

Macroeconomics III

Stochastic Environment and Finite Markov Chains

Diego Rodrigues

SciencesPo
diego.desousarodrigues@sciencespo.fr

Fall 2023

1 Stochastic Environment

2 Finite Markov Chains

Environment

- The agents make decision at date $t = 0$;
- There are infinite periods;
- At each date $t \geq 0$ there is a realization of a stochastic event $s_t \in \mathcal{S}$;
- The history of these events until period t is denoted by $s^t = [s_0, s_1, s_2, \dots, s_t]$;
- A particular sequence of events occur with probability $\pi_t(s^t)$;
- The chance that a sequence of events s^τ occurs given the sequence s^t occurred is given by $\pi_t(s^\tau | s^t)$;
- There is a set of I agents that receive a perfectly anticipated endowment $y_t^i(s^t)$ in each period. This endowment is perishable, but the agents can trade among themselves;
- The individual savings can be positive or negative, but the aggregate one will always be zero;

- Agents have utility $u(c)$ that is increasing and concave, i.e., $u'(c) > 0$ and $u''(c) < 0$;
- Agents will draw a consumption plan for all his life $\{c_t^i(s^t)\}_{t=0}^{\infty} \equiv C^i$, which will be subject to a discount factor $\beta \in (0, 1)$ such that:

$$U(C^i) = \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) u[c_t^i(s^t)]$$

- First of all we will solve the **social planner's problem** and then verify the **conditions such that the solution of the competitive equilibrium is efficient**.

The Social Planner's problem

$$\max_{\{C^i\}_{i=1}^I} \sum_{i=1}^I \lambda^i U(C^i) \quad \text{s.a.} \quad \sum_{i=1}^I c_t^i(s^t) \leq \sum_{i=1}^I y_t^i(s^t), \quad \forall t, \forall s^t$$

- The problem of the Social Planner is then:

$$\mathcal{L} = \sum_{i=1}^I \lambda^i \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) u[c_t^i(s^t)] + \sum_{t=0}^{\infty} \sum_{s^t} \theta_t(s^t) \left[\sum_{i=1}^I (y_t^i(s^t) - c_t^i(s^t)) \right]$$

Let's derive the F.O.C.

- $[c_t^i(s^t)] :$

Let's derive the F.O.C.

- $[c_t^i(s^t)] :$
- By defining the aggregate endowment as $Y_t(s^t) \equiv \sum_{i=1}^I y_t^i(s^t)$ and assuming the **aggregate endowment between any two periods t and τ is the same**, we can show:
$$Y_t(s^t) = Y_\tau(s^\tau) \implies c_t^i(s^t) = c_\tau^i(s^\tau), \forall i \in I$$

Agent's problem in an Arrow-Debreu structure

- Assume there are only two possible states of nature: 0 and 1, i.e., $\mathcal{S} = \{0, 1\}$
- Let the economy always begin in state 0 (i.e., the initial state is deterministic $\pi_0(0) = 1$)

Agent's problem in an Arrow-Debreu structure

- Assume there are only two possible states of nature: 0 and 1, i.e., $\mathcal{S} = \{0, 1\}$
- Let the economy always begin in state 0 (i.e., the initial state is deterministic $\pi_0(0) = 1$)
- The structure for an economy with 3 periods can be represented by the following tree:

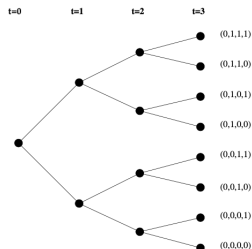


Figure 1: The Arrow-Debreu commodity space for a two-state.

Agent's problem in an Arrow-Debreu structure

- The **market structure is complete** in the sense that the agent can acquire **rights of consumption for any period and for any possible history**.

Agent's problem in an Arrow-Debreu structure

The problem of the agents is

$$\max_{\{c_t^i(s^t)\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) u[c_t^i(s^t)]$$

subject to

$$\sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) y_t^i(s^t) \geq \sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) c_t^i(s^t)$$

Agent's problem in an Arrow-Debreu structure

- Since the markets open only once, in $t = 0$, we will have just one Lagrange multiplier in the problem below:

$$\mathcal{L} = \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) u[c_t^i(s^t)] + \gamma^i \sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) [y_t^i(s^t) - c_t^i(s^t)]$$

- The F.O.C.
[$c_t^i(s^t)$] :

