



# ToFu

*Tomography for Fusion*

An advanced open-source Python library  
for a common approach to tomography



# Outline

## **Section 1**

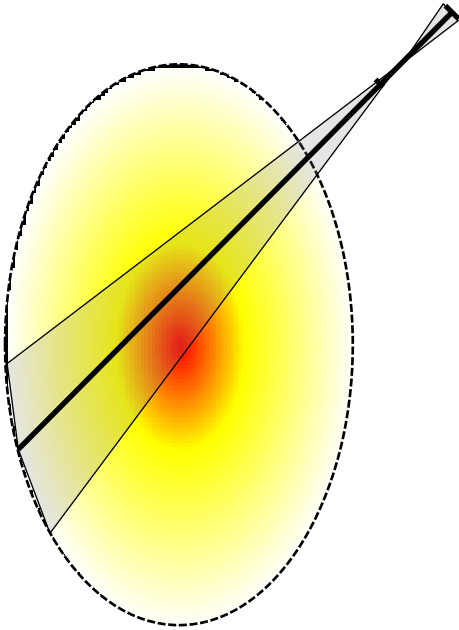
- Reminder on tomography diagnostics
- The need for common and transparent tools

## **Section 2**

- Structure of ToFu
- Spatial integration in ToFu
- Basis functions in ToFu
- ToFu Perspectives
- Example of application

# Reminder : tomography diagnostics

$$M_i(t) = \iiint_{V_i} \overrightarrow{\varepsilon(x,t)} \cdot \vec{n} \Omega_i dV \approx E_i \int_{L_i} \varepsilon(l,t) dt$$



# Reminder : tomography diagnostics

$$M_i(t) = \iiint_{V_i} \overrightarrow{\varepsilon(x,t)} \cdot \vec{n} \Omega_i dV$$

**Direct problem** (synthetic diagnostic):

Simulated emissivity

=> integrated measurements

Requires : spatial integration

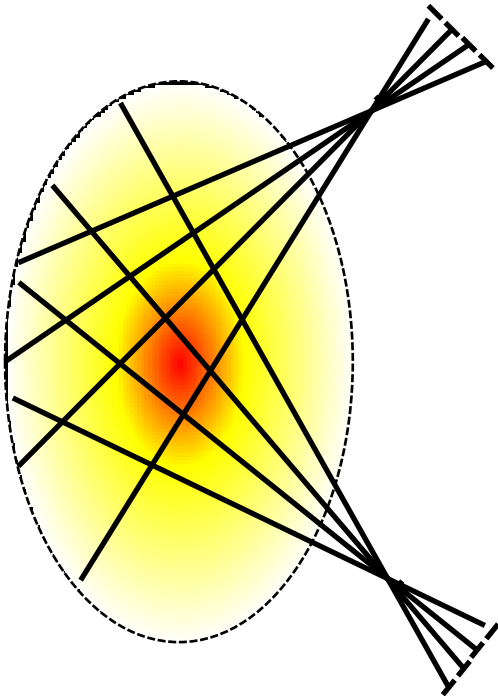
**Inverse problem** (tomography):

Integrated measurements

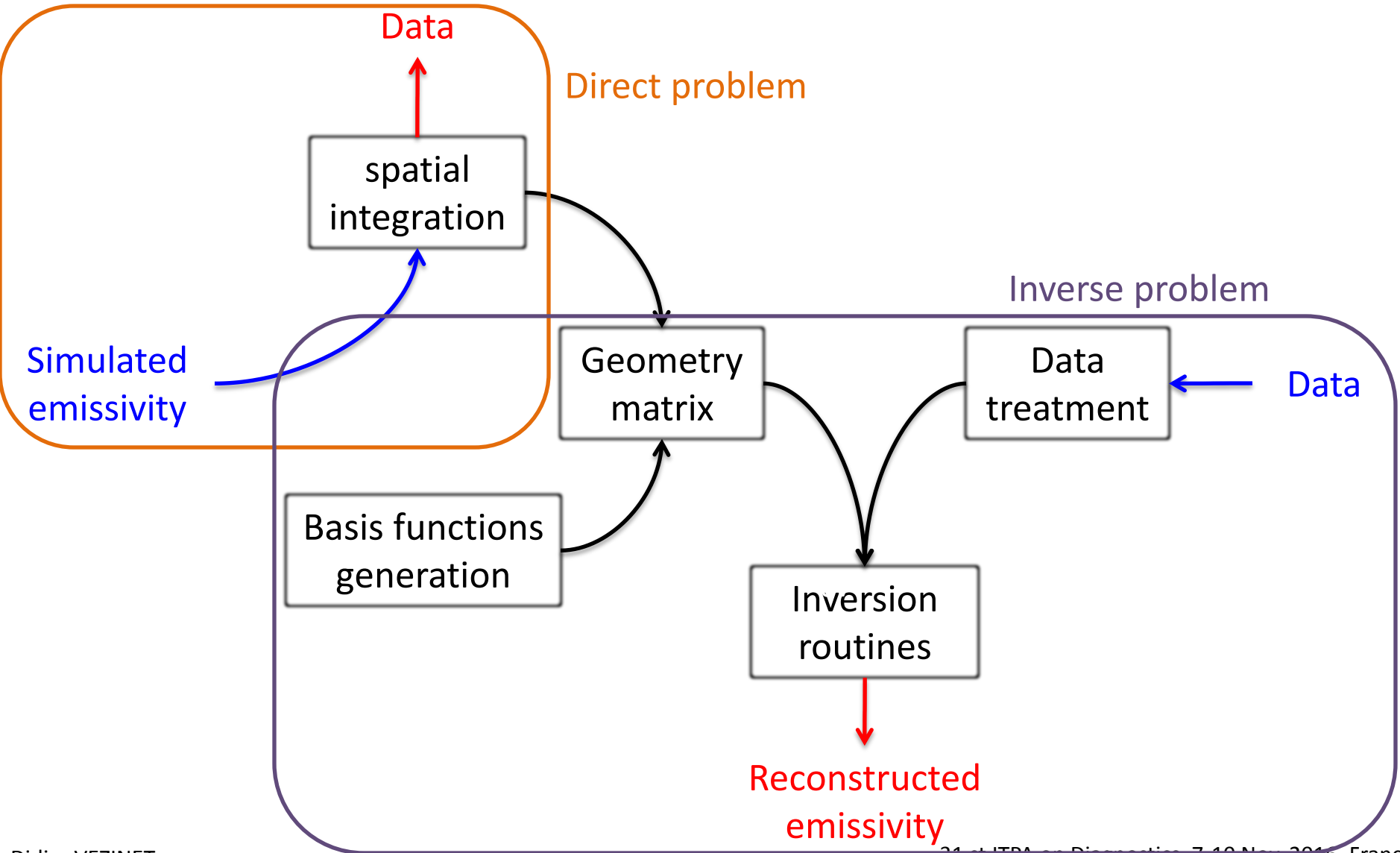
=> Reconstructed emissivity

Requires (series expansion):

- Basis functions
- Spatial integration (geometry matrix)
- Data filtering (noise...)
- Inversion routines



# Need for common / transparent tools



# Need for common / transparent tools

## Each lab creates its own tools:

- Optimised for a specific machine
- Rarely documented or commented
- Often created by students, unmaintained after they leave
- A new student comes and re-does most of it....

