

# Class Documentation

## pwmBoard Class Reference

Hardware interface class for the **pwmBoard** PCA9634 based PWM dimmer board.

```
#include <pwmBoard.h>
```

### Public Member Functions

- **pwmBoard** (uint8\_t, uint8\_t)  
*Constructor for multiple board setups.*
- **pwmBoard** (uint8\_t)  
*Constructor for single board setups.*
- void **start** ()  
*Starts the i2c bus and initializes the board. This must be called before any other member functions.*
- void **setLevel** (uint8\_t, uint8\_t)  
*Sets the output level of one output channel and if autoUpdate==true, sends the values to the boards.*
- void **setLevel** (uint8\_t)  
*Sets the output level to all outputs and if autoUpdate==true, sends the values to the boards.*
- void **setLevelSend** (uint8\_t, uint8\_t)  
*Sets the output level of one output channel and sends the values to the boards. This function is for backward compatibility.*
- void **setLevelSend** (uint8\_t)  
*Sets the output level to all outputs and sends the values to the boards. This function is for backward compatibility.*
- byte \* **getPtr** ()  
*Get a pointer to the output buffer.*
- void **send** ()  
*Identical to **send()**, only here for backwards compatibility. Use **send()** for all new code.*
- void **update** ()  
*Send the current output buffer to all boards.*

### Public Attributes

- boolean **autoUpdate**
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## Detailed Description

Hardware interface class for the **pwmBoard** PCA9634 based PWM dimmer board.

#### Author:

Keegan Morrow

#### Version:

4

Revision history:

r2 - 12/2011 - KM - update for compatibility with arduino 100

r3 - 2/2012 - KM - added support for multiple boards per class instance

r4 - 8/2012 - KM - added **update()** and **autoUpdate** for similarity with other libraries

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## Constructor & Destructor Documentation

### **pwmBoard::pwmBoard (uint8\_t *baseAddress*, uint8\_t *numBoards*)**

Constructor for multiple board setups.

#### **Parameters:**

<i>baseAddress</i>	Address of the first board.
<i>numBoards</i>	Number of boards with sequential addresses.

### **pwmBoard::pwmBoard (uint8\_t *baseAddress*)**

Constructor for single board setups.

#### **Parameters:**

<i>baseAddress</i>	Address of the board.
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## Member Function Documentation

### **byte \* pwmBoard::getPtr ()**

Get a pointer to the output buffer.

#### **Returns:**

Pointer to the output buffer.

### **void pwmBoard::send ()**

Identical to **send()**, only here for backwards compatibility. Use **send()** for all new code.

### **void pwmBoard::setLevel (uint8\_t *index*, uint8\_t *level*)**

Sets the output level of one output channel and if **autoUpdate==true**, sends the values to the boards.

#### **Parameters:**

<i>index</i>	Output channel to set
<i>level</i>	Level to set the channel to [0..255]

### **void pwmBoard::setLevel (uint8\_t *level*)**

Sets the output level to all outputs and if autoUpdate==true, sends the values to the boards.

#### **Parameters:**

<i>level</i>	Level to set the outputs [0..255]
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### **void pwmBoard::setLevelSend (uint8\_t *index*, uint8\_t *level*)**

Sets the output level of one output channel and sends the values to the boards. This function is for backward compatibility.

[long description]

#### **Parameters:**

<i>index</i>	Output channel to set
<i>level</i>	Level to set the channel to [0..255]

### **void pwmBoard::setLevelSend (uint8\_t *level*)**

Sets the output level to all outputs and sends the values to the boards. This function is for backward compatibility.

#### **Parameters:**

<i>level</i>	Level to set the outputs [0..255]
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### **void pwmBoard::start ()**

Starts the i2c bus and initializes the board. This must be called before any other member functions.

### **void pwmBoard::update ()**

Send the current output buffer to all boards.

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## **Member Data Documentation**

### **boolean pwmBoard::autoUpdate**

If autoUpdate is set to true, **update()** is called automatically from **setLevel()**

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The documentation for this class was generated from the following files:

- **pwmBoard.h**
- **pwmBoard.cpp**

# File Documentation

## pwmBoard.cpp File Reference

```
#include "pwmBoard.h"
```

### Macros

- `#define WIRE_WRITE_FUNCTION send`
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### Macro Definition Documentation

```
#define WIRE_WRITE_FUNCTION send
```

## pwmBoard.h File Reference

```
#include "WProgram.h"  
#include <inttypes.h>  
#include "../Wire/Wire.h"
```

### Classes

- class `pwmBoard`

***Hardware interface class for the pwmBoard PCA9634 based PWM dimmer board.***

### Macros

- `#define PWMBOARD 4`
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### Macro Definition Documentation

```
#define PWMBOARD 4
```