Agent's problem in an Arrow-Debreu structure

- Using the same idea we used for the Social Planner's problem we can divide the F.O.C. of the agent i by the F.O.C. of an agent 1 generic and obtain:

Agent's problem in an Arrow-Debreu structure

- Using the same idea we used for the Social Planner's problem we can divide the F.O.C. of the agent i by the F.O.C. of an agent 1 generic and obtain:
- In other words, by setting $\lambda^i = \frac{\gamma^i}{\gamma^1} \lambda^1$ and using those weights to solve the SP, we will reach the same allocation as the competitive equilibrium. In other words, **there are weights such that the allocation of the social planner is a competitive equilibrium.**

Agent's problem in an Arrow-Debreu structure

- So far, we obtained 4 important equations, which are:

$$\lambda^i \beta^t \pi_t(s^t) u' [c_t^i(s^t)] = \theta_t(s^t), \quad \forall i \in I, \forall t, \forall s^t \quad (\text{F.O.C. SP})$$

$$\beta^t \pi_t(s^t) u' [c_t^i(s^t)] = \gamma^i q_t^0(s^t), \quad \forall i \in I, \forall t, \forall s^t \quad (\text{F.O.C. AD})$$

$$\sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) [y_t^i(s^t) - c_t^i(s^t)] = 0 \quad (\text{BC})$$

$$Y_t(s^t) = \sum_{i=1}^I y_t^i(s^t) = \sum_{i=1}^I c_t^i(s^t) \quad (\text{F})$$

Agent's problem in an Arrow-Debreu structure

- By assuming $q_0^0(s^0) = 1$ we can then reach the Euler Equation:

Agent's problem in an Arrow-Debreu structure

- By assuming $q_0^0(s^0) = 1$ we can then reach the Euler Equation:

$$u' [c_0^i(s^0)] = \frac{\beta^t \pi_t(s^t) u' [c_t^i(s^t)]}{q_t^0(s^t)}$$

Agent's problem in an Arrow-Debreu structure

- By assuming $q_0^0(s^0) = 1$ we can then reach the Euler Equation:

$$u' [c_0^i(s^0)] = \frac{\beta^t \pi_t(s^t) u' [c_t^i(s^t)]}{q_t^0(s^t)}$$

- From the Euler Equation we can have idea about the prices in this economy:

$$q_t^0(s^t) = \beta^t \pi_t(s^t) \frac{u' [c_t^i(s^t)]}{u' [c_0^i(s^0)]}$$

Agent's problem in an Arrow-Debreu structure

- Suppose **there is no aggregate uncertainty**, $Y_t(s^t) = \bar{Y}$, $\forall t, \forall s^t$
- By the analysis we already made we can conclude $u'[c_t^i(s^t)] = u'[c_0^i(s^0)]$, which will lead us to a completely exogenous price:

$$q_t^0(s^t) = \beta^t \pi_t(s^t)$$

Agent's problem in an Arrow-Debreu structure

- Suppose $u(c) = \log(c) \implies u'(c) = \frac{1}{c}$
- **Show that the consumption of the agent is always a function of the total endowment.**

Agent's problem in an Arrow-Debreu structure

- By still considering the case where there is no aggregate uncertainty

$$q_t^0(s^t) = \beta^t \pi_t(s^t) \frac{u'[c_t^i(s^t)]}{u'[c_0^i(s^0)]}$$

$$\sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) c_t^i(s^t) \Rightarrow \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t \in S} \beta^t \pi_t(s^t) c_t^i(s^t)$$

Agent's problem in an Arrow-Debreu structure

- By still considering the case where there is no aggregate uncertainty

$$q_t^0(s^t) = \beta^t \pi_t(s^t) \frac{u'[c_t^i(s^t)]}{u'[c_0^i(s^0)]}$$

$$\sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) c_t^i(s^t) \Rightarrow \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t \in S} \beta^t \pi_t(s^t) c_t^i(s^t)$$

Define $\bar{C}^i \equiv \sum_{t=0}^{\infty} \sum_{s^t} c_t^i(s^t)$

Agent's problem in an Arrow-Debreu structure

- By still considering the case where there is no aggregate uncertainty

$$q_t^0(s^t) = \beta^t \pi_t(s^t) \frac{u'[c_t^i(s^t)]}{u'[c_0^i(s^0)]}$$

$$\sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) c_t^i(s^t) \Rightarrow \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t \in S} \beta^t \pi_t(s^t) c_t^i(s^t)$$

