

Tribhuvan University
Institute of Science and Technology
2067

Bachelor Level/ First Year/ Second Semester/ Science
Computer Science and Information Technology (MTH 155)
(Linear Algebra)

Full Marks: 80
Pass Marks: 32
Time: 3 hours.

Candidates are required to give their answers in their own words as far as practicable.

The figures in the margin indicate full marks.

Attempt all questions:

Group A

(10x2=20)

1. Illustrate by an example that a system of linear equations has either no solution or exactly one solution.
2. Define singular and nonsingular matrices.
3. Using the Invertible matrix Theorem or otherwise, show that

$$A = \begin{bmatrix} 1 & 0 & -2 \\ 3 & 1 & -2 \\ -5 & -1 & 9 \end{bmatrix}$$

is invertible.

4. What is numerical drawback of the direct calculation of the determinants?
5. Verify with an example that $\det(AB) = \det(A) \det(B)$ for any $n \times n$ matrices A and B.
6. Find a matrix A such that $w = \text{col}(A)$.

$$w = \left\{ \begin{bmatrix} 6a - b \\ a + b \\ -7a \end{bmatrix} : a, b \in \mathbb{R} \right\}.$$

7. Define subspace of a vector with an example.
8. Are the vectors;

$$u = \begin{bmatrix} 6 \\ -5 \end{bmatrix} \text{ and } v = \begin{bmatrix} 3 \\ 2 \end{bmatrix} \text{ eigen vectors of } \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}?$$

9. Find the distance between vectors $u = (7, 1)$ and $v = (3, 2)$. Define the distance between two vectors in \mathbb{R}^n .

10. Let $w = \text{span} \{x_1, x_2\}$, where $x_1 = \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix}$, $x_2 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$.

Then construct orthogonal basis for w.

Group B

(5x4=20)

11. If a set $s = \{v_1, v_2, \dots, v_p\}$ in \mathbb{R}^n contains the zero vector, then prove that the set is linearly dependent. Determine if the set

$$\begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}, \quad \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \quad \begin{bmatrix} 1 \\ 1 \\ 8 \end{bmatrix}$$

is linearly dependent.

12. Given the Leontief input-output model $x = Cx + d$, where the symbols have their usual meanings, consider any economy whose consumption matrix is given by

$$C = \begin{bmatrix} .50 & .40 & .20 \\ .20 & .30 & .10 \\ .10 & .10 & .30 \end{bmatrix}$$

Suppose the final demand is 50 units for manufacturing 30 units for agriculture, 20 units for services. Find the production level x that will satisfy this demand.

13. Define rank of a matrix and state Rank Theorem. If A is a 7×9 matrix with a two-dimensional null space, find the rank of A .

14. Determine the eigen values and eigen vectors of $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ in complex numbers.

OR

Let $A = \begin{bmatrix} 4 & -9 \\ 4 & 8 \end{bmatrix}$, $b_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$, $b_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and basis $B = \{b_1, b_2\}$.

Find the B-matrix for the transformation $x \rightarrow Ax$ with $P = [b_1, b_2]$.

15. Let u and v be nonzero vectors in \mathbb{R}^2 and the angle between them be θ then prove that

$$u \cdot v = \|u\| \|v\| \cos \theta,$$

where the symbols have their usual meanings.

16. Determine if the following homogeneous system has a nontrivial solution. Then describe the solution set.

$$3x_1 + 5x_2 - 4x_3 = 0, \quad -3x_1 - 2x_2 + 4x_3 = 0, \quad 6x_1 + x_2 - 8x_3 = 0.$$

17. An $n \times n$ matrix A is invertible if and only if A is row equivalent to I_n , and in this case, any sequence of elementary row operations that reduces A to I_n also transform $I_{n \times m}$ into A^{-1} .

Use this statement to find the inverse of the matrix $A = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 3 \\ 4 & -3 & 8 \end{bmatrix}$, if exists.

18. What do you mean by basis change? Consider two bases $B = \{b_1, b_2\}$ and $C = \{c_1, c_2\}$ for a vector space V , such that $b_1 = 4c_1 + c_2$ and $b_2 = 6c_1 + c_2$. Suppose $[x]_B = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ i.e., $x = 3b_1 + b_2$. Find $[x]_C$.

OR

Define basis of a subspace of a vector space.

Let $v_1 = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$, $v_2 = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}$, $v_3 = \begin{bmatrix} 6 \\ 16 \\ -5 \end{bmatrix}$, where $v_3 = 5v_1 + 3v_2$, and let $H = \text{span}\{v_1, v_2, v_3\}$.

Show that $\text{span}\{v_1, v_2, v_3\} = \text{span}\{v_1, v_2\}$ and find a basis for the subspace H .

19. Diagonalize the matrix $A = \begin{bmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{bmatrix}$, if possible.

20. What do you mean by least-squares lines? Find the equation $y = \beta_0 + \beta_1 x$ of the least-squares line that fits the data points $(2, 1)$, $(5, 2)$, $(7, 3)$, $(8, 3)$.

OR

Find the least-squares solution of $Ax = b$ for

$$A = \begin{bmatrix} 1 & 3 & 5 \\ 1 & 1 & 0 \\ 1 & 1 & 2 \\ 1 & 3 & 3 \end{bmatrix}, \quad b = \begin{bmatrix} 3 \\ 5 \\ 7 \\ -3 \end{bmatrix}.$$