MGMT MFE 407: Empirical Methods in Finance Homework 2: Solution

Prof. Lars A. Lochstoer TA: Danyu Zhang

January 22, 2020

Problem 1: AR(p) Processes

- 3. Consider an AR(2) process with $\phi_1=1.1$ and $\phi_2=-0.25$
 - (a) Plot the autocorrelation function for this process for lags 0 through 20.

Suggested Solution: We know that $\rho_0 = 1$ we can further solve for ρ_1 using

$$\rho_1 = \phi_1 \rho_0 + \phi_2 \rho_1 \tag{1}$$

and for $j \geq 2$

$$\rho_i = \phi_1 \rho_{i-1} + \phi_2 \rho_{i-2} \tag{2}$$

Figure 1 shows the bar plot for the autocorrelations for lags 0 through 20.

(b) Is the process stationary? Explain why or why not.

Suggested Solution: We solve for the characteristic roots for the AR(2) using

$$x_1, x_2 = \frac{\phi_1 \pm \sqrt{\phi_1^2 + 4\phi_2}}{-2\phi_2} \tag{3}$$

and that $\omega_1 = x_1^{-1}$, $\omega_2 = x_2^{-1}$. We have that $\omega_1 = 0.321$ and $\omega_2 = 0.779$. Both of the characteristic roots are less than one, so this AR(2) is stationary.

(c) Give the dynamic multiplier for a shock that occurred 6 periods ago. That is, calculate $\frac{\partial [r_{t+6}-\mu]}{\partial \epsilon_t}$

Suggested Solution: We can rewrite the AR(2) process as

$$r_t - \mu = \phi_1(r_{t-1} - \mu) + \phi_2(r_{t-2} - \mu) + \epsilon_t \tag{4}$$

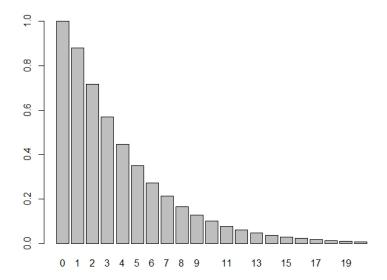


Figure 1: Autocorrelation for lags 0 through 20

We then iterate this formula

$$r_{t+1} - \mu = \phi_1(r_t - \mu) + \phi_2(r_{t-1} - \mu) + \epsilon_{t+1}$$
(5)

$$= (\phi_1^2 + \phi_2)(r_{t-1} - \mu) + \phi_1\phi_2(r_{t-2} - \mu) + \phi_1\epsilon_t + \epsilon_{t+1}$$
(6)

$$r_{t+2} - \mu = \phi_1(r_{t+1} - \mu) + \phi_2(r_t - \mu) + \epsilon_{t+2} \tag{7}$$

$$= \dots + \phi_1^2 \epsilon_t + \phi_2 \epsilon_t \tag{8}$$

$$r_{t+3} - \mu = \phi_1(r_{t+2} - \mu) + \phi_2(r_{t+1} - \mu) + \epsilon_{t+3}$$
(9)

$$= \dots + (\phi_1^3 + 2\phi_1\phi_2)\epsilon_t \tag{10}$$

$$r_{t+4} - \mu = \phi_1(r_{t+3} - \mu) + \phi_2(r_{t+2} - \mu) + \epsilon_{t+4}$$
(11)

$$= \dots + (\phi_1^4 + 3\phi_1^2\phi_2 + \phi_2^2)\epsilon_t \tag{12}$$

$$r_{t+5} - \mu = \phi_1(r_{t+4} - \mu) + \phi_2(r_{t+3} - \mu) + \epsilon_{t+5}$$
(13)

$$= \dots + (\phi_1^5 + 4\phi_1^3\phi_2 + 3\phi_1\phi_2^2)\epsilon_t \tag{14}$$

$$r_{t+6} - \mu = \phi_1(r_{t+5} - \mu) + \phi_2(r_{t+4} - \mu) + \epsilon_{t+6}$$
(15)

$$= \dots + (\phi_1^6 + 5\phi_1^4\phi_2 + 6\phi_1^2\phi_2^2 + \phi_2^3)\epsilon_t$$
 (16)

Thus the dynamic multiplier for a shock that occurred 6 periods ago is 0.380.

(d) Now, instead assume $\phi_1 = 0.9$ and $\phi_2 = 0.8$. Give the dynamic multiplier for a shock that occurred 6 periods ago. Is the process stationary? Why/why not?

Suggested Solution: The dynamic multiplier for a shock that occurred 6 periods ago is 6.778. This process is not stationary as the influence of a shock does not seem to be going away as time goes on. In fact in this case, the characteristic roots are 1.451 and -0.551, one of which is greater than 1.

