

L06: Embeddings & RL

Deep Dive: Theory, Implementation, and Applications

Methods and Algorithms

MSc Data Science

Spring 2026

Outline

1 Problem

2 Method

3 Solution

4 Practice

5 Decision Framework

6 Summary

The Problem with One-Hot Encoding

- Vocabulary of 10,000 words → 10,000-dim sparse vectors
- No semantic similarity: “king” and “queen” equally distant from “car”
- Curse of dimensionality

Solution: Dense Embeddings

- Map words to dense vectors (50-300 dimensions)
- Similar words → similar vectors
- Learn from context (distributional hypothesis)

“You shall know a word by the company it keeps” – Firth, 1957

Word2Vec: Skip-gram

Objective: Predict context words given target word

$$P(w_{context} | w_{target}) = \frac{\exp(v_{context}^T v_{target})}{\sum_{w \in V} \exp(v_w^T v_{target})}$$

Training:

- Slide window over text corpus
- For each word, predict surrounding words
- Update embeddings via gradient descent

Skip-gram works well for rare words; CBOW better for frequent words

Skip-gram: Computational Challenge

Problem: The softmax denominator sums over **entire vocabulary**:

$$\sum_{w \in V} \exp(v_w^T v_{target}) \quad - O(|V|) \text{ per update!}$$

For $|V| = 100,000$ words, this is computationally intractable.

Solution: Negative Sampling (Mikolov et al., 2013b)

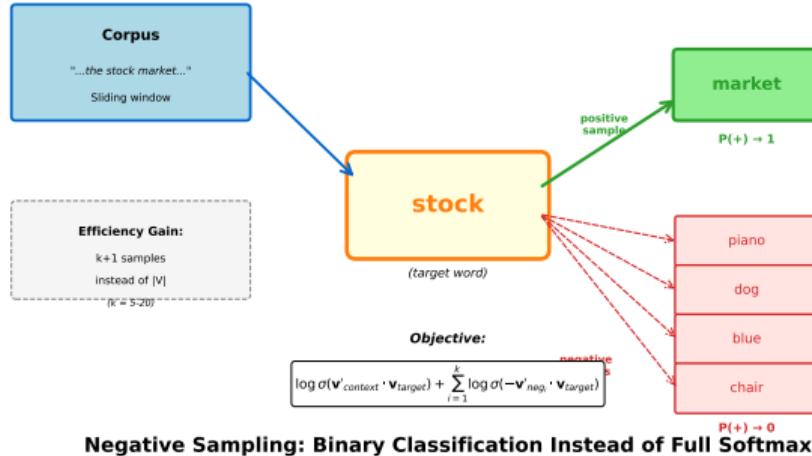
Replace full softmax with binary classification:

$$\log \sigma(v'_{w_O}^T v_{w_I}) + \sum_{i=1}^k \mathbb{E}_{w_i \sim P_n} [\log \sigma(-v'_{w_i}^T v_{w_I})]$$

- Positive pair: (target, true context) \rightarrow predict 1
- k negative pairs: (target, random word) \rightarrow predict 0
- Reduces $O(|V|)$ to $O(k)$ where $k = 5-20$

Negative sampling: the key innovation that made Word2Vec practical

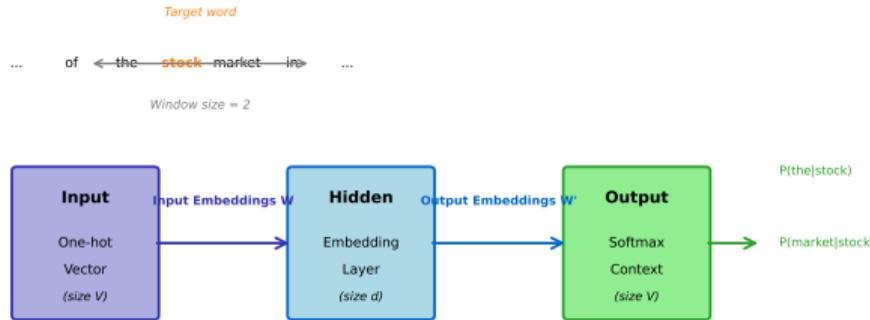
Negative Sampling Illustrated



Negative Sampling: Binary Classification Instead of Full Softmax

Binary classification: distinguish true context words from random “noise” words

Skip-gram Architecture



Skip-gram Architecture: Predict Context from Target

Two embedding matrices: input W (word vectors) and output W' (context vectors)

