



# Gaussian noise

In signal processing theory, **Gaussian noise**, named after Carl Friedrich Gauss, is a kind of signal noise that has a probability density function (pdf) equal to that of the normal distribution (which is also known as the Gaussian distribution).<sup>[1][2]</sup> In other words, the values that the noise can take are Gaussian-distributed.

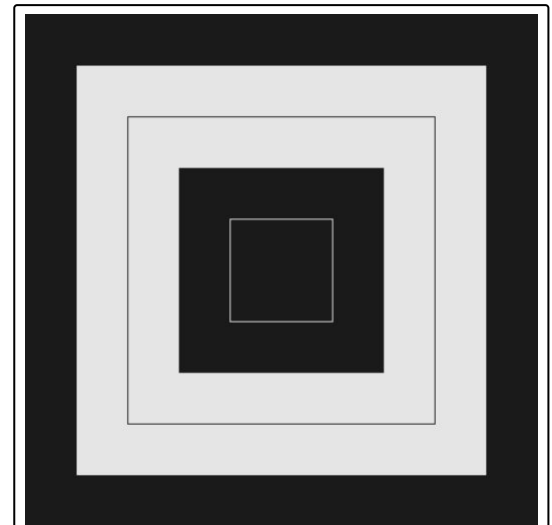
The probability density function ***p*** of a Gaussian random variable ***z*** is given by:

$$\varphi(z) = \frac{1}{\sigma\sqrt{2\pi}} e^{-(z-\mu)^2/(2\sigma^2)}$$

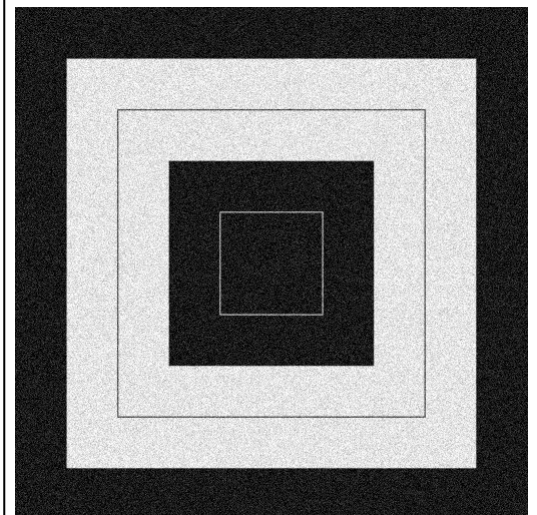
where ***z*** represents the grey level, ***μ*** the mean grey value and ***σ*** its standard deviation.<sup>[3]</sup>

A special case is *white Gaussian noise*, in which the values at any pair of times are identically distributed and statistically independent (and hence uncorrelated). In communication channel testing and modelling, Gaussian noise is used as additive white noise to generate additive white Gaussian noise.

In telecommunications and computer networking, communication channels can be affected by wideband Gaussian noise coming from many natural sources, such as the thermal vibrations of atoms in conductors (referred to as thermal noise or Johnson–Nyquist noise), shot noise, black-body radiation from the earth and other warm objects, and from celestial sources such as the Sun.



Without noise



With Gaussian noise

## Gaussian noise in digital images

Principal sources of Gaussian noise in digital images arise during acquisition e.g. sensor noise caused by poor illumination and/or high temperature, and/or transmission e.g. electronic circuit noise.<sup>[3]</sup> In digital image processing Gaussian noise can be reduced using a spatial filter, though when smoothing an image, an undesirable outcome may result in the blurring of fine-scaled image

edges and details because they also correspond to blocked high frequencies. Conventional spatial filtering techniques for noise removal include: mean (convolution) filtering, median filtering and Gaussian smoothing.<sup>[1][4]</sup>

## See also

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- Gaussian process
- Gaussian smoothing

## References

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1. Tudor Barbu (2013). "Variational Image Denoising Approach with Diffusion Porous Media Flow" (<https://doi.org/10.1155%2F2013%2F856876>). *Abstract and Applied Analysis*. **2013**: 8. doi:10.1155/2013/856876 (<https://doi.org/10.1155%2F2013%2F856876>).
2. Barry Truax, ed. (1999). "Handbook for Acoustic Ecology" ([https://web.archive.org/web/20171010053540/http://www.sfu.ca/sonic-studio/handbook/Gaussian\\_Noise.html](https://web.archive.org/web/20171010053540/http://www.sfu.ca/sonic-studio/handbook/Gaussian_Noise.html)) (Second ed.). Cambridge Street Publishing. Archived from the original ([https://www.sfu.ca/sonic-studio/handbook/Gaussian\\_Noise.html](https://www.sfu.ca/sonic-studio/handbook/Gaussian_Noise.html)) on 2017-10-10. Retrieved 2012-08-05.
3. Philippe Cattin (2012-04-24). "Image Restoration: Introduction to Signal and Image Processing" (<https://web.archive.org/web/20160918164948/https://miac.unibas.ch/SIP/06-Restoration.html>). MIAC, University of Basel. Archived from the original (<http://miac.unibas.ch/SIP/06-Restoration.html>) on 2016-09-18. Retrieved 11 October 2013.
4. Robert Fisher; Simon Perkins; Ashley Walker; Erik Wolfart. "Image Synthesis — Noise Generation" (<http://homepages.inf.ed.ac.uk/rbf/HIPR2/noise.htm>). Retrieved 11 October 2013.

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