=> Many unmaintained black-box codes

=> High redundancy and work time used

=> Low reproducibility & transparency, little long-term improvements

Tomography very sensitive to errors, noise and bias

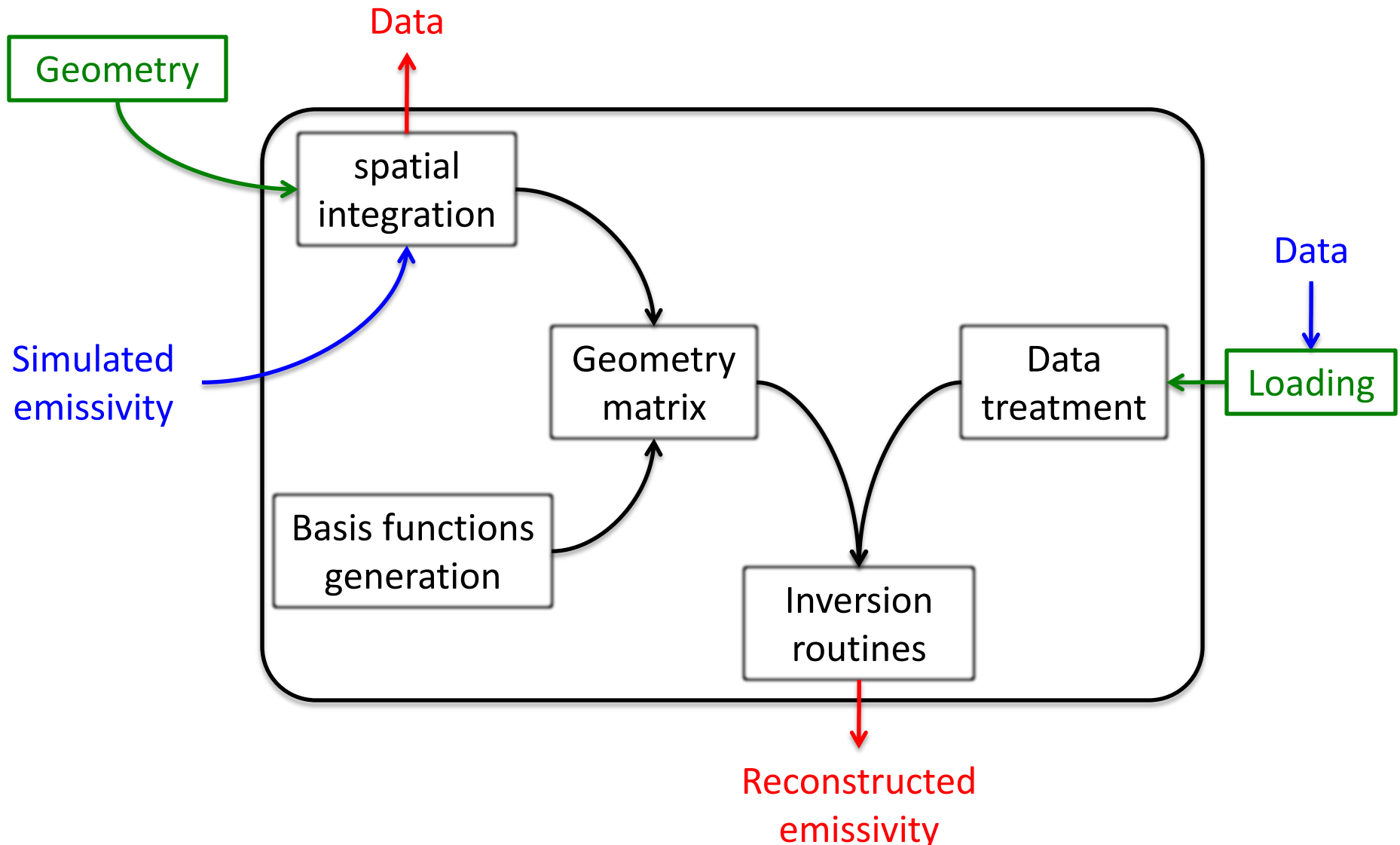
=> Reputation for low reproducibility (reliability ?)

## Value of a common tool:

- **Accessible to** everyone (e.g.: open-source)
- **Documented online**
- **Generic** (not machine-dependent)
- **Transparent**, for reproducibility and updates (e.g.: open-source)
- **Flexible** (user-defined choices)

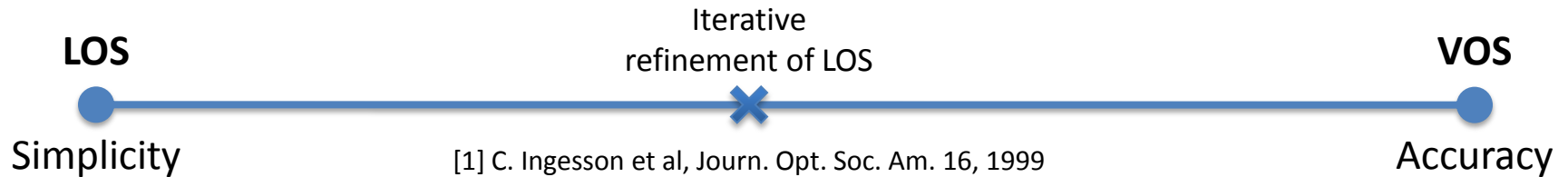
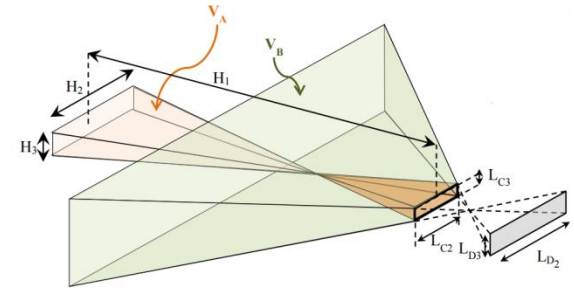
The word "Python" is written in a black, sans-serif font and is enclosed within a blue oval border.

