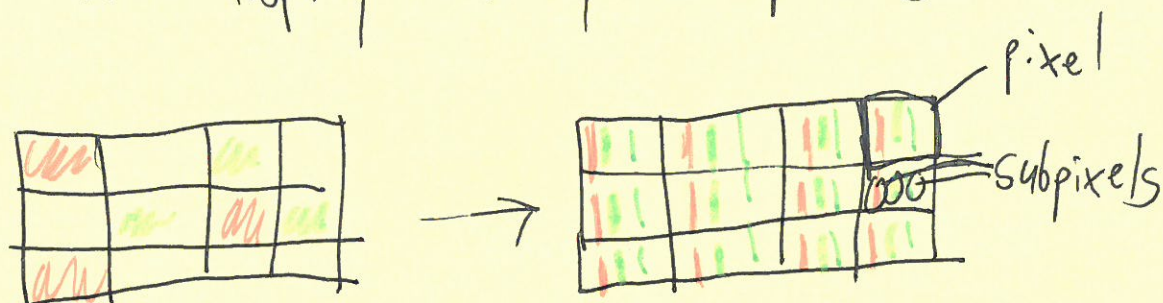


# Rasters, Colors, & Coordinates

18 Jan

def Pixel - short for picture element

def Raster display - array of pixels



As input device

- Camera Ex Bayer mosaic



G B G B G B  
R G R G R G  
G B G B G B  
⋮

- Raster is ~~device~~ device independent description of an image

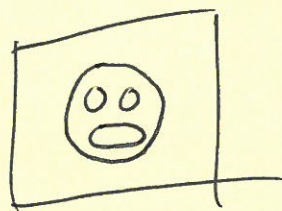
# Vector images

- description of how to draw image

circle .5 .5 .25

circle 4 4 r

|  
|



Why is vector good! Scale well

Why use vector images! independent of scale

- text/fonts

- high precision is important

