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# IMPORTANT: RUN THIS CELL IN ORDER TO IMPORT YOUR KAGGLE DATA SOURCES,
# THEN FEEL FREE TO DELETE THIS CELL.
# NOTE: THIS NOTEBOOK ENVIRONMENT DIFFERS FROM KAGGLE'S PYTHON
# ENVIRONMENT SO THERE MAY BE MISSING LIBRARIES USED BY YOUR
# NOTEBOOK.
import kagglehub
wjybuqi_traffic_light_detection_dataset_path = kagglehub.dataset_download('wjybuqi/traffic-light-detection-dataset')
print('Data source import complete.')
# This Python 3 environment comes with many helpful analytics libraries installed
# It is defined by the kaggle/python Docker image: <a href="https://github.com/kaggle/docker-python">https://github.com/kaggle/docker-python</a>
# For example, here's several helpful packages to load
import numpy as np # linear algebra
import pandas as pd # data processing, CSV file I/O (e.g. pd.read_csv)
\# Input data files are available in the read-only "../input/" directory
# For example, running this (by clicking run or pressing Shift+Enter) will list all files under the input directory
import os
# for dirname, _, filenames in os.walk('/kaggle/input'):
        for filename in filenames:
              print(os.path.join(dirname, filename))
# You can write up to 20GB to the current directory (<a href="//kaggle/working/">/kaggle/working/</a>) that gets preserved as output when you create a version
# You can also write temporary files to /kaggle/temp/, but they won't be saved outside of the current session
# Implementation based on https://learnopencv.com/mask-r-cnn-instance-segmentation-with-pytorch/
import matplotlib.pyplot as plt
from PIL import Image
import torch
import torchvision
from torchvision import transforms as T
from cv2 import cv2
import random
model = torchvision.models.detection.maskrcnn_resnet50_fpn(pretrained=True)
model.eval()
def random_colour_masks(image):
  colours = [[0, 255, 0],
                   [0, 0, 255],
                   [255, 0, 0],
                   [0, 255, 255],
                   [255, 255, 0],
                   [255, 0, 255],
                   [80, 70, 180],
                   [250, 80, 190],
                   [245, 145, 50],
                   [70, 150, 250],
                   [50, 190, 190]]
  r = np.zeros_like(image).astype(np.uint8)
  g = np.zeros_like(image).astype(np.uint8)
  b = np.zeros_like(image).astype(np.uint8)
  r[image == 1], g[image == 1], b[image == 1] = colours[random.randrange(0,10)]
  coloured_mask = np.stack([r, g, b], axis=2)
   return coloured_mask
     D_INSTANCE_CATEGORY_NAMES = [

'__background__', 'person', 'bicycle', 'car', 'motorcycle', 'airplane', 'bus',

'train', 'truck', 'boat', 'traffic light', 'fire hydrant', 'N/A', 'stop sign',

'parking meter', 'bench', 'bird', 'cat', 'dog', 'horse', 'sheep', 'cow',

'elephant', 'bear', 'zebra', 'giraffe', 'N/A', 'backpack', 'umbrella', 'N/A', 'N/A',

'handbag', 'tie', 'suitcase', 'frisbee', 'skis', 'snowboard', 'sports ball',

'kite', 'baseball bat', 'baseball glove', 'skateboard', 'surfboard', 'tennis racket',

'bottle', 'N/A', 'wine glass', 'cup', 'fork', 'knife', 'spoon', 'bowl',

'banana', 'apple', 'sandwich', 'orange', 'broccoli', 'carrot', 'hot dog', 'pizza',

'donut', 'cake', 'chair', 'couch', 'potted plant', 'bed', 'N/A', 'dining table',

'N/A', 'N/A', 'toilet', 'N/A', 'tv', 'laptop', 'mouse', 'remote', 'keyboard', 'cell phone',

'microwave', 'oven', 'toaster', 'sink', 'refrigerator', 'N/A', 'book',

'clock', 'vase', 'scissors', 'teddy bear', 'hair drier', 'toothbrush'
COCO_INSTANCE_CATEGORY_NAMES = [
      'clock', 'vase', 'scissors', 'teddy bear', 'hair drier', 'toothbrush'
]
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def get_prediction(img_path, threshold):
 img = Image.open(img_path)
 transform = T.Compose([T.ToTensor()])
 img = transform(img)
 pred = model([img])
 pred_score = list(pred[0]['scores'].detach().numpy())
 pred_t = [pred_score.index(x) for x in pred_score if x>threshold][-1]
 masks = (pred[0]['masks']>0.5).squeeze().detach().cpu().numpy()
 pred_class = [COCO_INSTANCE_CATEGORY_NAMES[i] for i in list(pred[0]['labels'].numpy())]
 pred\_boxes = [[(i[0], i[1]), (i[2], i[3])] \ for \ i \ in \ list(pred[0]['boxes'].detach().numpy())]
 masks = masks[:pred_t+1]
 pred_boxes = pred_boxes[:pred_t+1]
 pred_class = pred_class[:pred_t+1]
 return masks, pred_boxes, pred_class
def instance_segmentation_api(img_path, threshold=0.5, rect_th=3, text_size=3, text_th=3):
 masks, boxes, pred_cls = get_prediction(img_path, threshold)
 img = cv2.imread(img_path)
 img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
 for i in range(len(masks)):
    rgb_mask = random_colour_masks(masks[i])
    img = cv2.addWeighted(img, 1, rgb_mask, 0.5, 0)
    ## following lines are fixed compared to the original source of the code
   cv2.rectangle(img,
                  (int(boxes[i][0][0]),int(boxes[i][0][1])),
                  (int(boxes[i][1][0]),int(boxes[i][1][1]))
                  ,color=(0, 255, 0), thickness=rect_th)
   cv2.putText(img,pred_cls[i], (int(boxes[i][0][0]),int(boxes[i][0][1])), cv2.FONT_HERSHEY_SIMPLEX, text_size, (0,255,0),t
 plt.figure(figsize=(20,30))
 plt.imshow(img)
 plt.xticks([])
 plt.yticks([])
 plt.show()
img = Image.open('/kaggle/input/traffic-light-detection-dataset/test\_dataset/test\_images/02585.jpg')
display(img)
instance_segmentation_api('/kagqle/input/traffic-light-detection-dataset/test_dataset/test_images/02585.jpg')
```