# Structure of ToFu



# Spatial integration in ToFu

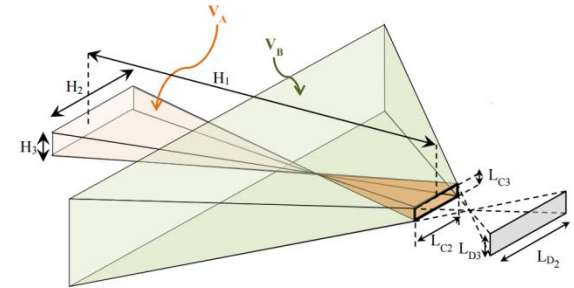
$$M_i(t) = \iiint_{V_i} \overrightarrow{\varepsilon(x,t)} \cdot \vec{n} \Omega_i dV \approx E_i \int_{L_i} \varepsilon(l,t) dt$$





# Spatial integration in ToFu

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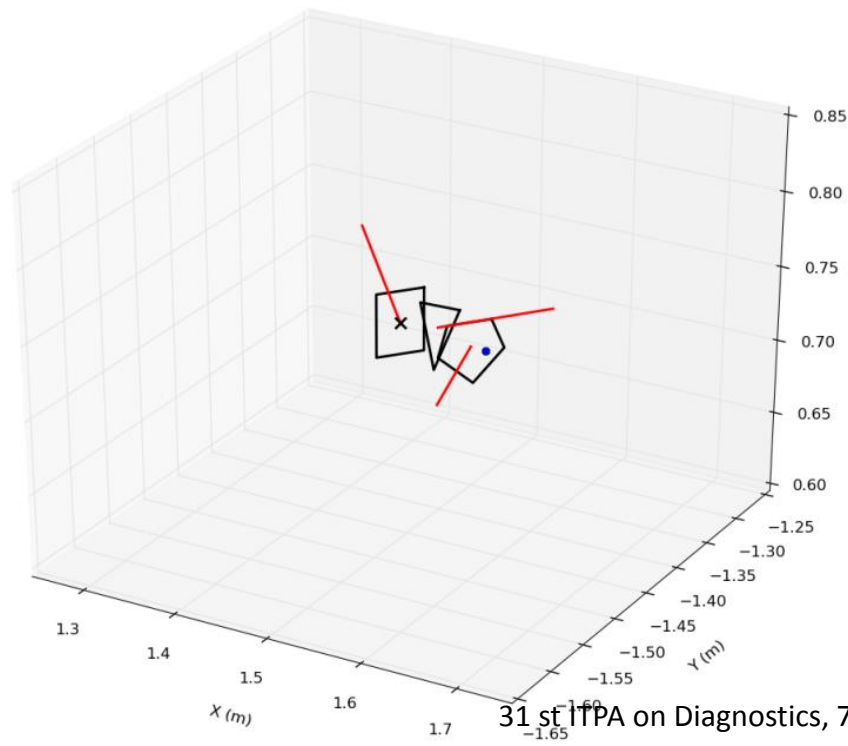


LOS

Simplicity

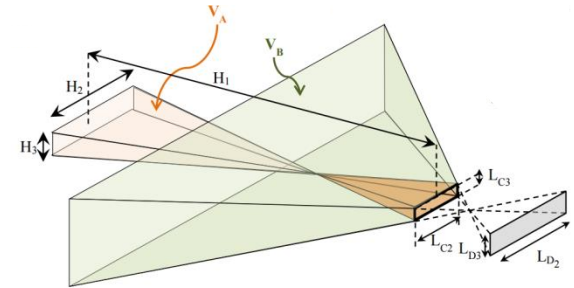
VOS

Accuracy



# Spatial integration in ToFu

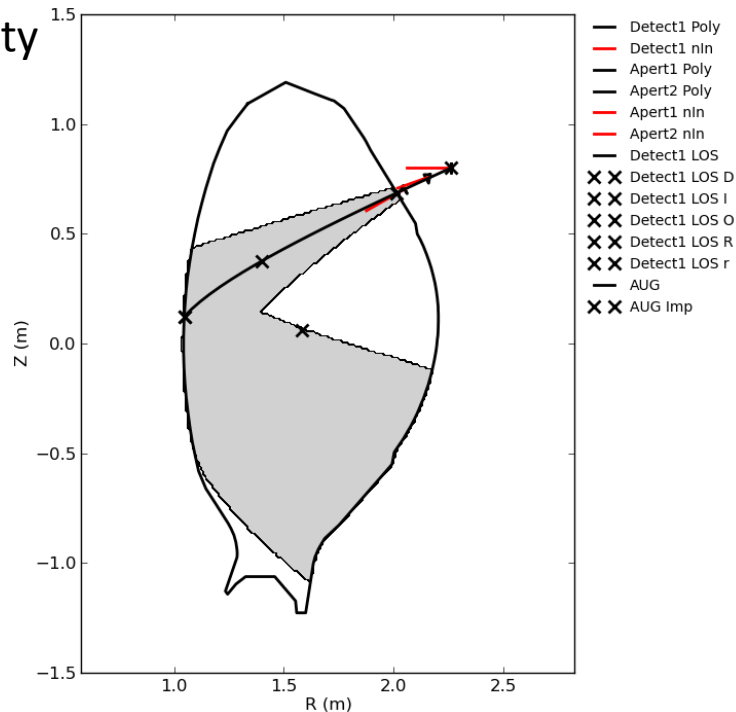
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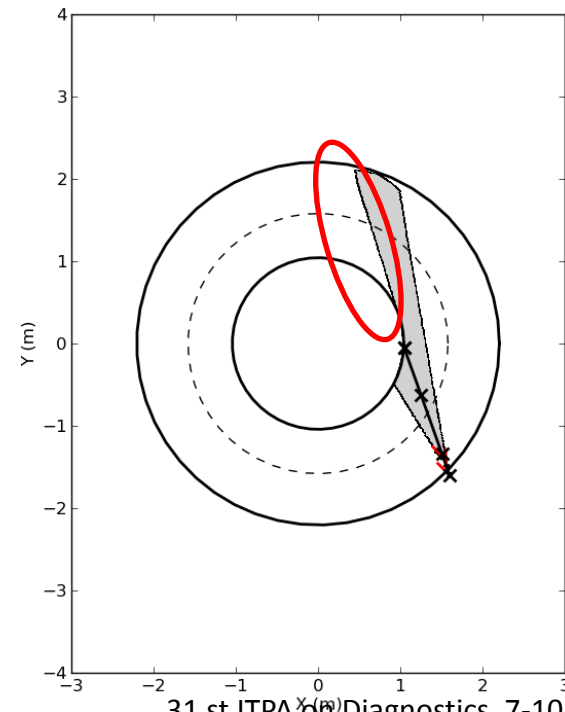
LOS

