

# Hyperbolic Learning in Action

## Deep Learning in Hyperbolic Space



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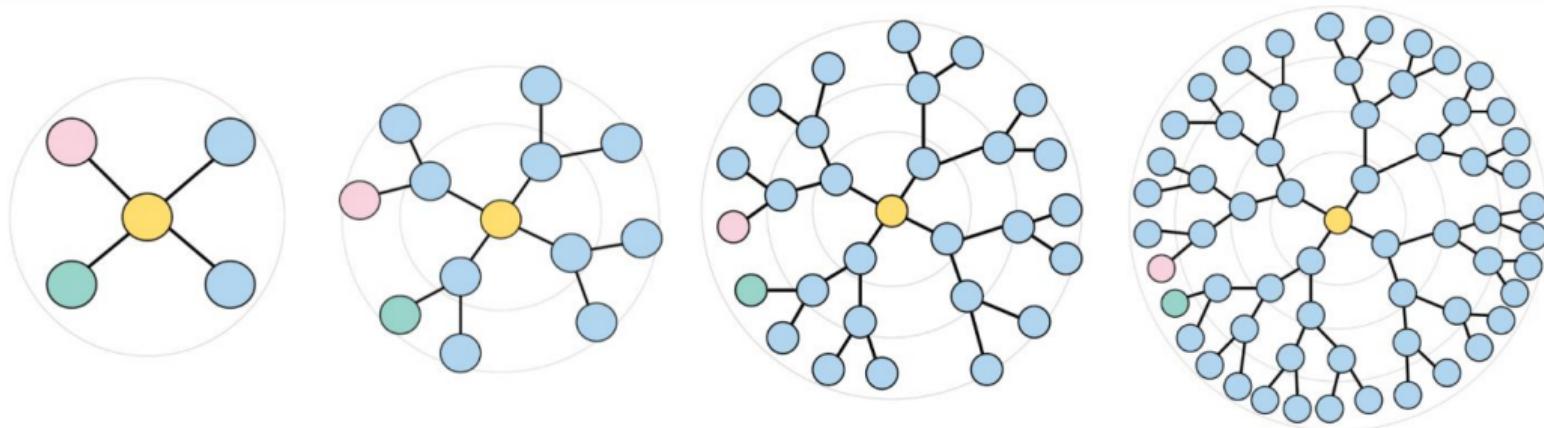
Thursday 13<sup>th</sup> February, 2025

## Embedding Hierarchies

# The trouble with embedding hierarchies

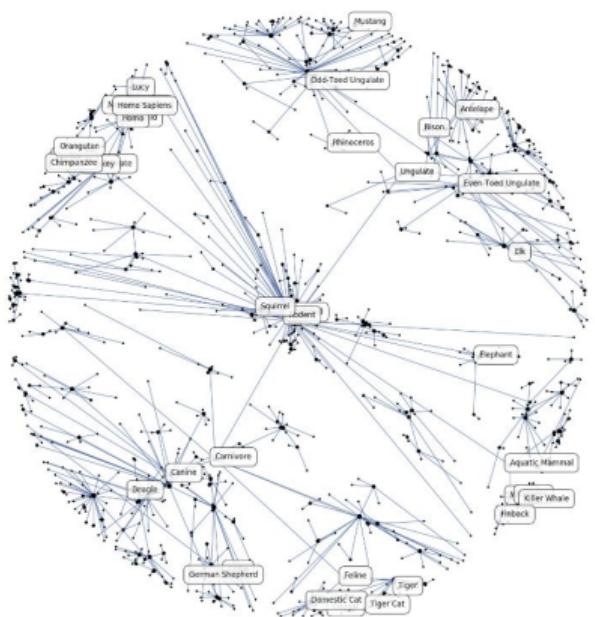
Hierarchies grow exponentially in depth, Euclidean spaces grows linearly with norm.

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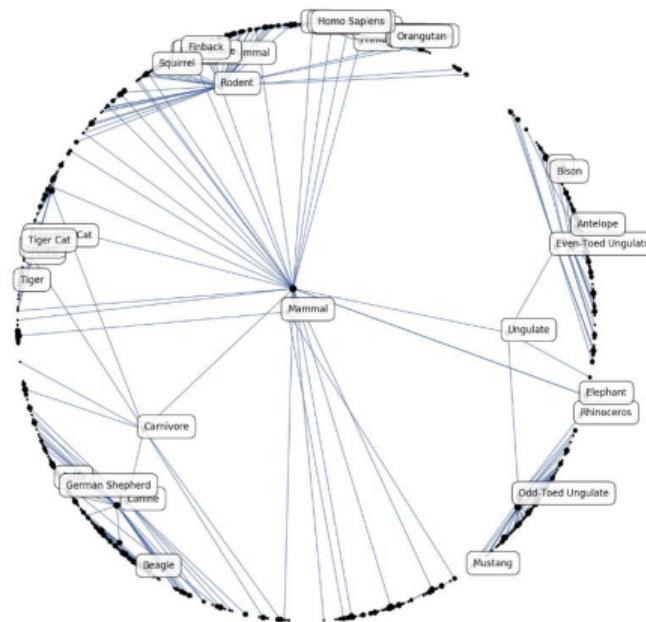


The exponential growth of distances in hyperbolic space is a direct fit with hierarchies.

## Poincaré embeddings



(a) Intermediate embedding after 20 epochs



### (b) Embedding after convergence

# Optimizing Poincaré embeddings

Nodes:

$$\mathcal{S} = \{x_i\}_{i=1}^n$$

Parent-child relations:

$$\mathcal{D} = \{(u, v)\}$$

Non-Parent-child relations:

$$\mathcal{N}(u) = \{v' \mid (u, v') \notin \mathcal{D}\} \cup \{v\}$$

# Optimizing Poincaré embeddings

Nodes:

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Parent-child relations:

$$\mathcal{D} = \{(u, v)\}$$

Non-Parent-child relations:

$$\mathcal{N}(u) = \{v' | (u, v') \notin \mathcal{D}\} \cup \{v\}$$

Hyperbolic representation of nodes:  $\Theta = \{\theta_i\}_{i=1}^n$

$$\Theta' \leftarrow \operatorname{argmin} \mathcal{L}(\Theta) \quad \text{s.t. } \forall \theta_i \in \Theta : \|\theta_i\| < 1 \quad (1)$$

Pull parent-child nodes, push others.

$$\mathcal{L}(\Theta) = \sum_{(u,v) \in \mathcal{D}} \log \frac{e^{-d(\mathbf{u}, \mathbf{v})}}{\sum_{\mathbf{v}' \in \mathcal{N}(u)} e^{-d(\mathbf{u}, \mathbf{v}')}} \quad (2)$$

$$d(\mathbf{u}, \mathbf{v}) = \operatorname{arccosh} \left( 1 + 2 \frac{\|\mathbf{u} - \mathbf{v}\|^2}{(1 - \|\mathbf{u}\|^2)(1 - \|\mathbf{v}\|^2)} \right) \quad (3)$$

## Optimizing Poincaré embeddings

$$\theta_{t+1} = \Re_{\theta_t} (-\eta_t \nabla_R \mathcal{L}(\theta_t)) \quad (4)$$

Optimize node embeddings with Riemmanian gradient descent.

$$\theta_{t+1} \leftarrow \text{proj} \left( \theta_t - \eta_t \frac{(1 - \|\theta_t\|^2)^2}{4} \nabla_E \right) \quad (5)$$

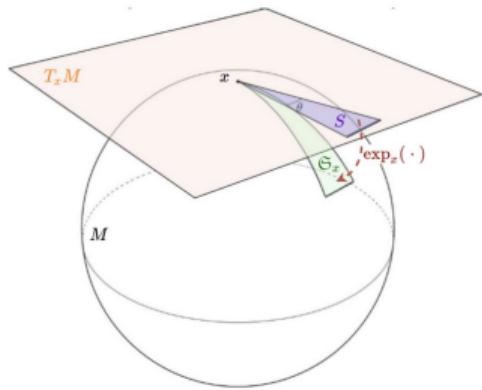
Riemmanian gradient descent = Standard gradient + scaling + projection.

# Poincaré embeddings

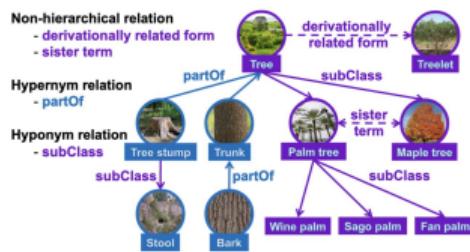
		Dimensionality					
		5	10	20	50	100	200
WORDNET Reconstruction	<b>Euclidean</b>	Rank 3542.3	2286.9	1685.9	1281.7	1187.3	1157.3
	MAP	0.024	0.059	0.087	0.140	0.162	0.168
WORDNET Link Pred.	<b>Translational</b>	Rank 205.9	179.4	95.3	92.8	92.7	91.0
	MAP	0.517	0.503	0.563	0.566	0.562	0.565
WORDNET Link Pred.	<b>Poincaré</b>	Rank 4.9	4.02	3.84	3.98	3.9	<b>3.83</b>
	MAP	0.823	0.851	0.855	0.86	0.857	<b>0.87</b>
WORDNET Link Pred.	<b>Euclidean</b>	Rank 3311.1	2199.5	952.3	351.4	190.7	81.5
	MAP	0.024	0.059	0.176	0.286	0.428	0.490
WORDNET Link Pred.	<b>Translational</b>	Rank 65.7	56.6	52.1	47.2	43.2	40.4
	MAP	0.545	0.554	0.554	0.56	0.562	0.559
WORDNET Link Pred.	<b>Poincaré</b>	Rank 5.7	<b>4.3</b>	4.9	4.6	4.6	4.6
	MAP	0.825	0.852	0.861	<b>0.863</b>	0.856	0.855

		Dimensionality							
		Reconstruction				Link Prediction			
		10	20	50	100	10	20	50	100
ASTROPH N=18,772; E=198,110	<b>Euclidean</b>	0.376	0.788	0.969	0.989	0.508	0.815	0.946	0.960
	<b>Poincaré</b>	0.703	0.897	0.982	0.990	0.671	0.860	0.977	0.988
CONDMAT N=23,133; E=93,497	<b>Euclidean</b>	0.356	0.860	0.991	0.998	0.308	0.617	0.725	0.736
	<b>Poincaré</b>	0.799	0.963	0.996	0.998	0.539	0.718	0.756	0.758
GRQC N=5,242; E=14,496	<b>Euclidean</b>	0.522	0.931	0.994	0.998	0.438	0.584	0.673	0.683
	<b>Poincaré</b>	0.990	0.999	0.999	0.999	0.660	0.691	0.695	0.697
HEPPH N=12,008; E=118,521	<b>Euclidean</b>	0.434	0.742	0.937	0.966	0.642	0.749	0.779	0.783
	<b>Poincaré</b>	0.811	0.960	0.994	0.997	0.683	0.743	0.770	0.774

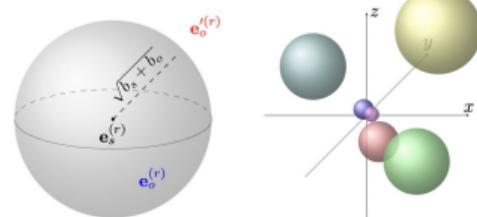
# Improving Poincaré embeddings



Hyperbolic entailment cones.

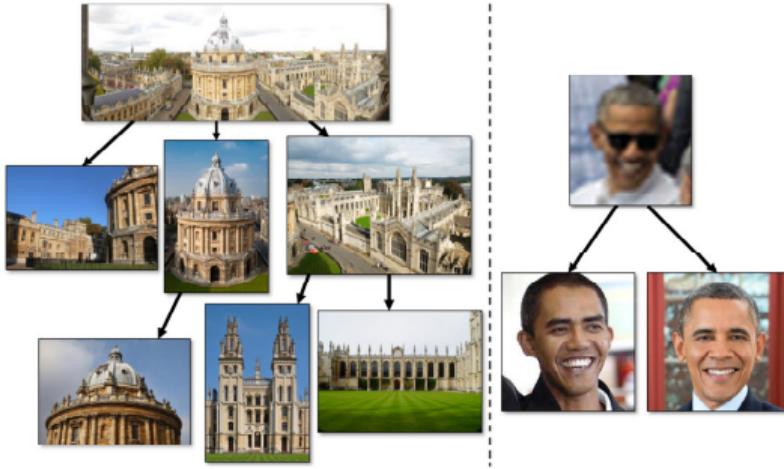


Multi-relational Poincaré embeddings.