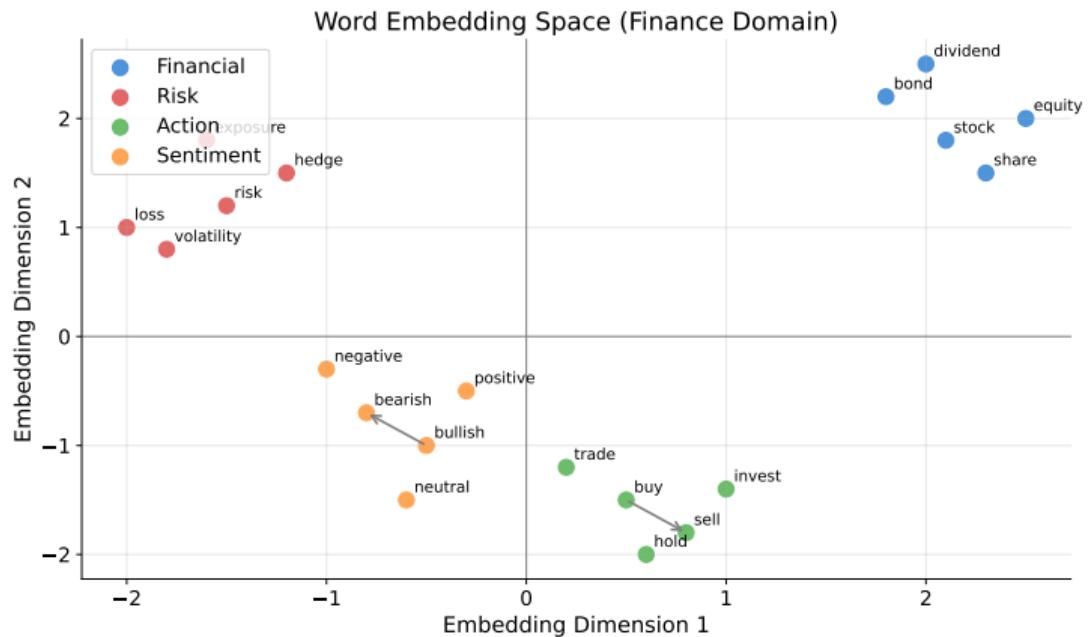
Skip-Gram with Negative Sampling: Algorithm

Require: corpus, embedding dim d , negatives k , window size, epochs

```
1: Initialize  $W, W' \in \mathbb{R}^{|V| \times d}$  randomly
2: for each epoch do
3:   for each word  $w_t$  in corpus do
4:     for each context word  $w_c$  within window do
5:       Positive: update  $(w_t, w_c)$  to increase  $\sigma(v_{w_t}^\top v'_{w_c})$ 
6:       for  $i = 1, \dots, k$  do
7:         { $k$  negative samples}
8:         Sample  $w_n \sim P_n(w) \propto f(w)^{3/4}$ 
9:         Negative: update  $(w_t, w_n)$  to decrease  $\sigma(v_{w_t}^\top v'_{w_n})$ 
10:        end for
11:      end for
12:    end for
13:  return  $W$  (word embeddings)
```

Mikolov et al. (2013). Distributed representations of words and phrases. NeurIPS, 3111–3119.

Word Embedding Space



Finance terms cluster by semantic category in embedding space

Famous Example:

$$\vec{king} - \vec{man} + \vec{woman} \approx \vec{queen}$$

Finance Examples:

- $\vec{stock} - \vec{equity} + \vec{debt} \approx \vec{bond}$
- $\vec{CEO} - \vec{company} + \vec{country} \approx \vec{president}$

How it works:

- Vector arithmetic in embedding space
- Relationships encoded as directions

Embeddings capture relational structure, not just similarity

Known Issues:

- Success rates typically 40–70%, not near 100% (Levy & Goldberg, 2014)
- Evaluation methodology inflates accuracy (nearest-neighbor dominance)
- Finance-domain analogies ($\vec{stock} - \vec{equity} + \vec{debt} \approx \vec{bond}$) not empirically validated

