Dikshant
Civil Engineering
Indian Institute of Technology Bombay
UG Second Year
180040033

ACADEMIC DETAILS

Examination	University	Institute	Year	CPI/%
Graduation	IIT Bombay	IIT Bombay	2020	8.64
Intermediate/ $+2$	Delhi Public school, Hisar	Delhi Public School, Hisar	2018	91.20
Matriculation	K.L. Arya D.A.V. Public School	K.L. Arya D.A.V. Public School	2016	10.00

SCHOLASTIC ACHIEVEMENTS

• Secured a 97.79 percentile in JEE Advanced among 0.25 million+ candidates

(May 2018)

• Secured a 99.47 percentile in JEE Mains among 0.25 million+ aspirants

(April 2018)

 $\bullet \ \text{Currently ranked } \mathbf{sixth} \ \text{on the basis of cpi among } \mathbf{100} + \ \text{students in Civil Department} \ (\textit{July 2018-present})$

• Recipient of Kishore Vaigyanik Protsahan Yojana out of 0.1 million candidates

(Feb 2018)

• Pursuing a Minor Degree in the Department of Electrical Engineering

(July 2019-present)

Projects Undertakings ____

Autonomous Quadruped Robot

(Sep 2019 - Present)

Stride— IIT Bombay

Technical team

- Part of 17 member team working on autonomous quadruped for its easy manoeuvering on any terrain
- Stabilised an inverted pendulum cart system using Kalman filter with the aid of matlab simulink
- Investigating the field of inverse kinematics and controls for maintaining optimum balance of bot
- Modelled and simulated the rigid-body mechanics of a walking robot using Simscape Multibody

Driverless Car Simulations

(April, 20 - Present)

Guide — Prof. Leena Vacchani and Prof. Arpita Sinha

Summer Project

- Creating interface between ROS and Webots for designing a controller by writing python script
- Designing Artificial Intelligence algorithm for multi-agent patrolling by creating data points for navigation
- Planning the most appropriate path for avoiding static and dynamic obstacles while manoeuvering it

Room service automation robot

(April, 20 - Present)

Golden Oak Projects - Startup in India

Summer Internship

- Building a robot which can automate room services like supplying food items autonomously
- Mapped a room environment, build using gazebo interface, and navigated the bot using **DWA** algorithm
- Interfacing R-pi, teensy, IMUs and lidars for proper SLAM, localization and navigation

Terrace Farming Bot

(Oct 2019-Dec 2019)

Inter IIT technical meet

8th edition

- Designed a lightweight autonomously driven bot which can do the of plowing, seeding and harvesting
- Implemented **PID** controller to control the motion of bot using distance from the wall by ultrasonic sensor
- Worked on development of reliable navigation plan using visual odometry and stepper motor encoders
- Presented the controls mechanism on the behalf of inter IIT tech contingent in the DIC problem statement

Impact Resistance Remote Control Car

(Jan'20 - Present)

Guide- Prof. Leena Vacchani and Prof. Nagamani Jaya Balila

MakerSpace Project

- Designing an carbon fibre composite chassis as it is as high stiffness and tensile stress with low weight
- Aiming to make **shock absorbing tyres** after being inspired from sand flea robot of the Boston Dynamics
- Ideating the CAD Model considering all aspects such as position and alignment of electric components
- Implementing PID control to maintain the position of the bot in a straight line with the help of MPU

Application of Machine Learning in Quantum Mechanics

(April 2019 - July 2019)

Guide - Prof. Alok Shukla, Department of Engineering Physics — IIT Bombay

SURP

- Wrapped up basics of Machine Learning algorithms like Neural Networks, K-means clustering,
- Brushed up the basics of quantum mechanics including energy quantisation and stablity criterion
- Trained a **Neural Network** to find the **minimum energy** of Hydrogen molecule using an open-source

Line Follower Bot using Arduino and IR Sensors

(Jan'19 - Jan'19)

- Implemented a closed-loop PID algorithm using Arduino UNO for controlling L293D motor driver
- Integrated five Infra-red LED Sensors to follow the path consisting of white lines on black background
- Took feedback from sensors to control the direction of bot using differential steering mechanism
- \bullet Successfully able to navigate through all the tracks designed for the competition among 100+ participants

Bluetooth Controlled Bot

(Jan'19 - Jan'19)

Electronics and Robotics Club — IIT Bombay

Flagship Event of ERC

- Made a bot which can be connected to any andriod using the help of **bluetooth module**(HC05) will communicate with microcontroller(**At-tiny**) to give commands to motor driver(L293d).
- Designed an acrylic chassis for it and applied Differential steering mechanism to it for its proper controls.
- Sketched the printed circuit board for the competition using Autodesk software

Technical Strengths —

Programming Python, C++, Matlab, Markdown, Git, CSS, HTML, Octave & LATEX Softwares Webots, ROS, Gazebo, Adams, RViz, CoppeliaSim Player & Auto-CAD Raspberry Pi, Arduino, Node MCU, ESP32 & MPU

Positions of Responsibility _____

Convener

(April'19 - Present)

Electronics and Robotics Club

Institue Technical Council

- Part of a 17 Member Team responsible for introducing & mentoring 1000+ Students in technical field
- Managed Get Mechanised and conducted Get Electrified session for the club's main flagship event, XLR8 attended by 600+ enthusiasts, mainly compromising of fresh year students, across the institute.
- Improved the participation rate by 30% in the XLR8 and enhanced a huge success rate of 92% y/o/y
- Conducted sessions on Arduino, Raspberry Pi, Image Processing and Serial Communication
- Escorted session on MATLAB and taught about implementing PID algorithm on a cart on a hilly terrain

Robowars Coordinator

(April'19 - Jan'20)

Techfest IIT Bombay

Asia's largest technical fest

- International Robowars Competition Co-Ordinator in techfest which have a huge footfall of 175,000+ and a budget exceeding 4 Million compromising of around 15+ international teams
- Canvassed track for the India's largest Robot Combat Competition where participants from around the globe battle each other for the coveted Robowars Competition Title and aided all the participants for it
- Spearheaded a team of 10+ organizers responsible for the planning and execution of 280+ events
- Amplified Techfest's national reach by expanding tech competitions into 125+ colleges across India

Courses Undertaken _

Computational Motion Planning Introduction to Robotics* Linear Control Theory Signals and systems Calculus Differential Equations Robot Motion Planning

ROS: localization, navigation and SLAM Linear and Non-linear Control theory Computer Programming and Utilisation Electronic Devices and circuits Linear Algebra

* to be completed by J 2020

Extracurriculars .

- Replicated thor hammer, which only "worthy" people can access using the mechanism of electromagnetism and RFID sensor among the fresh students in Institute Technical Council orientation
- Mentored a team for the **meshmerize** competition involving path planning for the technical fest, 2019
- Demonstrated an Arduino based game for EnPoWER using the help of 16*2 LCD in UG orientation
- Successfully completed the introduction to machine learning course by Andrew NG on coursera
- Grabbed first position from my hostel in logic GC, organized by Maths and Physics Club, IIT Bombay
- Organized informal events during IIT Bombay's Mood Indigo'18, Asia's Largest Cultural Festival
- Member of the winning team in inter hostel football and cricket general championship
- Served as an NCC cadet in the 2 Maharashtra Engineering Regiment of IITB 2018-19 while being in the selected cadets for the Republic Day Parade '19 and awarded with the NCC ATC certificate
- Represented IIT Bombay in Football, Volleyball, Tug of War and Athletics in Annual Training Camp, 2018
- Counseled school students of BMC under Career Counseling Campaign organized by Abhyuday