(e) Instead of analytically solving for dynamic multipliers, we can easily simulate a full impulse response (that is, dynamic multipliers at all horizons). In particular, consider a positive ε_t shock with magnitude one standard deviation. Assume the standard deviation is 1 for simplicity. Define $x_t \equiv r_t - \mu$ as in class. Thus:

$$x_t = 1.1x_{t-1} - 0.25x_{t-2} + \varepsilon_t.$$

Set the initial values equal to the unconditional mean: $x_{t-1} = x_{t-2} = 0$. Set all future shock equal to their expectations, $\varepsilon_{t+j} = 0$ for all j > 0. As stated earlier, let $\varepsilon_t = 1$. Simulate x_{t+j} for j = 0, ..., 60 given the above initial values and sequence of shocks. Plot the resulting series from x_{t-1} through x_{t+60} . This is the Impulse-Response plot for a one standard deviation positive shock to ε_t .

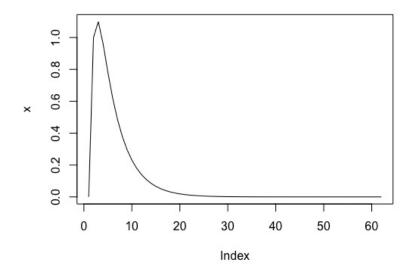


Figure 2: Impulse-Response plot

Problem 2: Applying the Box-Jenkins methodology

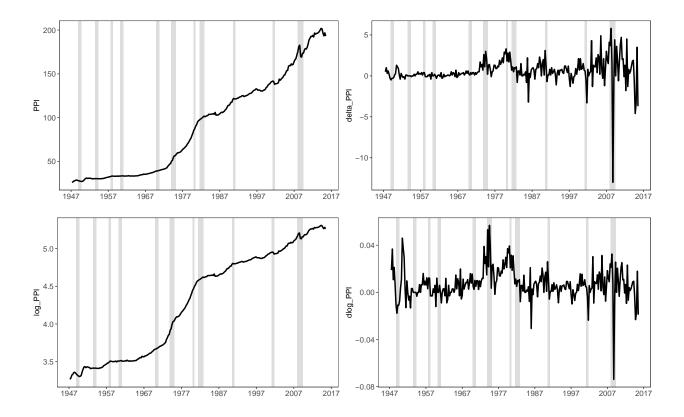


Figure 3: PPI Plots. The vertical shaded bars indicate NBER recessions.

In PPIFGS.xls you will find quarterly data for the Producer Price Index. Our goal is to develop a quarterly model for the PPI, so we can come up with forecasts. Our boss needs forecasts of inflation, because she wants to hedge inflation exposure. There is not a single 'correct' answer to this problem. Well-trained econometricians can end up choosing different specifications even though they are confronted with the same sample. However, there definitely are some wrong answers.

- 1. We look for a covariance-stationary version of this series. Using the entire sample, make a graph with four subplots:
 - (a) Plot the PPI in levels.
 - (b) Plot ΔPPI
 - (c) Plot $\log PPI$
 - (d) Plot $\Delta \log PPI$.

Suggested Solution: Figure 3 presents the plots.

2. Which version of the series looks covariance-stationary to you and why? Let's call the covariance stationary version $y_t = f(PPI_t)$.

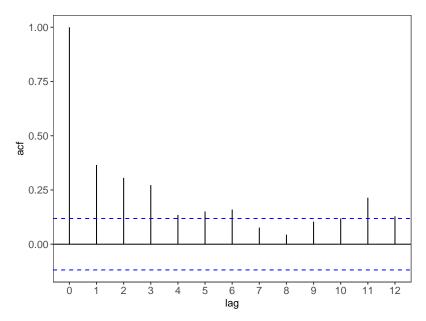


Figure 4: ACF of $\Delta \log PPI$

Suggested Solution: It seems $\Delta \log PPI$ is covariance-stationary by looking at the time series graph. For ΔPPI , the unconditional variance seem to be changing. For $\Delta \log PPI$, the unconditional mean and variance seems quite stable. We'll need to do more tests to identify stationarity.

3. Plot the ACF of y_t for 12 quarters. What do you conclude? If the ACF converges very slowly, re-think whether y_t really is covariance stationary.

Suggested Solution: Figure 4 shows the ACF for $\Delta \log PPI$. It converges to zero after 3 lags, though there is no clear cut off for lag 4-6. I will include 3 or 4 lags in the MA process.

4. Plot the PACF of y_t for 12 quarters. What do you conclude?

Suggested Solution: Figure 5 shows PACF for $\Delta \log PPI$. I will include 2-3 lags in the AR process.

- 5. On the basis of the ACF and PACF, select two different AR model specifications that seem the most reasonable to you. Explain why you chose these.
 - (a) Using the entire sample, estimate each one of these. Report the coefficient estimates and standard errors. Check for stationarity of the parameter estimates.

Suggested Solution: I will estimate the time series using AR(2) and AR (3). Table 1 gives the coefficients and standard errors for these models.