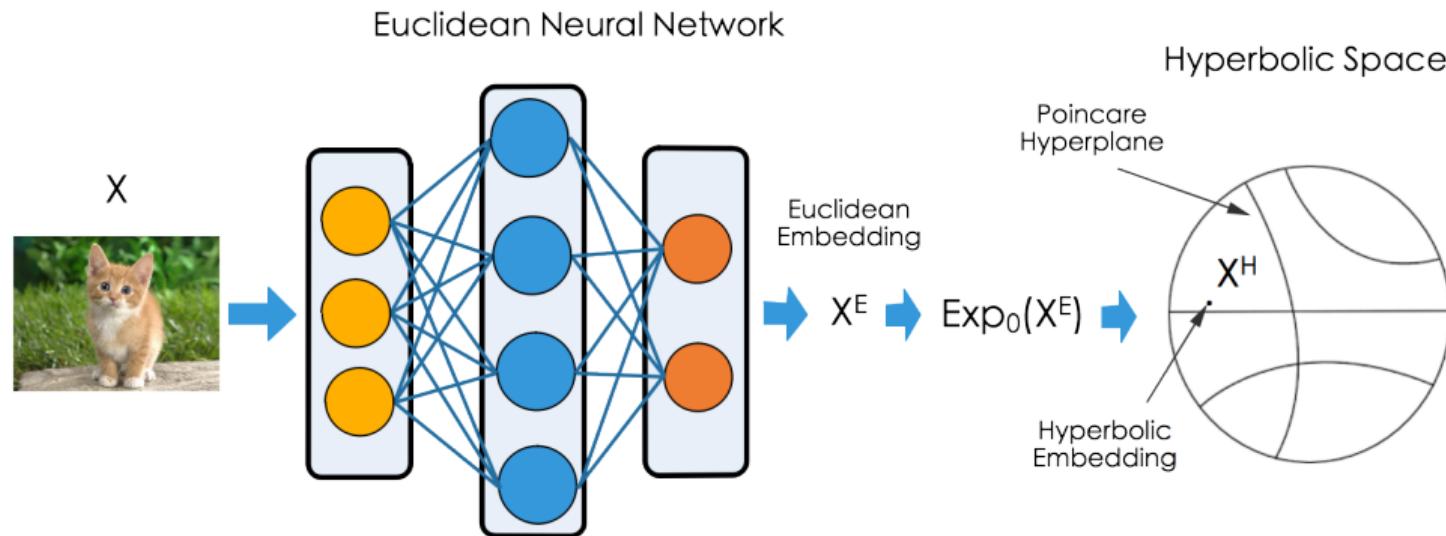
Modelling heterogeneous hierarchies.

# Hyperbolic Image Embeddings



Encoder	Dataset			
	CIFAR10	CIFAR100	CUB	MiniImageNet
Inception v3 [49]	0.25	0.23	0.23	0.21
ResNet34 [14]	0.26	0.25	0.25	0.21
VGG19 [42]	0.23	0.22	0.23	0.17

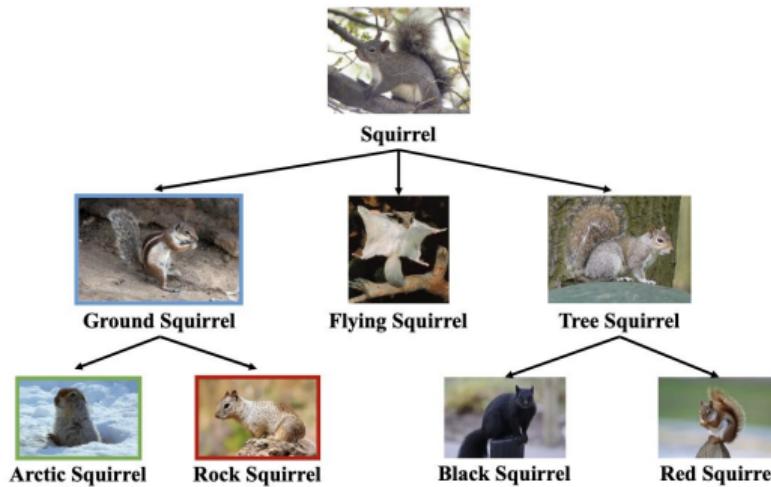
# Convolutional Networks with Hyperbolic Embeddings



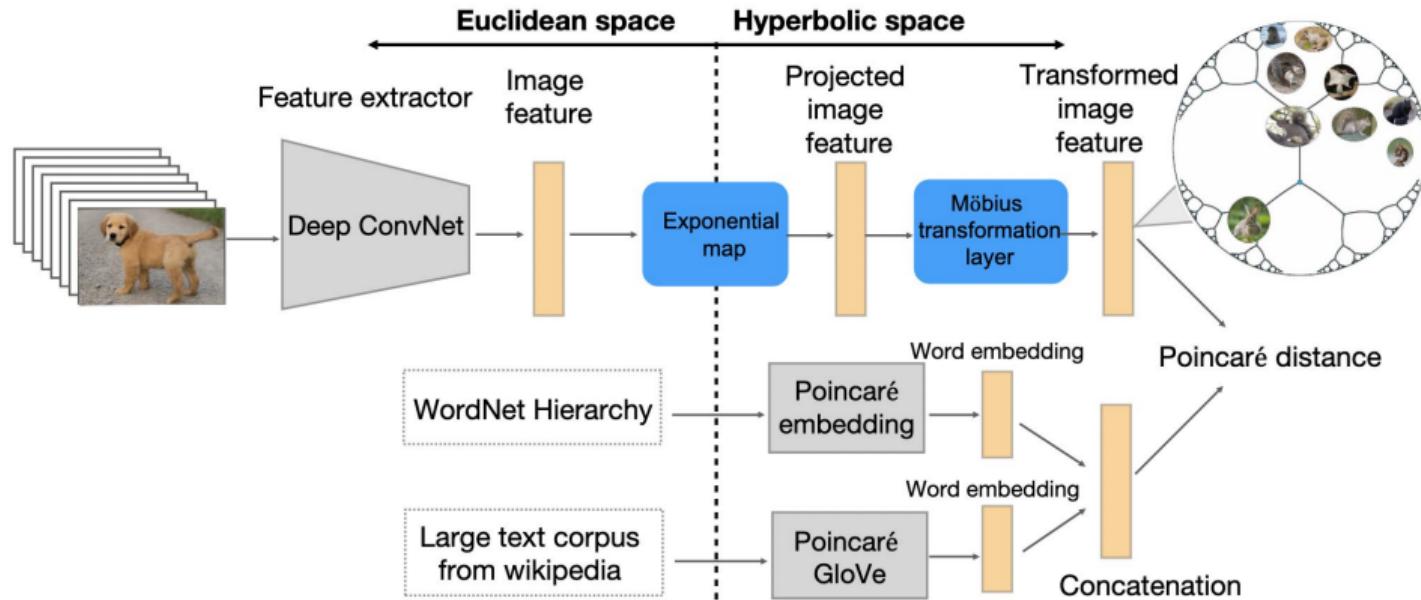
## Zero-Shot Generalization

# Hyperbolic Zero-Shot Visual Embedding Learning

If labels are hierarchical, does a hyperbolic embedding enable zero-shot generalization?



# Hyperbolic Zero-Shot Visual Embedding Learning



# Hyperbolic Zero-Shot Visual Embedding Learning

If prior knowledge is a hierarchy then use hyperbolic geometry for zero-shot learning.

Data Set	Model	Hierarchical precision@k(%)				
		1	2	5	10	20
2-hops & Their Parents	DeViSE	3.2	5.3	9.5	15.6	21.2
	DeViSE*	4.5	7.0	9.9	15.6	22.0
	ConSE	4.2	6.8	12.3	18.5	25.1
	GCNZ	9.2	15.6	27.5	36.8	44.5
	Ours	<b>16.6</b>	<b>24.3</b>	<b>43.8</b>	<b>58.6</b>	<b>70.3</b>
3-hops & Their Parents	DeViSE	1.3	2.1	3.3	4.9	7.3
	DeViSE*	1.7	2.6	4.4	6.6	9.3
	ConSE	1.9	2.6	4.4	7.2	9.7
	GCNZ	2.7	4.6	8.2	12.5	15.1
	Ours	<b>7.9</b>	<b>12.5</b>	<b>21.4</b>	<b>28.7</b>	<b>37.5</b>
All	DeViSE	0.9	1.5	2.9	4.4	6.5
	DeViSE*	1.0	1.6	2.9	4.4	6.5
	ConSE	1.5	2.4	4.2	6.5	9.7
	GCNZ	2.2	3.8	7.2	10.5	13.9
	Ours	<b>5.1</b>	<b>6.9</b>	<b>12.9</b>	<b>16.5</b>	<b>19.3</b>