Bias in Embeddings:

- Embeddings encode societal biases from training data (Bolukbasi et al., 2016)
- Example: man:programmer :: woman:homemaker
- **Finance concern:** Biased embeddings in credit scoring or hiring tools

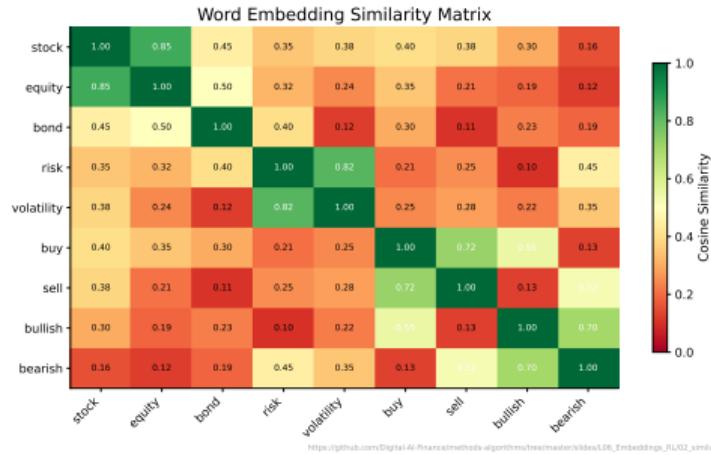
Critical thinking: embeddings capture statistical patterns, including harmful ones

Similarity Measures

Cosine Similarity:

$$\text{sim}(u, v) = \frac{u \cdot v}{\|u\| \cdot \|v\|} = \cos(\theta)$$

- Range: $[-1, 1]$; 1=same direction, 0=orthogonal, -1=opposite



Cosine similarity ignores magnitude, focuses on direction

Popular Options:

- **Word2Vec**: Google, 300-dim, 3M words
- **GloVe**: Stanford, trained on Wikipedia + Common Crawl
- **FastText**: Facebook, handles subwords (OOV robust)

Domain-Specific:

- **FinBERT**: BERT further pre-trained on financial corpora (Araci, 2019)
- BioBERT: Biomedical domain

Fine-tuning pre-trained embeddings usually outperforms training from scratch

Static Embeddings (Word2Vec, GloVe, FastText):

- ONE fixed vector per word, regardless of context
- “bank” in “river bank” = “bank” in “bank account”
- Fast, simple, good baseline

Contextual Embeddings (BERT, GPT, FinBERT):

- DIFFERENT vector per occurrence based on surrounding context
- “bank” gets different representations in different sentences
- State-of-the-art for most NLP tasks

Key Insight: Contextual models solve polysemy (multiple word senses)

Static: one meaning per word. Contextual: meaning depends on context.

Applications:

- **Sentiment Analysis:** News → embedding → positive/negative
- **Document Similarity:** Find similar SEC filings
- **Named Entity Recognition:** Extract company names
- **Event Detection:** Identify earnings announcements

Sentence Embeddings:

- Average word vectors (simple but loses word order: “bank robber” = “robber bank”)
- Doc2Vec (paragraph vectors)
- Sentence-BERT (state-of-the-art)

Aggregate word embeddings to represent documents

Finance Example: Embedding-Based Sentiment

Task: Classify “Fed signals rate hike” as positive or negative

Step 1: Average word embeddings (simplified 3-dim vectors):

$$\vec{v}_{\text{sentence}} = \frac{1}{4}(\vec{v}_{\text{Fed}} + \vec{v}_{\text{signals}} + \vec{v}_{\text{rate}} + \vec{v}_{\text{hike}}) = [0.12, -0.31, 0.45]$$

Step 2: Compare to sentiment anchors via cosine similarity:

- $\text{sim}(\vec{v}_{\text{sentence}}, \vec{v}_{\text{positive}}) = 0.23$
- $\text{sim}(\vec{v}_{\text{sentence}}, \vec{v}_{\text{negative}}) = 0.61$

Step 3: Classify: **Negative sentiment** (rate hikes → tighter policy)

Real-world: Use FinBERT for production sentiment (up to 87% accuracy on financial text; Araci, 2019)

Simplified example — real embeddings are 300-768 dimensions with learned sentiment structure

