odom Broadcaster: /gazebo Average rate: 30.199 Hz Most recent transform: 1058.833 (0.004 sec old) Buffer length: 4.967 sec base_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1058.837 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 30.211 Hz Average rate: 30.211 Hz Most recent transform: 0.000 (1058.837 sec old) Most recent transform: 0.000 (1058.837 sec old) Most recent transform: 0.000 (1058.837 sec old) Most recent transform: 1058.799 (0.038 sec old) Most recent transform: 0.000 (1058.837 sec old) \Most recent transform: 0.000 (1058.837 sec old) \Most recent transform: 0.000 (1058.837 sec old) Most recent transform: 1058.799 (0.038 sec old) Buffer length: 0.000 sec Buffer length: 4.932 sec Buffer length: 0.000 sec Buffer length: 4.932 sec link1 caster_back_left_link imu_link wheel_left_link wheel_right_link camera_link caster_back_right_link base_scan Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /camera_link_camera_frame Average rate: 10000.000 HzAverage rate: 50.405 Hz Average rate: 10000.000 Hz Most recent transform: 1058.802 (0.035 sec old) Most recent transform: 0.000 (1058.837 sec old) Most recent transform: 0.000 (1058.837 sec old) Buffer length: 4.940 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera_rgb_optical_frame link2 camera_rgb_frame Broadcaster: /robot_state_publisher Broadcaster: /ar_track_alvar Average rate: 50.405 Hz Average rate: 28.035 Hz Most recent transform: 1058.802 (0.035 sec old) Most recent transform: 1058.817 (0.020 sec old) Buffer length: 4.940 sec Buffer length: 4.958 sec link3 ar_marker_11 Broadcaster: /robot_state_publisher Average rate: 50.405 Hz Most recent transform: 1058.802 (0.035 sec old) Buffer length: 4.940 sec link4 Broadcaster: /robot_state_publisher Average rate: 50.405 Hz Most recent transform: 1058.802 (0.035 sec old) Buffer length: 4.940 sec link5 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.405 Hz Average rate: 50.405 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1058.837 sec old) | Most recent transform: 0.000 (1058.837 sec old) | Most recent transform: 1058.802 (0.035 sec old) | Most recent transform: 1058.802 (0.035 sec old) | Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.940 sec Buffer length: 4.940 sec gripper_link end_effector_link gripper_link_sub raspicam_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1058.837 sec old) Buffer length: 0.000 sec raspicam_rgb_frame Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1058.837 sec old) Buffer length: 0.000 sec raspicam_rgb_optical_frame

view_frames Result

Recorded at time: 1058.837