DeViSE: teddy, orangutan, valley, langur, cliff

GCNZ: phalanger, **red squirrel**, kangaroo, lemur, tree wallaby

Ours: **red squirrel**, **tree squirrel\***, squirrel, kangaroo, phalanger



DeViSE: rugby ball, soccer ball, golf ball, basketball, cricket

GCNZ: **volleyball**, basketball, golf ball, punching bag, rugby ball

Ours: **volleyball**, **ball\***, basketball, rugby ball, soccer ball

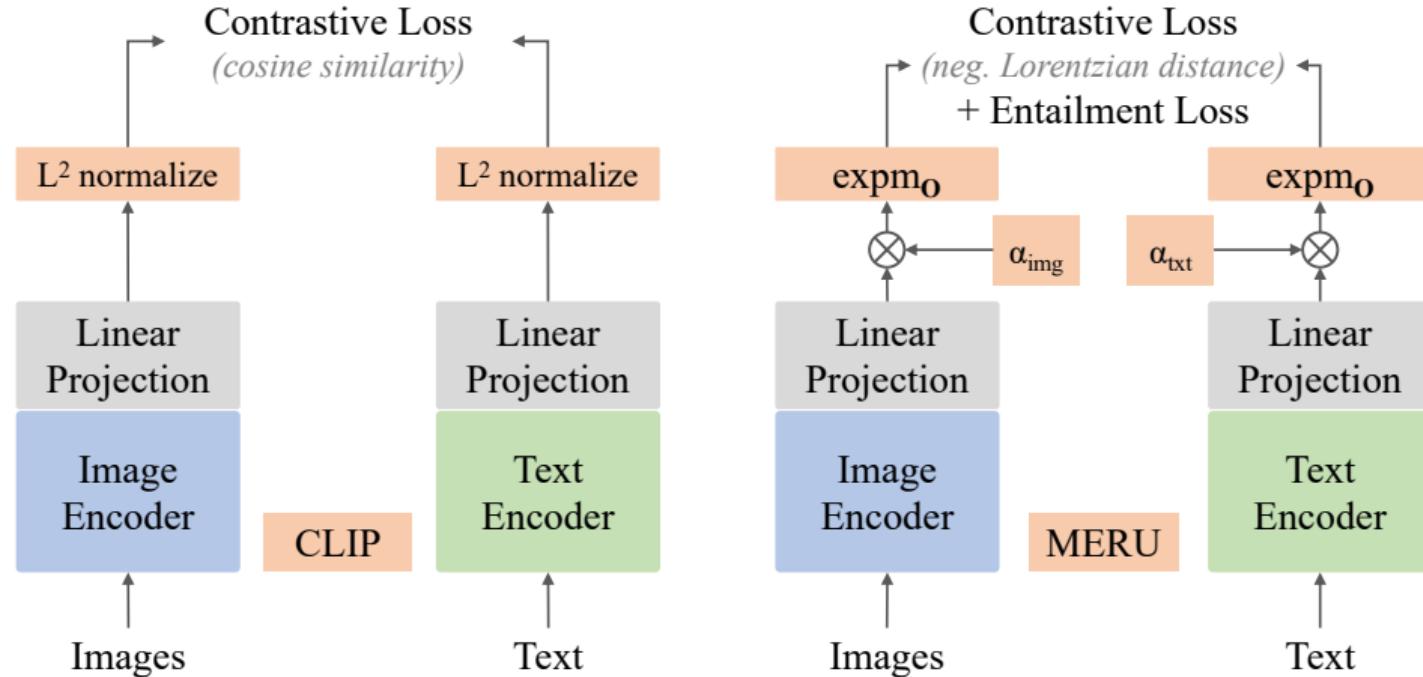


DeViSE: bullet train, freight car, school bus, police van, minibus

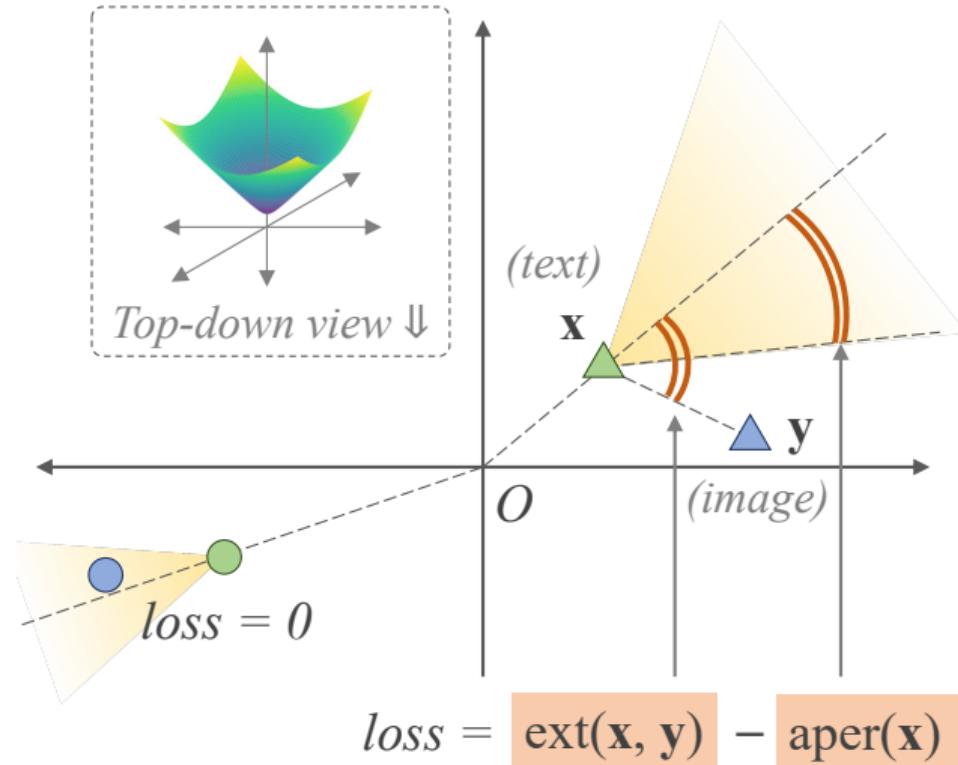
GCNZ: mail train, express, **passenger train**, cargo ship, shuttle bus

Ours: **passenger train**, **railroad train\***, bus, school bus, trolleybus

# Hyperbolic Image-Text Representations



# Entailment Cones



# MERU



MERU	CLIP
avocado toast	avocado toast
healthy breakfast	delicious
delicious	↓
homemade	↓
fresh	↓
[ROOT]	[ROOT]



MERU	CLIP
brooklyn bridge	photo of brooklyn bridge, new york
new york city	new york city
city	new york
outdoors	↓
day	↓
[ROOT]	[ROOT]



MERU	CLIP
taj mahal	taj mahal through an arch
monument	travel
architecture	inspiration
travel	↓
day	↓
[ROOT]	[ROOT]



MERU	CLIP
sydney opera house	sydney opera house
opera house	opera house
holiday	gift
day	beauty
[ROOT]	[ROOT]

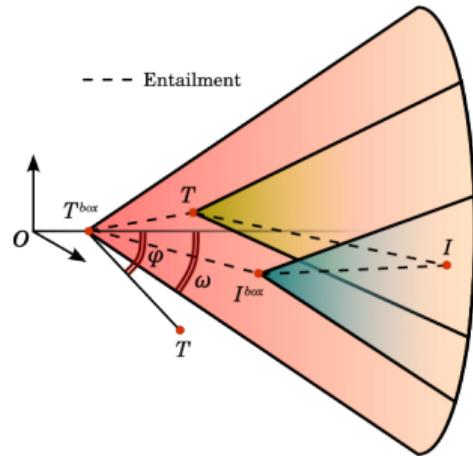
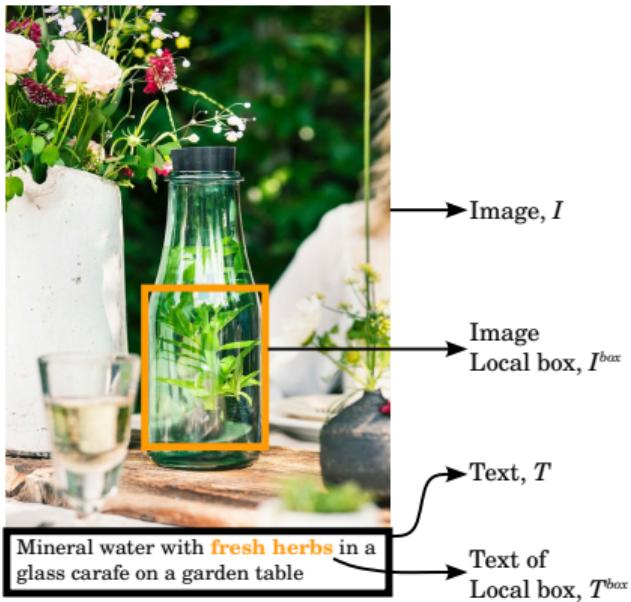
# MERU

**Table 2. Zero-shot image classification.** We train MERU and CLIP models with varying parameter counts and transfer them *zero-shot* to 20 image classification datasets. Best performance in every column is highlighted in green. Hyperbolic representations from MERU match or outperform CLIP on 13 out of the first 16 datasets. On the last four datasets (gray columns), both MERU and CLIP have *near-random* performance, as concepts in these datasets are not adequately covered in the training data.

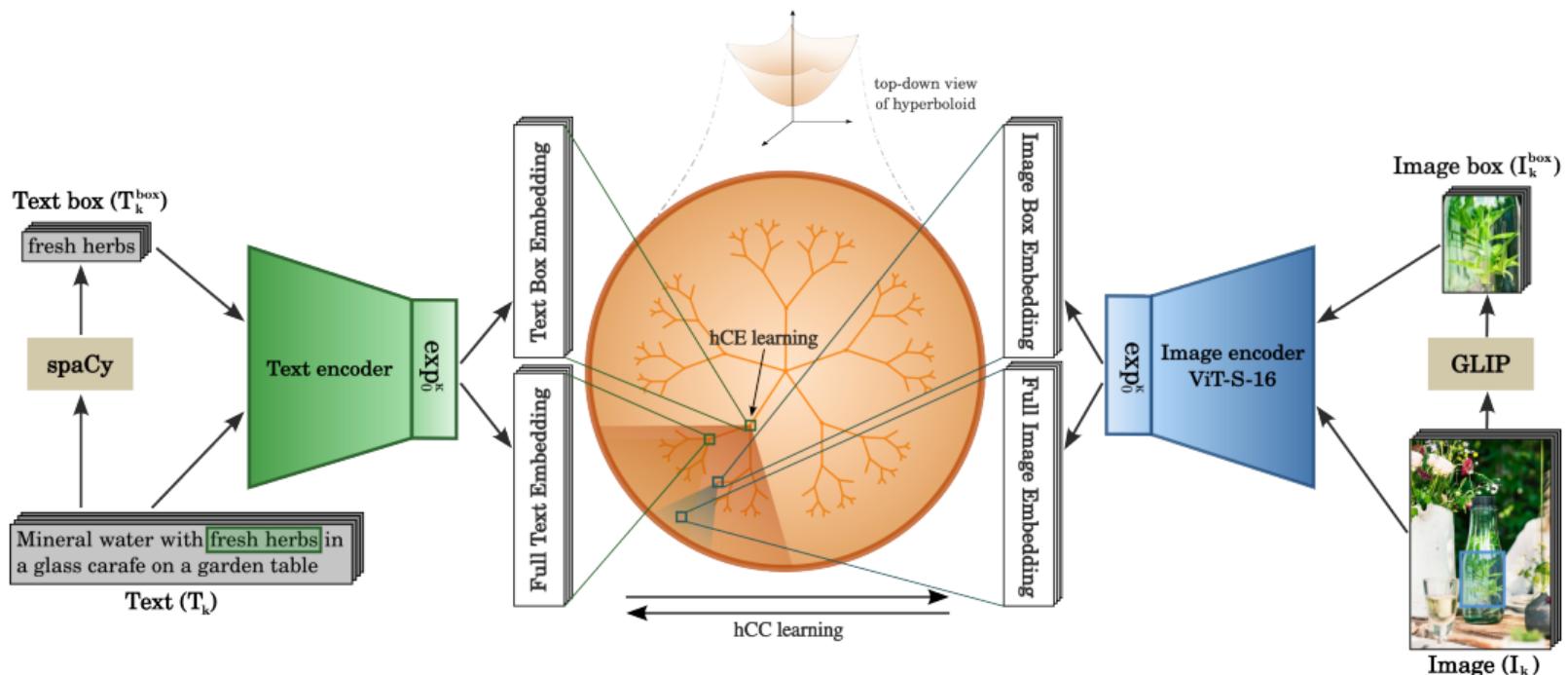
		ImageNet	Food-101	CIFAR-10	CIFAR-100	CUB	SUN397	Cars	Aircraft	DTD	Pets	Caltech-101	Flowers	STL-10	EuroSAT	RESISC45	Country211	MNIST	CLEVR	PCAM	SST2
ViT S/16	CLIP	34.3	74.5	<b>60.1</b>	24.4	<b>33.8</b>	27.5	<b>11.3</b>	<b>1.4</b>	15.0	<b>73.7</b>	63.9	47.0	88.2	18.6	31.4	<b>5.2</b>	10.0	19.4	50.2	50.1
	MERU	<b>34.4</b>	<b>75.6</b>	52.0	<b>24.7</b>	33.7	<b>28.0</b>	11.1	1.3	<b>16.2</b>	72.3	<b>64.1</b>	<b>49.2</b>	<b>91.1</b>	<b>30.4</b>	<b>32.0</b>	4.8	7.5	14.5	51.0	50.0
ViT B/16	CLIP	<b>37.9</b>	<b>78.9</b>	65.5	<b>33.4</b>	33.3	29.8	<b>14.4</b>	1.4	17.0	77.9	<b>68.5</b>	50.9	92.2	25.6	31.0	<b>5.8</b>	10.4	14.3	54.1	51.5
	MERU	37.5	78.8	<b>67.7</b>	32.7	<b>34.8</b>	<b>30.9</b>	14.0	<b>1.7</b>	<b>17.2</b>	<b>79.3</b>	<b>68.5</b>	<b>52.1</b>	<b>92.5</b>	<b>30.2</b>	<b>34.5</b>	5.6	13.0	13.5	49.8	49.9
ViT L/16	CLIP	38.4	80.3	<b>72.0</b>	<b>36.4</b>	36.3	32.0	<b>18.0</b>	1.1	16.5	78.8	<b>68.3</b>	48.6	<b>93.7</b>	26.7	35.4	6.1	14.8	13.6	51.2	51.1
	MERU	<b>38.8</b>	<b>80.6</b>	68.7	35.5	<b>37.2</b>	<b>33.0</b>	16.6	<b>2.2</b>	<b>17.2</b>	<b>80.0</b>	67.5	<b>52.1</b>	<b>93.7</b>	<b>28.1</b>	<b>36.5</b>	<b>6.2</b>	11.8	13.1	52.7	49.3