Part 2: Reinforcement Learning Framework

Key Components:

- **Agent**: Learner/decision-maker
- **Environment**: What agent interacts with
- **State s** : Current situation
- **Action a** : What agent can do
- **Reward r** : Feedback signal

Reinforcement Learning: Agent-Environment Interaction



At each time step t :

Agent observes state, takes action, receives reward

https://github.com/Digital-AI-Finance/methods-algorithms/tree/master/slides/l06_EMBEDDINGS_RL/03_rl_loop

RL: Learning from interaction, not from labeled examples

MDP Tuple: (S, A, P, R, γ)

- S : Set of states
- A : Set of actions
- $P(s'|s, a)$: Transition probability
- $R(s, a, s')$: Reward function
- $\gamma \in [0, 1]$: Discount factor (or $\gamma \in [0, 1]$ for episodic tasks)

Markov Property:

$$P(s_{t+1}|s_t, a_t, s_{t-1}, \dots) = P(s_{t+1}|s_t, a_t)$$

Future depends only on current state, not history

Policy and Value Functions

Policy: $\pi(a|s) = P(A_t = a|S_t = s)$

- Maps states to action probabilities
- Goal: Find optimal policy π^*

Value Function:

$$V^\pi(s) = \mathbb{E}_\pi \left[\sum_{t=0}^{\infty} \gamma^t R_{t+1} | S_0 = s \right]$$

Q-Function (Action-Value):

$$Q^\pi(s, a) = \mathbb{E}_\pi \left[\sum_{t=0}^{\infty} \gamma^t R_{t+1} | S_0 = s, A_0 = a \right]$$

Q-function: expected return starting from state s , taking action a

Optimal Q-Function:

$$Q^*(s, a) = \mathbb{E} \left[R + \gamma \max_{a'} Q^*(s', a') \right]$$

Interpretation:

- Value = immediate reward + discounted future value
- Recursive definition enables dynamic programming

Optimal Policy:

$$\pi^*(s) = \arg \max_a Q^*(s, a)$$

Bellman equation: foundation of all value-based RL methods

TD(0) Update Rule — learn from each transition:

$$V(s) \leftarrow V(s) + \alpha [r + \gamma V(s') - V(s)]$$

TD Error: $\delta_t = r + \gamma V(s') - V(s)$ (surprise signal)

- **vs Monte Carlo:** MC waits for episode end; TD updates every step
- **vs Dynamic Programming:** DP requires model $P(s'|s, a)$; TD is model-free
- **Q-learning:** TD applied to Q-function with max over actions

TD learning: the theoretical foundation connecting DP, MC, and Q-learning (Sutton, 1988)

Update Rule:

$$Q(s, a) \leftarrow Q(s, a) + \alpha \left[r + \gamma \max_{a'} Q(s', a') - Q(s, a) \right]$$

Algorithm:

1. Initialize $Q(s, a)$ arbitrarily
2. For each episode:
 - Observe state s
 - Choose action a (ϵ -greedy)
 - Execute a , observe r, s'
 - Update $Q(s, a)$

Q-learning is off-policy: converges to Q^* given sufficient exploration and decaying α (Watkins & Dayan, 1992)

Q-Learning: Worked Example

Trading scenario: State $s_1 = [\text{RSI}=25, \text{position}=\text{none}]$

Current Q-values: $Q(s_1, \text{buy}) = 3.2, Q(s_1, \text{hold}) = 1.0$

Agent takes action **buy**, observes:

- Reward $r = -0.5$ (transaction cost)
- New state $s_2 = [\text{RSI}=35, \text{position}=\text{long}]$
- Best future: $\max_{a'} Q(s_2, a') = 4.0$

Update ($\alpha = 0.1, \gamma = 0.9$):

$$\underbrace{r + \gamma \max_{a'} Q(s_2, a')}_{\text{TD target}} - \underbrace{Q(s_1, \text{buy})}_{\text{current}} = -0.5 + 0.9 \times 4.0 - 3.2 = -0.1$$

$$Q(s_1, \text{buy}) \leftarrow 3.2 + 0.1 \times (-0.1) = \mathbf{3.19}$$

Each update moves Q toward the “better” estimate: immediate reward + discounted future

