

Dikshant Civil Engineering Indian Institute of Technology Bombay Specialization: Civil Engineering 180040033

UG Third Year (B.Tech.)

Male

DOB: 12/12/2000

Examination	University	Institute	Year	CPI / %
Graduation	IIT Bombay	IIT Bombay	2021	8.68
Intermediate/+2	Delhi Public School, Hisar	Delhi Public School, Hisar	2018	91.20
Matriculation	K.L. Arya Public School, Hisar	K.L. Arya Public School, Hisar	2016	10.00

SCHOLASTIC ACHIEVEMENTS __

• Pursuing a Minor Degree in the Department of Electrical Engineering

(July 2019-present)

• Secured a 97.79 percentile in JEE Advanced among 0.15 million+ candidates

(May 2018)

- Currently ranked tenth on the basis of cpi in a batch of 112 students in Civil Department (present)
- Recipient of Kishore Vaigyanik Protsahan Yojana fellowship award given by IISc Bangalore (2018)
- Awarded by **special mention** award by technical council of hostel for excellence in the field (2020)

Projects Undertakings _____

Multi-Agent Patrolling

(April 2020 - present)

Guide — Prof. Leena Vacchani and Prof. Arpita Sinha

Summer Project

- Designing a multi-agent patrolling algorithm using **Deep Q Network** Reinforcement Learning technique
- Formulating an algorithm which will allow smooth movement on any curved road and their junctions
- Created an interface between ROS and Webots for designing a controller for a car on CAIR map
- Planned the most appropriate path for avoiding static and dynamic obstacles while maneuvering map

Autonomous Quadruped Robot

(Sep 2019 - present)

Stride— IIT Bombay

Technical team

- Part of 17 member team working on autonomous quadruped for its easy maneuvering on any terrain
- Stabilised an inverted pendulum cart system using Kalman filter with the aid of matlab simulink
- Investigated the field of inverse kinematics and controls for maintaining optimum balance of bot
- Studied rhythmic movement of each leg of the quadruped robot for optimal gait selection

Terrace Farming Bot

(Oct 2019 - Dec 2019)

Inter IIT technical meet

8th edition

- Designed a lightweight autonomously driven bot which can do the of plowing, seeding and harvesting
- Implemented PID controller to control the motion of bot using distance from the wall by ultrasonic sensor
- Worked on development of reliable navigation plan using visual odometry and stepper motor encoders
- Presented the controls mechanism on the behalf of inter IIT tech contingent in the DIC problem statement

Intelligent Picking Bot

(June 2020 - present)

Flipkart Robotics Challenge

D2C competition

- Working on a bot which is capable of locating, picking and stowing the items in a warehouse autonomously
- Using YOLO algorithm for object detection and OpenCV techniques to find out the grasping point
- Mapped the path between pick and drop area using **SLAM**, and used **A*** algorithm for path planning
- Incorporated MoveIt package for the robotic arm movement and calculated the Jacobian matrix for it

Application of Machine Learning in Quantum Mechanics

(April 2019 - July 2019)

Guide — Prof. Alok Shukla, Department of Engineering Physics — IIT Bombay

SURP

- Wrapped up basics of Machine Learning algorithms like Neural Networks, K-means clustering
- Brushed up the basics of quantum mechanics including **energy quantisation** and **stablity criterion**
- Trained and tested a **Neural Network** to find the **minimum energy** of the Hydrogen molecule
- Received the SURP certificate for satisfactory results and validation of the proofs in the project

Impact Resistance Remote Control Car

(Jan 2020 - March 2020)

Guide — Prof. Leena Vacchani and Prof. Nagamani Jaya Balila

MakerSpace Project

- Designing an carbon fibre composite chassis as it is as high stiffness and tensile stress with low weight
- Aiming to make **shock absorbing tyres** after being inspired from sand flea robot of the Boston Dynamics
- Ideating the CAD Model considering all aspects such as position and alignment of electric components
- Implementing PID control to maintain the position of the bot in a straight line with the help of MPU