# Compositional Entailment Learning

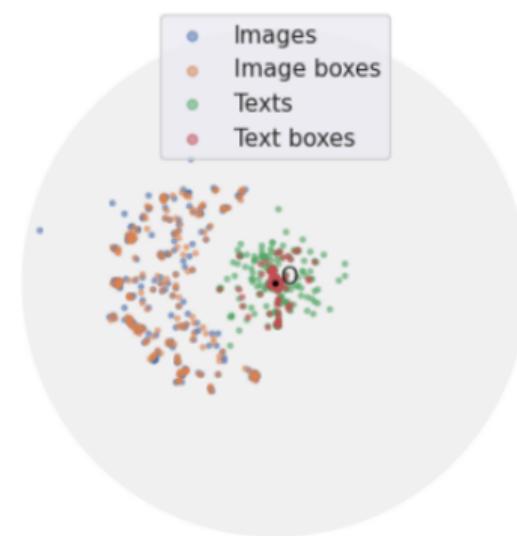
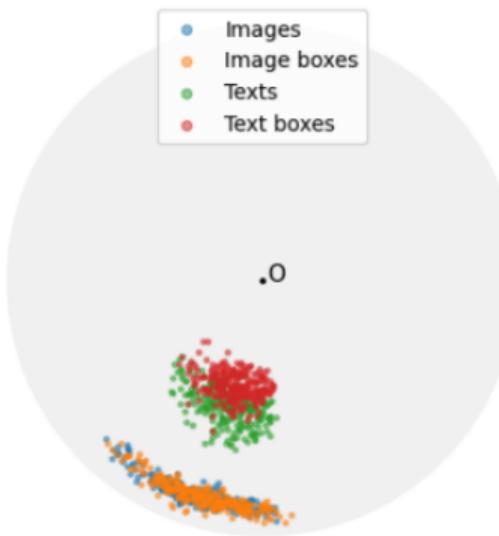
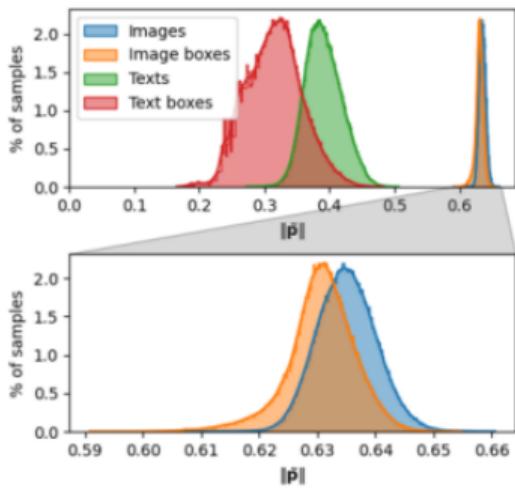
An image is not only described by a sentence but is itself a composition of multiple object boxes, each with their own textual description



# Compositional Entailment Learning

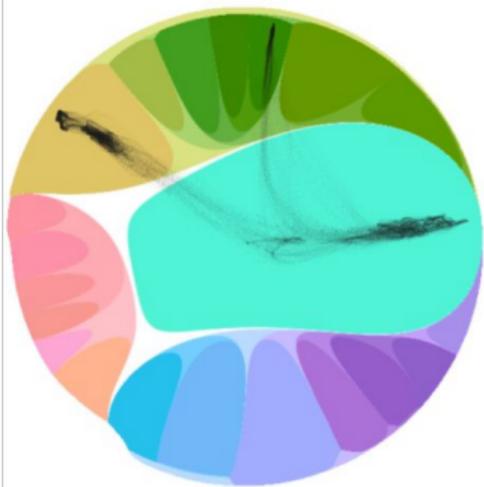


# Compositional Entailment Learning

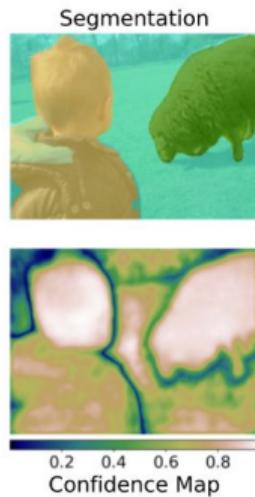


## Robustness and Uncertainty

# Hyperbolic Segmentation

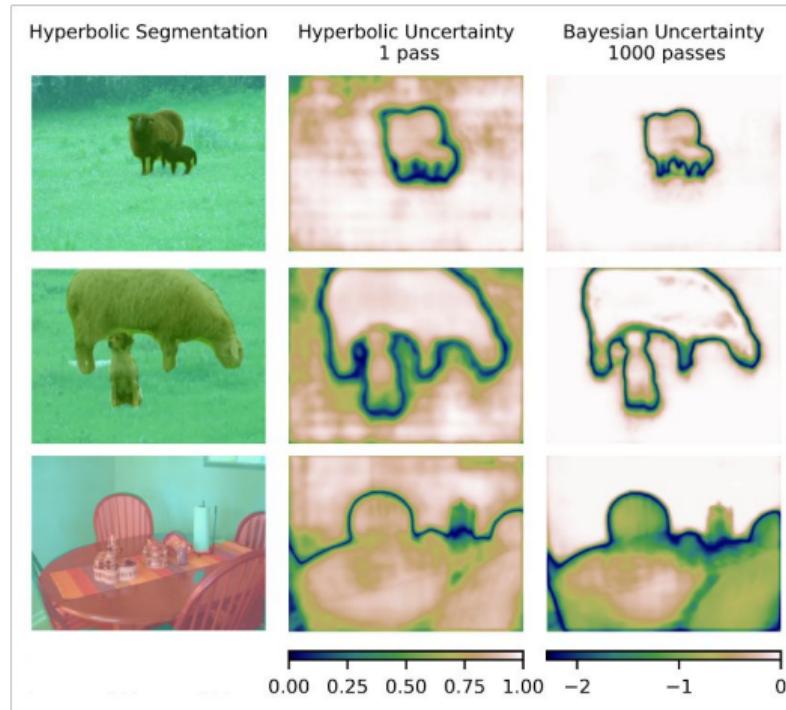


(a) Prediction uncertainty for free

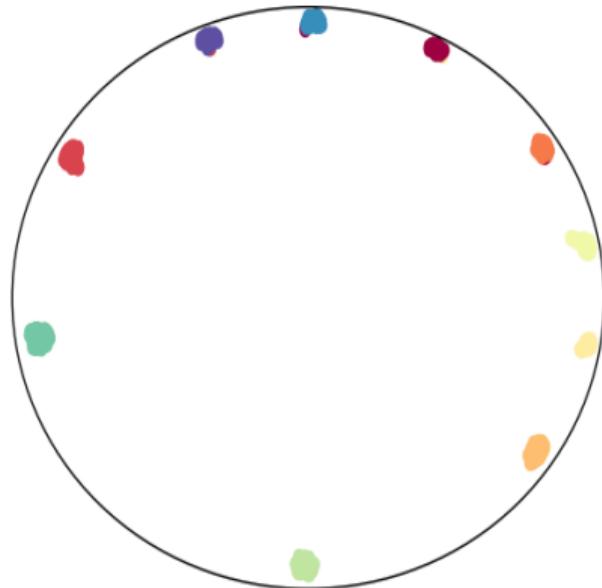


(b) Boundary information for free

# Uncertainty and boundary information for free

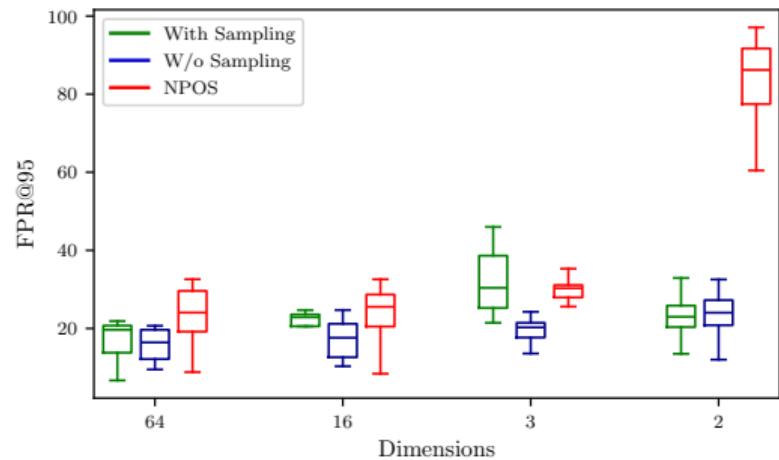
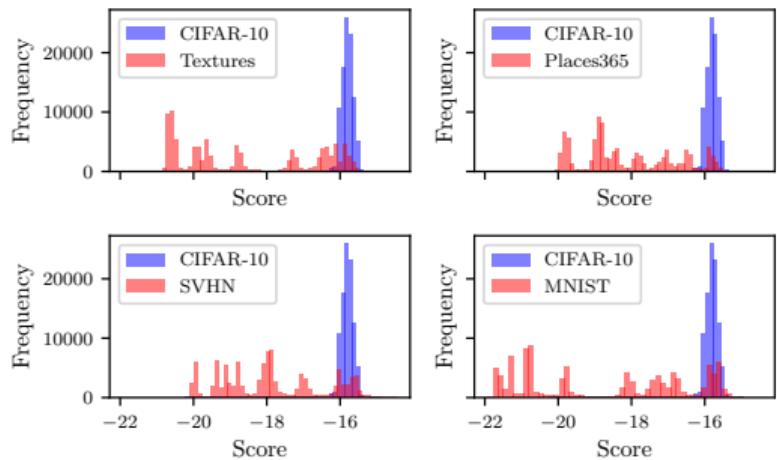


## How to exploit robustness properties?



- ▶ Learn in-distribution representations promoting low variations and high separation.
- ▶ Hyperbolic geometry offers *more space* than Euclidean!

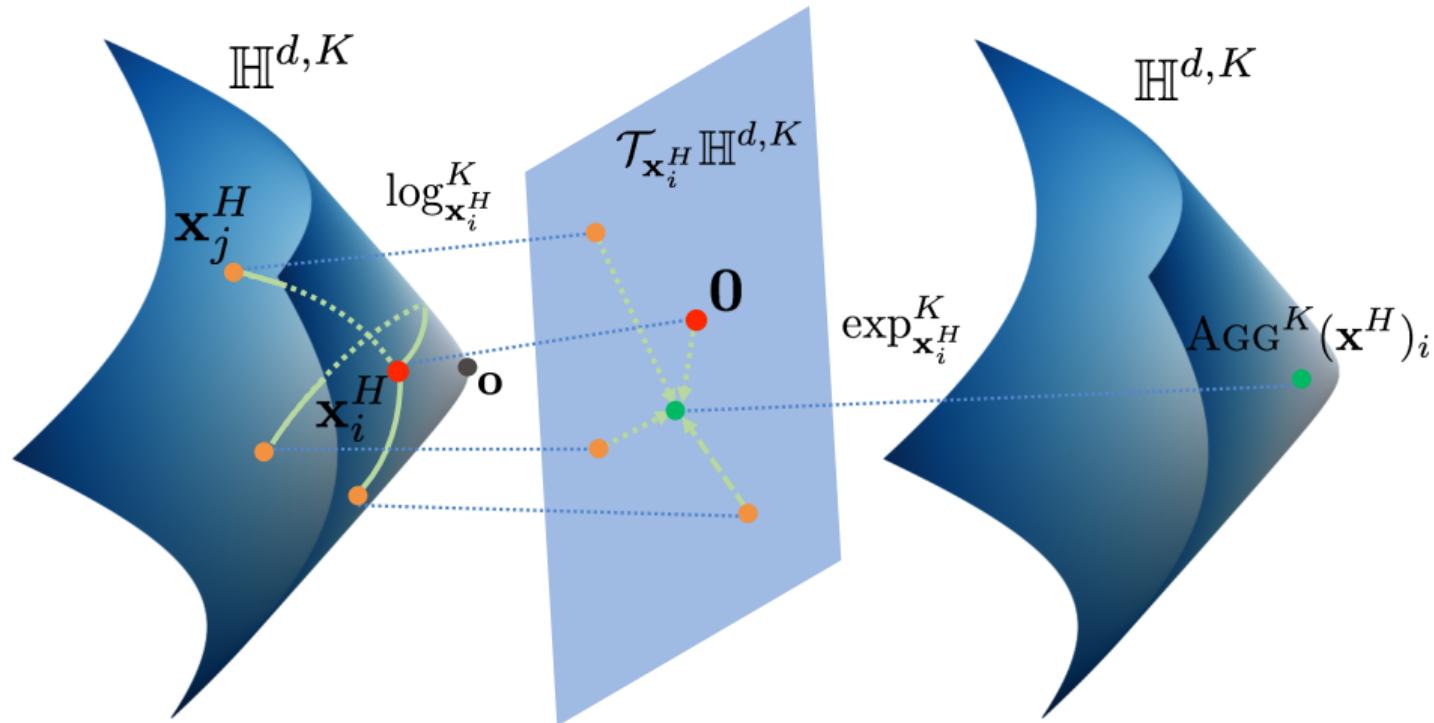
# Hyperbolic Outlier Detection



## Fully Hyperbolic Networks

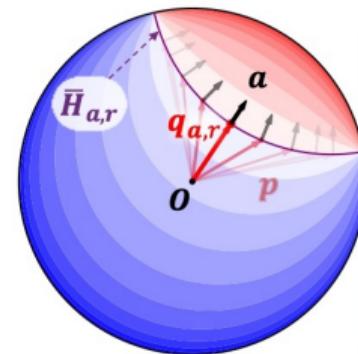
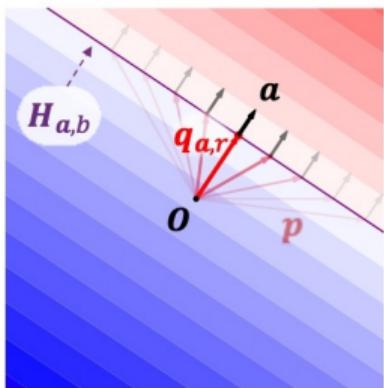
# Extend Hyperbolic Space for the entire network

Mapping back and forth between hyperbolic and Euclidean manifolds.



