	50, 100, 150, 200, 300, 500, 1000		50, 100, 150, 200, 300, 500, 1000
Alignment of cable outlet in relation to motor flange	0	15		15

CCX 10 S EASY, QUAD 68 CCX 10 L EASY, QUAD 69 CCX 12 S EASY, QUAD 70 CCX 12 L EASY, QUAD 71 CCX 14 L EASY, QUAD 72-73 CCX 16 S EASY, QUAD 76-77 CCX 16 L EASY, QUAD 76-77 CCX 19 S CCX 22 S EASY, QUAD CCX 23 S CCX 24 L EASY, QUAD CCX 25 S CCX 25 S CCX 26 L EASY, QUAD CCX 26 S CCX 27 S CCX 28 S CCX 28 S CCX 38 S CC	maxon Modular Sy	stem	Page	Dimensions Standard Configuration	M 1:1 Notes
OC-max 22 S EASY, QUAD 92-93	maxon DC motor DCX 10 S DCX 10 L DCX 12 S DCX 12 L DCX 14 L DCX 16 S DCX 16 L DCX 19 S DCX 22 S DCX 22 L DCX 26 L DCX 32 L DCX 35 L	EASY, QUAD	68 69 70 71 72–73 74–75 76–77 78–79 80–81 82–83 84–85 86	Ø10 -0.05	encoder. 2 maxon controllers require a resolution of at least 16 counts per turn. 3 Option: 6-pol 2.54 mm pin header. 4 For attachment to DCX motors: plus 2-4 mm thic intermediate plate. 5 Option: Also available with FFC cable, 0.5 mm pitch matching connector Molex 52745-1097,
	DC-max 10 S DC-max 22 S DC-max 26 S	EASY, QUAD	92-93		