

# ONE SECTOR GROWTH MODEL

- REPRESENTATIVE CONSUMER WHO LIVES FOREVER
- $C(t)$  IS CONSUMPTION AT TIME  $t$

$$V = \int_0^{\infty} e^{-\rho \cdot t} \cdot u(C(t)) dt$$

$\rho > 0$ ,  $u(\cdot)$  IS STRICTLY INCREASING, CONCAVE AND DEFINED ON  $[0, \infty)$

- $\rho$  IS DISCOUNT FACTOR

$$\left. \begin{aligned} C(t) + x(t) &= \phi(K(t)) \\ \dot{K}(t) &= -\delta \cdot K(t) + x(t) \end{aligned} \right\}$$

$$C(t), K(t) > 0 \\ \forall t \in [0, \infty)$$

- $K(0)$  IS GIVEN

$$C(t) + \dot{K}(t) = \phi(K(t)) - \delta \cdot K(t)$$

$$Q = \int_0^{\infty} e^{-s \cdot t} [u(c|x)| + \lambda(x) \cdot (Q(x) - s \cdot k(x) - k(x) - c(x))] dt$$

$$\int_a^b Q'(x) g(x) dx :$$

$$Q(x) g(x) \Big|_a^b - \int_a^b Q(x) g'(x) dx$$

$$\int_0^{\infty} e^{-s \cdot t} \cdot \lambda(x) \cdot k(x) dt$$

$$\begin{aligned} Q'(x) &= k(x) \\ Q(x) &= K(x) \\ g'(x) &= e^{-s \cdot t} \\ g(x) &= -\frac{1}{s} \cdot e^{-s \cdot t} \cdot \lambda(x) + e^{-s \cdot t} \cdot \dot{\lambda}(x) \\ g'(x) &= e^{-s \cdot t} \cdot (1 - s \cdot \lambda(x) + \dot{\lambda}(x)) \end{aligned}$$

$$\int_0^{\infty} e^{-st} \cdot \gamma(t) \cdot k(t) dt =$$

$$e^{-st} \cdot \gamma(t) \cdot k(t) \Big|_0^{\infty} -$$

$$\int_0^{\infty} e^{-st} \cdot (1 - \gamma(t) + \gamma(t) \cdot k(t)) dt$$

$$\lim_{t \rightarrow \infty} e^{-st} \cdot \gamma(t) \cdot k(t) -$$

$$\gamma(0) \cdot k(0)$$

$$\int_0^{\infty} e^{-st} \cdot \gamma(t) \cdot k(t) dt =$$

$$\lim_{t \rightarrow \infty} e^{-st} \gamma(t) \cdot k(t) - \quad (2)$$

$$\gamma(0) \cdot k(0) - \int_0^{\infty} e^{-st} \cdot (1 - \gamma(t) + \gamma(t) \cdot k(t)) dt$$

$$\begin{aligned}
 \mathcal{L} = & \int_0^\infty e^{-\beta x} \cdot [u(c(x)) \\
 & + \lambda(x) \cdot (Q(w(x)) - \beta \cdot k(x) \\
 & - \beta \cdot k(x) - c(x)) + \dot{\lambda}(x) \cdot k(x)] \\
 & dx + \lambda(0) \cdot k(0) - \\
 & \lim_{T \rightarrow \infty} e^{-\beta \cdot T} \cdot \lambda(T) \cdot k(T) \quad (3)
 \end{aligned}$$