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Accuracy

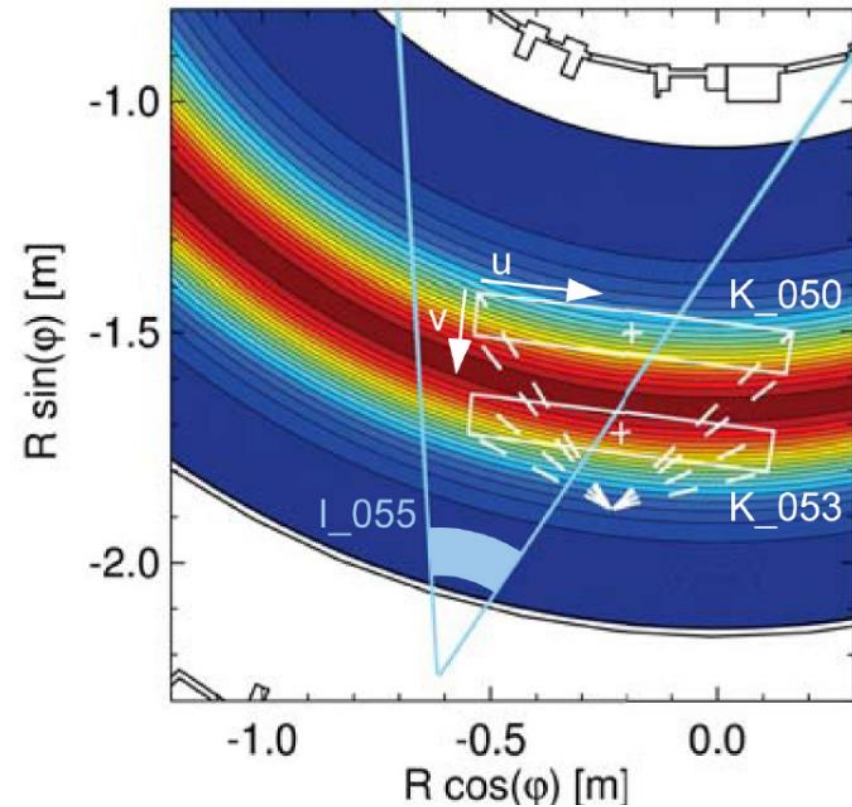


# Spatial integration in ToFu

## Why VOS ?

- **Shift towards LFS**

Toroidal curvature and beam width



[2] M. Weiland et al, Nuc. Fus. 57

# Spatial integration in ToFu

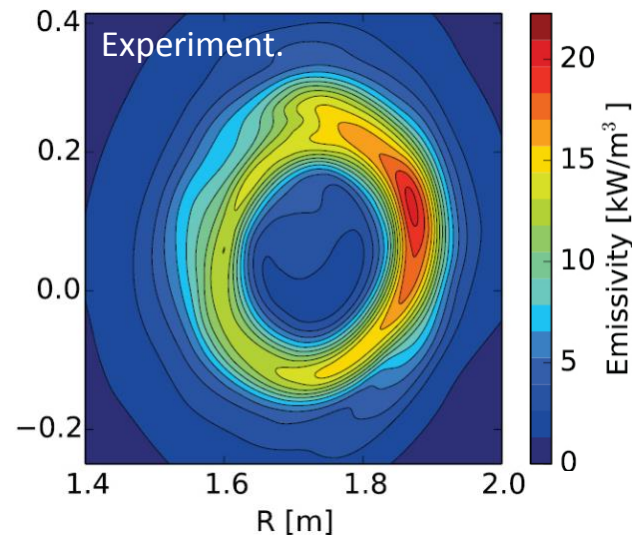
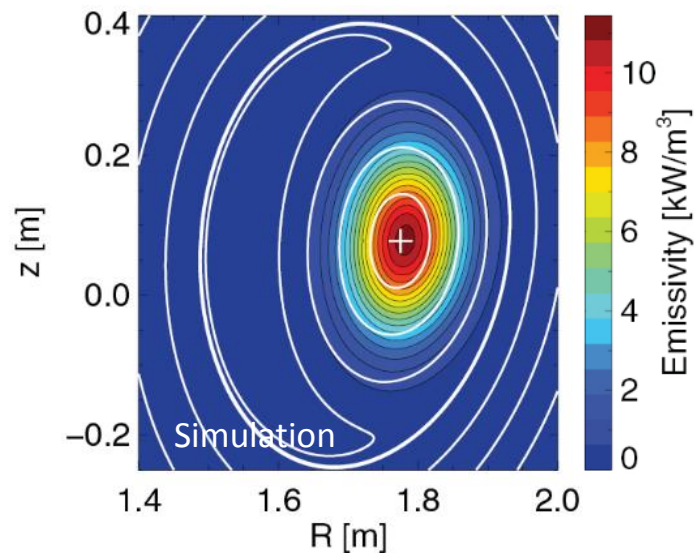
## Why VOS ?

- **Shift towards LFS**

Toroidal curvature and beam width

- **No 2<sup>nd</sup> derivative perpendicular to LOS**

- Core SXR with W (very peaked or hollow)
- Divertor region for bolometry



[2] M. Weiland et al, Nuc. Fus. 57

31 st ITPA on Diagnostics, 7-10 Nov. 2016, France

# Spatial integration in ToFu

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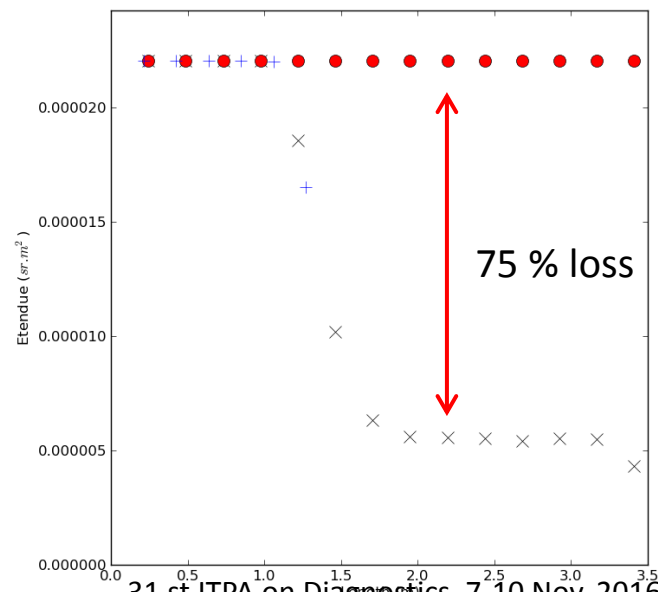
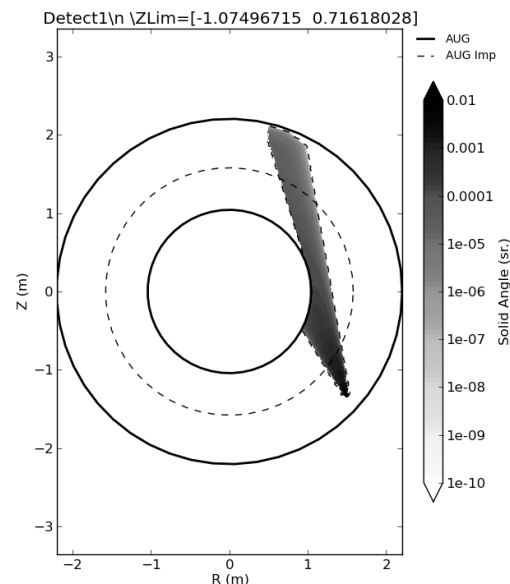
Toroidal curvature and beam width

