

University of Moratuwa

CIRCUITS AND SYSTEMS EN3030 TEAM ZIGMA

RISC-V processor Design

Group members:

Jayashinghe D.R. 190262L Mathotaarachchi M.M. 190388D Rukmal M.A.D. 190531L Udara A.G.N. 190636M

Lecturer:

Dr. Ajith Pasqual



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1 Introduction

A processor is an integrated electronic circuit that performs the calculations that run a computer. A processor performs arithmetical, logical, input/output, and other basic instructions that are passed from an operating system. Most other processes are dependent on the operations of a processor.

As a fulfillment for EN3030 module project, we were tasked with designing and implementing a RISC-V RV32I processor with a direct mapping cache having victim cache functionality. This document is the final fulfillment of our project.

1.1 Functionality

We designed our processor to support single-cycle instructions and the instruction types that our processor supports are as follows.

- R Type
- I Type
- S Type
- SB Type
- U Type
- UJ Type

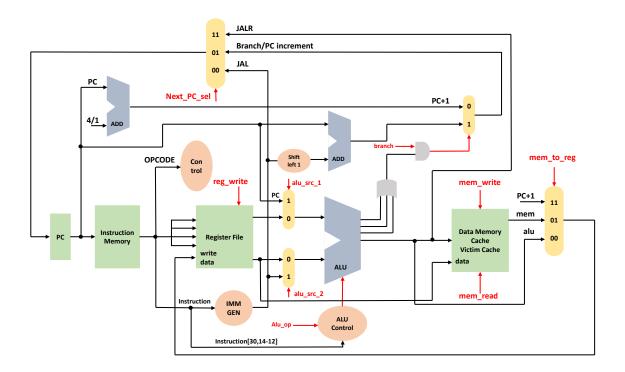


Figure 1: Datapath



2 Method

Our design comprises with following sub parts.

- Program counter
- PC selection and branching
- CLK input and management
- Main Control Unit
- Instruction Memory
- Instruction Decode
- Register File
- ALU input selection
- ALU
- ALU Control
- Data Memory

2.1 Program counter

In RISC-V, the program counter (PC) is a special register that holds the address of the instruction being executed. This is 32-bit in size. The PC is automatically incremented by 4 (for 32-bit implementations) after each instruction is executed, to keep track of the sequence of instructions in the program.

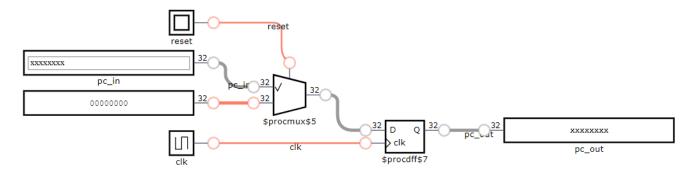


Figure 2: PC RTL view

The RISC-V architecture provides a set of instructions for manipulating the PC, including jump and branch instructions. The branch instructions can be used to change the flow of execution in a program by updating the PC with the address of a target instruction. In RISC-V, the PC is also used to implement subroutines and other control structures. When a subroutine is called, the current value of the PC is pushed onto the stack, and



the PC is updated with the address of the first instruction in the subroutine. When the subroutine returns, the PC is popped from the stack, returning control to the instruction called the subroutine.

In our implementation, PC is initiated to 0 and we have designed the instruction memory with the memory width of a word. So after the instruction is executed we need to increment the PC only by 1 (not by 4). The triggering signal to the PC is the clock. At the positive edge of the clock, the PC register gives the next PC value as the output. For increment the PC, a simple adder is used. This adder adds 1 to the current value of the PC and generates the new PC value.

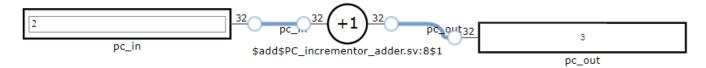


Figure 3: PC incrementor RTL view

2.2 PC selection and branching

Branching is a fundamental aspect of computer architecture, and it refers to the process of determining the next instruction to be executed based on the outcome of a previous instruction. In the RISC-V architecture, branching is performed using the program counter (PC) register.

