Dikshant Civil Engineering Indian Institute of Technology Bombay UG Second Year 180040033

ACADEMIC DETAILS

Examination	University	Institute	Year	CPI/%
Graduation	IIT Bombay	IIT Bombay	2020	8.64
Intermediate/ $+2$	Delhi Public school, Hisar	Delhi Public School, Hisar	2018	91.20
Matriculation	K.L. Arya D.A.V. Public School	K.L. Arya D.A.V. Public School	2016	10.00

SCHOLASTIC ACHIEVEMENTS

• Secured a 97.79 percentile in JEE Advanced among 0.25 million+ candidates

(May 2018)

• Secured a 99.47 percentile in JEE Mains among 0.25 million+ aspirants

(April 2018)

• Currently ranked sixth on the basis of cpi among 100+ students in Civil Department (July 2018-present)

• Recipient of Kishore Vaigyanik Protsahan Yojana out of 0.1 million candidates

(Feb 2018)

• Pursuing a Minor Degree in the Department of Electrical Engineering

(July 2019-present)

PROJECTS UNDERTAKINGS

Autonomous Quadruped Robot

(Sep 2019 - Present)

Stride— IIT Bombay

Technical team

- Part of 17 member team working on autonomous quadruped for its easy manoeuvering on any terrain
- Stabilised an inverted pendulum cart system using Kalman filter with the aid of matlab simulink
- Investigating the field of inverse kinematics and controls for maintaining optimum balance of bot
- Modelled and simulated the rigid-body mechanics of a walking robot using Simscape Multibody

Terrace Farming Bot

(Oct 2019-Dec 2019)

Inter IIT technical meet

8th edition

- Designed a lightweight autonomously driven bot which can do the of plowing, seeding and harvesting
- Implemented **PID** controller to control the motion of bot using distance from the wall by ultrasonic sensor
- Worked on development of reliable navigation plan using visual odometry and stepper motor encoders
- Presented the controls mechanism on the behalf of inter IIT tech contingent in the DIC problem statement

Mini Autonomous Car using Computer Vision

Electronics and Robotics Club — IIT Bombay

(Sep'19 - Present)

Hobby Project

- Using Canny edge detection function for detecting the lanes and Yolo algorithm for object detection
- Operating Convolutional Neural Networks for traffic sign, pedestrian detection and handling
- Ideating and creating the kernel arrays and convolving it with the processed low grayscale input images
- Incorporating raspberry pi camera for video capturing with raspberry pi board for motion control

Impact Resistance Remote Control Car

(Jan'20 - Present)

Guide- Prof. Leena Vacchani and Prof. Nagamani Jaya Balila

MakerSpace Project

- Designing an carbon fibre composite chassis as it is as high stiffness and tensile stress with low weight
- Aiming to make **shock absorbing tyres** after being inspired from sand flea robot of the Boston Dynamics
- Ideating the CAD Model considering all aspects such as position and alignment of electric components
- Implementing PID control to maintain the position of the bot in a straight line with the help of MPU

Autonomous Soldering Bot

(Jan'20 - Present)

Guide- Prof. Abhishek Gupta

Course Project

- Making an robot which have tendency of doing soldering in a straight line on a perforated board
- Simulated a model of this bot on matlab using the **simulink** and identified the equations behind it
- Applying the knowledge of **inverse kinematics** for adjusting the orientation of motors accordingly
- Embracing the arduino for specified controls and designing the printed circuit board using eagle software

Application of Machine Learning in Quantum Mechanics

(April 2019 - July 2019)

Guide - Prof. Alok Shukla, Department of Engineering Physics — IIT Bombay

SURP

- Wrapped up basics of Machine Learning algorithms like Neural Networks, K-means clustering,
- Brushed up the basics of quantum mechanics including energy quantisation and stablity criterion
- Trained a Neural Network to find the minimum energy of Hydrogen molecule using an open-source