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- **Etendue must be constant along LOS**

- Partial obstruction of the VOS
  - Edge lines close to PFCs
  - Divertor region for bolometry
  - Toroidal views



# Spatial integration in ToFu

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Toroidal curvature and beam width

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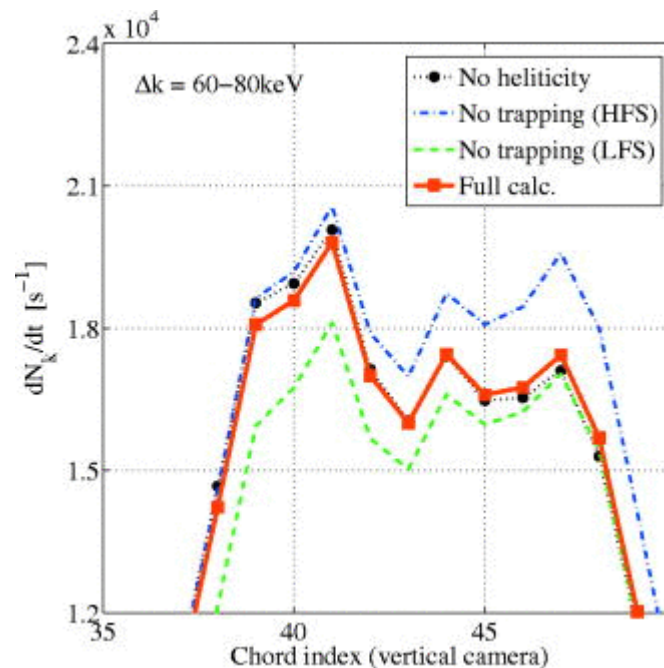
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- **Etendue must be constant along LOS**

- Partial obstruction of the VOS
  - Edge lines close to PFCs
  - Divertor region for bolometry
  - Toroidal views

- **Anisotropic radiation**

- High energy electrons (HXR, runaways...)