We are choosing  $c(x)$   
and  $k(x)$

TRANSVERSALITY CONDITION

$$\lim_{T \rightarrow \infty} e^{-\beta \cdot T} \cdot \lambda(T) \cdot k(T) = 0 \quad (a)$$

$$\begin{aligned}
 (c(x)) : & e^{-\beta x} \cdot u'(c(x)) \\
 - e^{-\beta x} \cdot \lambda(x) & = 0 \Rightarrow
 \end{aligned}$$

$$u'(c(x)) = \lambda(x) \quad (b)$$

$$(N/A):$$

$$\chi(x) \cdot [Q(x) - (S + S)] + \chi(x) = 0 \Rightarrow$$

$$15 \times 81 - 11 \times 111 = 12 \times 111 - 11 \times 111 = 111$$

$$C(a), K(a) \wedge Q(a) \\ \text{THAT SATISFIES } S(a), (b) \\ \wedge (c)$$

$$\gamma(x) = u(c(x)) \quad (1)$$

$$\dot{\chi}(x) = u''(c(x)) \cdot \dot{c}(x) \cdot (2)$$

$$- \frac{u''(c(x)) \cdot \dot{c}(x)}{u'(c(x))} =$$

STEADY STATE

$$\dot{x}(t) = 0, \quad \dot{w}(t) = 0$$

$$\dot{c}(t) = 0$$

$$Q(w^*) = |P + S| =$$

$$w^* = Q^{-1} |P + S|$$

$$c^* = Q(w^*) - S \cdot w^*$$

# Macroeconomics I

## Recitation 2

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### 1 The Hamiltonian: A Practical Guide and Some Examples

The Hamiltonian is the handiest way to solve a problem of dynamic optimization in continuous time. The typical problem is of the form:

$$\max_{c(t), k(t)} V(0) = \int_0^\infty e^{-rt} \cdot V[c(t), k(t)] dt \quad (1)$$

subject to:

$$\dot{k}(t) = g[c(t), k(t), t] \quad (2)$$

$$k(0) = k_0 \quad (3)$$

$$\lim_{t \rightarrow \infty} e^{-rt} k(t) \geq 0 \quad (4)$$

The formula of the Hamiltonian is:

$$\mathcal{H} = e^{-rt} \cdot V[c(t), k(t)] + \lambda(t) \cdot g[c(t), k(t), t] \quad (5)$$

For practical purposes, *learn Equation (5) by heart*. Once you know it, you are equipped to apply the four-step method. In problem sets or exams, you need not (and should not) redo the proof that we covered during the lecture. Just apply the method!

*Step 1.* Determine the state and control variables. State variable(s) have dots on top of them in the constraint(s).

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*Step 2.* Write the Hamiltonian. Here,  $c(t)$  is the control, and  $k(t)$  the state.

*Step 3.* Set the derivative(s) of the Hamiltonian with respect to control variable(s) to zero, and its derivative(s) with respect to state variable(s) to  $-\dot{\lambda}(t)$ :

$$\frac{\partial \mathcal{H}}{\partial c(t)} = 0 \quad (6)$$

$$\frac{\partial \mathcal{H}}{\partial k(t)} = -\dot{\lambda}(t) \quad (7)$$

*Step 4.* Add the transversality condition:

$$\lim_{t \rightarrow +\infty} e^{-rt} \cdot k(t) = 0 \quad (8)$$

### Example 1 (Investment)

$$\max_{I(t), L(t), K(t)} V(0) = \int_0^T e^{-rt} \cdot [F(K(t), L(t), A) - w(t) \cdot L(t) - I(t)] dt$$

*subject to:*

$$\dot{K}(t) = I(t) - \delta K(t)$$

$$K(0) = K_0 > 0$$

$$\lim_{t \rightarrow +\infty} e^{-rt} \cdot K(t) \geq 0$$

$I(t)$  and  $L(t)$  are the control variables.  $K(t)$  is the state. The Hamiltonian writes:

$$\mathcal{H} = e^{-rt} [F(K(t), L(t), A) - w(t) \cdot L(t) - I(t)] + \lambda(t) [I(t) - \delta \cdot K(t)]$$

