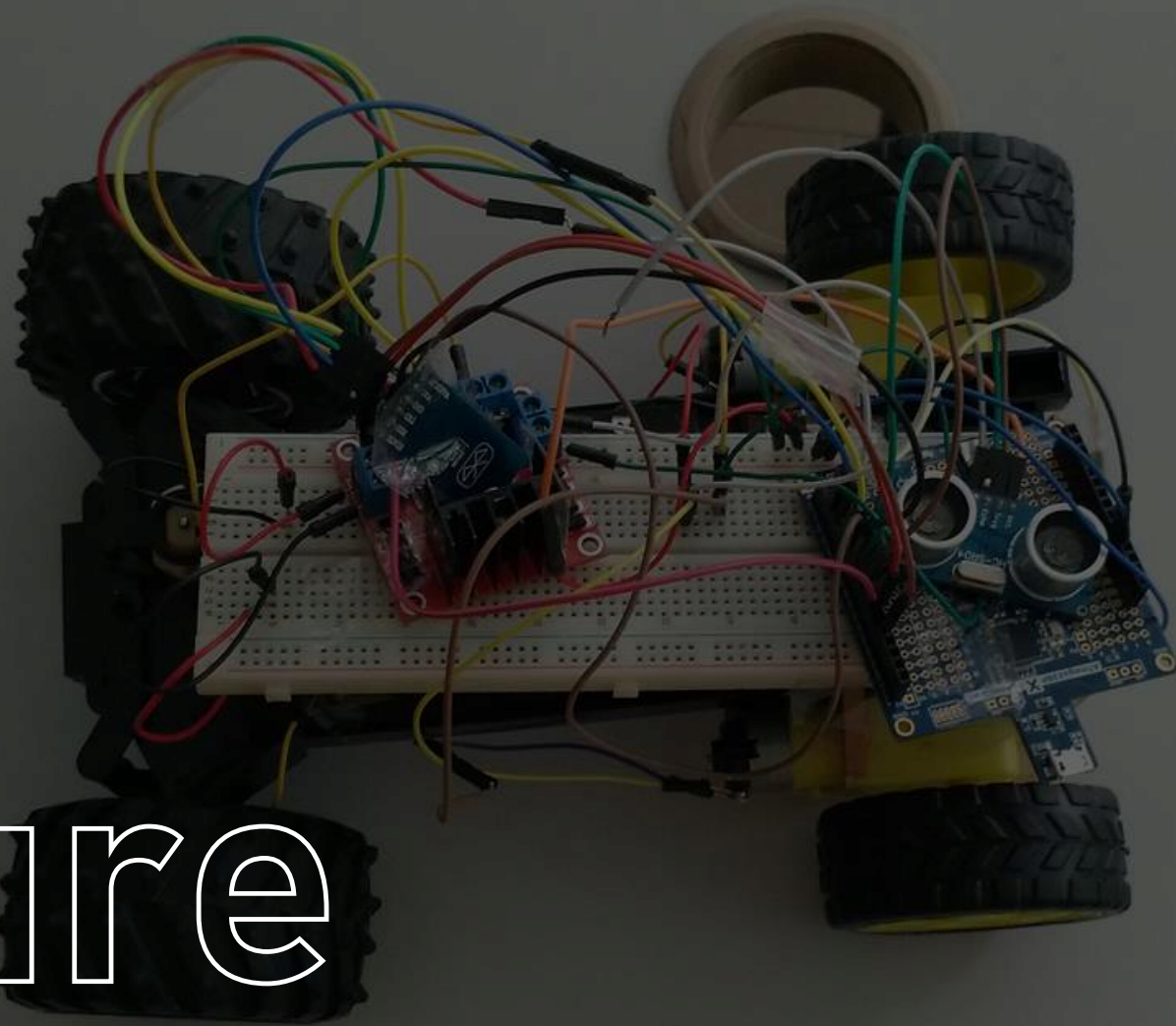


Voiture Télécommandée



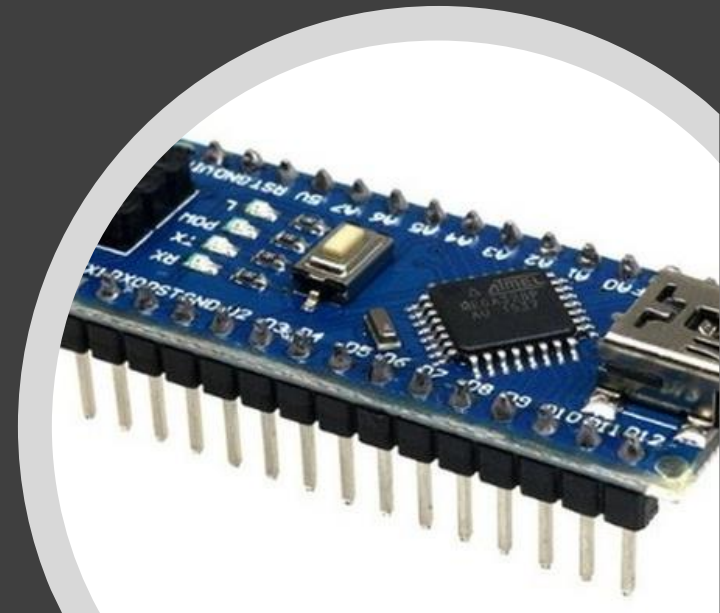
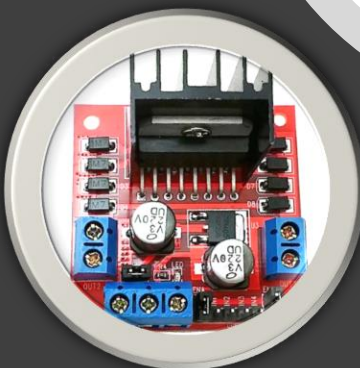
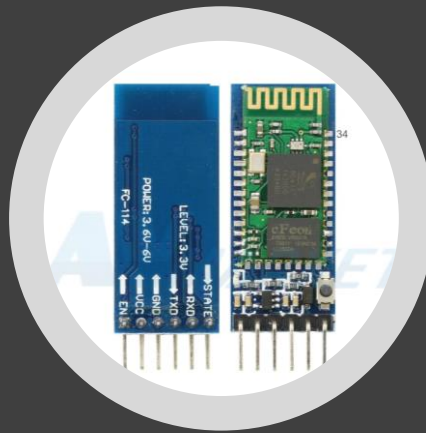
SOMMAIRE