Q-Learning Algorithm: Pseudocode

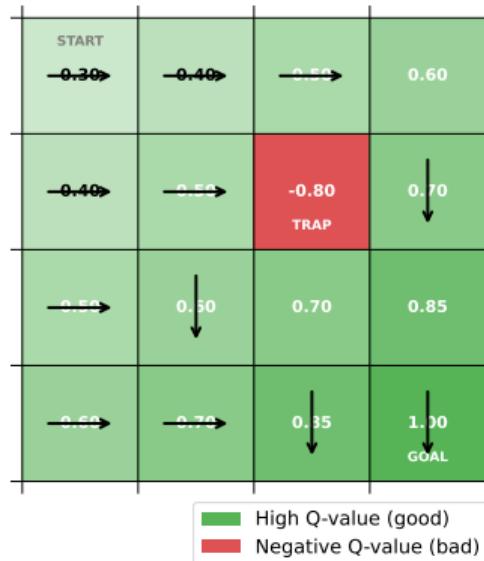
Require: environment, α , γ , ϵ , episodes

```
1: Initialize  $Q(s, a) \leftarrow 0$  for all  $s \in \mathcal{S}$ ,  $a \in \mathcal{A}$ 
2: for episode = 1, ..., episodes do
3:    $s \leftarrow$  initial state
4:   while  $s$  is not terminal do
5:      $a \leftarrow \begin{cases} \text{random } a \in \mathcal{A} & \text{with prob. } \epsilon \\ \arg \max_{a'} Q(s, a') & \text{otherwise} \end{cases}$   $\{\epsilon\text{-greedy}\}$ 
6:     Take action  $a$ , observe reward  $r$  and next state  $s'$ 
7:      $Q(s, a) \leftarrow Q(s, a) + \alpha[r + \gamma \max_{a'} Q(s', a') - Q(s, a)]$ 
8:      $s \leftarrow s'$ 
9:   end while
10: end for
11: return  $Q$ 
```

Key: The $\max_{a'}$ makes Q-learning **off-policy** — it learns the optimal policy regardless of the exploration strategy used.

Watkins & Dayan (1992). Q-learning. Machine Learning, 8(3-4), 279–292.

Q-Learning: Grid World with Learned Q-Values



https://github.com/Digital-AI-Finance/methods-algorithms/tree/master/slides/l06_EMBEDDINGS_RL/04_q_learning_grid

Arrows show policy; colors show Q-values (green=high, red=negative)

The Dilemma:

- **Exploit:** Choose best known action (greedy)
- **Explore:** Try new actions (discover better options)

ϵ -Greedy Strategy:

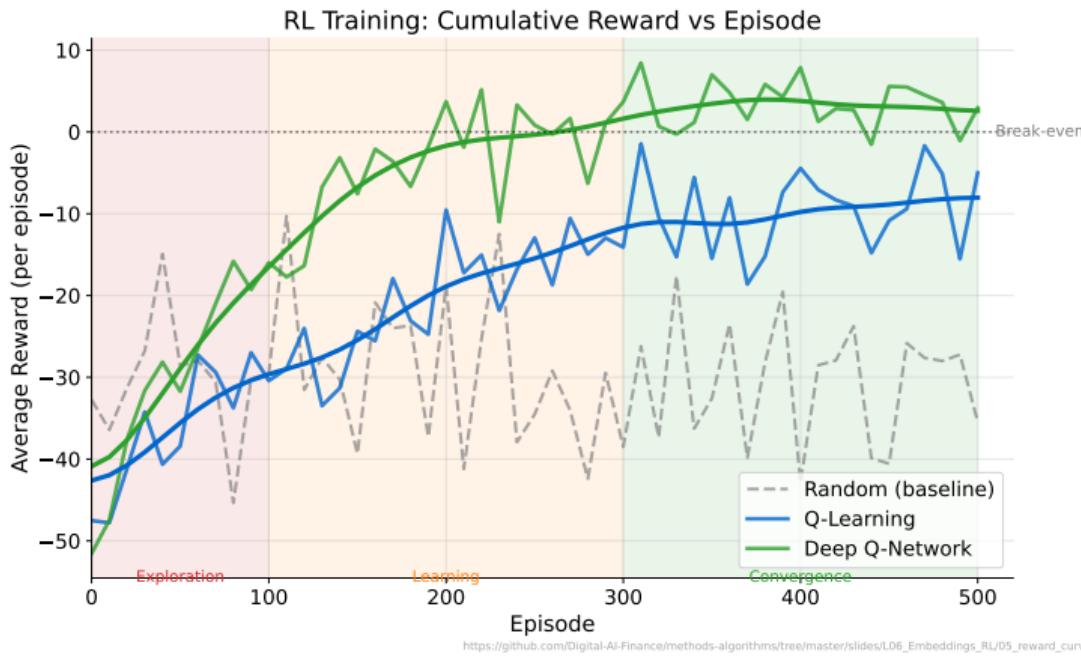
$$a = \begin{cases} \arg \max_a Q(s, a) & \text{with probability } 1 - \epsilon \\ \text{random action} & \text{with probability } \epsilon \end{cases}$$