# Move Everything to Hyperbolic Space

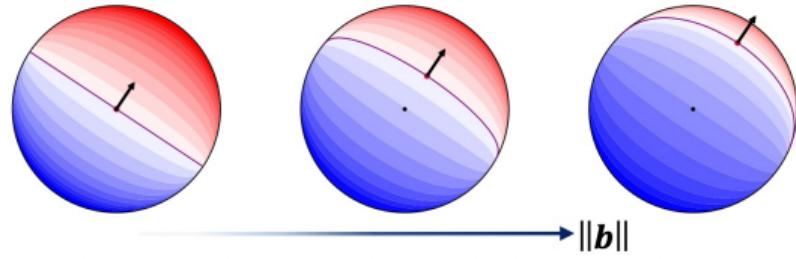
The current methods depend on the tangent space for several operations and the frequent back and forth mapping is both expensive and prone to a loss of data.



# Hyperbolic Network ++

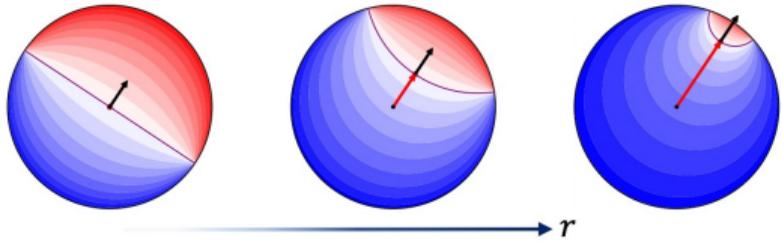
Poincaré Ball

$$y = \exp_0^c (W \log_0^c(x)) \oplus_c b \quad (6)$$

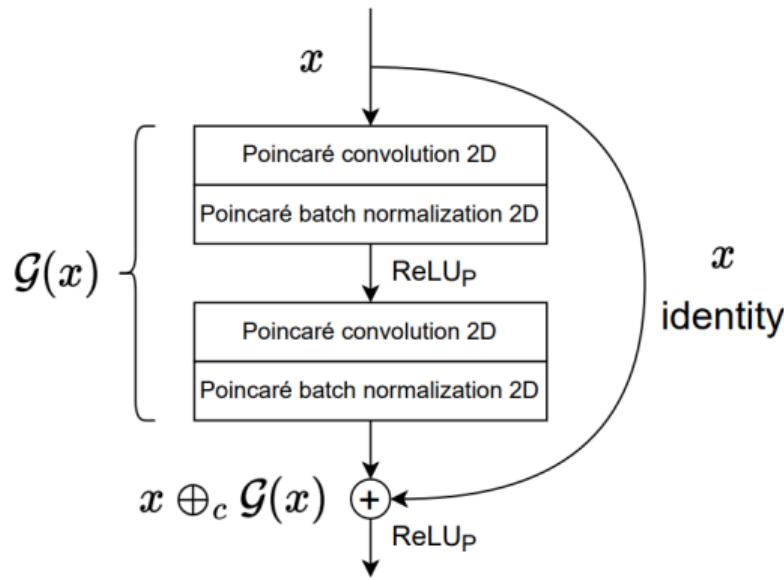


Hyperbolic Neural Networks++

$$y = \mathcal{F}^c(x; Z, r) = w \left(1 + \sqrt{1 + c\|w\|^2}\right)^{-1} \quad (7)$$



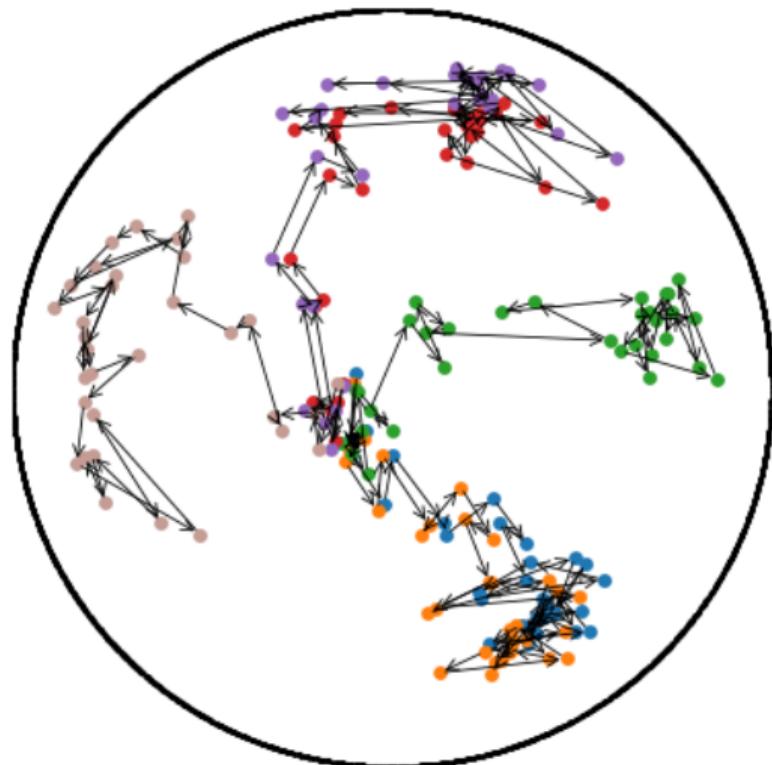
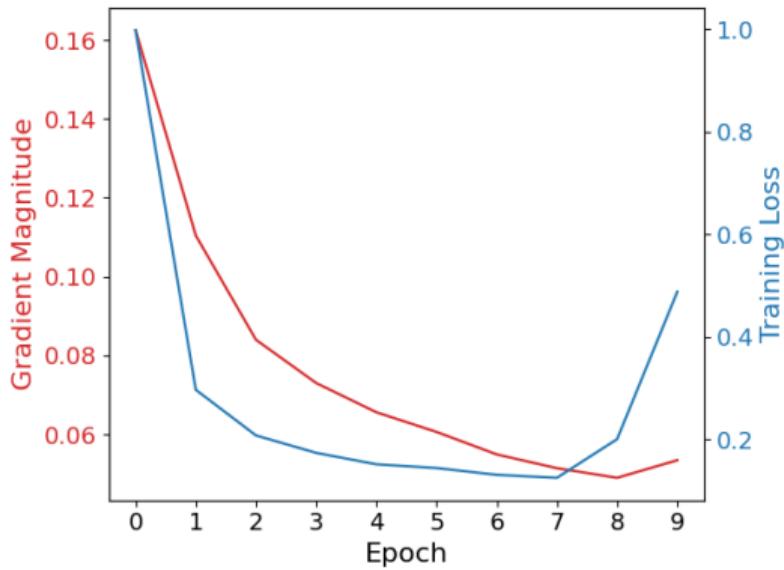
# Poincaré ResNet



- ▶ Extend Linear Layer from Hyperbolic Neural Network++ for Convolutions.
- ▶ Poincaré midpoint batch normalization for faster and equally effective alternative to Frechet Mean.
- ▶ Poincaré Resnets are (i) more robust to out-of-distribution samples, (ii) more robust to adversarial attacks and (iii) complementary to Euclidean networks.

## Weaknesses

# Gradients Vanishing



## Numerical Unstability

- ▶ It will sometimes lead to catastrophic NaN problems, encountering unrepresentable values in floating point arithmetic.
- ▶ Under the 64 bit arithmetic system, the Poincare ball has a relatively larger capacity than the Lorentz model for correctly representing points.
- ▶ Lorentz model is superior to the Poincare ball from the perspective of optimization.

## Prepare for Practical Session

Download codebase from:

[github.com/Digital-Dermatology/hyperbolic-learning-tutorial-code](https://github.com/Digital-Dermatology/hyperbolic-learning-tutorial-code)

## References |

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# PoincareResNet

Manifold		CIFAR-10						CIFAR-100					
		FPR95 ↓		AUROC ↑		AUPR ↑		FPR95 ↓		AUROC ↑		AUPR ↑	
		R20	R32										
Places-365	Euclidean	64.2	72.3	<b>84.7</b>	82.0	<b>96.2</b>	95.6	89.5	93.9	62.5	57.9	89.3	87.9
	w/ HNN++	<b>63.8</b>	72.7	79.6	77.7	94.5	94.2	93.2	86.3	63.3	66.6	89.8	91.1
	Poincaré	70.2	<b>70.7</b>	82.3	<b>82.6</b>	95.7	<b>95.9</b>	<b>82.8</b>	<b>83.8</b>	<b>71.5</b>	<b>71.1</b>	<b>92.3</b>	<b>92.2</b>
SVHN	Euclidean	97.3	94.7	68.8	73.4	92.8	94.1	99.5	98.8	43.7	54.6	83.7	88.2
	w/ HNN++	73.1	79.1	<b>85.5</b>	82.2	<b>96.9</b>	96.1	92.1	88.6	66.4	68.9	91.1	92.0
	Poincaré	<b>66.0</b>	<b>69.3</b>	85.0	<b>83.6</b>	96.6	<b>96.3</b>	<b>76.9</b>	<b>83.0</b>	<b>76.8</b>	<b>72.6</b>	<b>94.1</b>	<b>92.9</b>
Textures	Euclidean	87.3	88.0	73.6	77.3	93.2	94.7	98.1	96.0	33.5	42.9	75.9	79.4
	w/ HNN++	<b>63.8</b>	<b>56.6</b>	79.6	<b>85.8</b>	94.5	<b>96.6</b>	85.9	<b>77.5</b>	58.9	65.7	86.8	89.0
	Poincaré	68.2	66.2	<b>82.1</b>	82.3	<b>95.5</b>	95.6	<b>83.9</b>	84.2	<b>67.7</b>	<b>68.8</b>	<b>91.0</b>	<b>91.5</b>

# Hyperbolic Learning in Action

## Tools for Hyperbolic Learning



Lionetti  
Simone

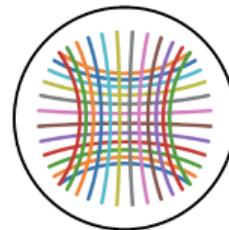


Gonzalez-Jimenez  
Alvaro

Thursday 13<sup>th</sup> February, 2025

# Geomstats

- ▶ An extensive library for differential geometry, supporting a wide range of manifolds and operations.
- ▶ Offers thorough documentation and tutorials, which help users get started quickly.
- ▶ Well-maintained and actively developed with frequent updates.
- ▶ Lacks in-depth focus on hyperbolic space, leading to missing important features and models.



# Geomstats

# Geoopt

- ▶ Started as *just for fun* paper implementation and grow to a Python Package.<sup>1</sup>
- ▶ Support various hyperbolic models and operations.
- ▶ The most widely used library in literature for manifold-based optimization.
- ▶ Lacks active maintenance, with outdated implementations for key operations such as sinh, cosh, etc.
- ▶ Performance issues and steep learning curve for beginners.

---

<sup>1</sup><https://www.youtube.com/watch?v=6VZ0Gk4QMME>

# HypLL

- ▶ A recent library with a strong focus on hyperbolic space.
- ▶ Provides support for hyperbolic layers and operations, designed like PyTorch (`hypll.nn`, `hypll.optim`).
- ▶ User-friendly for creating fully hyperbolic networks.
- ▶ Only support Poincaré Ball, other models will be implemented.

