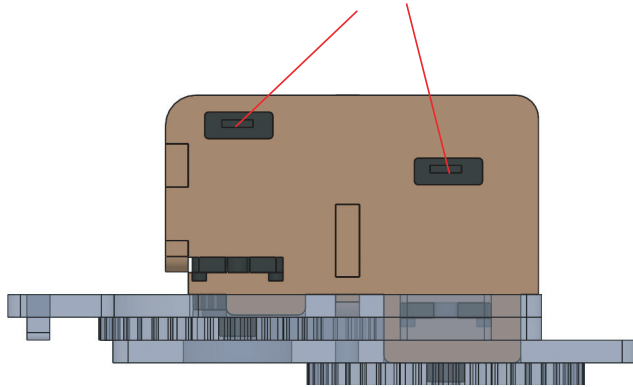


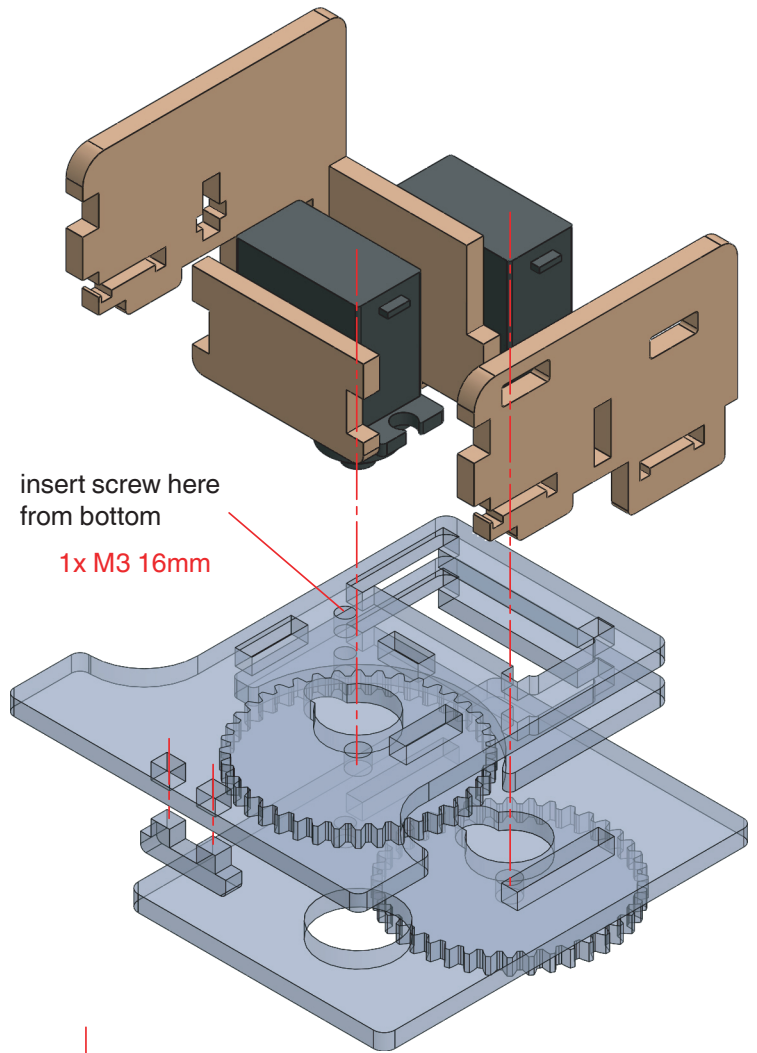
### X-Stage

insert servo cables  
through here

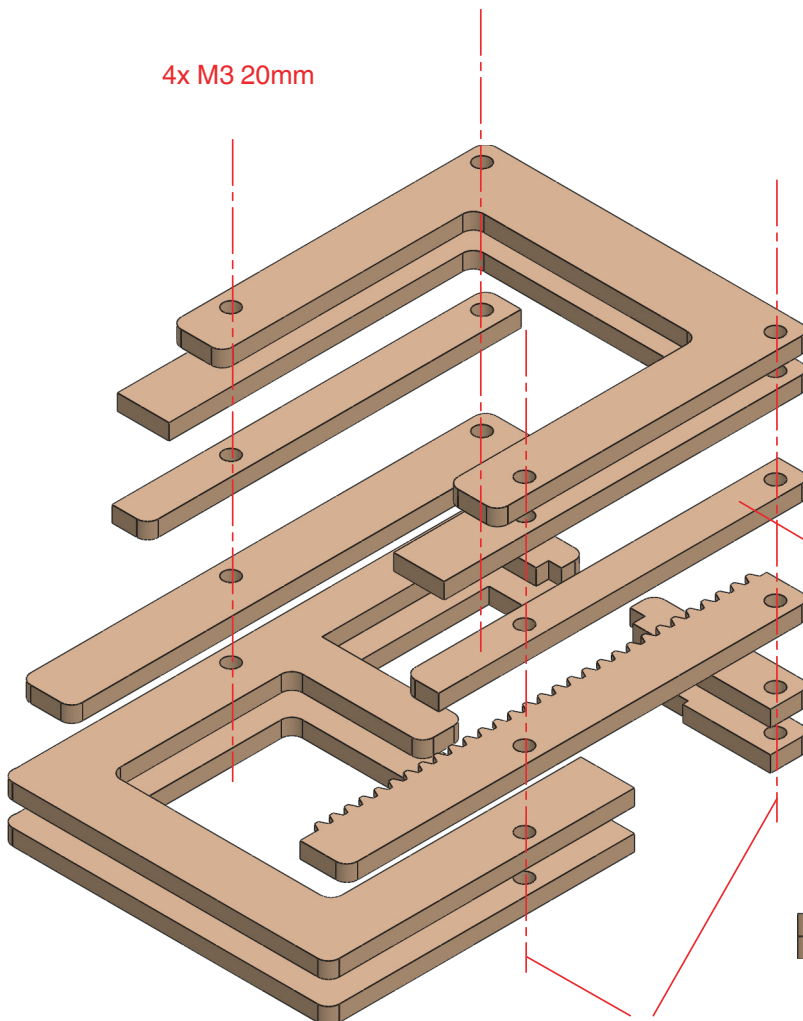


insert screw here  
from bottom

1x M3 16mm



4x M3 20mm



### Base

add paper spacers here



insert screws from bottom