[3] Y. Peysson et al, Phys. Plasm. 15

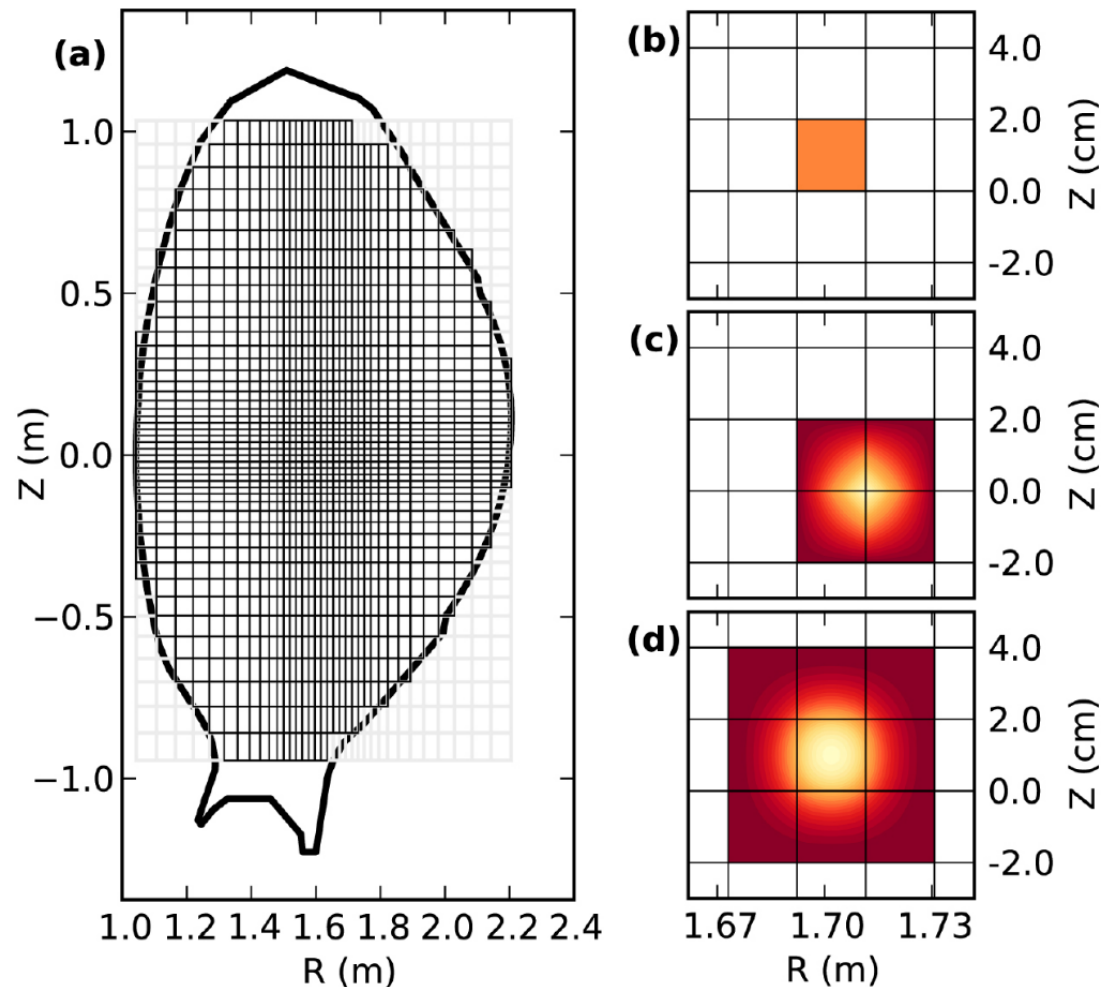
# Basis functions in ToFu

## Local Basis Functions (LBF)

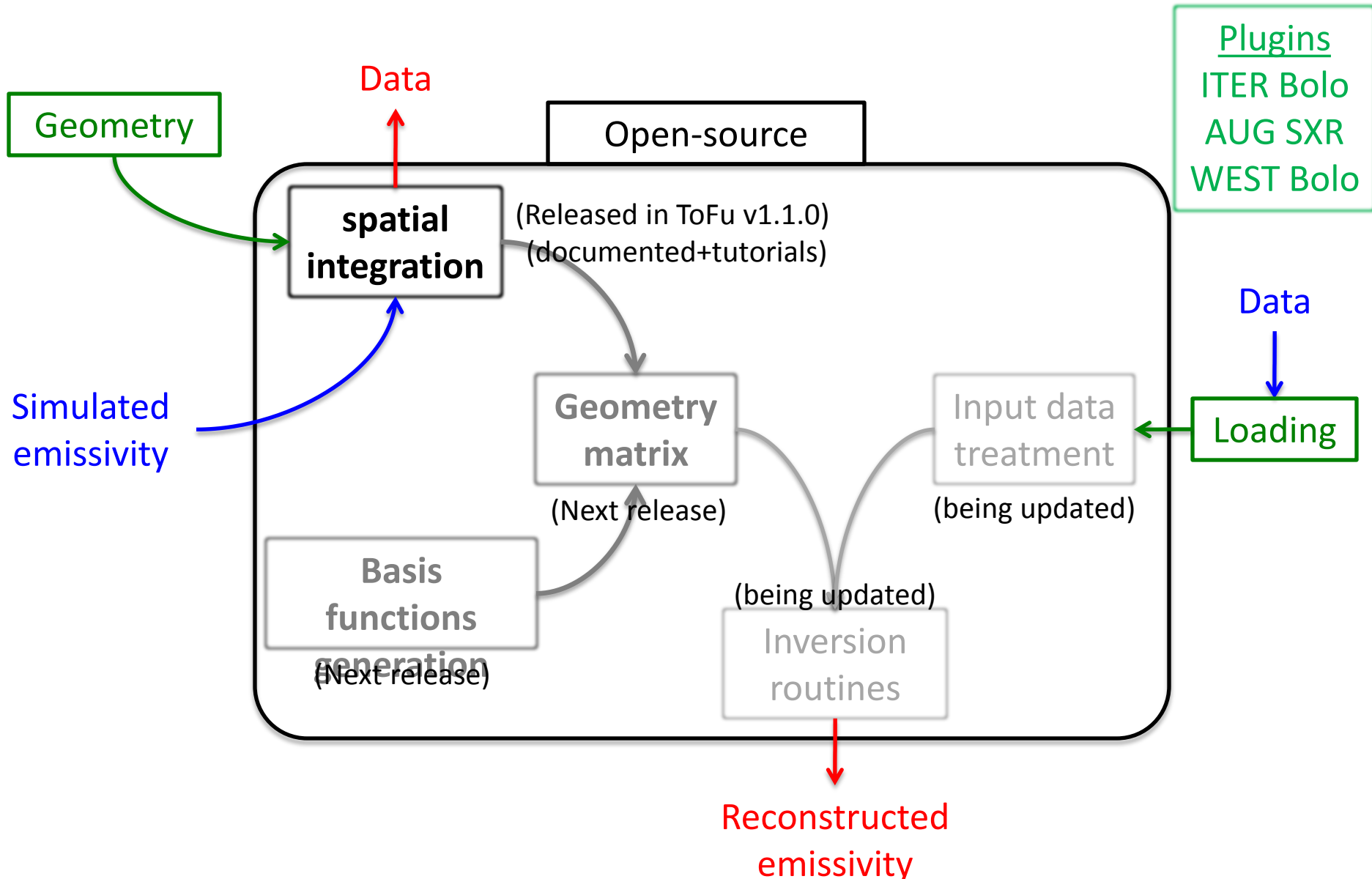
- Variable mesh size
- Bidimensional b-splines, deg 0-3

## Global Basis Functions (GBF)

- Equilibrium-based : in progress  
(Fourier-Bessel,  
Fourier-Zernicke,  
Fourier-Splines  
...)



# ToFu current status





# ToFu current status

- Open-source under permissive MIT license
- Code available on GitHub (packaging to be done) at <https://github.com/Didou09/tofu>
- Online documentation at <https://didou09.github.io/tofu/index.html>

tofu v1.1 »

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Table Of Contents

Welcome to tofu's documentation!

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Overview

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Welcome to tofu's documentation!

**ToFu** (TOMography for FUision) is an open-source python library first created at the Max-Planck Institute for Plasma Physics (IPP) in Garching (Germany) by Didier Vezinet (as a postdoc) through the years 2014-2016. It is continuously maintained, debugged and upgraded to this day.

It aims at providing the fusion and plasma community with an object-oriented, transparent and documented tool for designing tomography diagnostics, computing synthetic signal (direct problem) as well as tomographic inversions (inverse problem). It gives access to a full 3D description of the diagnostic geometry, thus reducing the impact of geometrical approximations on the direct and, most importantly, on the inverse problem.

It is modular and generic in the sense that it was developed with the objective of being machine-independent, thus guaranteeing that it can be used for arbitrary geometries and with an arbitrary number of apertures for each detector.

**Open-source:**

ToFu is distributed under the very permissive MIT license, thus allowing free use, keeping in mind that neither the author nor any of the laboratories in which he worked can be held responsible for unwanted behaviour or results. It is instead transparency, reproducibility and incremental improvements that guarantee quality on the long-term.

ToFu is hosted on [github](#).

**Versions:**

A list of the successive versions of ToFu, with a brief description can be found [here](#).

**Dependencies:**

ToFu uses the following python packages.

**Citing ToFu:**

If you decide to use ToFu for research and published results please acknowledge this work by [citing](#) the project.

**Feedback - bug report - wish list**

To provide feedback on ToFu itself please use the [github](#) page.

To provide feedback on a specific plugin, please refer to that plugin's webpage where a contact will be indicated.

**Miscellaneous**

ToFu is tested with the [nose/1.3.4](#) library (not all methods are tested yet, in process...) ToFu can be installed using the [distutils](#) library.

Contents:

**Description of the library structure:**

- [Overview](#)

**Code documentation:**

Notice that the main ToFu classes and methods have docstrings so you can access contextual help with the usual python syntax from a lython console (print <method>.\_\_doc\_\_ or <method>?).

