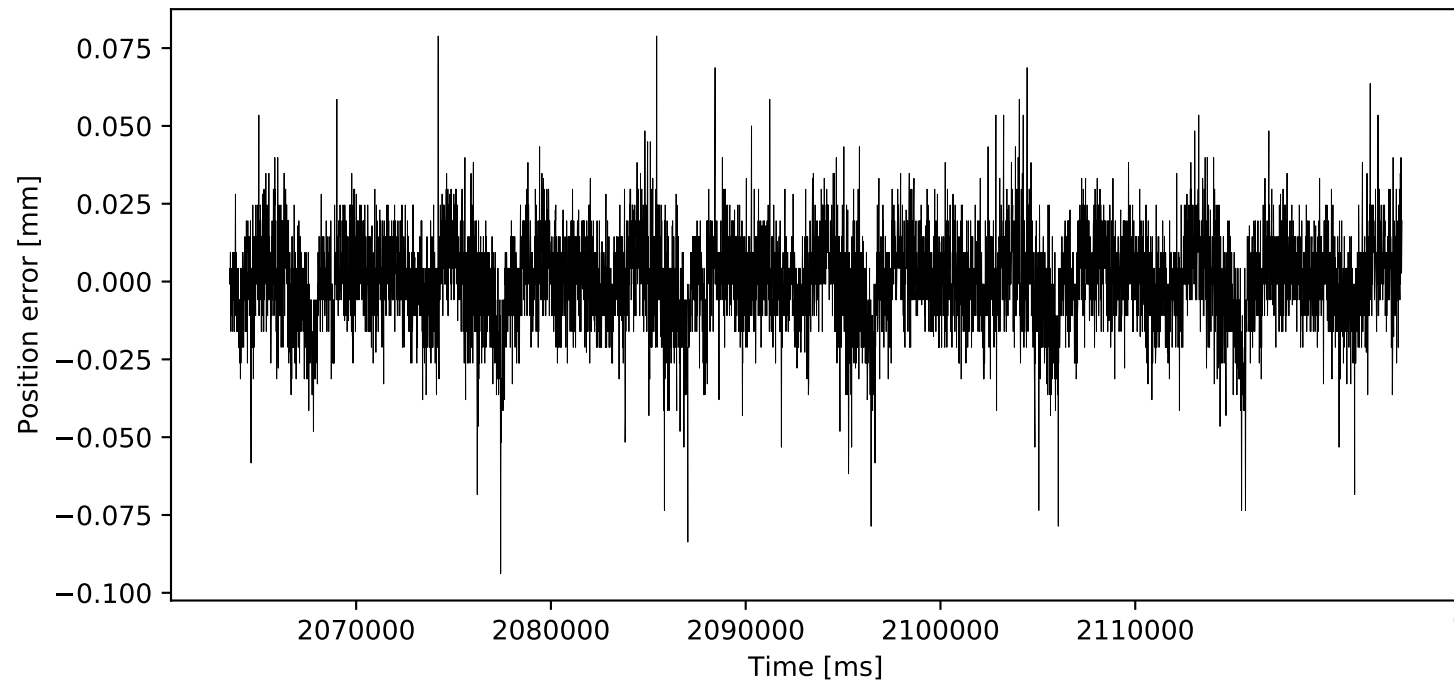


Position error at speed = 0.01 [m/s]



Position error distribution at speed = 0.01 [m/s]

