

DREVAN: Deep Reinforcement Learning-based Vulnerability-Aware Network Adaptations for Resilient Networks

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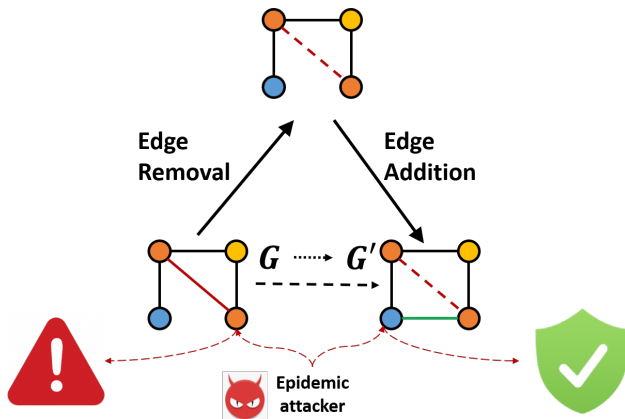


Outline

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Motivation

- Achieving network security and network resilience by network topology adaptation under software polyculture environment.



Key Contributions

- Proposed a network topology adaptation technique to achieve network resilience in terms of maximizing system security and network connectivity.
- Presented two algorithms to support the DRL agent to efficiently identify an optimal adaptation budget strategy to meet the two system goals.
 - VREN: Vulnerability Ranking algorithm of Edges and Nodes
 - FSS: Fractal-based Solution Search algorithm
- Conducted extensive comparative performance analysis based on six network topology adaptation schemes.
- Found that DRL-based network topology adaptations particularly outperform with regard to minimizing system security vulnerability.

Related Work

■ Deployment of diversity-based network adaptations

- Metric-based: graph coloring based software allocation/assignment ¹
- Metric-free: software assignment ²; network topology shuffling ³

■ DRL-based network topology shuffling

- Addition: adding edges to networks ⁴
- Removal: removing edges from networks ⁵
- Shuffling: redirecting edges in networks ^{6 7}

■ Limitations

- Lack of study to determine an optimal number of edge adaptations for resilient networks
- Limited topology operations
- Slow convergence for DRL agents to identify optimal solutions

¹ Borbor et al., 2019

² Yang et al., 2016

³ Hong et al., 2016

⁴ Darvariu et al., 2020

⁵ Dai et al., 2018

⁶ Chai et al., 2020

⁷ Zhang et al., 2020

Problem Statement

- **Main idea:** optimize network security(\mathcal{F}_C) + resilience(\mathcal{S}_G)
- **Objective function :**

$$\arg \max_{b_A, b_R} f(G') - f(G), \quad s.t. \quad 0 \leq b_A + b_R \leq B, \quad (1)$$

G : original network

G' : adapted network

b_A : addition budget

b_R : removal budget

$$f : G \mapsto \mathcal{S}_G(G) - \mathcal{F}_C(G)$$

System Model

- **Network Model:** A centralized system with one centralized controller
- **Node Model**
 - Activity indicator(IDS): $na_i = 1(\text{alive})/0(\text{failed})$
 - Compromise indicator: $nc_i = 1(\text{compromised})/0(\text{not compromised})$
 - Software version: $s_i \in [1, N_s]$, N_s : # of available software packages
 - Software vulnerability: $sv_i \in [0, 1]$ ⁸
- **Attack Model**
 - Epidemic attacks: P_a
 - Perform two attack trials to infect its direct neighbors
 - Learn software versions along attacks
 - State manipulation attacks: P_s
 - Inject fake rewards

⁸ The extent of a Common Vulnerabilities and Exposures (CVE) based on a Common Vulnerability Scoring System (CVSS)

Vulnerability Ranking of Edges and Nodes (VREN)

- Precision control by $\#$ of attack simulations
- Edge vulnerability level V_E : $\#$ of times it is used by attackers to compromise other nodes
- Node vulnerability level V_V : $\#$ of times it becomes an attacker (being compromised)
- Ranking system
 - R_E : edge ranking based on V_E in descending order
 - R_V : node ranking based on V_V in ascending order
- Adaptation based on budget constraints $[b_R, b_A]$
 - b_R : edge removal budget
 - b_A : edge addition budget

Fractal-based Solution Search (FSS)

■ Self-similar fractals

- Centroid representation for each division
- Logarithm complexity: $\lceil \log B \rceil$
(B : the upper bound of the total adaptation budget)

■ Discrete evaluation

- Nearest integer points: (b_R, b_A)
(b_R : edge removal budget, b_A : edge addition budget)

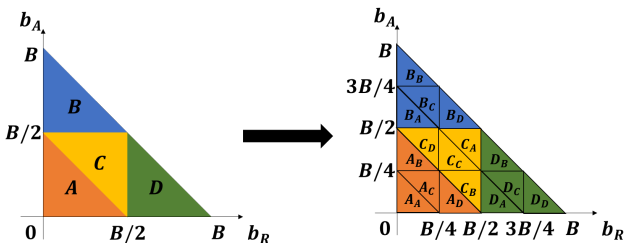


Figure 1: Generation of self-similar fractals to reduce solution search space in edge addition and removal budgets, (b_A, b_R) .