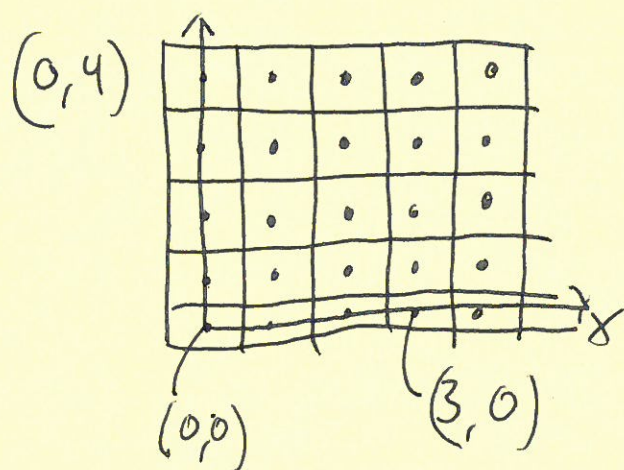


Images, Pixels & Geometry

w/  $R \subset \mathbb{R}^2$

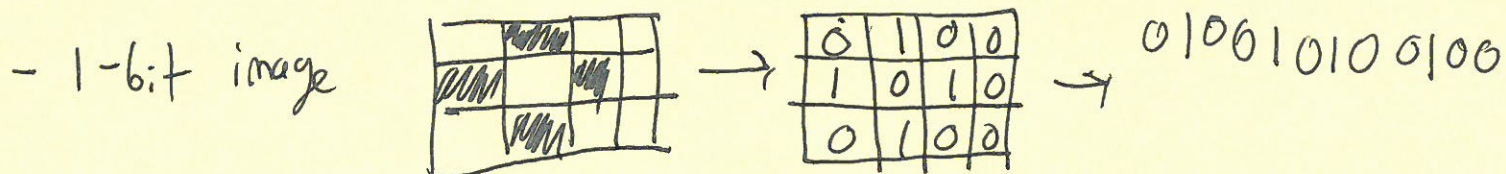
$U$  is set of all pixel values

$$I(x, y) : R \rightarrow U$$

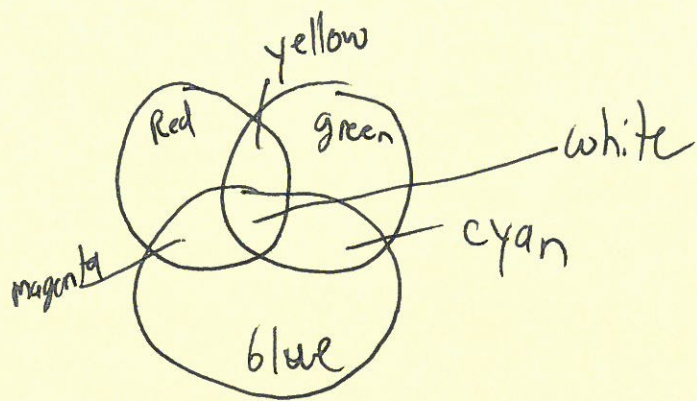


What could we store in each pixel?

- RGB values
- grey scale



# Representing Color



$$\begin{array}{ccc} \text{red} & + & \text{green} & = & \text{yellow} \\ 100 & & 010 & & 110 \end{array}$$

## A representation

— each RGB is a float  $\text{color} = (r, g, b)$

$$\forall r, g, b \in [0, 1]$$

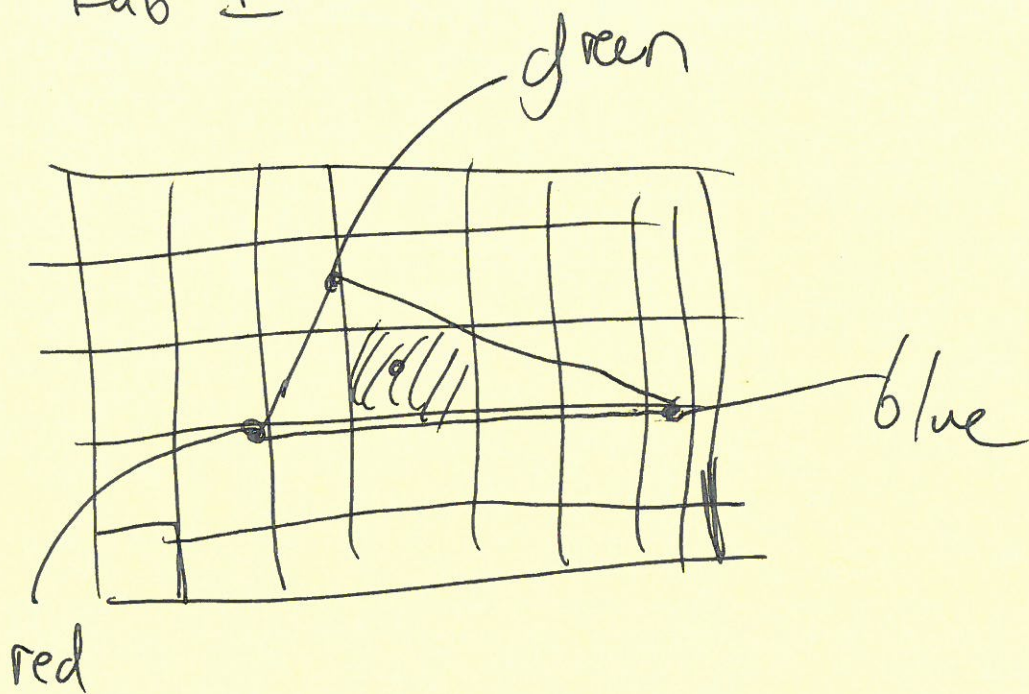
(high dynamic range)

