

Tribhuvan University
Institute of Science and Technology
2074



Bachelor Level / First Year / Second Semester / Science
Computer Science and Information Technology (MTH. 155)
(Linear Algebra)

Full Marks: 80
Pass Marks: 32
Time: 3 hours.

Candidates are required to give their answers in their own words as far as practicable.
The figures in the margin indicate full marks.
Attempt all questions:

Group A

(10×2=20)

1. What are the criteria for a rectangular matrix to be in echelon form?
2. Prove that (a) $(A^T)^T = A$ (b) $(A + B)^T = A^T + B^T$, Where A and B denote matrices whose size are appropriate for the above mentioned operations.
3. Define square matrix. Can a square matrix with two identical columns be invertible? Why or why not?
4. Let A and B be two square matrices. By taking suitable examples, show that even though AB and BA may not be equal, it is always true that $\det AB = \det BA$.

5. Using Cramer's rule solve the following simultaneous equations:

$$\begin{aligned} 5x + 7y &= 3 \\ 2x + 4y &= 1 \end{aligned} \quad \text{5/6, 1-2/6}$$

6. Define vector space with suitable examples.

7. Let W be the set of all vectors of the form $\begin{bmatrix} 5b + 2c \\ b \\ c \end{bmatrix}$, where b and c are arbitrary. Find vector u and v such that $W = \text{Span}\{u, v\}$.

8. What are necessary and sufficient conditions for a matrix to be invertible?

9. Determine whether the pair of vectors $u = \begin{bmatrix} 12 \\ 3 \\ -5 \end{bmatrix}$ and $v = \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix}$ are orthogonal or not?

10. What do you understand by least square line? Illustrate.

Group B

(5×4=20)

11. What are the criteria for a transformation T to be linear? If $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is defined by $T(x) = 3x$, show that T is a linear transformation. Also give a geometric description of the transformation

$$x \mapsto Ax, \text{ where } A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

12. Prove that if A is an invertible matrix, then so is A^T , and the inverse of A^T is the transpose of A^{-1} .
13. Define subspace of a vector space V . Given v_1 and v_2 in a vector space V , let $H = \text{span} \{v_1, v_2\}$. Show that H is a subspace of V .

OR

If $\mathcal{B} = \{b_1, \dots, b_n\}$ is a basis for a vector space V and x is in V , define the coordinate of x relative to

the basis \mathcal{B} . Let $v_1 = \begin{bmatrix} 3 \\ 6 \\ 2 \end{bmatrix}$, $v_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$, $x = \begin{bmatrix} 3 \\ 12 \\ 7 \end{bmatrix}$, $\mathcal{B} = \{v_1, v_2\}$. Then \mathcal{B} is a basis for $H = \text{Span}$

$\{v_1, v_2\}$. Determine if x is in H , and if it is, find the coordinate vector of x relative to \mathcal{B} .

14. The mapping $T: P_2 \rightarrow P_2$ defined by $T(a_0 + a_1t + a_2t^2) = a_1 + 2a_2t$ is a linear transformation.

a) Find the \mathcal{B} -matrix for T , when \mathcal{B} is the basis $\{1, t, t^2\}$.

b) Verify that $[T(p)]_{\mathcal{B}} = [T]_{\mathcal{B}}[p]_{\mathcal{B}}$ for each p in P_2 .

15. Let $A = \begin{bmatrix} 1 & -3 & -3 \\ 1 & 5 & 1 \\ 1 & 7 & 2 \end{bmatrix}$ and $b = \begin{bmatrix} 5 \\ -3 \\ -5 \end{bmatrix}$. Find a least square solution of $Ax = b$, and compute the

associated least square error.

Group C

(5×8=40)

16. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation and let A be the standard matrix for T . Then prove that: T map \mathbb{R}^n on to \mathbb{R}^m if and only if the columns of A span \mathbb{R}^m ; and T is one-to-one if and only if the columns of A are linearly independent. Let $T(x_1, x_2) = (3x_1 + x_2, 5x_1 + 7x_2, x_1 + 3x_2)$. Show that T is a one-to-one linear transformation. Does T map \mathbb{R}^2 onto \mathbb{R}^3 ?

17. Compute the multiplication of partitioned matrices for

$$A = \left[\begin{array}{ccc|cc} 2 & -3 & -1 & 0 & -2 \\ 1 & 5 & -2 & 3 & -1 \\ 0 & 4 & 1 & 7 & -3 \end{array} \right]$$

and $B = \left[\begin{array}{cc} 6 & 4 \\ -2 & 3 \\ -3 & 7 \\ -1 & 2 \\ 5 & 3 \end{array} \right]$

18. Let $\mathcal{B} = \{b_1, \dots, b_n\}$ be a basis for a vector space V . Then the coordinate mapping $x \mapsto [X]_{\mathcal{B}}$ is

one-to-one linear transformation from V into \mathbb{R}^n . Let $b_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $b_2 = \begin{bmatrix} -3 \\ 4 \\ 0 \end{bmatrix}$, $b_3 = \begin{bmatrix} 3 \\ -6 \\ 3 \end{bmatrix}$, and

$$x = \begin{bmatrix} -8 \\ 2 \\ 3 \end{bmatrix}.$$

- Show that the set $\mathcal{B} = \{b_1, \dots, b_n\}$ is a basis of \mathbb{R}^3 .
- Find the change-of-coordinates matrix for \mathcal{B} to the standard basis.
- Write the equation that relates x in \mathbb{R}^3 to $[x]_{\mathcal{B}}$.
- Find $[x]_{\mathcal{B}}$ for the x give above.

19. Diagonalize the matrix $\begin{bmatrix} 7 & 4 & 16 \\ 2 & 5 & 8 \\ -2 & -2 & -5 \end{bmatrix}$ if possible.

OR

Suppose $A = PDP^{-1}$, where D is a diagonal $n \times n$ matrix. If \mathcal{B} is the basis for \mathbb{R}^n formed for the columns of P , then prove that D is the \mathcal{B} matrix for the transformation $x \mapsto Ax$. Define

$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(x) = Ax$, where $A = \begin{bmatrix} 7 & 2 \\ -4 & 1 \end{bmatrix}$. Find a basis \mathcal{B} for \mathbb{R}^2 with the property that the \mathcal{B} -matrix for T is a diagonal matrix.

20. What is a least squares solution? Find a least squares solution of $Ax = b$, where $A = \begin{pmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{pmatrix}$,

$$b = \begin{pmatrix} 2 \\ 0 \\ 11 \end{pmatrix}.$$

OR

What do you understand by orthonormal set? Show that $\{v_1, v_2, v_3\}$ is an orthonormal basis of \mathbb{R}^3 , where

$$v_1 = \begin{bmatrix} 3/\sqrt{11} \\ 1/\sqrt{11} \\ 1/\sqrt{11} \end{bmatrix}, v_2 = \begin{bmatrix} -1/\sqrt{6} \\ 2/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}, \text{ and } v_3 = \begin{bmatrix} -1/\sqrt{66} \\ -4/\sqrt{66} \\ 7/\sqrt{66} \end{bmatrix}.$$

Prove that an $m \times n$ matrix U has orthonormal columns if and only if $U^T U = I$.