Decay Schedule:

- Start with high ϵ (explore more)
- Decay ϵ over time (exploit more)

Balance: too much exploration wastes time; too little misses optima

Learning Curves



Reward improves as agent learns; DQN often outperforms tabular Q-learning

Part 3: RL for Trading

Formulation:

- **State:** Price history, portfolio, technical indicators
- **Action:** Buy, sell, hold (+ position size)
- **Reward:** Profit/loss, risk-adjusted return

Challenges:

- Non-stationary environment
- High noise, low signal-to-noise ratio
- Transaction costs
- Partial observability

RL for trading is active research area; not solved problem

Reward with transaction costs:

$$r_t = R_t^{\text{portfolio}} - c \cdot |\Delta w_t|$$

where $R_t^{\text{portfolio}}$ = portfolio return, c = transaction cost rate, Δw_t = position change

Common State Features:

- Price returns (1-day, 5-day, 20-day)
- Technical indicators: RSI, MACD, Bollinger width
- Current position and unrealized P&L

Alternative Rewards:

- Sharpe ratio: $r_t = \frac{\bar{R}_t}{\sigma_{R_t}}$ (risk-adjusted, but non-stationary)
- Log return: $r_t = \log(1 + R_t)$ (additive over time)

Reward design is THE most critical decision in RL for trading

Critical Challenge: RL agents overfit to historical data

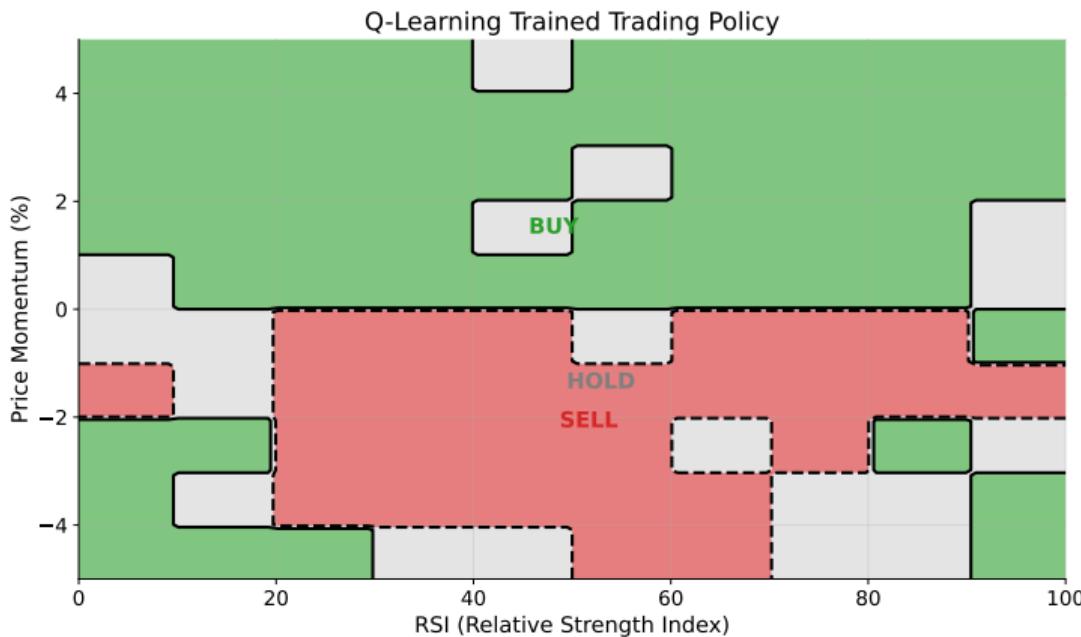
Walk-Forward Validation:

1. Train on period $[t_0, t_1]$, test on $[t_1, t_2]$
2. Roll forward: train on $[t_1, t_2]$, test on $[t_2, t_3]$
3. Report average out-of-sample performance

Honest Evaluation:

- Compare to buy-and-hold benchmark (most RL strategies fail to beat after costs)
- Include realistic transaction costs (0.1–0.5% per trade)
- Test across multiple market regimes (bull, bear, sideways)

If your RL agent beats buy-and-hold after costs, you likely have a bug — verify carefully



https://github.com/Digital-AI-Finance/methods-algorithms/tree/master/slides/L06_EMBEDDINGS_RL/06_policy_viz

Q-learning trained policy: agent discovers buy/sell/hold regions from reward signal

Deep Q-Networks (DQN)

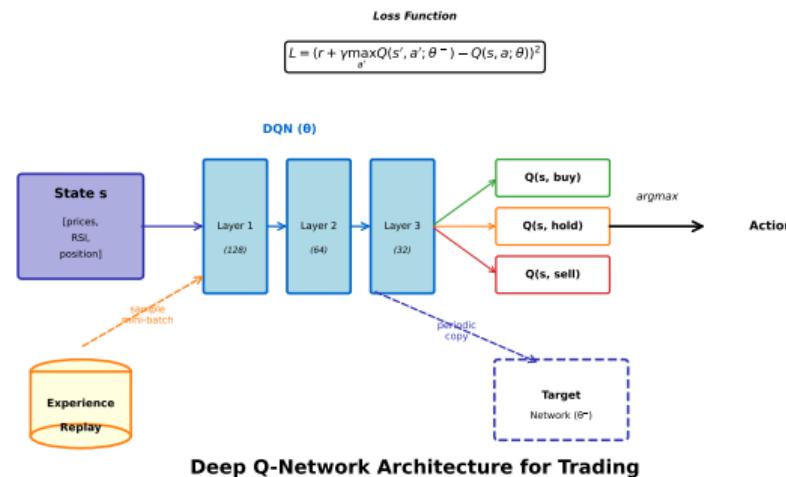
Idea: Neural network approximates Q-function: $Q(s, a; \theta) \approx Q^*(s, a)$

Loss Function:

$$L(\theta) = \mathbb{E} \left[\left(r + \gamma \max_{a'} Q(s', a'; \theta^-) - Q(s, a; \theta) \right)^2 \right]$$

Key Innovations:

- **Experience Replay:** Store (s, a, r, s') , sample random mini-batches (breaks temporal correlation)
- **Target Network θ^- :** Separate, slowly-updated copy for stability



DQN: Atari-level play from raw pixels (Mnih et al., 2015); loss is mean squared TD error

Policy Gradient Theorem (Sutton et al., 2000):

$$\nabla_{\theta} J(\theta) = \mathbb{E}_{\pi_{\theta}} [\nabla_{\theta} \log \pi_{\theta}(a|s) \cdot A^{\pi_{\theta}}(s, a)]$$

where $A^{\pi}(s, a) = Q^{\pi}(s, a) - V^{\pi}(s)$ is the **advantage function**

- **REINFORCE**: Uses episode returns G_t as A ; high variance
- **Actor-Critic**: Actor (policy π_{θ}) + Critic (learns V^{ϕ}); lower variance
- **PPO**: Clips policy ratio to prevent large updates; widely used

Policy gradient handles continuous actions; advantage reduces variance vs raw returns

Embedding Uncertainty:

- Bootstrap cosine similarity: resample corpus, retrain, compute CI
- Permutation test: shuffle word-context pairs, check if similarity is significant

RL Uncertainty:

- Q-value confidence: run N independent training runs, report mean \pm std
- Off-policy evaluation: importance sampling to estimate policy value from logged data

$$\hat{V}(\pi) = \frac{1}{n} \sum_{i=1}^n \prod_{t=0}^T \frac{\pi(a_t|s_t)}{\beta(a_t|s_t)} \cdot G_i$$