Define $\bar{C}^i \equiv \sum_{t=0}^{\infty} \sum_{s^t} c_t^i(s^t)$

$$= \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) c_t^i(s^t) = \bar{C}^i \sum_{t=0}^{\infty} \beta^t \sum_{s^t} \pi_t(s^t) = \bar{C}^i \cdot \frac{1}{1-\beta} \cdot 1$$

Agent's problem in an Arrow-Debreu structure

- By still considering the case where there is no aggregate uncertainty

$$q_t^0(s^t) = \beta^t \pi_t(s^t) \frac{u'[c_t^i(s^t)]}{u'[c_0^i(s^0)]}$$

$$\sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t} q_t^0(s^t) c_t^i(s^t) \Rightarrow \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) y_t^i(s^t) = \sum_{t=0}^{\infty} \sum_{s^t \in S} \beta^t \pi_t(s^t) c_t^i(s^t)$$

Define $\bar{C}^i \equiv \sum_{t=0}^{\infty} \sum_{s^t} c_t^i(s^t)$

$$= \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) c_t^i(s^t) = \bar{C}^i \sum_{t=0}^{\infty} \beta^t \sum_{s^t} \pi_t(s^t) = \bar{C}^i \cdot \frac{1}{1-\beta} \cdot 1$$

$$\frac{\bar{C}^i}{1-\beta} = \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) y_t^i(s^t) \Rightarrow \bar{C}^i = (1-\beta) \sum_{t=0}^{\infty} \beta^t \sum_{s^t} \pi_t(s^t) y_t^i(s^t)$$

- Therefore, **the present value of consumption is equal to the expected value of the endowment of the agent.**

Agent's problem in a Sequential structure

- First of all define $Q(s_{t+1}|s^t)$ as being the price in t , given the history s^t of an unit of consumption good in period $t + 1$ contingent to the realization s_{t+1} .

Agent's problem in a Sequential structure

- First of all define $Q(s_{t+1}|s^t)$ as being the price in t , given the history s^t of an unit of consumption good in period $t + 1$ contingent to the realization s_{t+1} .
- The problem of the agents will be given by:

$$\max_{\{c_t^i(s^t), a_{t+1}^i(s^{t+1})\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) u[c_t^i(s^t)]$$

subject to:

$$c_t^i(s^t) + \sum_{s_{t+1}} Q_t(s_{t+1} | s^t) a_{t+1}^i(s^{t+1}) \leq y_t^i(s^t) + a_t^i(s^t) \quad \forall t, \forall s^t$$

Agent's problem in a Sequential structure

- Let us define now a **natural limit for the debt** of the agent:

$$-a_t^i(s^t) \leq \sum_{\tau=t+1}^{\infty} \sum_{s^\tau | s^{t+1}} q_\tau^0(s^\tau) y_\tau^i(s^\tau)$$

- The **debt of the agent has to be lower than the present value of the income of the agent for the remaining of his/her life.**

Agent's problem in a Sequential structure

$$\mathcal{L} = \sum_{t=0}^{\infty} \sum_{s^t} \beta^t \pi_t(s^t) u[c_t^i(s^t)] + \sum_{t=0}^{\infty} \sum_{s^t} \eta_t^i(s^t) [y_t^i(s^t) + a_t^i(s^t) - c_t^i(s^t) - \sum_{s^{t+1}} Q_t(s_{t+1} | s^t) a_{t+1}^i(s^{t+1})]$$

In this case we will have the following F.O.C.

- The F.O.C.
 $[c_t^i(s^t)] :$

$$[a_{t+1}^i(s^{t+1})] :$$

Agent's problem in a Sequential structure

- So far, we obtained 4 important equations, which are:

$$Q_t(s_{t+1} | s^t) = \beta \pi_t(s^{t+1} | s^t) \frac{u'[c_{t+1}^i(s^{t+1})]}{u'[c_t^i(s^t)]} \quad (\text{EE})$$

$$c_t^i(s^t) + \sum_{s_{t+1}} Q_t(s_{t+1} | s^t) a_{t+1}^i(s^{t+1}) = y_t^i(s^t) + a_t^i(s^t) \quad \forall t, \forall s^t \quad (\text{BC})$$

$$Y_t(s^t) = \sum_{i=1}^I y_t^i(s^t) = \sum_{i=1}^I c_t^i(s^t) \quad (\text{F})$$

$$\sum_{i=1}^I a_t^i(s^t) = 0 \quad (\text{A})$$

Equivalence of equilibrium in both structures

Remember we have the following important equations in the two structures:

$$q_t^0(s^t) = \beta^t \pi_t(s^t) \frac{u'[c_t^i(s^t)]}{u'[c_0^i(s^0)]}$$

$$Q_t(s_{t+1} | s^t) = \beta \pi_t(s^{t+1} | s^t) \frac{u'[c_{t+1}^i(s^{t+1})]}{u'[c_t^i(s^t)]}$$

How do we guarantee that the allocations are the same ?