Room service automation robot

Golden Oak Projects — Startup in India

(June 2020 - July 2020) Summer Internship

- Building a robot which can automate room services like supplying food items autonomously
- Mapped a room environment, build using gazebo interface, and navigated the bot using **DWA** algorithm
- Interfacing R-pi, arduino, IMUs and lidars for proper SLAM, localization and navigation of the bot

Line Follower Bot using Arduino and IR Sensors

(Jan 2019)

Electronics and Robotics Club — IIT Bombay

Event of ERC

- Implemented a closed-loop PID algorithm using Arduino UNO for controlling L293D motor driver
- Integrated five Infra-red LED Sensors to follow the path consisting of white lines on black background
- Took feedback from sensors to control the direction of bot using differential steering mechanism
- Successfully able to navigate through all the tracks designed for the competition among 100+ participants

Technical Strengths _____

LanguagesPython, C++, Matlab, Git, Octave, CSS, HTML, Markdown & IATEXFrameworksROS, PyTorch, Tensorflow, Keras, OpenCV, Numpy, Pandas & ScikitSoftwaresWebots, Gazebo, Carla, CoppeliaSim Player, Solidworks & Auto-CAD

Electrical Raspberry Pi, Arduino, Node MCU & ESP32

Positions of Responsibility ____

Convener (April'19 - Present)

Electronics and Robotics Club

Institue Technical Council

- Part of a 17 Member Team responsible for introducing & mentoring 1000+ Students in technical field
- ullet Conducted **ROS** session for beginners during quarantine period resulting in high participation of 300+
- Improved the participation rate by 30% in the XLR8 and enhanced a huge success rate of 92% y/o/y
- Conducted sessions on Arduino, Raspberry Pi, Image Processing and Serial Communication
- Escorted session on MATLAB and taught about implementing PID algorithm on a cart on a hilly terrain

Robowars Coordinator

(April'19 - Jan'20)

Techfest IIT Bombay

Asia's largest technical fest

- International Robowars Competition Co-Ordinator in techfest which have a huge footfall of 175,000+ and a budget exceeding 4 Million compromising of around 15+ international teams
- Spearheaded a team of 10+ organizers responsible for the planning and execution of 280+ events
- Amplified Techfest's national reach by expanding tech competitions into 125+ colleges across India

Courses Undertaken

Neural Networks and deep learning Computational Motion Planning Introduction to Robotics Linear Control Theory Signals and systems

Calculus

Differential Equations

Robot Motion Planning
ROS: localization, navigation and SLAM
Digital circuits*
Computer Programming and Utilisation

Electronic Devices and circuits

Linear Algebra

* to be completed by December 2020

Extracurriculars

- Replicated thor hammer, which only "worthy" people can access using the mechanism of electromagnetism and RFID sensor among the fresh students in Institute Technical Council orientation
- Made a bluetooth controlled bot which can be controlled using a mobile app in XLR8 competition
- Mentored a team for the **meshmerize** competition involving path planning for the technical fest, 2019
- Demonstrated an Arduino based game for EnPoWER using the help of 16*2 LCD in UG orientation
- Grabbed first position from my hostel in logic GC, organized by Maths and Physics Club, IIT Bombay
- Organized informal events during IIT Bombay's Mood Indigo'18, Asia's Largest Cultural Festival
- Member of the winning team in inter hostel football and cricket general championship
- Served as an NCC cadet in the 2 Maharashtra Engineering Regiment of IITB 2018-19 while being in the selected cadets for the Republic Day Parade '19 and awarded with the NCC ATC certificate
- Represented IIT Bombay in Football, Volleyball, Tug of War and Athletics in Annual Training Camp, 2018
- Counseled school students of BMC under Career Counseling Campaign organized by Abhyuday