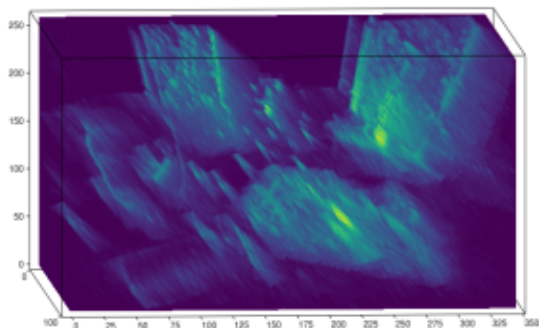


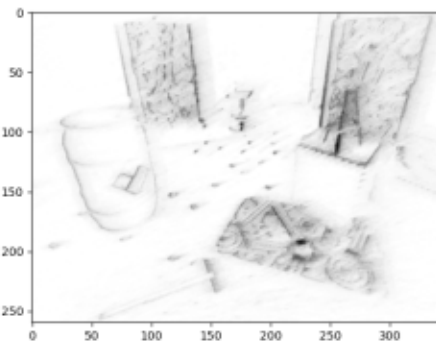
1. DSI from Events and Camera Pose



Confidence
Map

Pixel
Selection

2. Filter for Confident Pixels



3. Neural Network

4. Pixel wise Depth Estimation