# HypLL Overview

```
1 from hypll.tensors import TangentTensor
2 from hypll.optim import RiemannianAdam
3 from hypll.manifolds.poincare_ball import Curvature, PoincareBall
4 from models import hyperbolic_model
5 ...
6
7 manifold = PoincareBall(c=Curvature(value=0.1, requires_grad=True))
8 model = hyperbolic_model(manifold=manifold)
9
10 optimizer = RiemannianAdam(model.parameters(), lr=0.001)
11 criterion = nn.CrossEntropyLoss()
12
13 for epoch in range(100):
14     running_loss = 0.0
15     for i, data in enumerate(trainloader, 0):
16         inputs, labels = data[0].to(device), data[1].to(device)
17
18         tangents = TangentTensor(data=inputs, man_dim=1, manifold=manifold)
19         manifold_inputs = manifold.expmap(tangents)
20
21         optimizer.zero_grad()
22         outputs = model(manifold_inputs)
23         loss = criterion(outputs.tensor, labels)
24         loss.backward()
25         optimizer.step()
26         ...
```

Library	Advantages	Disadvantages
Geomstats	Extensive support for differential geometry Well maintained and documented	Not focus for hyperbolic learning Missing operations and features
Geoopt	Support many models (Lorentz, Hyperboloid, Klein, etc.) Rich in hyperbolic operations Widely used in hyperbolic papers	Slow performance (outdated code) Not maintained Difficult for beginners
HypLL	Follows PyTorch style Support hyperbolic layers for Fully Hyperbolic Networks User-friendly	Only Poincare model is supported

# Hyperbolic Learning in Action

## Conclusions & Learning



Lionetti  
Simone



Gonzalez-Jimenez  
Alvaro

Thursday 13<sup>th</sup> February, 2025

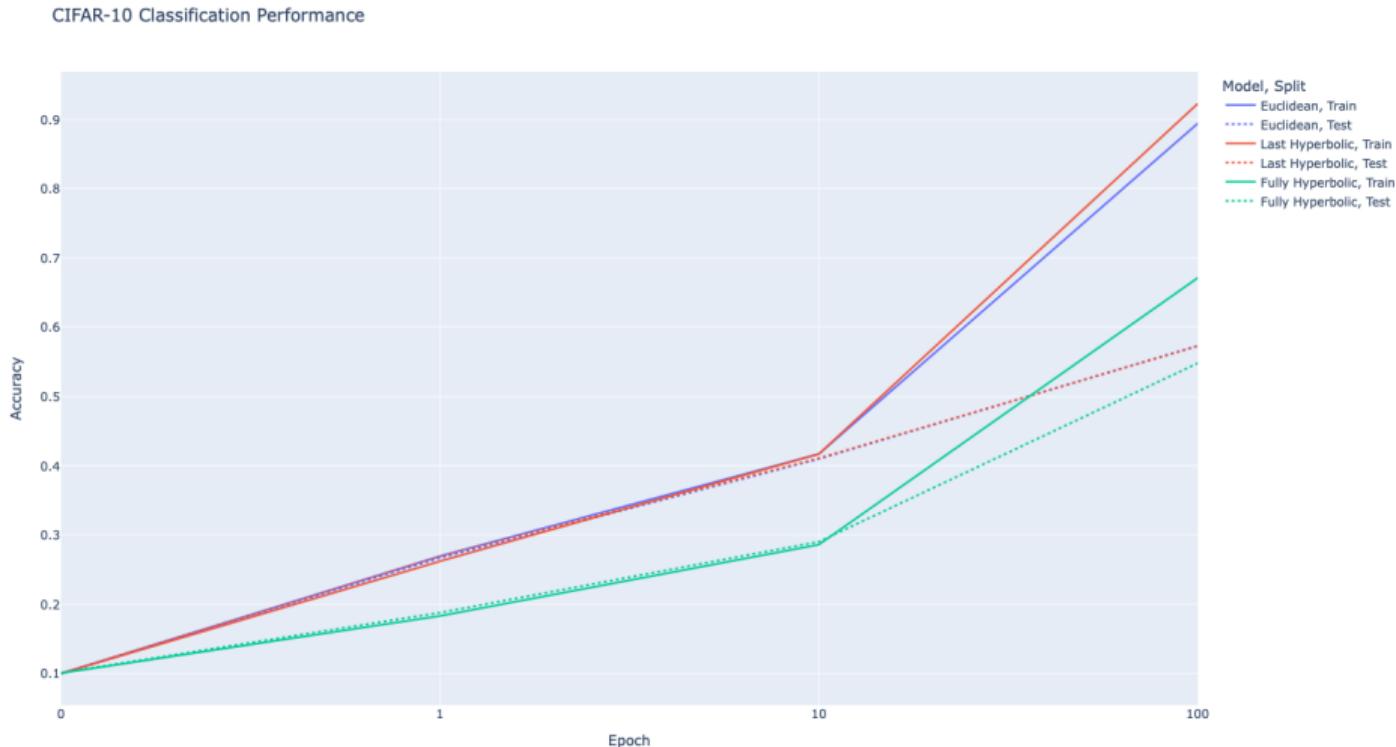
## Discussion

## Learnings from the practical session

Tell us what you have discovered or learned from the practical session!