Equivalence of equilibrium in both structures

Remember we have the following important equations in the two structures:

$$q_t^0(s^t) = \beta^t \pi_t(s^t) \frac{u'[c_t^i(s^t)]}{u'[c_0^i(s^0)]}$$

$$Q_t(s_{t+1} | s^t) = \beta \pi_t(s^{t+1} | s^t) \frac{u'[c_{t+1}^i(s^{t+1})]}{u'[c_t^i(s^t)]}$$

How do we guarantee that the allocations are the same ?

Just set

Equivalence of equilibrium

$$\frac{q_{t+1}^0(s^{t+1})}{q_t^0(s^t)} \equiv Q_t(s_{t+1} | s^t)$$

Equivalence of equilibrium in both structures

Now we need to check whether the allocation in AD is comparable to that in a Sequential Market Equilibrium:

Set the following value and we will be done:

$$a_t^i(s^t) = \sum_{\tau=t}^{\infty} \sum_{s^\tau | s^t} q_\tau^t(s^\tau) [c_\tau^i(s^\tau) - y_\tau^i(s^\tau)]$$

1 Stochastic Environment

2 Finite Markov Chains

A **Markov chain** process is a simple type of stochastic process. Markov chains are one of the most useful classes of stochastic processes being:

A **Markov chain** process is a simple type of stochastic process. Markov chains are one of the most useful classes of stochastic processes being:

- simple, flexible and supported by many elegant theoretical results;

A **Markov chain** process is a simple type of stochastic process. Markov chains are one of the most useful classes of stochastic processes being:

- simple, flexible and supported by many elegant theoretical results;
- valuable for building intuition about random dynamic models;

A **Markov chain** process is a simple type of stochastic process. Markov chains are one of the most useful classes of stochastic processes being:

- simple, flexible and supported by many elegant theoretical results;
- valuable for building intuition about random dynamic models;
- central to quantitative modeling in their own right.

Definition

Let S be a **finite** set with n elements $\{x_1, \dots, x_n\}$.

Definition

Let S be a **finite** set with n elements $\{x_1, \dots, x_n\}$. The set S is called the **state space** and x_1, \dots, x_n are the **state values**. A state space is the space in which the possible values of each x_t lie.

Definition

Let S be a **finite** set with n elements $\{x_1, \dots, x_n\}$. The set S is called the **state space** and x_1, \dots, x_n are the **state values**. A state space is the space in which the possible values of each x_t lie.

A Markov chain is a **stochastic process** - a sequence of random variables - on S , a discrete set, with **Markov property**.

Definition

Let S be a **finite** set with n elements $\{x_1, \dots, x_n\}$. The set S is called the **state space** and x_1, \dots, x_n are the **state values**. A state space is the space in which the possible values of each x_t lie.

A Markov chain is a **stochastic process** - a sequence of random variables - on S , a discrete set, with **Markov property**.

A Markov chain (x, P, π) is characterized by a triple of three objects: a **state space** identified with an n -vector x , an $n \times n$ **transition matrix** P and an **initial distribution**, a n -vector π_0 .

Definition

Markov property

A stochastic process $\{X_t\}$ has the **Markov property** if, knowing its **current** state is enough to know probabilities for its future states :

$$\mathbb{P}\{X_{t+1} = y | X_t\} = \mathbb{P}\{X_{t+1} = y | X_t, X_{t-1}, \dots\}$$

The dynamics of a Markov chain are fully determined by the set of values

$$P(x, y) := \mathbb{P}\{X_{t+1} = y | X_t = x\} \quad (x, y \in S)$$

Definition

Markov chain and Markov matrix

We can view P as a stochastic matrix with $P_{ij} = \mathbb{P}(X_{t+1} = x_j | X_t = x_i)$, $1 \leq i, j \leq n$. **A stochastic matrix defines the probability of moving from each value of the state to any other in one period.**

Definition

Markov property

A stochastic matrix (or **Markov matrix**) is an $n \times n$ square matrix P such that:

- each element of P is non-negative;
- each row of P sums to one.