*The first-order conditions are:*

$$\frac{\partial \mathcal{H}}{\partial L(t)} = 0 \iff \frac{\partial F}{\partial L(t)} = w(t)$$

$$\frac{\partial \mathcal{H}}{\partial I(t)} = 0 \iff \lambda(t) = e^{-rT}$$

$$\frac{\partial \mathcal{H}}{\partial K(t)} = -\dot{\lambda}(t) \iff e^{-rT} \frac{\partial F}{\partial K(t)} - \lambda(t) \cdot \delta = -\dot{\lambda}(t)$$



The transversality condition is:

$$\lim_{t \rightarrow +\infty} \lambda(t) \cdot K(t) = 0$$

### Example 2 (Consumption)

$$\max_{c(t), a(t)} V(0) = \int_0^\infty e^{-rt} \cdot u[c(t)] dt$$

subject to:

$$\dot{a}(t) = w(t) + r \cdot a(t) - c(t)$$

$$a(0) = a_0$$

$$\lim_{t \rightarrow +\infty} e^{-rt} \cdot a(t) \geq 0$$

with  $w(t)$  exogenous.

$c(t)$  is the control,  $a(t)$  the state. The Hamiltonian writes:

$$\mathcal{H} = e^{-rt} \cdot u[c(t)] + \lambda(t) \cdot [w(t) + r \cdot a(t) - c(t)]$$

The first-order conditions are:

$$\begin{aligned} \frac{\partial \mathcal{H}}{\partial c(t)} = 0 &\iff e^{-rt} \cdot u'(c(t)) = \lambda(t) \\ \frac{\partial \mathcal{H}}{\partial a(t)} = -\dot{\lambda}(t) &\iff \lambda(t) \cdot r = -\dot{\lambda}(t) \end{aligned}$$

The transversality condition is:

$$\lim_{t \rightarrow +\infty} \lambda(t) \cdot a(t) = 0$$

## 2 The Transversality Condition

The transversality condition is usually puzzling to the first-year graduate student. In particular, it is often confused with the no-Ponzi condition. In fact, the transversality condition is a mix of two things:

- an external constraint, imposed by financial markets, that forbids the agent to die in debt. This constraint is called the no-Ponzi condition;
- an optimality condition that pushes the agent to leave as much debt as she can.

To understand this, remember the finite horizon problem studied in class:

$$\max_{c(t), k(t)} V(0) = \int_0^T e^{-rt} \cdot V[c(t), k(t)] dt \quad (9)$$

subject to:

$$\dot{k}(t) = g[k(t), c(t), t] \quad (10)$$

$$k(0) = k_0 > 0 \quad (11)$$

$$e^{-rT} \cdot k(T) \geq 0 \quad (12)$$

Equation (12) is the no-Ponzi condition.

After some algebra involving an integration by part, we showed that the Lagrangian could be written<sup>1</sup>:

$$\mathcal{L} = \int_0^T \left( \mathcal{H}(c(t), k(t), t) + \dot{\lambda}(t) \cdot k(t) \right) + \lambda(0) \cdot k_0 - \lambda(T) \cdot k(T) + \nu \cdot e^{-rT} \cdot k(T)$$

where:  $\mathcal{H}(c(t), k(t), t) = e^{-rt} \cdot V[c(t), k(t)] + \lambda(t) \cdot g[k(t), c(t), t]$ . The first-order condition of this Lagrangian with respect to  $k(T)$  is<sup>2</sup>:

$$\lambda(T) = \nu \cdot e^{-rT} \quad (13)$$

To which one can add the complementary slackness condition that is associated with Equation (12):

$$\nu \cdot e^{-rT} \cdot k(T) = 0 \quad (14)$$

Equations (13) and (14) combine to give the transversality condition:

$$\lambda(T) \cdot k(T) = 0 \quad (15)$$

While Equation (14) is inherited from the no-Ponzi condition, Equation (13) comes from optimization: as long as  $k$  has a marginal value at the time of death ( $\lambda(T) > 0$ ), the constraint is binding ( $\nu > 0$ ). Indeed, the agent would like to leave some debt to increase consumption. Put another way, financial markets would be fine with  $k(T) > 0$ ; while the agent would rather leave  $k(T) < 0$  (as long as  $\lambda(T) > 0$ ). Since both have to agree, they meet half way:  $k(T) = 0$  (as long as  $\lambda(T) > 0$ ).