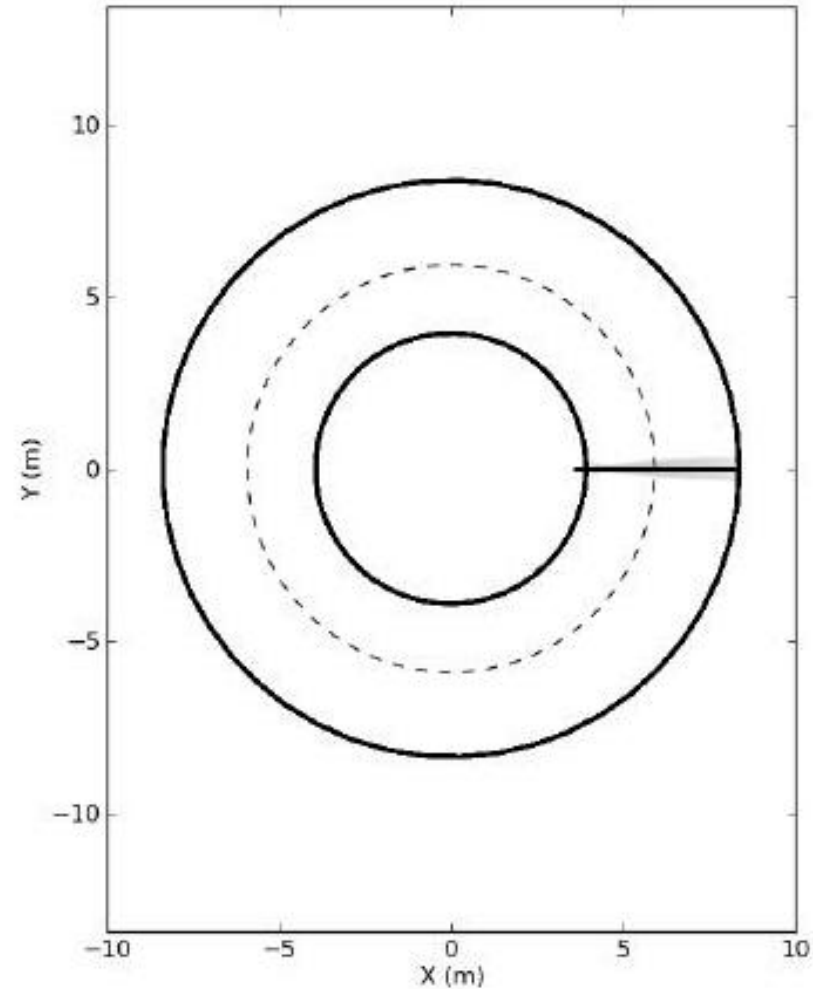
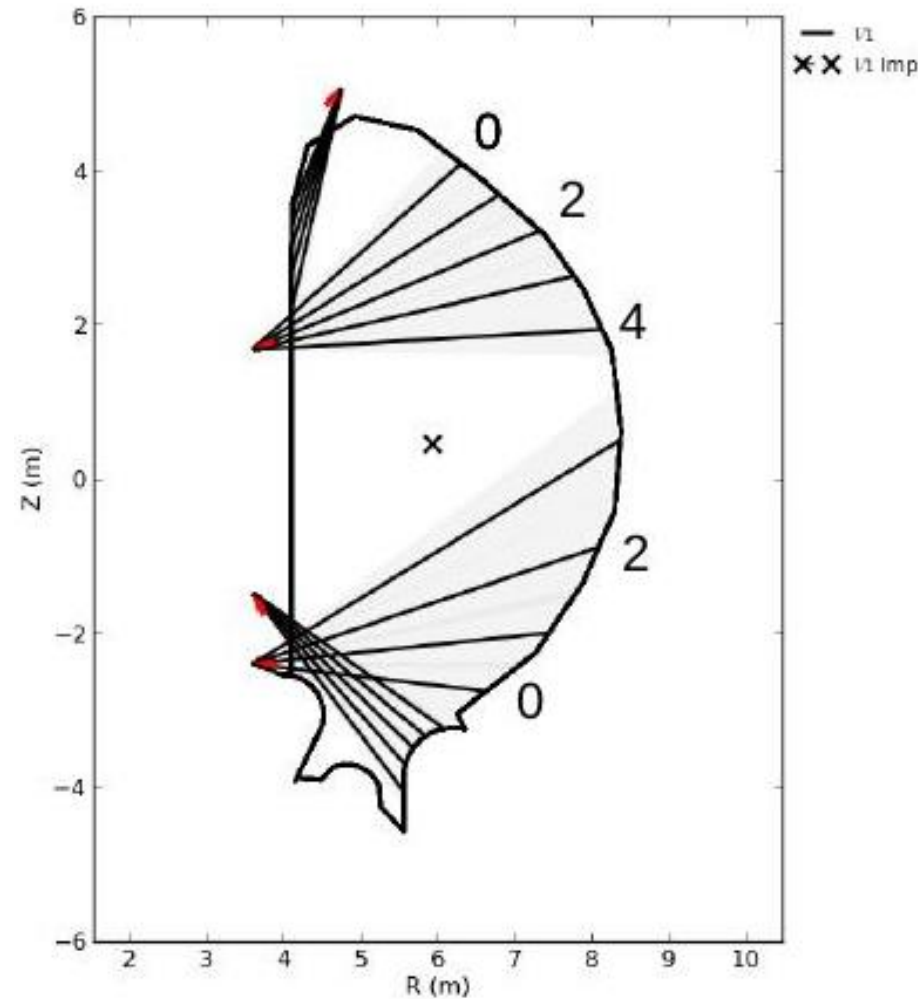
- 1. [tofu.geom](#)
- 2. [tofu.treat](#)
- 3. [tofu.pathfile](#)
- 4. [tofu.plugins](#)
  - 4.1.1. [AUG](#)
  - 4.1.2. [ITER](#)