Each row of P can be regarded as the probability mass function over n possible outcomes.

A **probability mass function** is a function that gives the probability that a discrete random variable is exactly equal to some value

Definition

Markov chain and Markov matrix

With $P_{ij} = \mathbb{P}(x_i, x_j)$, fix a row i , then the elements in each of the j columns give the **conditional probabilities of transiting from state x_i to state x_j** .

Definition

Markov chain and Markov matrix

With $P_{ij} = \mathbb{P}(x_i, x_j)$, fix a row i , then the elements in each of the j columns give the **conditional probabilities of transiting from state x_i to state x_j** . Example :

At any given time t , a worker is either **unemployed (state 1)** or **employed (state 2)**. Over a one month period, a **u worker** finds a job with probability $\alpha \in (0, 1)$ and a **e worker** loses her job and with probability $\beta \in (0, 1)$

$$P = \begin{pmatrix} \square & \square \\ \square & \square \end{pmatrix}$$

Here : $S =$; $P(1, 2) =$; $P(2, 1) =$

Definition

Markov chain and Markov matrix

Example :

$$P = \begin{pmatrix} 1 - \alpha & \alpha \\ \beta & 1 - \beta \end{pmatrix}$$

Here : $S = \{1, 2\}$; $P(1, 2) = \alpha$; $P(2, 1) = \beta$

Definition

Markov chain and Markov matrix

Example :

$$P = \begin{pmatrix} 1 - \alpha & \alpha \\ \beta & 1 - \beta \end{pmatrix}$$

Here : $S = \{1, 2\}$; $P(1, 2) = \alpha$; $P(2, 1) = \beta$

Once we have the values of α and β we will be able to answer the following questions:

- What is the **average duration of unemployment**?
- Over the long-run, **what fraction of time does a worker find herself unemployed**?
- **Conditional on employment, what is the probability of becoming unemployed at least once over the next 12 months?**

Definition

Markov chain and Markov matrix

The initial distribution $\pi_0 = [\pi_{0,i}]$ has elements with the interpretation

$$\pi_{0,i} = \mathbb{P}\{X_0 = x_i\}$$

The initial distribution is often set to have $\pi_i = 1$ for some i and zero everywhere else so that the chain is started in state i with probability 1

Marginal Distributions

Suppose that $\{X_t\}$ is a **Markov chain** with stochastic matrix P and a distribution π_t . You would like to know the distribution of $\{X_{t+1}\}$ i.e., **to know π_{t+1} given π_t and P (and more generally, the distribution of X_{t+m})**. Using the law of total probability, we can decompose the probability that $X_{t+1} = y$ (for any given $y \in S$) :

$$\mathbb{P}\{X_{t+1} = y\} = \sum_{x \in S} \mathbb{P}\{X_{t+1} = y | X_t = x\} \cdot \mathbb{P}\{X_t = x\}$$

To get the probability of being at y tomorrow, **we account for all ways this can happen and sum their probabilities.**

Rewriting the previous statement in terms of **marginal and conditional probabilities** gives:

$$\pi_{t+1}(y) = \sum_{x \in S} P(x, y) \pi_t(x)$$

Or (in matrix form, with π a row vector) :

$$\pi_{t+1} = \pi_t P$$

Marginal Distributions

To move the distribution forward (1 unit of time), we multiply by P

$$\begin{aligned}\pi_{t+2} &= \pi_{t+1}P \\ &= \pi_t P \times P = \pi_t P^2\end{aligned}$$

Then,

$$\pi_{t+m} = \pi_t P^m$$

Marginal Distributions

Intuition

The marginal distributions can be viewed either **as probability or as cross-sectional frequencies in large samples**, it records the fractions of workers e and u at a given moment.

Example : consider a large population of workers; let π be the current cross-sectional distribution over $\{u, e\}$. Then, $\pi(1)$ **is the unemployment rate**.

Marginal Distributions

Intuition

The marginal distributions can be viewed either **as probability or as cross-sectional frequencies in large samples**, it records the fractions of workers e and u at a given moment.

Example : consider a large population of workers; let π be the current cross-sectional distribution over $\{u, e\}$. Then, $\pi(1)$ **is the unemployment rate**.

The **same distribution also describes the fractions of a particular worker's career spent being employed and unemployed**.