## Y-Stage

4x M3 12mm

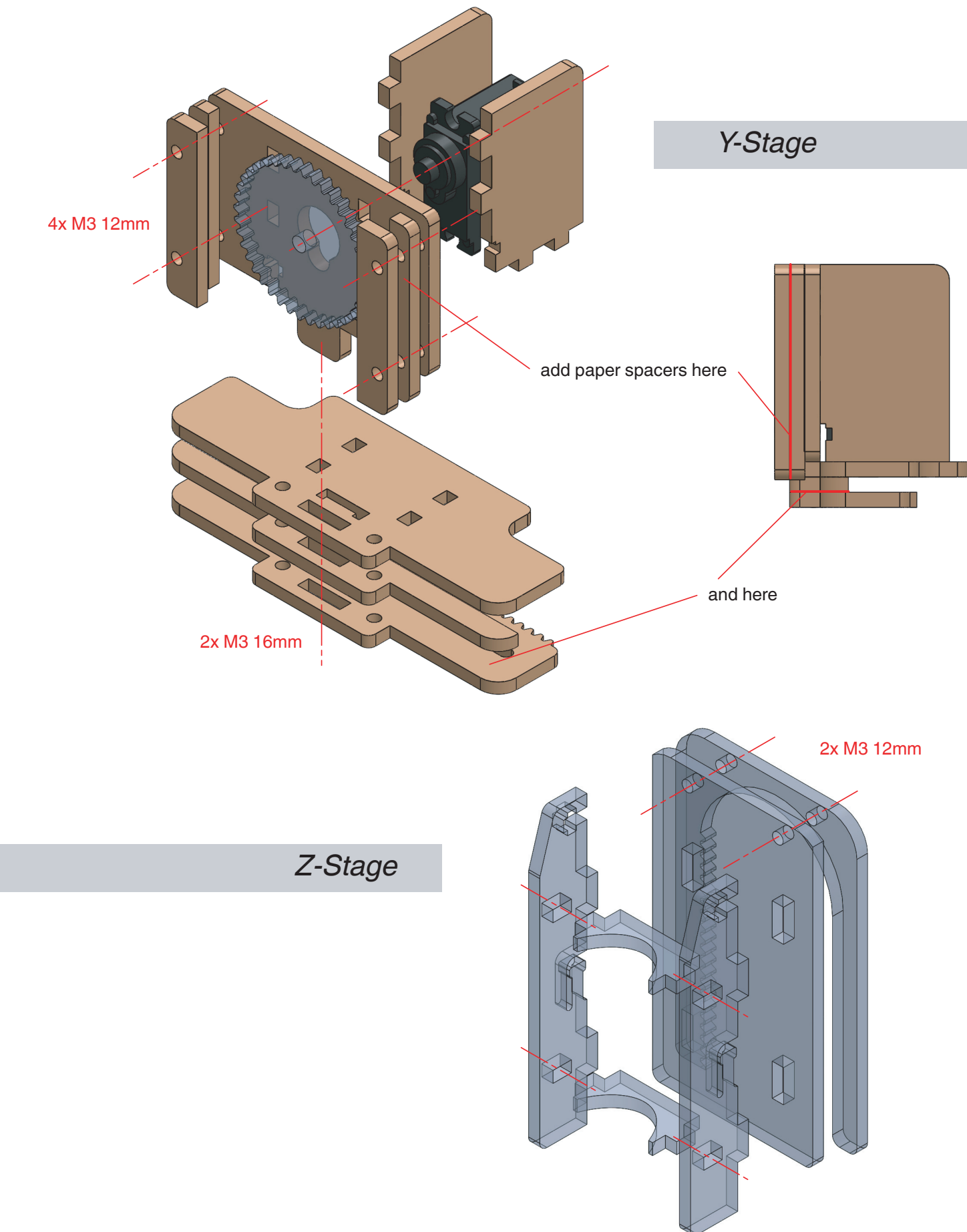
add paper spacers here

and here

2x M3 16mm

## Z-Stage

2x M3 12mm



Assemble X, Y and Z stages by turning servos to their minimum positions, and then sliding the rack onto the gear.

## *Arduino & Base-plate*