In RISC-V, branching can occur in two ways: unconditional branching and conditional branching.

- Unconditional Branching: In unconditional branching, the program execution is transferred to a specified address regardless of the outcome of any previous instruction. This is achieved by loading the desired target address into the PC register. "jal" and "jalr" are the two instructions responsible for this.
- Conditional Branching: In conditional branching, the program execution is transferred to a specified address only if a certain condition is met. This is achieved using conditional branches, such as "beq" (branch if equal) or "bne" (branch if not equal). These instructions compare the values in two registers, and based on the result of the comparison, the PC register is updated with the target address or the next instruction address is fetched from the current PC value.

In both cases, the branching operation is performed by updating the value in the PC register. So there should be a separate adder to increment the PC count by a supplied value from the instruction. For that, an adder was implemented to add the immediate offset to the current PC value and calculate the next PC value.

For branching instructions, we raised three flags from ALU.

- "eq" branch if r1 and r2 register values are equal.
- "a lt b" branch if r1 value is less than r2 value .
- "a lt ub" branch if unsigned r1 value less than unsigned r2 value.



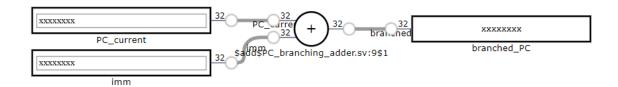


Figure 4: Immediate offset adder to PC RTL view

The logic was designed to generate a branching command if at least one flag is raised with branch control signal from the control unit.

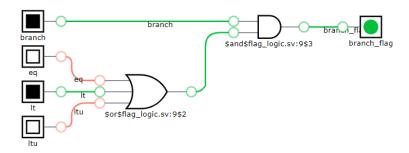


Figure 5: Branching logic RTL view

The branching command is used to select how next PC address is calculated with a help of multiplexer.

Branch command	Operation
0	PC increment by 1
1	PC shift by given offset

Other than branching instructions, unconditional jump instructions also change the PC value by a given amount. So we had to choose the next PC value from "branched_PC", "JAL" and "JALR". For this, we generated 'next_pc_sel' command from control logic and gives the correct next PC value to PC with the help of another multiplexer.

${ m next_pc_se}$	l next_PC
10	JALR
00	PC+imm or PC+1
01	JAL

2.3 CLK and input management

The inputs for the RISC V are,

- Input clock.
- Reset.



• Instructions.

The Input clock provides timing sense for the RISC V and the reset pin input provides the reset functionality for the register bank and PC counter. It will initiate the modules to be 0. The instructions are provided via a .mif file containing HEX codes for the program. You can pass the instruction data in the real-time via Quartus In-System Memory Content Editor. The memory is created using an IP core of a 1 port RAM. The clock is provided via a high 50MHZ for the module to get combinations logic behaviour. The base clock for the other modules are 50KHZ. A clock divider is used for the clock slowing. We have to downgrade the clock to provide enough timing for the combinations delays.

2.4 Instruction Memory

A Single clocked, 1 port RAM IP core from the Quartus to use an inbuilt memory module. This provides the ability to Read and write data to the registers in run time. There will be 32Bit instructions and 1024 total instructions at a time. This can be extended if there is need to be.

2.5 Instruction Decode

With the different type of instructions, the instruction encoding is different. We can differentiate them mostly by the 7 bit opcode. We have identified 9 types of instructions,

- Arithmetic and Shift Operations based on R instructions.
- Immediate Operations with Arithmetic and logic operations.
- Load Operations, with similar syntax to Immediate Operations.
- Store Operations.
- Branch Jump Operations.
- J type.
- JALR with similar syntax to Immediate Operations.
- Upper type, LUI.
- Upper AUIPC.

2.6 Register Bank

With Total of 32 registers, our design have only one hardwired register which provides integer 0, located at address 0. All other registers are to be used as anyway user like. There are no constrains.