Moments of the Markov chain

$$\mathbb{E}\{X_1\} =$$

$$\mathbb{E}\{X_2\} =$$

...

$$\mathbb{E}\{X_t\} =$$

And,

$$\mathbb{E}\{X_{t+m}|X_t = x\} =$$

Moments of the Markov

$$\mathbb{E}\{X_1\} = \pi_0 x$$

$$\mathbb{E}\{X_2\} = \pi_0 P x$$

...

$$\mathbb{E}\{X_t\} = \pi_0 P^t x$$

And,

$$\mathbb{E}\{X_{t+m} | X_t = x\} = P^m x$$

The probability that the economy is in state x is estimated to be $\pi(x)$.

Considering the example we are working, what is the probability of being **employed** after 1 month given a initial distribution π_0 ?

The probability that the economy is in state x is estimated to be $\pi(x)$.

Considering the example we are working, what is the probability of being **employed** after 1 month given a initial distribution π_0 ?

$$\pi_0 P \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

The probability that the economy is in state x is estimated to be $\pi(x)$.

Considering the example we are working, what is the probability of being **employed** after 1 month given a initial distribution π_0 ?

$$\pi_0 P \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

and after **6 months**?

$$\pi_0 P^6 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Few Properties

A matrix is said to be **irreducible** if we can reach any state from any other state (eventually)

If certain regions of the state space cannot be accessed from other regions a matrix is said to have **infinite persistence**.

A Markov chain is called **periodic** if it cycles in a **predictable** way, and **aperiodic** otherwise.

Few Properties

Consider the following case:

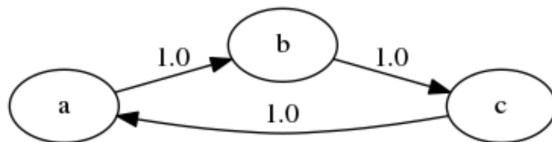


Figure 2: A chain cycle with period 3.

In this case what is the **matrix P**?

Few Properties

Consider the following case:

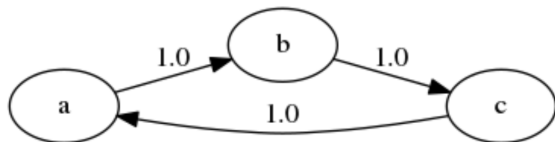


Figure 2: A chain cycle with period 3.

In this case what is the **matrix P**?

$$P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

Stationary probability distribution

A **stationary probability distribution**¹ on S is a vector $\bar{\pi}$ such that $\bar{\pi} = \bar{\pi}P$, ie the distribution is invariant under the updating process.

$$\bar{\pi} = \bar{\pi}P \iff \bar{\pi}' = P'\bar{\pi}' \iff (P' - I_n)\bar{\pi} = \underset{n \times n}{0}$$

(P, π) is a stationary Markov chain if the initial distribution π_0 is such that this equation holds. The stationary probability distribution is an eigenvector associated with a unit eigenvalue of P' .

¹A stationary distribution is a fixed point of P when P is thought of as the map $\pi \rightarrow \pi P$ from (row) vectors to (row) vectors

Stationary probability distribution

P must have ² at least one unit eigenvalue, but there may be more than one such eigenvalue. **Then, every stochastic matrix P (on a finite state space S) has at least one stationary distribution.**

Stationary distributions have a natural interpretation as **stochastic steady states**.

²Because $1 \leq p_{ij} \leq 0$ and $\sum_{i=1}^n p_{ij} = 1$

Stationary probability distribution

Example of a stationary distribution :

$$P = \begin{pmatrix} 0.4 & 0.6 \\ 0.2 & 0.8 \end{pmatrix} \quad \pi = \begin{pmatrix} 0.25 \\ 0.75 \end{pmatrix} \quad \pi P = \begin{pmatrix} 0.25 \\ 0.75 \end{pmatrix}$$

And,

$$P = \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{5} & \frac{1}{2} & \frac{3}{10} \\ 0 & 0 & 1 \end{pmatrix} \quad \pi_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \pi_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

If P is both aperiodic and irreducible : (i) P has exactly one stationary distribution $\bar{\pi}$ (ii) the chain will asymptotically converge to this unique stationary distribution for all initial conditions $\|\pi_0 P^t - \bar{\pi}\|$ as $t \rightarrow \infty$.

A sufficient condition for a matrix to be aperiodic and irreducible is that every element of P is strictly positive.