Proposed DREVAN Framework

■ DRL-based Budget Adaptation

■ States

- $s_t = (b_A^t, b_R^t, G_t')$
- b_R^t : removal budget at time t ; b_A^t : addition budget at time t ; G_t' : the network at time t

■ Actions

- FSS: $a_t = \{A, B, C, D\}$, where $1 \leq t \leq \lceil \log_2 B \rceil$
- LS (Linear Search): $a_t = \{stop, add, remove\}$, where $1 \leq t \leq B$

■ Rewards

- $\mathcal{R}(s_t, a_t, s_{t+1}) = f(G_{t+1}') - f(G_t')$, where $f: G \mapsto S_G(G) - \mathcal{F}_C(G)$ (size of the giant component - fraction of compromised nodes).

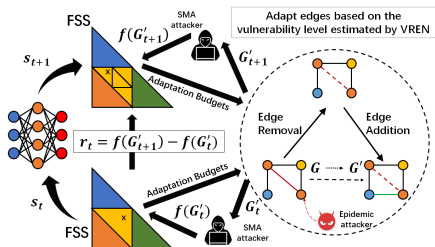


Figure 2: The overall architecture of the proposed DREVAN: The color of each node refers to a different software package installed in it.

Experimental Setup

- Random Graph
 - ER: Erdős–Rényi random graph model
 - Number of nodes $N = 200$
 - Connection probability $p = 0.05$
- Attack Types Considered
 - State Manipulation Attacks
 - Probability for a system state to be manipulated by the attacker $P_s = 0.3$
 - Epidemic Attacks
 - Fraction of initial attackers in a network $P_a = 0.3$

Experimental Setup

Table 1: Key Design Parameters, Meanings, and Default Values

Param.	Meaning	Value
n_a	Attack simulation times	500
n_r	Number of simulation runs	200
n_e	Training episodes of DRL-based schemes	1000
N	Total number of nodes in a network	200
k	Upper hop bound for edge addition	3
γ	Intrusion detection probability	0.9
P_{fn}, P_{fp}	False negative or positive probability	0.1, 0.05
x	Degree of software vulnerability	0.5
p	Connection probability between pairs of nodes in an ER network	0.05
l	Number of software packages available	5
P_a	Fraction of initial attackers in a network	0.3
B	Upper bound of the total adaptation budget	500
P_s	Probability of state manipulation attacks	0.3
D_r	Detection rate of state manipulation attacks	0.99

Asymptotic Analysis of the Compared Schemes

Scheme	Complexity
DQN with DREVAN	$O(n_e \times \lceil \log_2 B \rceil \times T_{\text{train}} \times n_a)$
DQN with FSS	$O(n_e \times \lceil \log_2 B \rceil \times T_{\text{train}} \times n_a)$
DQN with VREN	$O(n_e \times B \times T_{\text{train}} \times n_a)$
DQN	$O(n_e \times B \times T_{\text{train}} \times n_a)$
Greedy	$O(\lceil \log_2 B \rceil \times n_a)$
Random	$O(n_a)$
Optimal	$O(B^2 \times n_a)$

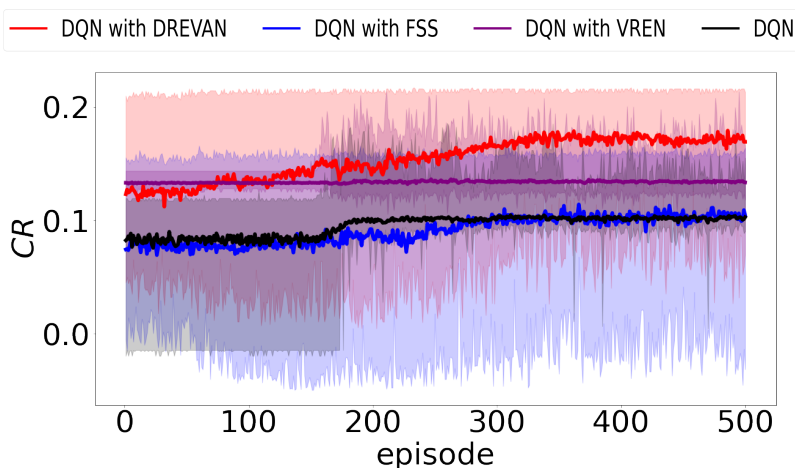
n_e : the training episode

B : the upper bound of total adaptation budget

T_{train} : the training time per episode

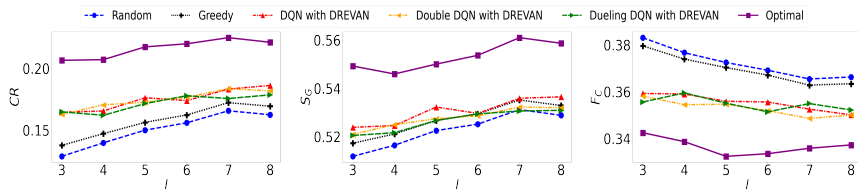
n_a : the attack simulation times

Converged Reward with respect to Training Episodes



- DQN with DREVAN performs the best.
- DQN with FSS can only learn a sub-optimal policy.
- DQN with VREN and DQN cannot learn well with LS.