Didier VEZINET

31 st ITPA on Diagnostics, 7-10 Nov. 2016, France

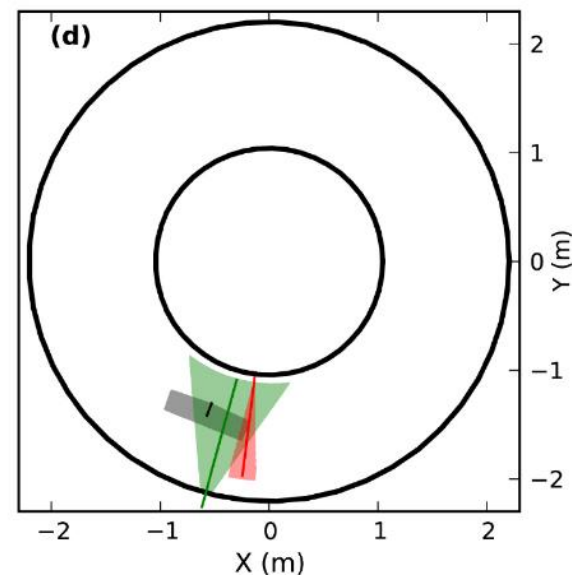
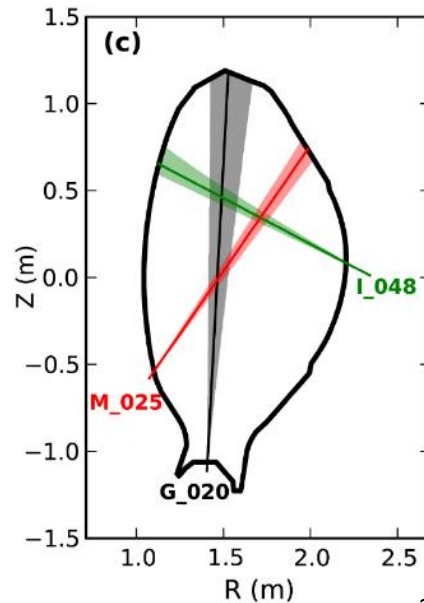
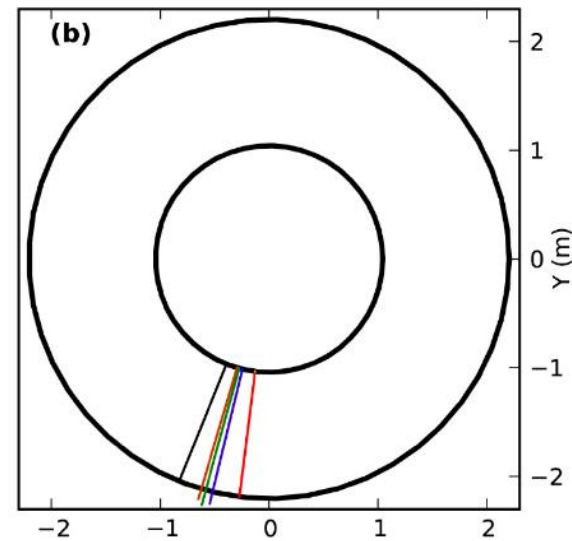
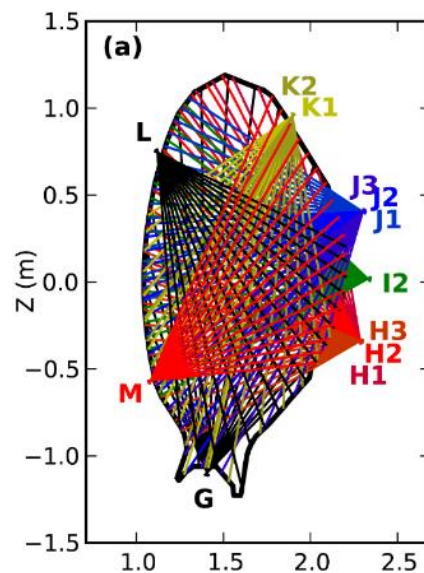
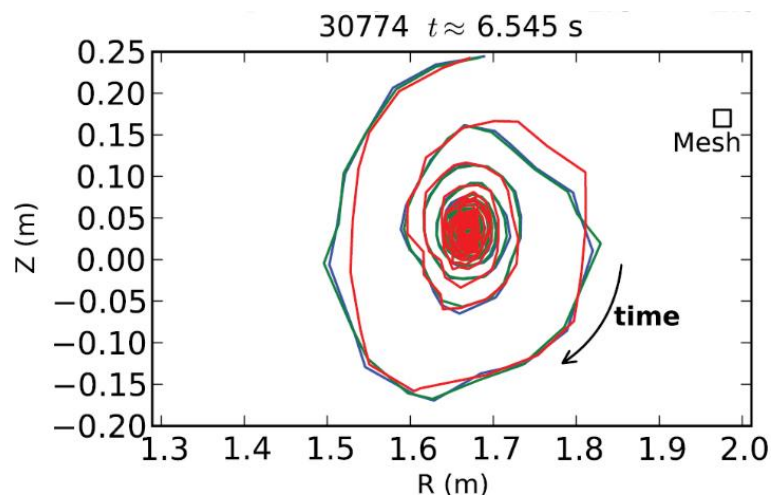
# ToFu examples: ITER bolometry analysis

(Courtesy of G. Veres et al, FPA384, Progress Meeting 07)



# ToFu examples: AUG SXR for MHD

- SXR diagnostic on AUG
- Inversions (localization of maximum)



# ToFu perspectives

## **Natural: finish and maintain**

- Release updated modules with doc
- Non-linear regularization (MFI, Bayes...)
- Create additional plugins (on-demand)
- Export to python 3

## **Update: faster geom. more flexible bsplines**

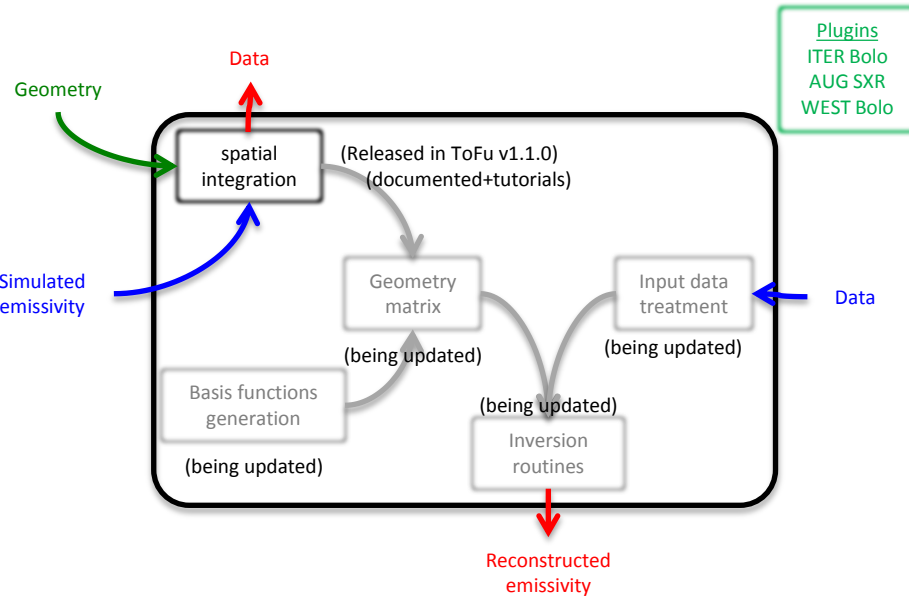
- Optimize & parallelize geom (CPU, GPU)
- Add ray tracing option (for reflections)
- Replace BF by advanced NMPP bspline library

## **Extend: Spectroscopy diagnostics**

- ⇒ 1D & 2D spectroscopy
- ⇒ Spectral & spatial inversion

## **Full problem: uncertain geometry**

- ⇒ Iterate on the geometry too
- ⇒ Fast and accurate 3D computation
- ⇒ « Cross-calibration »



Postdoc (computer scientist)

1 ppy/year for 2 years ?

## **Anisotropic emissivity:**

- ⇒ Investigate possible inversions

PhD  
3 years

# Open-source !

**ITER and the whole community benefit from it !**

- **Direct problem:**

- Diagnostic design and performance analysis (bolo, SXR, HXR...)
- Code validation

- **Inverse problem:**

- Transparent & reproducible tomography
- Impurity (W) transport and MHD studies
- Potential runaway and superthermal studies

- **Incremental improvements by the community**

- **Tool available for every machine**

- **Sets community-defined minimum standards !**

(proprietary solutions must do as least as good)



Thank you for your attention !