# Performance comparison



# Euclidean, epoch 0



# Euclidean, epoch 1



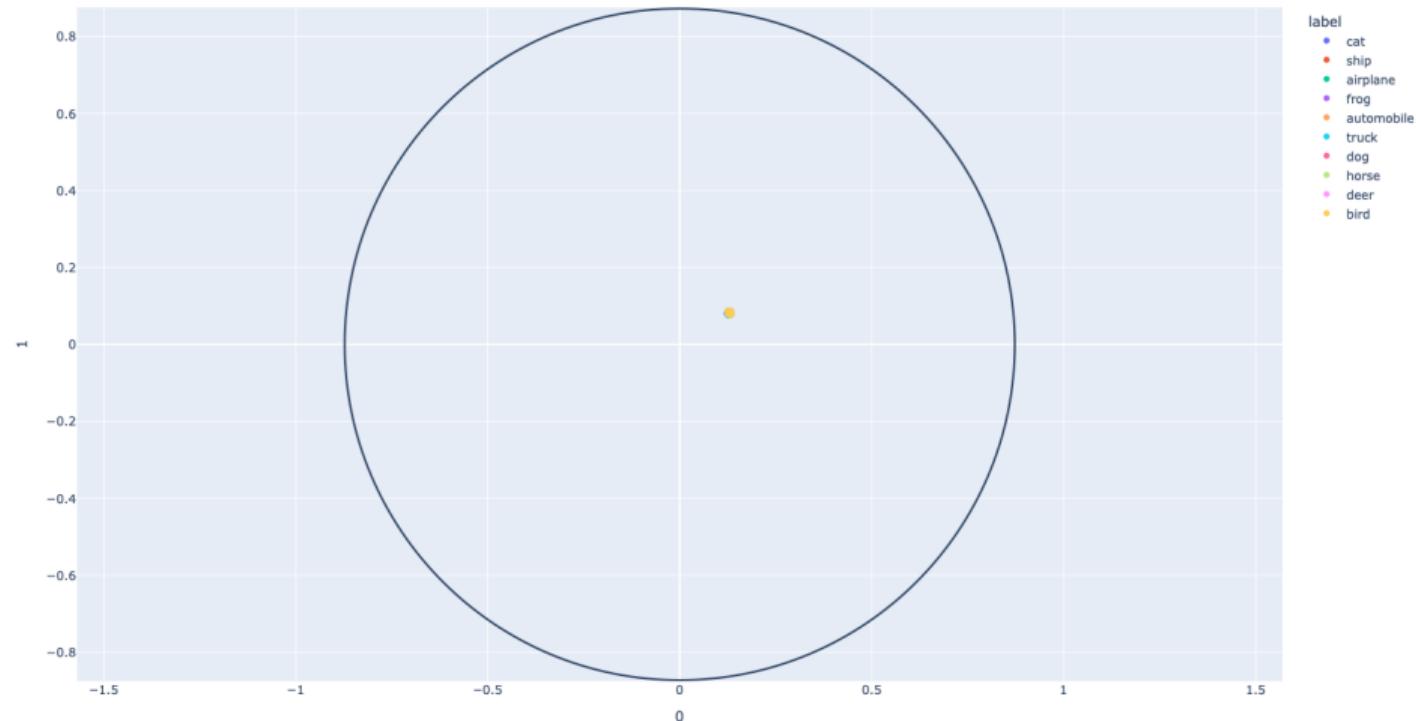
# Euclidean, epoch 10



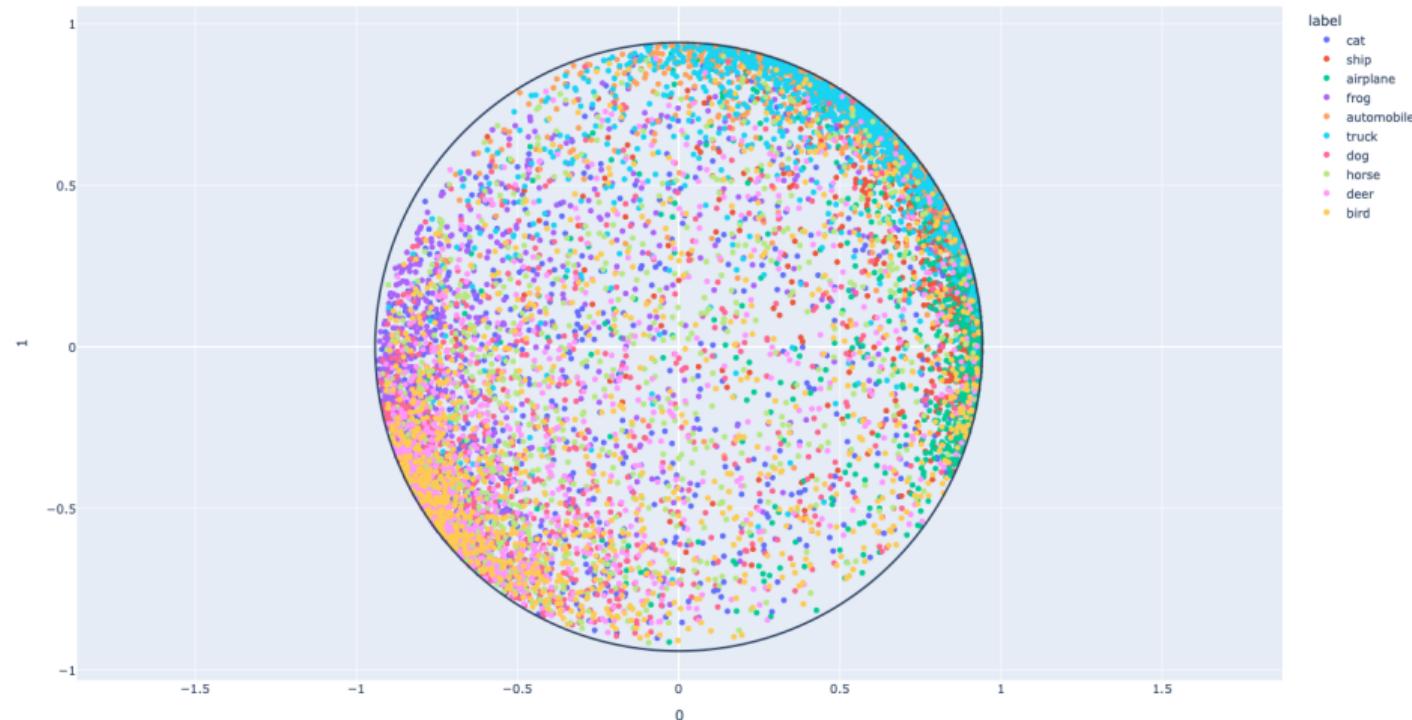
# Euclidean, epoch 100



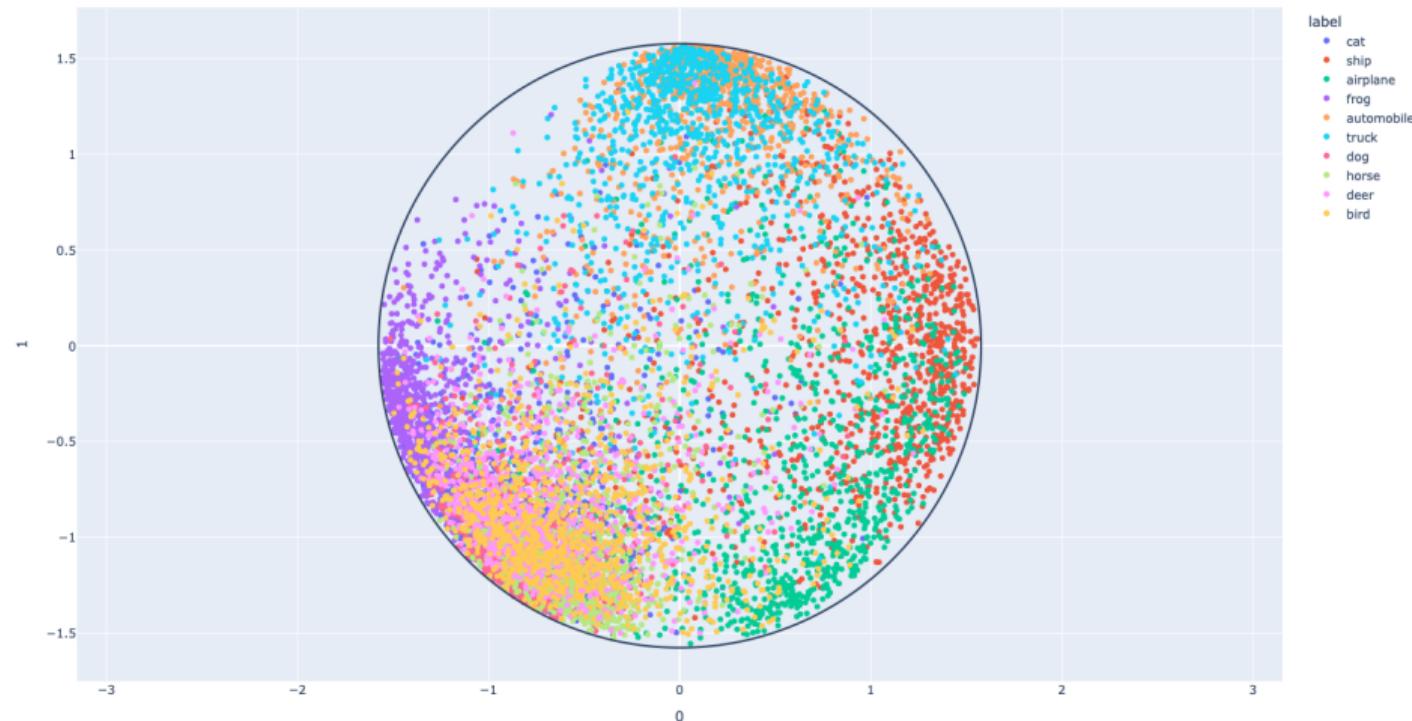
# Last hyperbolic, epoch 0



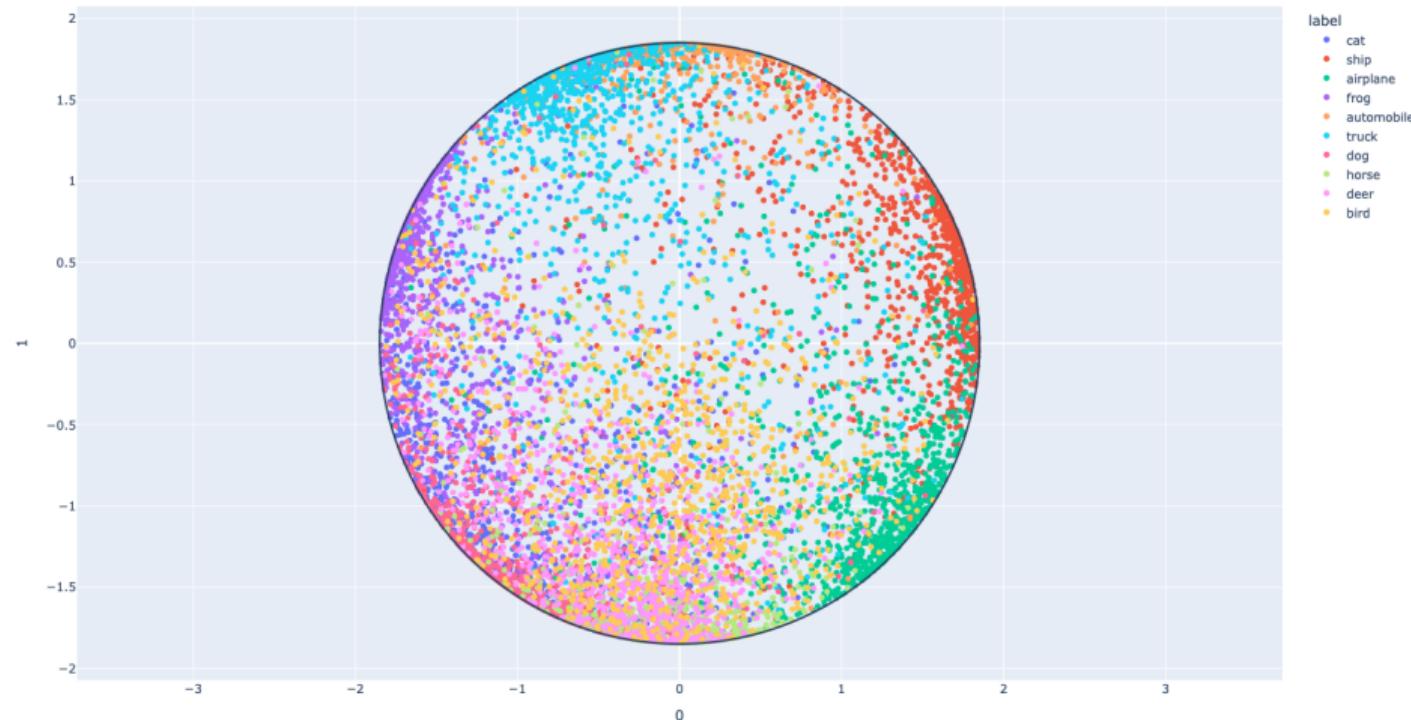
## Last hyperbolic, epoch 1



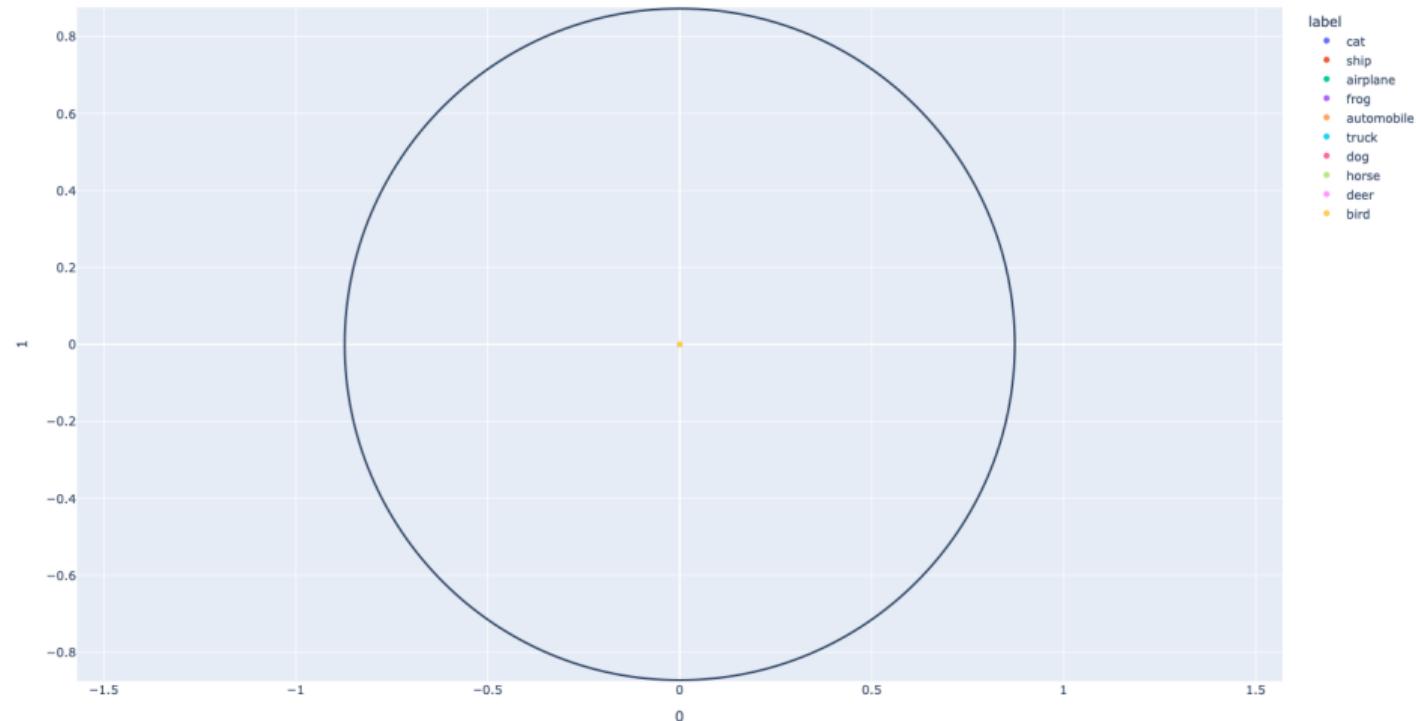
# Last hyperbolic, epoch 10



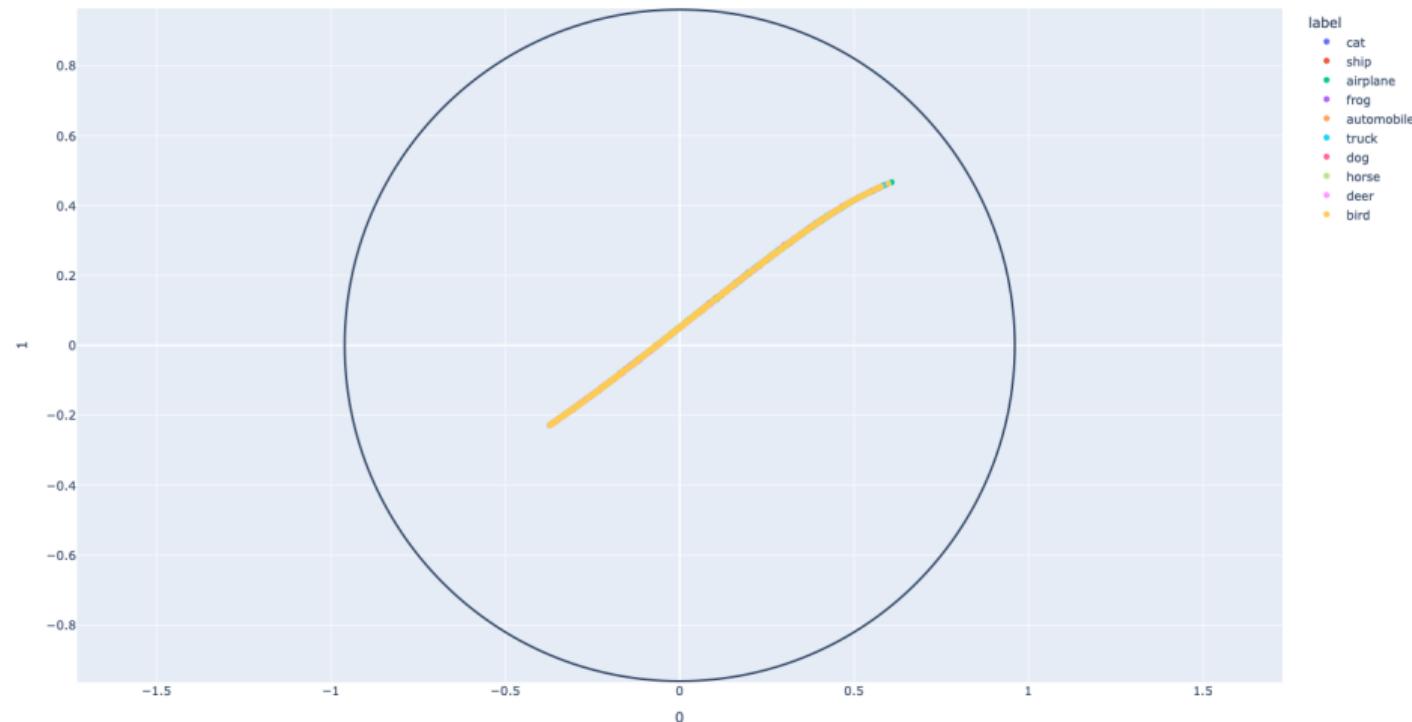
# Last hyperbolic, epoch 100



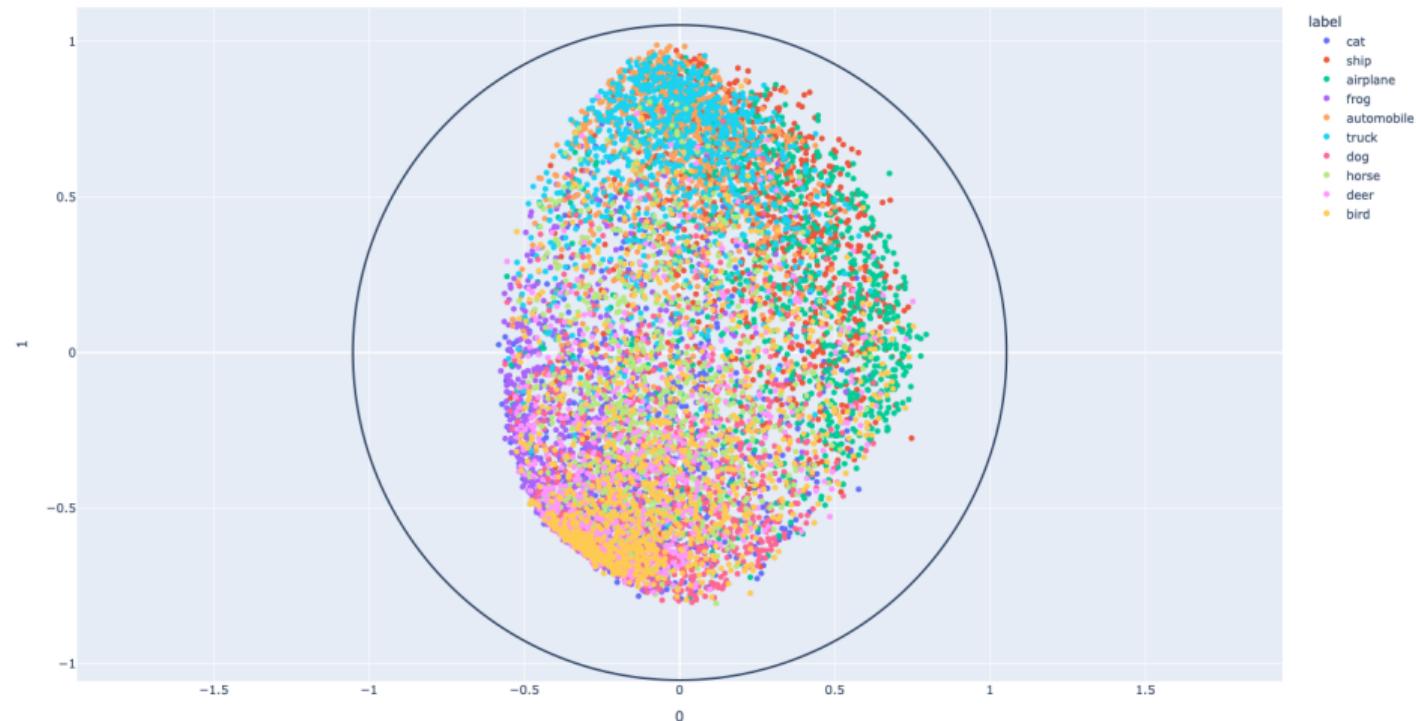
# Fully hyperbolic, epoch 0



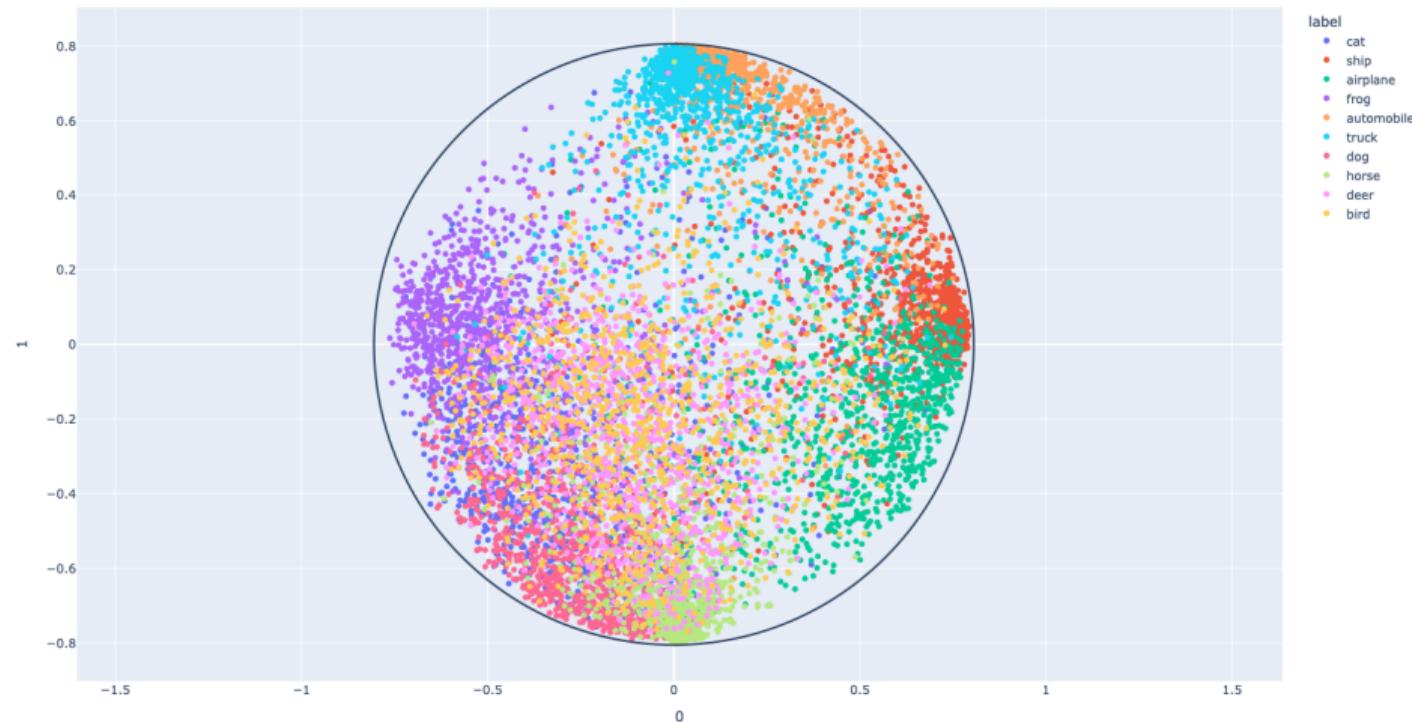
# Fully hyperbolic, epoch 1



# Fully hyperbolic, epoch 10

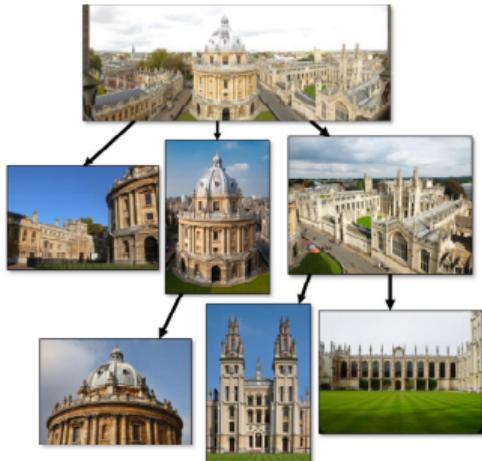