Decoded data from instructions will provide input addresses for the module. The Write enable is provided by the Main Control Unit. With a clock event, after the all calculations are done, we will write to the provided address, if the instruction is required to do so.



Inputs		
Register Address 1	For register output selection	
Register Address 2	For register output selection	
Write Address	Where to be stored the data	
Write Enable	If writing needs to be done	
Write Data	The data which need to be stored	
Clock	Timing event for the Data writing process	
Outputs		
Data 1	Data stored at location of Address 1	
Data 2	Data stored at location of Address 2	

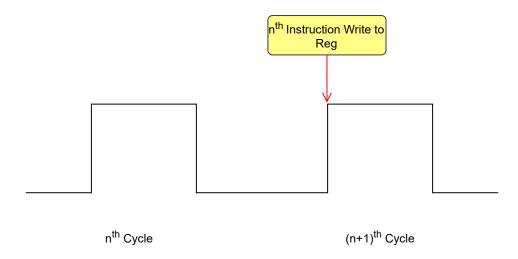


Figure 6: Clock Details for reg

In the single-cycle design, we have to restrict clock usage as much as possible. Here, the clock trigger is used only for register write.

Since the PC increment also happen at the same clock trigger, with the path delays, the access of the written data from the previous instruction writing will not be a problem.

2.7 ALU input selection

For the inputs of ALU, We have to choose between 4 inputs.

- Register input 1
- PC
- Register input 2
- Immediate value

There are two independent 2×1 multiplexers to Select for two inputs of the ALU unit. The multiplexers are controlled with 2 flags provided by the control unit and the flags are dependent on the opcodes. For further clarifications refer to the Main controller section.



2.8 ALU

To execute all the Arithmetic and Logic tasks except for the PC increment and branching increment, we rely on the ALU of our processor.

It has total of 11 tasks. Getting control signals from ALU control unit with help of 4bit FCODE, we can differentiate those unique tasks.

Task	FCODE
Add Two Numbers	0000
Subtract Two Numbers	0001
Left Shift One Number	0010
Signed Compare	0011
Unsigned Compare	0100
XOR bitwise	0101
Right Shift	0110
Signed Right Shift	0111
OR	1000
AND	1001
Address Save and Jump	1010

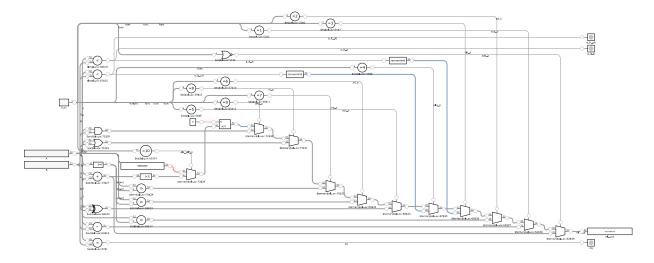


Figure 7: ALU RLT view

2.9 Data Memory

RISC-V is a load-store architecture, which means that all data processing operations are performed on data stored in registers. The data memory of a RISC-V processor consists of two types of memory: cache memory(with victim cache functionality) and main memory. Cache memory is a small, fast memory that is used to temporarily store frequently accessed data. It is typically divided into multiple levels, with each level having a larger size and a longer access time than the previous level. The purpose of the cache memory is to reduce the time it takes to access data from the main memory, which is slower. Main memory is the primary storage area for data in a RISC-V processor. It is typically



composed of DRAM (dynamic random access memory) chips and is organized into a hierarchy of memory banks, with each bank consisting of multiple memory modules. The size and speed of the main memory depend on the specific implementation of the RISC-V processor.

A victim cache is a hardware cache designed to decrease conflict misses and improve hit latency for direct-mapped caches. It is employed at the refill path of a Level 1 cache, such that any cache line which gets evicted from the cache is cached in the victim cache. The RISC-V architecture provides instructions for loading data from memory into registers and storing data from registers into memory. These instructions can be used to read and write data from the cache memory and main memory. Two control signals and two inputs (one from ALU and one from the register file) come into the data memory and one output comes out from the data memory.