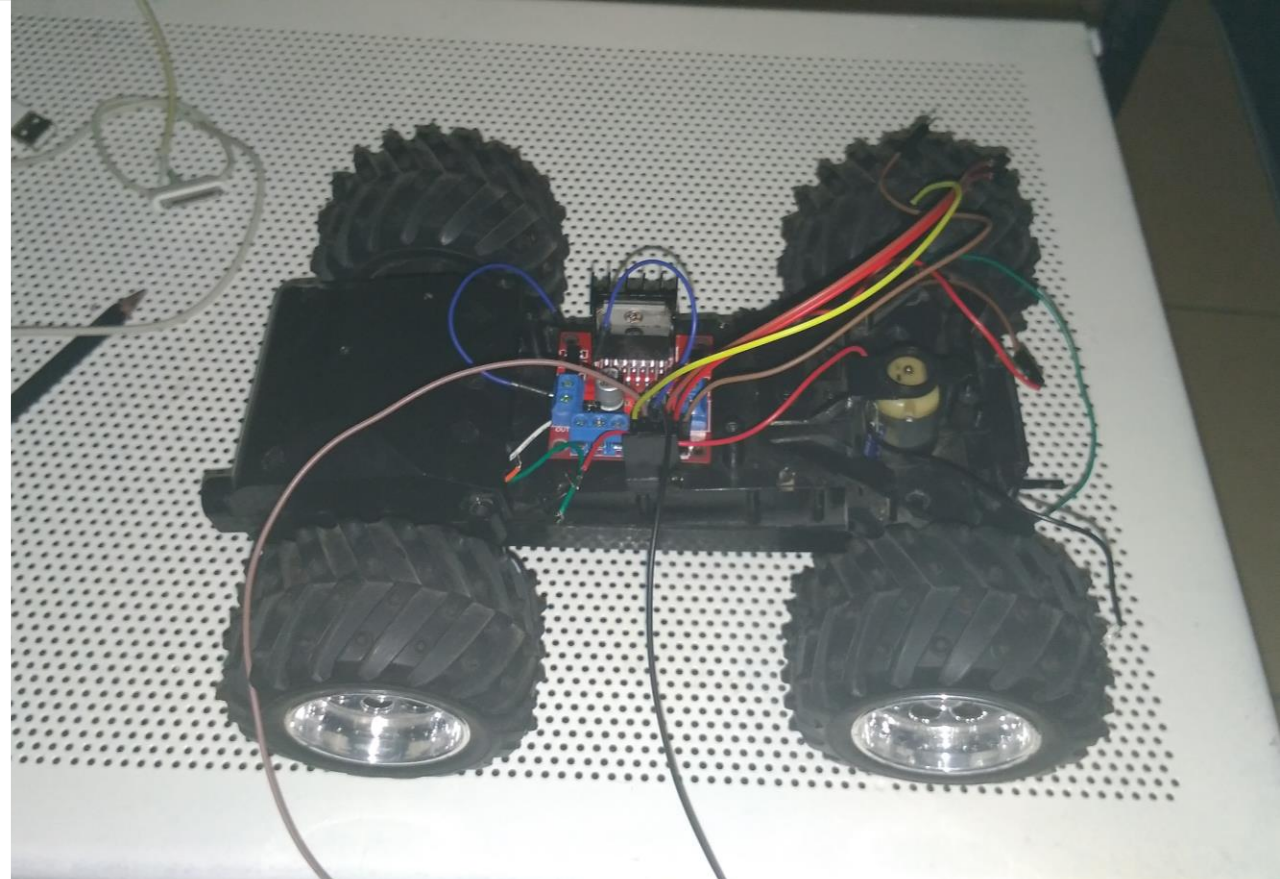
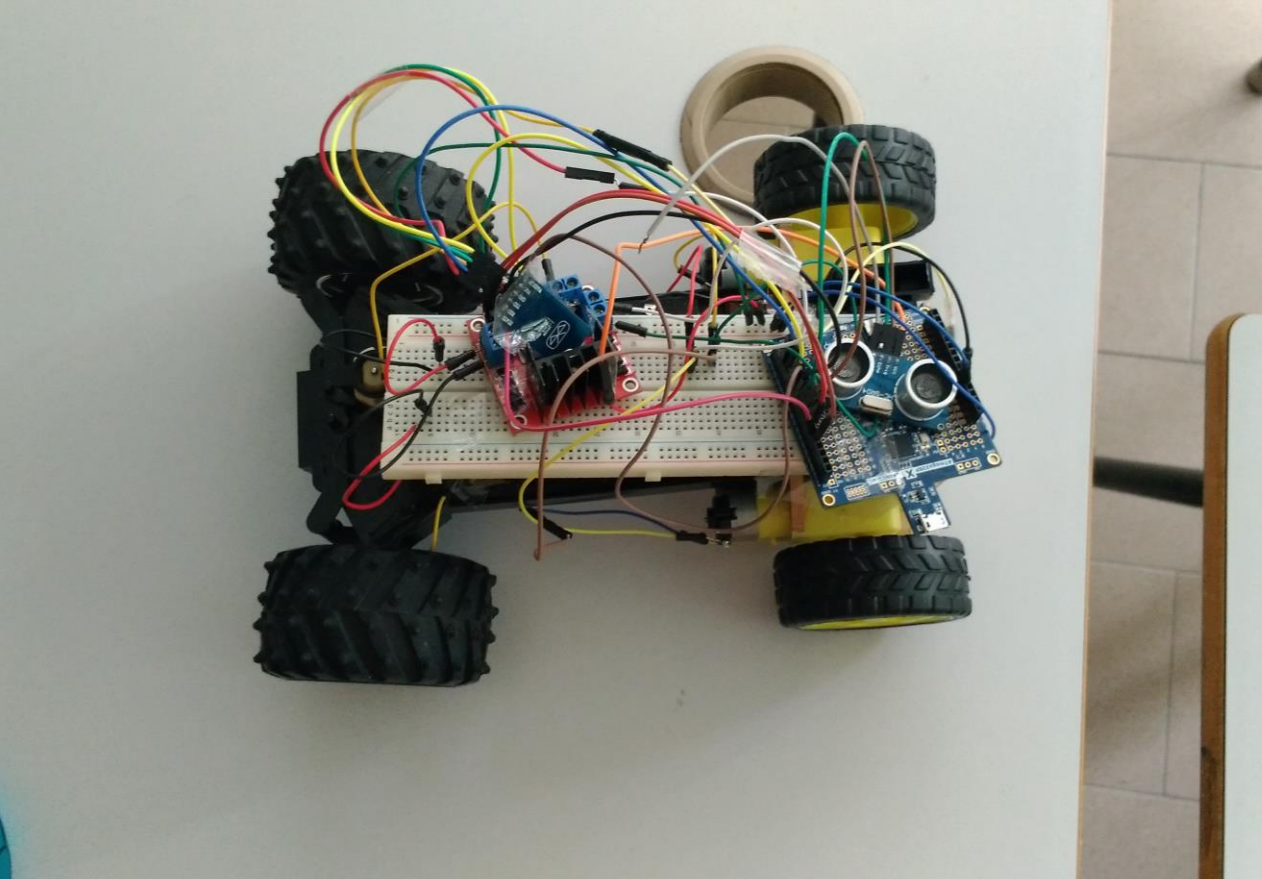
- Matériel
- Réalisation
- Problème
- Planning
- Conclusion