# Fully hyperbolic, epoch 100

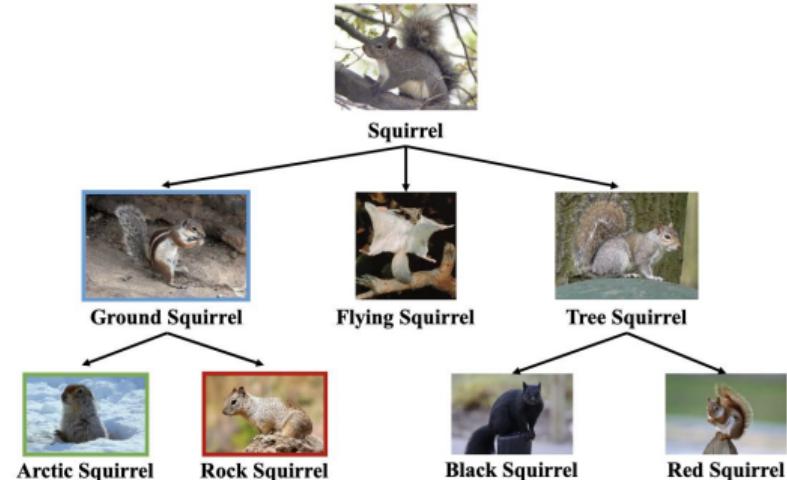
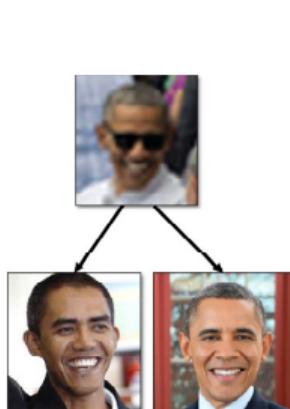


## Recap

# Why should we care about Hyperbolic Learning

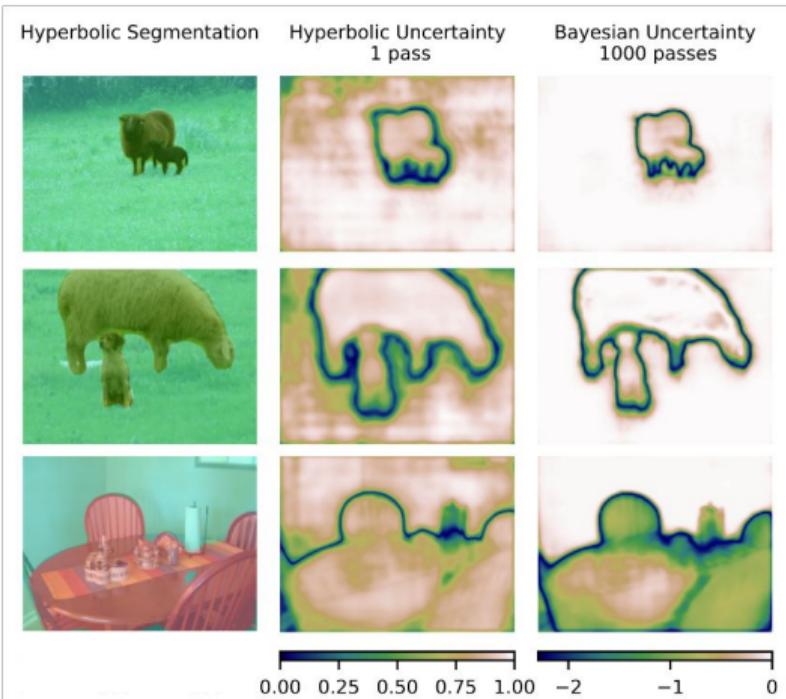
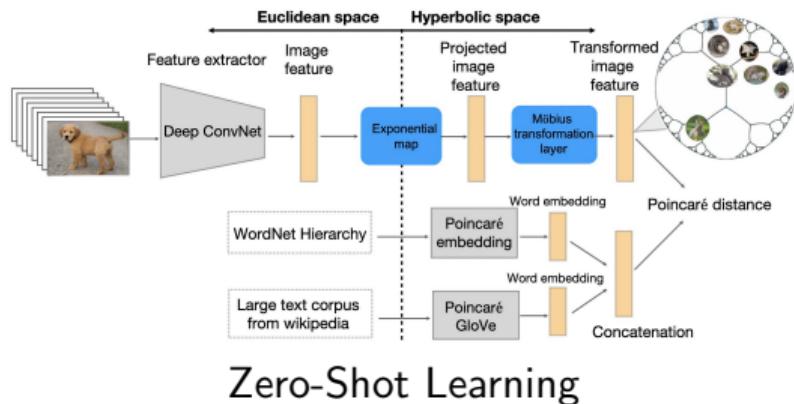


Visual Hierarchies



Semantic Hierarchies

# Why should we care about Hyperbolic Learning



Robustness

## Future Potential

- ▶ Fully hyperbolic CNNs, Transformers, etc.
- ▶ Stable learning on any and all hyperbolic models.
- ▶ Fast forward and backward computation.
- ▶ Adjust curvature to data and problem.
- ▶ What model is suitable for data and problem?
- ▶ Large-scale hyperbolic learning.

# Thank you



<https://forms.gle/KdhQPt6e9NwKUkfGA>