Stationary probability distribution

Back to the **employed / unemployed** example : let $\bar{\pi} = (p, 1 - p)$ be the stationary distribution. Then, you know that :

$$(p \quad 1 - p) \begin{pmatrix} 1 - \alpha & \alpha \\ \beta & 1 - \beta \end{pmatrix} = (p \quad 1 - p)$$

$$\iff p(1 - \alpha) + (1 - p)\beta = p$$

$$\iff p = \frac{\beta}{\beta + \alpha}$$

In the cross-sectional interpretation, this is the fraction of people unemployed.

Example

Using US data, Hamilton ³ estimated the stochastic matrix (monthly frequency). The first state represents “**normal growth**”, the second “**mild recession**”, the third “**severe recession**”.

$$P = \begin{pmatrix} 0.971 & 0.029 & 0 \\ 0.145 & 0.778 & 0.077 \\ 0 & 0.508 & 0.492 \end{pmatrix}$$

³James D Hamilton. What's real about the business cycle? Federal Reserve Bank of St. Louis Review, (July-August):435–452, 2005.

Coming back to our stochastic environment

Remember we have the following price structure:

$$Q_t(s_{t+1} | s^t) = \beta \pi_t(s_{t+1} | s^t) \frac{u' [c_{t+1}^i(s^{t+1})]}{u' [c_t^i(s^t)]}$$

Now assume that the probabilities follow a Markov Process

$$\pi(s_{t+1} | s_t) \implies \pi(s' | s), \quad s, s' \in S$$

As a consequence:

$$\begin{aligned} Q(s' | s) &= \beta \pi(s' | s) \frac{u'[c^i(s')]}{u'[c^i(s)]}, \quad \forall i, \forall s, \forall s' \\ c^i(s) + \sum_{s'} Q(s' | s) a^i(s') &= y^i(s) + a^i, \quad \forall i, \forall s, \forall s' \\ \sum_{i=1}^I c^i(s) &= \sum_{i=1}^I y^i(s), \quad \forall s \\ \sum_{i=1}^I a^i(s) &= 0, \quad \forall s \end{aligned}$$

As a consequence:

$$\begin{aligned} Q(s' | s) &= \beta \pi(s' | s) \frac{u'[c^i(s')]}{u'[c^i(s)]}, \quad \forall i, \forall s, \forall s' \\ c^i(s) + \sum_{s'} Q(s' | s) a^i(s') &= y^i(s) + a^i, \quad \forall i, \forall s, \forall s' \\ \sum_{i=1}^I c^i(s) &= \sum_{i=1}^I y^i(s), \quad \forall s \\ \sum_{i=1}^I a^i(s) &= 0, \quad \forall s \end{aligned}$$

Now assume we have only two states $S = \{H, L\}$ and two agents $i = \{1, 2\}$.

How the prices in this environment should behave?...

The transition matrix will be given by:

$$\begin{bmatrix} \pi(H | H) & \pi(L | H) \\ \pi(H | L) & \pi(L | L) \end{bmatrix} = \begin{bmatrix} \pi_{HH} & \pi_{LH} \\ \pi_{HL} & \pi_{LL} \end{bmatrix}$$

Observe the endowments in each case will be such that:

$$y_{1L} + y_{2L} = Y_L \text{ e } y_{1H} + y_{2H} = Y_H$$

The transition matrix will be given by:

$$\begin{bmatrix} \pi(H | H) & \pi(L | H) \\ \pi(H | L) & \pi(L | L) \end{bmatrix} = \begin{bmatrix} \pi_{HH} & \pi_{LH} \\ \pi_{HL} & \pi_{LL} \end{bmatrix}$$

Observe the endowments in each case will be such that:

$$y_{1L} + y_{2L} = Y_L \text{ e } y_{1H} + y_{2H} = Y_H$$

Assume the following is true:

$$u(c) = \frac{-1}{c} \implies u'(c) = \frac{1}{c^2} > 0 \implies u''(c) = \frac{-2}{c^3} < 0$$

Therefore, we have the final prices will be:

$$Q(H | H) = \beta \pi_{HH}$$

$$Q(L | L) = \beta \pi_{LL}$$

$$Q(H | L) = \beta \pi_{HL} \left(\frac{Y_L}{Y_H} \right)^2$$

$$Q(L | H) = \beta \pi_{LH} \left(\frac{Y_H}{Y_L} \right)^2$$