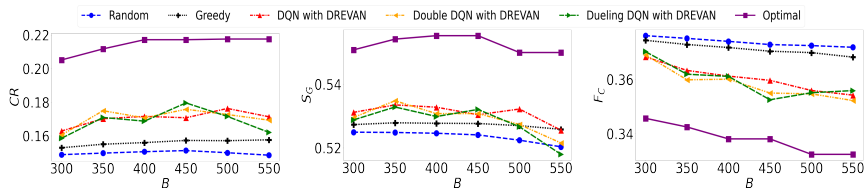
Effect of Varying the Number of Software Packages Available (l) under an ER Network



(a) Converged reward (CR) (b) Size of the giant component (S_G) (c) Fraction of compromised nodes (F_C)

- As l increases, F_C drops and S_G increases.
- Overall performance order: Optimal \geq DQN \approx Double DQN \approx Dueling DQN \geq Greedy \geq Random.

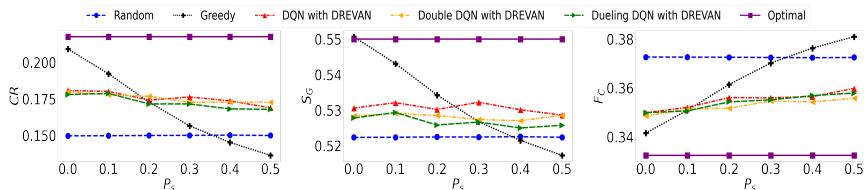
Effect of Varying the Upper Bound of the Total Adaptation Budget (B) under an ER Network



(a) Converged reward (\mathcal{CR}) (b) Size of the giant component (\mathcal{S}_G) (c) Fraction of compromised nodes (\mathcal{F}_C)

- Higher B increases \mathcal{CR} while decreasing \mathcal{F}_C , but it does not necessarily improve \mathcal{S}_G .
- Overall performance order: Optimal \geq DQN with DREVAN \approx Double DQN with DREVAN \approx Dueling DQN with DREVAN \geq Greedy \geq Random.
- Dueling DQN with DREVAN is more sensitive to B than DQN with DREVAN and Double DQN with DREVAN.

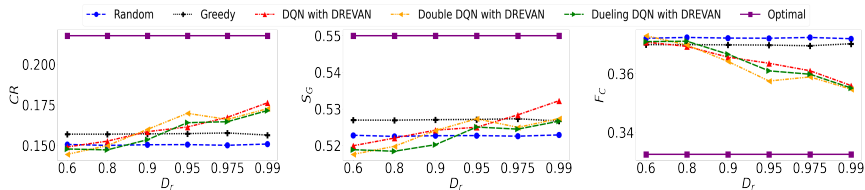
Effect of Varying Probability of State Manipulation Attacks (P_s) under an ER Network



(a) Converged reward (\mathcal{CR}) (b) Size of the giant component (\mathcal{S}_G) (c) Fraction of compromised nodes (\mathcal{F}_C)

- Higher P_s brings lower \mathcal{CR} and \mathcal{S}_G while introducing more \mathcal{F}_C .
- The Greedy scheme is more sensitive to P_s than DRL-based schemes.

Effect of Varying Detection Rate of State Manipulation Attacks (D_r) under an ER Network



(a) Converged reward (\mathcal{CR}) (b) Size of the giant component (\mathcal{S}_G) (c) Fraction of compromised nodes (\mathcal{F}_C)

- Higher D_r increases \mathcal{CR} and \mathcal{S}_G while lowering \mathcal{F}_C .
- DRL-based schemes only outperform with higher D_r .
- Overall DQN with DREVAN performs slightly better than Double DQN with DREVAN and Dueling DQN with DREVAN.

Conclusions

- Proposed a fractal-based environment (FSS) that can significantly reduce the training complexity of our DRL algorithms.
- Proposed a vulnerability-aware ranking algorithm (VREN) to strategically adapt edges for efficient and effective network configurations.
- Proposed a DRL-based framework, DREVAN, to minimize system vulnerability while maintaining comparable or better network connectivity.
- Showed the outperformance of three different types of Deep Q-learning algorithms against the counterpart and baseline schemes.

Any Questions?

Thank you!

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