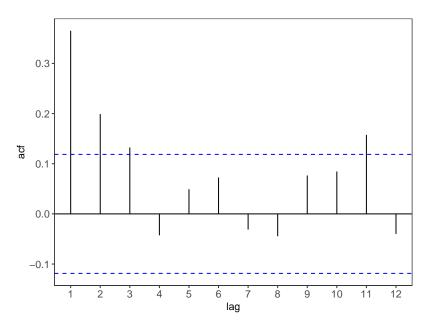


Figure 5: PACF of $\Delta \log PPI$

Table 1: AR Estimates for $\Delta \log PPI$

	$Dependent\ variable:$		
	${\mathrm{dlog(PPI)}}$		
	AR(2)	AR(3)	
	(1)	(2)	
ar1	0.29***	0.27***	
	(0.06)	(0.06)	
ar2	0.20***	0.16**	
	(0.06)	(0.06)	
ar3		0.14**	
		(0.06)	
intercept	0.01***	0.01***	
•	(0.001)	(0.002)	
Observations	273	273	
Log Likelihood	822.29	824.87	
σ^2	0.0001	0.0001	
Akaike Inf. Crit.	-1,636.59	-1,639.75	
Notes	*n <0.1. **n <0.05. ***n <0.01		

Note:

^{*}p<0.1; **p<0.05; ***p<0.01

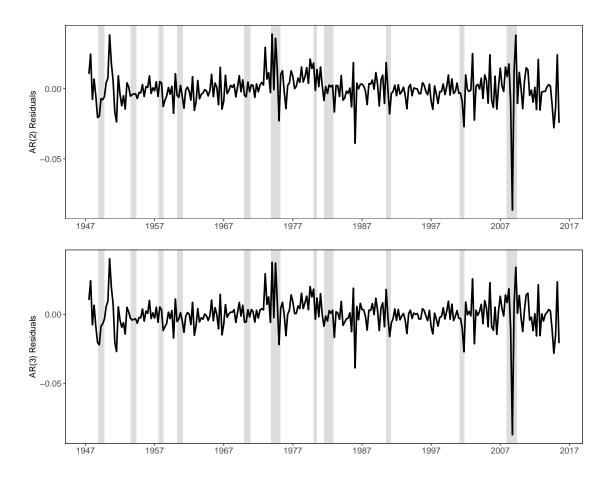


Figure 6: Residuals for AR(2) and AR(3) Models. The vertical shaded bars indicate NBER recessions.

We can check whether the AR part for each model is stationary by solving for the roots for polynomials, and then make sure 1/root<1.

$$AR(2):1 - \phi_1 x - \phi_2 x^2 = 0 (17)$$

$$AR(3):1 - \phi_1 x - \phi_2 x^2 - \phi_3 x^3 = 0$$
(18)

The AR(2) model has 2 real roots (1.41 and -2.41) and the AR(3) has one real and two complex roots (1.32, and $-1.16 \pm 1.84i$), respectively, all are greater than 1, thus stationary.

(b) Plot the residuals. (Note: the residuals will have conditional heteroskedasticity or 'GARCH effects'. We will talk about this later. However, in well-specified models, the residuals should not be autocorrelated.)

Suggested Solutions: Figure 6 plots the residuals for AR(2) and AR(3) models. .

(c) Report the Q-statistic for the residuals for 8 and 12 quarters, as well as the AIC and BIC. Select a preferred model on the basis of these diagnostics. Explain your choice.

Suggested Solution: Table 2 gives the statistics for these four models. I will choose AR (3) model because the AIC is the smallest and the Q-stats are the lest significant.

Table 2: AR Model Statistics

	AR(2)	AR(3)
Q-stats(8Q) p -value	10.20 (0.12)	5.35 (0.38)
Q-stats(12Q) p -value	18.72** (0.04)	13.83 (0.13)
AIC	-1,636.59	-1,639.75
BIC	-1622.15	-1621.70
Note:	*p<0.1; **p<	(0.05; ***p<0.01

6. Re-estimate the two models using only data up to the end of 2005 and compute the MSPE (mean squared prediction error) on the remainder of the sample for one-quarter ahead forecasts:

$$\frac{1}{H} \sum_{t=1}^{H} v_t^2$$

where H is the length of the hold-out sample, and v_i is the one-step ahead prediction error. Also report the MSPE assuming there is no predictability in y_t , i.e. assuming y_t follows a random walk. What do you conclude?

Suggested Solution: The MSPE for these models are shown in Table 3. We fix the coefficient estimates using data prior to Dec 2005 and fit new data sequentially to get one period ahead prediction. For the random walk, we take the real value from last period plus drift as the prediction.

Table 3: AR MSPE. This table shows the MSPE for different models. The first line does the forecast without fitting in new data. The second line shows the forecast when we fix the model but keep fitting in new data for predictions.

	AR(2)	AR(3)	RW
without New Data	$3.40e{-4}$	$3.38e{-4}$	$6.38e{-4}$
with New Data	4.30e - 4	4.17e - 4	$5.69e{-4}$