

PyBOP: A Python package for battery model optimisation and parameterisation

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Summary

PyBOP provides a range of tools for the parameterisation and optimisation of battery models, offering both Bayesian and frequentist approaches with example workflows to assist the user. PyBOP can be used to parameterise various battery models, including the electrochemical and equivalent circuit models provided by the popular open-source package PyBaMM (Sulzer et al., 2021). Likewise, PyBOP can be used for design optimisation for a given parameter set under predefined operating conditions. PyBOP allows users to parameterise battery models through a variety of methods, providing diagnostics into the convergence of the optimisation task. These identified parameter sets can then be used for design optimisation to support development of improved battery configurations.

- PyBOP incorporates a PDE solver, and parameterisation/optimisation workflows into a single package.
- PyBOP provide identifiability estimates for the identified parameter set (Hessian approximation, fisher information?, Posterior variance, CI upper/lower)

Statement of need

PyBOP is designed to provide a user-friendly, object-oriented interface for the optimisation of battery models which have been implemented in existing battery modelling software, e.g. PyBaMM (Sulzer et al., 2021). This software package is intended to serve a broad audience of students, engineers, and researchers in both academia and the battery industry. PyBOP prioritises clear and informative diagnostics for both new and experienced users, while also leveraging advanced optimisation algorithms provided by SciPy (Virtanen et al., 2020), PINTS (Clerx et al., 2019), and internal implementations.

PyBOP supports the Battery Parameter eXchange (BPX) standard (Korotkin et al., 2023) for sharing battery parameter sets. These parameter sets are costly to obtain due to a number of factors: the equipment cost and time spent on characterisation experiments, the requirement of battery domain knowledge and the computational cost of parameter estimation. PyBOP reduces the barrier to entry and ongoing costs by providing an accessible workflow that efficiently connects battery models with numerical optimisers, as well as explanatory examples of battery parameterisation and design optimisation.

This package complements other tools in the field of lithium-ion battery modelling built around PyBaMM such as liionpack for simulating battery packs (Tranter et al., 2022).

39 Architecture

40 PyBOP is a Python package provided through PyPI, currently available for Python versions 3.9
41 to 3.12. The package composes the popular battery modelling package, PyBaMM for battery
42 model numerical solutions, while providing the parameterisation and optimisation workflows.
43 These workflows are constructed through a mixture of internal algorithms, as well as popular
44 optimisation packages such as Pints and SciPy. The PyBOP framework consists of 4 main
45 classes of Python object, namely the Model, Problem, Cost, and Optimiser classes, as shown in
46 Figure 1. Each of these objects has a base class and example subclasses that combine to form
47 a flexible and extensible codebase. The typical workflow would be to define an optimisation
48 problem by constructing the objects in sequence.

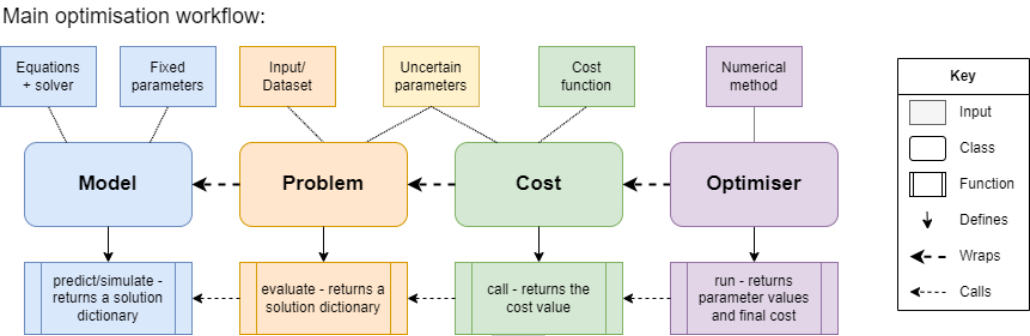


Figure 1: The core PyBOP classes and how they interact.

49 The current instances for each class are listed in Table 1 and Table 2.

Table 1: List of preset subclasses for the model, problem and cost classes.

