view_frames Result

Recorded at time: 1612490515.978

base_link link 6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1612490515.978 sec old) Most recent transform: 0.000 (1612490515.978 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec flange base Broadcaster: /robot state publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (1612490515.978 sec old) Buffer length: 0.000 sec tool0