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<sup>1</sup>Equation (A.61) in Barro and Sala-i Martin (Barro and Sala-i Martin, p. 608).

<sup>2</sup>Since death happens at time  $T$ ,  $k(T)$  and  $c(T)$  do not enter the objective function.

With an infinite horizon, the no-Ponzi and transversality conditions are:

$$\lim_{t \rightarrow +\infty} e^{-rt} \cdot k(t) \geq 0 \quad (16)$$

$$\lim_{t \rightarrow +\infty} \lambda(t) \cdot k(t) = 0 \quad (17)$$

The intuition is the same as in finite time.

Of course, you can (and should) use Equations (15) and (17) without any proof.

### 3 The Rate of Depreciation

Consider the capital accumulation constraint:

$$\dot{k}(t) = I(t) - \delta k(t) \quad (18)$$

The general solution of this differential equation is:

$$k(t) = e^{-\delta t} \int_0^t e^{\delta \tau} I(\tau) d\tau + b e^{-\delta t} \quad (19)$$

where  $b$  is some constant.

There are two possible interpretations of  $\delta$ . The first one stems from Equation (18):

$$\left. \frac{\dot{k}(t)}{k(t)} \right|_{I(t)=0} = -\delta \quad (20)$$

Equation (20) means that, without investment, the capital stock decreases at rate  $\delta$ . Put another way, capital depreciates at rate  $\delta$ . This does *not* mean that the economy (or the firm) loses  $\delta\%$  of its capital stock every millisecond. Indeed:

$$\frac{\dot{k}(t)}{k(t)} = \frac{dk(t)}{dt} \times \frac{1}{k(t)} \Rightarrow \left. \frac{dk(t)}{k(t)} \right|_{I(t)=0} = -\delta dt \quad (21)$$

So  $k(t)$  decreases by  $(\delta dt)\%$  at every infinitesimal time period  $dt$ . Since  $dt$  is infinitesimal, the percentage decrease is also infinitesimal.

Suppose now that, without investment, the capital stock shrinks by  $x\%$  every unit of time. Mathematically, this translates into:

$$\left. \frac{k(t+1)}{k(t)} \right|_{I(\tau)=0} = 1 - x\% \quad (22)$$

Note that we are still in continuous time:  $t$  does not need to be an integer. Using Equation (19), Equation (22) is equivalent to:

$$1 - x\% = \frac{e^{-\delta(t+1)}b}{e^{-\delta t}b} = e^{-\delta} \quad (23)$$

Taking logarithms:

$$\delta = -\log(1 - x\%) \approx x\% \quad (24)$$

So  $\delta$  is approximately the share of the capital stock that is lost to depreciation in one unit of time.

**Example 3 (Calibration)** *Time is counted in days. Say that we know from the data that capital depreciates by 10% every year:*

$$1 - 10\% = \left. \frac{k(t + 365)}{k(t)} \right|_{I(\tau)=0}$$

Using Equation (19):

$$1 - 10\% = \frac{e^{-\delta(t+365)}b}{e^{-\delta t}b} = e^{-365 \times \delta}$$

Therefore:

$$\delta = \frac{-\log(1 - 10\%)}{365} \approx \frac{10\%}{365}$$

Table 1: Depreciation in the US in 2016

Type	Depreciation rate	Depreciation as a share of GDP
Fixed assets	5%	16%
<i>Private nonresidential</i>	9%	10%
<i>Private residential</i>	2%	3%
<i>Government</i>	4%	3%
Consumer durable goods	20%	6%
Total	6%	21%

Source: BEA. Note: the third column does not necessarily add up because of rounding

## References

Barro, R. J. and X. Sala-i Martin. Economic growth (second ed.). *Cambridge: MIT Press*.