Battery Models	Problem Types	Cost Functions
Single Particle Model (SPM)	Fitting Problem	Sum of Squared Errors (SSE)
SPM with Electrolyte (SPMe)	Observer	Root Mean Squared Error (RMSE)
Doyle-Fuller-Newman (DFN)	Design Problem	Gaussian Log Likelihood
Many Particle Model (MPM)		Maximum a Posteriori (MAP)
Multi-Species Multi-Reaction (MSMR)		Unscented Kalman Filter (UKF)
Equivalent Circuit Models (ECM)		Gravimetric Energy Density
		Volumetric Energy Density

Table 2: List of available optimisers. (*) Note that Scipy Minimize provides both gradient and non-gradient-based methods.

Gradient-based algorithms	Non-gradient-based algorithms
Adaptive Moment Estimation with Weigth Decay (AdamW)	Covariance Matrix Adaptation Evolution Strategy (CMA-ES)
Improved Resilient Backpropagation (iRProp-)	Exponential Natural Evolution Strategy (xNES)
Gradient Descent	Nelder-Mead
SciPy Minimize (*)	Particle Swarm Optimization (PSO)
	SciPy Differential Evolution
	Separable Natural Evolution Strategy (sNES)
	(pending) Cuckoo Search

50 The cost functions are grouped by problem type, while each of the models and optimisers may
51 be selected in combination with any problem-cost pair.

52 Background

53 Battery models

54 In general, battery models can be written in the form of a differential-algebraic system of
55 equations:

$$\frac{dx}{dt} = f(t, x, y, u(t), \theta), \quad (1)$$

$$y(t) = g(t, x, y, u(t), \theta), \quad (2)$$

57 with initial conditions

$$x(0) = x_0(\theta). \quad (3)$$

58 Here, t is time, $x(t)$ are the (discretised) states, $y(t)$ are the outputs (for example the terminal
59 voltage), $u(t)$ are the inputs (e.g. the applied current) and θ are the uncertain parameters.

60 Common battery models include various types of equivalent circuit model (e.g. the Thévenin
61 model), the Doyle–Fuller–Newman (DFN) model (Doyle et al., 1993; Fuller et al., 1994)
62 based on porous electrode theory and its reduced-order variants including the single particle
63 model (SPM) (Planella et al., 2022), as well as the multi-scale, multi-reaction (MSMR) model
64 (Verbrugge et al., 2017).

65 Simplified models that retain good prediction capabilities at a lower computational cost are
66 widely used, for example within battery management systems, while physics-based models are
67 required to understand the impact of design parameters on battery performance.

68 Examples

69 Parameterisation

70 Battery model parameterisation is difficult due to the high ratio of the number of parameters
71 to measurable outputs (Andersson et al., 2022; Miguel et al., 2021; Wang et al., 2022). A
72 complete parameterisation often requires a step-by-step identification of smaller groups of
73 parameters from a variety of different datasets (Chen et al., 2020; Chu et al., 2019; Kirk et al.,
74 2023).

75 A generic data fitting optimisation problem may be formulated as:

$$\min_{\theta} L(\hat{y}_i)(\theta) \quad \text{subject to equations (1)-(3)} \quad (4)$$

76 in which $L : \theta \mapsto [0, \infty)$ is a cost (or likelihood) function that quantifies the agreement
77 between the model and a sequence of data points (\hat{y}_i) measured at times t_i . For gradient-based
78 optimisers, the gradient refers to the Jacobian of the cost function with respect to the uncertain
79 parameters, θ .

80 By way of example, we next demonstrate the fitting of some synthetic data for which we know
81 the true parameter values.

Design optimisation

Once a battery model has been parameterised, design optimisation can be performed in order to guide future development of the battery design by identifying parameter variations which may unlock improvements in battery performance. Battery performance is typically quantified via metrics such as a 1C discharge capacity.

Design optimisation can be written in the form of a constrained optimisation problem as:

$$\min_{\theta \in \Omega} L(\theta) \quad \text{subject to equations (1)-(3)} \quad (5)$$

in which $L : \theta \mapsto [0, \infty)$ is a cost function that quantifies the desirability of the design and Ω is the set of allowable parameter values.

As an example, let us consider the target of maximising gravimetric energy density subject to constraints on the geometric electrode parameters (Couto et al., 2023).

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