

# DIJIE ZHU

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## Education

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### M.S. University of California, Los Angeles (UCLA)

Sep 2024 – Present

Electrical and Computer Engineering    GPA: 3.957/4.0

- Major courses: Neural Network and Deep Learning (A+), Advanced Neural Network and Deep Learning (A), Computational Robotics (A), Modern Wireless Communication Systems (A), Large Scale Data Mining (A), Statistical Machine Learning (A-), Digital Communication System (A).

### B.Eng. University of Electronic Science and Technology of China & University of Glasgow

Sep 2020 – Jun 2024

Electrical and Electronic Engineering (Joint Programme)    First Class Honours (UK)    GPA: 3.9/4.0    Rank: 3/169

- Major courses: Microelectronic Systems (99), Circuit Analysis and Design (95), Signals and Systems (95), Communications Networks (84), AI and Machine Learning (95), Digital Circuit Design (86).

## Research Experience

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### Dynamic Threshold Adjustment and Novel Pseudo-Labeling Methods

Mar 2025 – Present

Instructor: Suhas Diggavi, UCLA    Semi-Supervised Learning

*Coding Language: Python*

- Followed Consistency Regularization and Pseudo-Label in SSL as base model.
- Developed a model training estimator without resorting to train or test accuracy.
- Designed a interpolation dynamic thresholding method based on estimator, Freematch SAT and data sample statistics.
- Surpassed SOTA on CIFAR10 with total 10 labels given.
- Achieved Fast converging speed and better final performance with WideResnet.

### NN-Aided Digital SIC under Time-Varying Channels

Sep 2024 – Jan 2025

Instructor: Ian Roberts, UCLA    Neural Network, Signal Processing, Communication Systems

*Coding Language: MATLAB, Python*

- Implemented an MLP-based neural network in MATLAB for digital SIC in IBFD systems under time-varying channels, solving an inverse channel-estimation problem.
- Engineered linear preprocessing features to encode channel dynamics without frame-wise retraining, reducing computational complexity by  $\sim 75\%$ .
- Conducted physics-based simulations with Jakes' fading model; achieved mean SIC gain of 6.93 dB with variance 1.21 dB<sup>2</sup>.
- Benchmarked against adaptive memory-polynomial and residual NN methods; demonstrated superior stability (variance  $\downarrow 30\times$ ) and real-time feasibility.

### CNN-Based Real-Time Street Photo Multi-Target Segmentation

Dec 2022 – Feb 2023

Instructor: Alexander Amini, MIT    Computer Vision, Machine Learning

*Coding Language: Python*

- Developed a custom PyTorch DataLoader pipeline for efficient preprocessing, augmentation, and batching to support real-time segmentation inference.
- Architected and implemented a convolutional neural network with optimized layer dimensions and skip connections for simultaneous multi-object detection and seg-

mentation.

- Integrated aleatoric and epistemic uncertainty estimation to quantify model confidence and guide selective data acquisition.
- Achieved 95% training accuracy and 90% evaluation accuracy, earning a final project score of 93/100.

### 5.5G to 6G IBFD System Simulation: Three-Stage SI Cancellation Techniques

Sep 2023 – Jun 2024

Instructor: Ying Liu, UESTC    Signal Processing, Communication Systems

Coding Language: MATLAB, Python

- Simulated horn-antenna rotation ( $0^\circ \rightarrow 90^\circ$ ) under a 3GPP CDL channel, achieving 35 dB directional isolation + 47 dB path-loss (total  $\approx 82$  dB passive SIC).
- Designed a two-tap FIR cancellation network targeting the direct path and strongest reflection, realizing  $\approx 30$  dB suppression pre-ADC via adaptive analog filtering.
- Applied a modified variable-step LMS algorithm ( $\alpha = 10$ ,  $\beta = 0.02$ ,  $m = 3$ , 15-tap FIR) to cancel residual interference, adding  $\approx 5$  dB and achieving  $\approx 117$  dB end-to-end SIC.

### Autonomous Mobile Robot: Multi-Environment Task Fulfillment

Mar 2023 – Jun 2023

Instructor: Abdullah Al-Khalidi, UESTC & Glasgow    Embedded Systems, Control, Computer Vision, Communication Systems

Coding Language: C/C++, Python


- Coordinated a team of 10 students; designed and assembled the robotic vehicle's mechanical, communication, vision, and control modules.
- Implemented HC-12 wireless link for real-time data exchange with the host PC.
- Achieved smooth navigation and decision execution through EMA filtering, YOLOv3, and PID integration.
- Validated performance in multiple environments, achieving 95% average task completion and a project score of 92/100.

## Publications

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### Digital Nonlinearity Cancellation Architecture Based on An Auxiliary Transmit Antenna Array

Jun 2023

Fang Nan, Nanxi Li, **Dijie Zhu**, Yuetian Zhou, Sujie Dai, Jianchi Zhu, Jinlong Tian, Xiaoming She. *ITCC'23: Proceedings of the 2023 5th International Conference on Information Technology and Computer Communications*, pp. 32–37. DOI: [10.1145/3606843.3606849](https://doi.org/10.1145/3606843.3606849)  


### A Post-Correction Method for Terahertz Nonlinear Distortion with Dual-Band Carrier Aggregation

Oct 2022

Mengyao Zhang, Jian Liu, **Dijie Zhu**, Xin Quan, Qiang Xu, Ying Liu, Zhi Chen. *2022 IEEE Globecom Workshops: Sixth IEEE International Workshop on Terahertz Communications*.

### Improved Almost Blank Subframe Technology with Cooperative Interference Suppression

Mar 2023

Cong Chen, Zixuan Long, Fang Nan, Luyao Xiao, **Dijie Zhu**, Xiang Li, Ying Liu, Shihai Shao. *International Journal of Numerical Modelling: Electronic Networks, Devices, and Fields*.

## Technical Strengths

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**Programming Languages**    C/C++, Python, MATLAB, Vivado

**ML Inference & Serialization**    PyTorch, TensorFlow    **Other Tools**    Git, Jupyter