— pixel has values for each component  
 $\{0, 1, \dots, 255\}$

→ to RGB in  $[0, 1]$   
divide by 255



Lab 1



Q1' is a point inside of the  $\Delta$

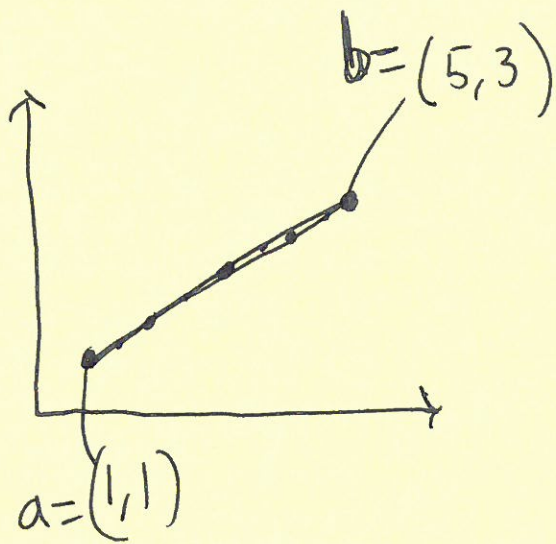
Q2' if it is in  $\Delta$  what color

Linear interpolation

$$a, b \in \mathbb{R}^2$$

$$t \in [0, 1]$$

def  $p = (1-t)a + tb$



$$t=0$$

$$(1-0) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$t=1$$

$$(1-1) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

$$t=.5$$

$$(1-.5) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + .5 \begin{bmatrix} 5 \\ 3 \end{bmatrix} =$$
$$\begin{bmatrix} .5 \\ .5 \end{bmatrix} + \begin{bmatrix} 2.5 \\ 1.5 \end{bmatrix} = \begin{matrix} 3 \\ 2 \end{matrix}$$



# Lines

General form for lines:  $Ax + By + C = 0$

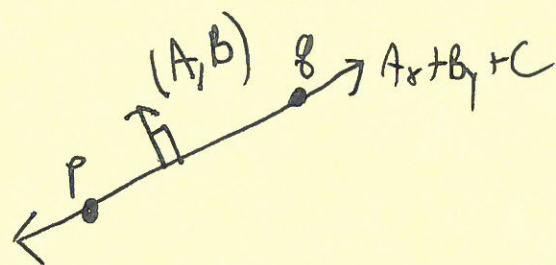
Given 2 points  $p, q \in \mathbb{R}^2$  what is  
general form line through  $p, q$

$$Ap_x + Bp_y + C = 0$$

$$Aq_x + Bq_y + C = 0$$

$$f(x, y) = Ax + By + C$$

$$\nabla f(x, y) = \begin{bmatrix} A \\ B \end{bmatrix}$$



~~$\Rightarrow$  vector  $\perp$   $\begin{bmatrix} q_y - p_y \\ q_x - p_x \end{bmatrix}$~~

$$\perp \text{ vector} = \begin{bmatrix} q_y - p_y \\ q_x - p_x \end{bmatrix} = \begin{bmatrix} p_y - q_y \\ q_x - p_x \end{bmatrix}$$

$\Rightarrow$  vector representing slope of line  ~~$\begin{bmatrix} q_y - p_y \\ q_x - p_x \end{bmatrix}$~~   $\begin{bmatrix} q_x - p_x \\ q_y - p_y \end{bmatrix}$

$$\Rightarrow A = p_y - q_y$$

$$B = q_x - p_x$$

$$A_x + B_y + C = 0$$

$$(p_y - q_y)x + (q_x - p_x)y + C = 0$$

$$C = p_x q_y - q_x p_y$$

$$(p_y - q_y)x + (q_x - p_x)y + p_x q_y - q_x p_y = 0$$

$$\Leftrightarrow \begin{vmatrix} p_x & p_y & 1 \\ q_x & q_y & 1 \\ x & y & 1 \end{vmatrix} = 0$$