1-Matériel

- -HC-06
- -L298n
- -Deux moteurs DC
- -2 Arduino Nano
- -HC-SR04

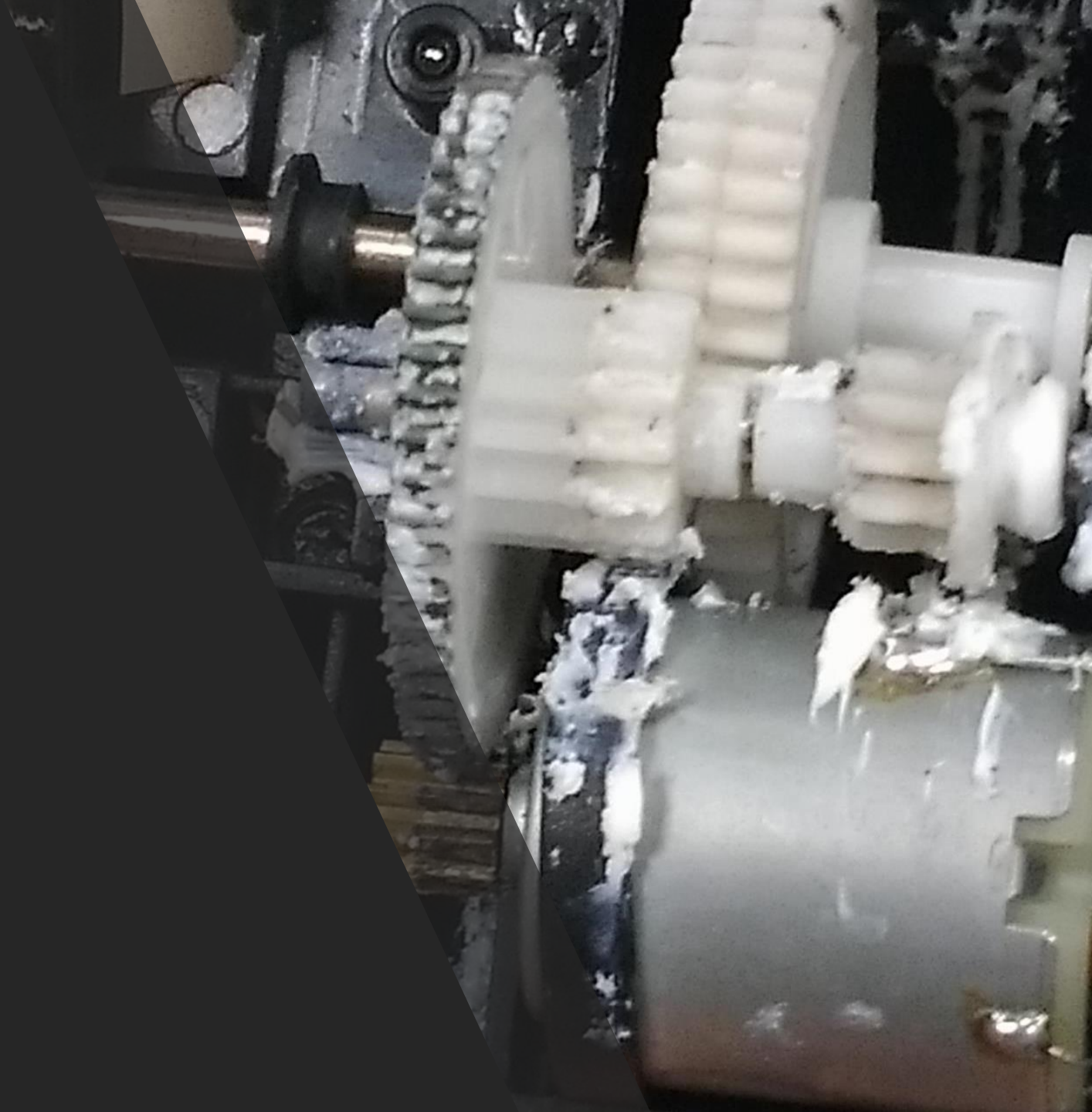




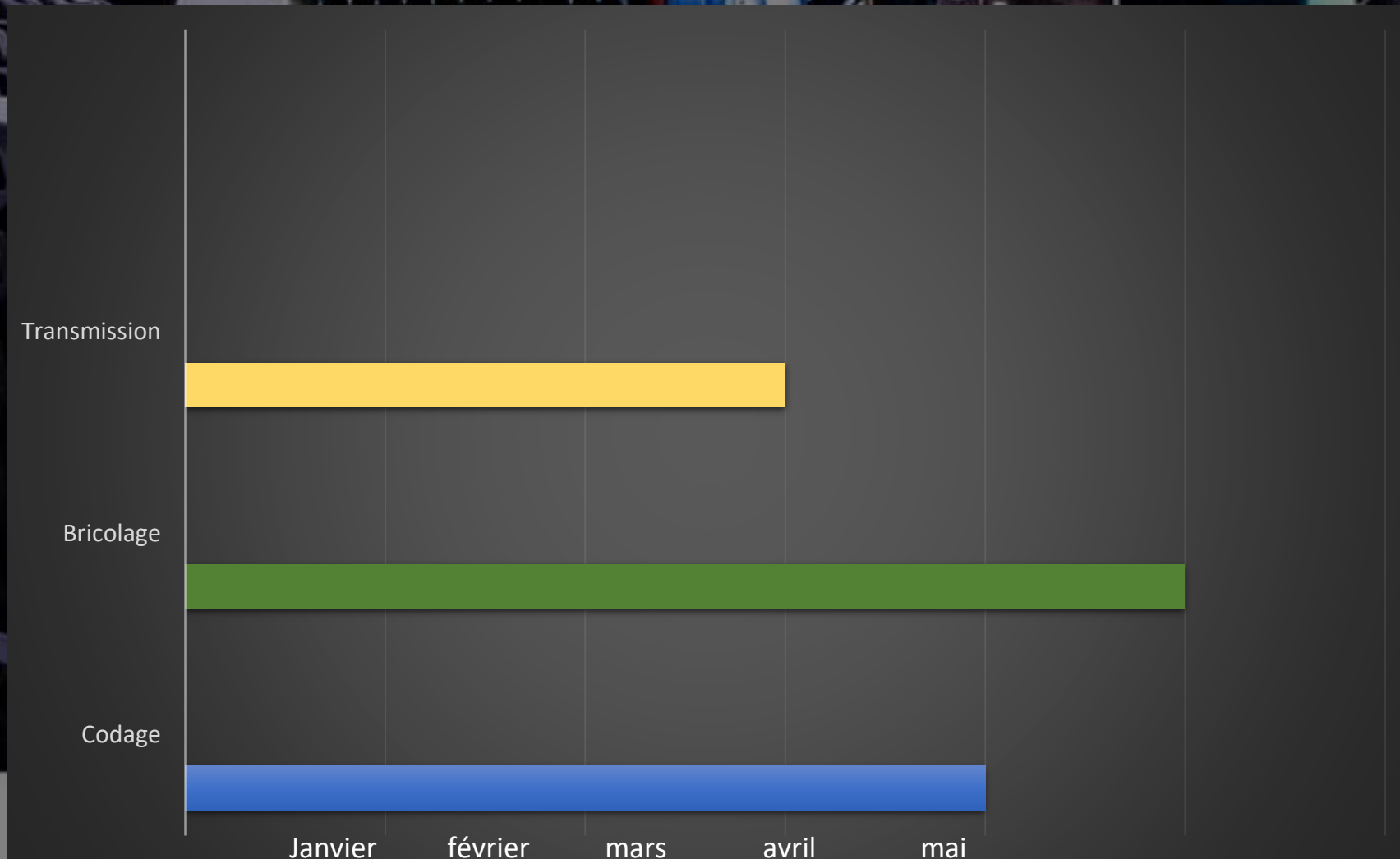
2-Réalisation

3-Problème

- *TRANSMISSION*
- *MOTEUR À 12 V*



3-planning



A custom-built four-wheeled robot is shown from a top-down perspective. The robot has a yellow chassis and four black, treaded wheels. A white breadboard is mounted on top, containing an Arduino Uno microcontroller, a blue motor driver module, and various electronic components. A dense network of colorful jumper wires connects the breadboard to the wheels and other parts of the robot. A roll of white tape is visible behind the robot. The robot is resting on a light-colored wooden table.

Conclusion