Line Follower Bot using Arduino and IR Sensors

Electronics and Robotics Club — IIT Bombay

(Jan'19 - Jan'19) Event of ERC

- Implemented a closed-loop PID algorithm using Arduino UNO for controlling L293D motor driver
- Integrated five Infra-red LED Sensors to follow the path consisting of white lines on black background
- Took feedback from sensors to control the direction of bot using differential steering mechanism
- Successfully able to navigate through all the tracks designed for the competition among 100+ participants

Bluetooth Controlled Bot

(Jan'19 - Jan'19)

Electronics and Robotics Club — IIT Bombay

Flagship Event of ERC

- Made a bot which can be connected to any andriod using the help of **bluetooth module**(HC05) will communicate with microcontroller(**At-tiny**) to give commands to motor driver(L293d).
- Designed an **acrylic chassis** for it and applied Differential steering mechanism to it for its proper controls.
- Sketched the printed circuit board for the competition using Autodesk software

Technical Strengths $_$

Programming C++, Matlab, Python, CSS, HTML, Javascript, Octave & LATEX
Softwares Adams, Arduino IDE, Eagle, Git, OpenCV, ESP 32 IDE & Auto-CAD

Electrical Raspberry Pi, Arduino, Node MCU, ESP32 & MPU

Positions of Responsibility —

Convener - Electronics and Robotics Club-ITC

(April '19 - Present)

- Part of a 17 Member Team responsible for introducing & mentoring 1000+ Students in technical field
- Managed Get Mechanised and conducted Get Electrified session for the club's main flagship event, XLR8 attended by 600+ enthusiasts, mainly compromising of fresh year students, across the institute.
- Improved the participation rate by 30% in the XLR8 and enhanced a huge success rate of 92% y/o/y
- Conducted sessions on Arduino, Raspberry Pi, Image Processing and Serial Communication
- Escorted session on MATLAB and taught about implementing PID algorithm on a cart on a hilly terrain

Techfest Coordinator - Asia's Largest Technical Fest

(April'19 - Present)

- International Robowars Competition Co-Ordinator in techfest which have a huge footfall of 175,000+ and a budget exceeding 4 Million compromising of around 15+ international teams
- Canvassed track for the India's largest Robot Combat Competition where participants from around the globe battle each other for the coveted Robowars Competition Title and aided all the participants for it
- Spearheaded a team of 10+ organizers responsible for the planning and execution of 280+ events
- Amplified Techfest's national reach by expanding tech competitions into 125+ colleges across India

Courses Undertaken ____

Introduction to Robotics* Linear Control Theory Signals and systems Differential Equations Linear Algebra Quantum Physics Linear and Non-linear Control theory Computer Programming and Utilisation Electronic Devices and circuits Calculus Basics of Electricity and Magnetism Structural Mechanics

* to be completed by May 2020

Extracurriculars

- Replicated thor hammer, which only "worthy" people can access using the mechanism of electromagnetism and RFID sensor among the fresh students in Institute Technical Council orientation
- Mentored a team for the **meshmerize** competition involving path planning for the technical fest, 2019
- Demonstrated an Arduino based game for EnPoWER using the help of 16*2 LCD in UG orientation
- Successfully completed the introduction to machine learning course by Andrew NG on coursera
- Grabbed first position from my hostel in logic GC, organized by Maths and Physics Club, IIT Bombay
- Organized informal events during IIT Bombay's Mood Indigo'18, Asia's Largest Cultural Festival
- Member of the winning team in inter hostel football and cricket general championship
- Served as an NCC cadet in the 2 Maharashtra Engineering Regiment of IITB 2018-19 while being in the selected cadets for the Republic Day Parade '19 and awarded with the NCC ATC certificate
- Represented IIT Bombay in Football, Volleyball, Tug of War and Athletics in **Annual Training Camp,2018**
- Counseled school students of BMC under Career Counseling Campaign organized by Abhyuday