

Year 2068

Attempt all question:

Group A

(10 × 2 = 20)

1. Write down the conditions for consistent of non-homogenous system of linear equations.
2. What is meant by independent of vectors?
3. What is normal form of a matrix?
4. Define nonsingular linear transformation with suitable example.
5. Consider the matrix $A = \begin{pmatrix} 2 & 5 \\ 1 & 7 \end{pmatrix}$ as a linear mapping. Write the corresponding co-ordinate equations.
6. State the numerical importance of determinant calculation by row operation.
7. Show that $\{(1,1), (-1,0)\}$ form a basis for R^2 .
8. Let $T: R^2 \rightarrow R^2$ be a linear transformation defined by
 $T(x, y) = (x + y, y)$. Find Ker T.
9. If λ is an eigen values of matrix A, find the eigen values of A^{-1} .
10. Let $u = (1, 2, -1, 3)$ and $v = (3, 0, 2, -2)$. Compute the inner product $(u, u + v)$.

Group B

(5 × 4 = 20)

11. Determine whether the following vectors in R^3 are linearly dependent:
 - a. $(1, 0, 1), (1, 1, 0), (-1, 0, -1)$,
 - b. $(2, 1, 1), (3, -2, 2), (-1, 2, -1)$.
12. Investigate and interpret geometrically the transformation of the unit square whose vertices are $O(0,0,1), A(1,0,1), B(0,1,1)$ and $C(1,1,1)$ effected by the 3×3 matrix:

$$\begin{bmatrix} 1 & 1 & a \\ 0 & 1 & b \\ 0 & 0 & 1 \end{bmatrix}$$

OR

Is the set of vectors $\{(1,0,1), (0,1,0), (-1,0,1)\}$ orthogonal? Obtain the corresponding orthonormal set in R^3 .

13. In the vector space R^2 , express the given vector $(1,2)$ as a linear combination of the vectors $(1,-1)$ and $(0,1)$
14. Find the matrix representation of the linear transformation $T: R^2 \rightarrow R^2$ defined by $T(x,y) = (x, x+2y)$ relative to the basis $(1,0)$ and $(1,1)$
15. Let u and v be nonzero vector in R^n and the angle between them be θ . Then prove that

$$u \cdot v = \|u\| \|v\| \cos \theta$$

Where the symbol have their usual meanings.

Group C

(5×8=40)

16. Test for consistency and solve:

$$2x - 3y + 7z = 5$$

$$3x + y - 3z = 13$$

$$2x + 19y - 47z = 32$$

17. Let U and V be vector spaces over a field and assume that $\dim U = \dim V$. If $T: U \rightarrow V$ is a linear transformation, then prove that the following are equivalent;
 - i. T is invertable
 - ii. T is one-one and onto, and
 - iii. T is non-singular

OR

Verify that the set of matrices of the form $\begin{bmatrix} 0 & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{bmatrix}$ is a subspace of the vector space of 3×3 matrices.

18. Verify Cayley-Hamilton Theorem for matrix:

$$A = \begin{bmatrix} 6 & 2 & -1 \\ -6 & -1 & 2 \\ 7 & 2 & -2 \end{bmatrix}$$

19. Diagonalize the matrix $A = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 2 & -1 \\ 0 & 0 & 3 \end{bmatrix}$

OR

Compute the multiplication of partitioned matrices for

$$A = \begin{bmatrix} 1 & 2 & 4 & 6 & 7 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 2 & 3 & 6 & -1 \end{bmatrix} \text{ and } B = \begin{bmatrix} 0 & -12 \\ 2 & 3 & 1 \\ 1 & 4 & 5 \\ 2 & 2 & 0 \\ 0 & 7 & 6 \end{bmatrix}$$

20. Find the equation $y = \beta_0 + \beta_1 x$ for the least squares line that best fits the data points $(2, 0)$, $(3, 4)$, $(4, 10)$, $(5, 16)$.