Always report uncertainty — a single training run is not evidence of a good policy

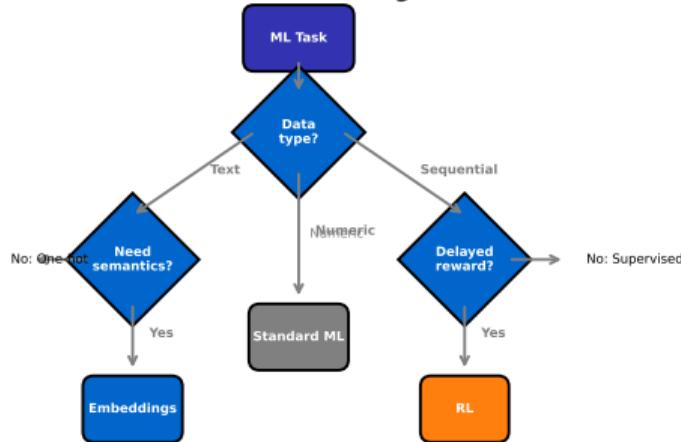
Open the Colab Notebook

- Exercise 1: Explore word embeddings with Word2Vec
- Exercise 2: Implement basic Q-learning
- Exercise 3: Apply RL to a simple trading environment

Link: https://colab.research.google.com/github/Digital-AI-Finance/methods-algorithms/blob/master/notebooks/L06_embeddings_rl.ipynb

Part 4: When to Use What

When to Use Embeddings vs RL



Embeddings: Text, categorical -> dense vectors (Word2Vec, BERT)

RL: Sequential decisions with delayed rewards (trading, games)

https://github.com/Digital-AI-Finance/methods-algorithms/tree/master/slides/L06_EMBEDDINGS_RL/07_decision_flowchart

Embeddings for text/categorical; RL for sequential decisions

Comparison Table

Aspect	Embeddings	RL
Input	Text, categorical	State sequence
Output	Dense vectors	Actions/policy
Learning	Unsupervised/supervised	Trial and error
Signal	Context (words)	Rewards
Key challenge	Semantics	Credit assignment
Finance use	Sentiment	Trading

Both transform complex inputs into learnable representations

Part 5: Implementation

Embeddings in Python:

- `gensim.models.Word2Vec`: Train your own
- `gensim.downloader.load('glove-wiki-gigaword-100')`: Pre-trained
- `transformers.BertModel`: BERT embeddings

RL Libraries:

- `gymnasium`: Environment interface (formerly OpenAI Gym)
- `stable-baselines3`: Pre-implemented algorithms
- `ray[rllib]`: Scalable RL

Start with pre-trained embeddings; use stable-baselines3 for RL

Embeddings:

- Start with pre-trained, fine-tune if needed
- Check domain match (general vs financial)
- Visualize with t-SNE/UMAP to verify quality

RL:

- Start simple (tabular Q-learning before DQN)
- Reward shaping is crucial (sparse rewards are hard)
- Normalize observations
- Use established environments first (Gym, FinRL)

Both domains: start simple, iterate, validate thoroughly

Embeddings:

- Dense vector representations of text/categories
- Capture semantic similarity
- Use pre-trained (Word2Vec, GloVe, BERT)

Reinforcement Learning:

- Agent learns from environment interaction
- Q-learning: value-based, tabular or deep (DQN)
- Applications: trading, portfolio optimization

Key Takeaway: Different tools for different problems

Course complete! Apply these methods in your capstone project

Embeddings:

- Mikolov et al. (2013). Word2Vec
- Pennington et al. (2014). GloVe
- Devlin et al. (2019). BERT
- Levy & Goldberg (2014). Linguistic Regularities in Word Embeddings
- Bolukbasi et al. (2016). Man is to Computer Programmer as Woman is to Homemaker?

Reinforcement Learning:

- Sutton & Barto (2018). RL: An Introduction (free online)
- Mnih et al. (2015). DQN (Atari)
- Schulman et al. (2017). PPO
- Watkins & Dayan (1992). Q-Learning Convergence

Finance Applications:

- Liu et al. (2021). FinRL: Deep RL for Trading
- Araci (2019). FinBERT

Sutton & Barto: the definitive RL textbook (free at incompleteideas.net)