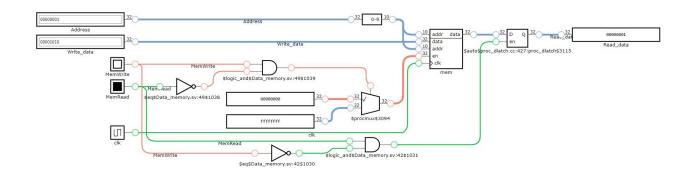


Figure 8: Data Memory RTL view

3 Control Signals

The control signals for the datapath are generated by 2 units; main controller and ALU controller.

3.1 Main Controller

The main controller gives the necessary control signals to the modules with the single cycle datapath. The main control unit takes as input the 7-bit opcode from the instruction and it outputs 9 control signals. The following table contains the control signal types and their destinations.



Control Signal	Signal bit size	Function
alu cre 1	1	Select the first input to the ALU
alu_src_1	1	(data from register file or PC)
		Select the second input to the ALU (data
alu_src_2	1	from register file or immediate value from
		instruction)
	2	Select which data is written to the register
mem_to_reg		file at the mux (data from memory, ALU
		output or incremented PC)
reg_write	1	Enable data write to registerfile
mom road	1	Enable memory read for load
mem_read	1	instruction
mom write	1	Enable memory write for store
mem_write	1	instruction
branch	1	Enable branching
alu on	2	This signal is sent to the ALU controller
alu_op		indicating the ALU operation type
next_pc_sel	2	Selects the next value of the PC

Table 1: Main control signals

3.2 ALU Controller

The ALU controller takes 2 inputs. One input is the 2-bit alu_op which comes from the main control unit and other input is 4 bits decoded from the intructions. These 4 bits comes from the function 3 (Instruction[14:12]) and the 6th bit of function 7 (Instruction[30]) in the instruction. Based on the input signals the ALU controller will output a 4-bit signal which will correspond to the ALU function required by the instruction such as addition, subtraction, bit shifting, comparison, etc.

The ALU OP from main controller categorises the signals into 4 types based on the opcode.

ALU Op	Relevant instructions
00	I-type (load) and S-type
01	SB-type (branching)
10	R-type and I-type (execpt load)
11	U-type and J-type

Table 2: ALU OP signal taken as input to ALU controller

4 Discussion

4.1 Processor Specifications

Following area some of the specifications of the processor we finally designed.



ALU Op	Relevant instructions
00	I-type (load) and S-type
01	SB-type (branching)
10	R-type and I-type (execpt load)
11	U-type and J-type

Table 3: Processor specifications

4.2 Verifying the Funcationality

Designing individual modules

We took a modular approach to processor design by initally designing the individual functional blocks such as the ALU, resignster file, controller, memory, etc. We used System Verilog as our HDL. We tested them individually using test benches on EDA simulation tools avaible on Xilinx Vivado and Modelsim Altera.

Creating the top module and simulations

After verifying the functionality of the individual blocks we moved on to connecting them in the top module. Here had to resolve several issues related to setting the clock. After that, we moved on to testing the top module using a testbench. Since our datapath was complete, we started testing our instructions. During this stage of testing, we were able to find some issues with modules which we have not encountered before, as well as connectivity issues. After resolving them we were able to successfully execute a sequence of instructions and verify the functionality through simulation.

FPGA implementation

We were given the Altera DE2-115 FPGA board. We used the Quartus II to program the FPGA. The main issue we encountered during our FPGA implementation was with the original 50MHz clock begin too fast. We used a clock divider module and got the clock down to a suitable value. We found that the maximum clock at which we could execute instructions without any timing issue was about 400Khz. After resolving some other minor error, we were able to successfully run several programs in our processor. We tested a few codes that covered the range of our instructions. To read the internal values of the registers during runtime, we used the tool SingalTap Logic Analyser avaible in Quartus Environment. As, for the instruction memory, we used a RAM block avaiable in Quartus to load the instructions.



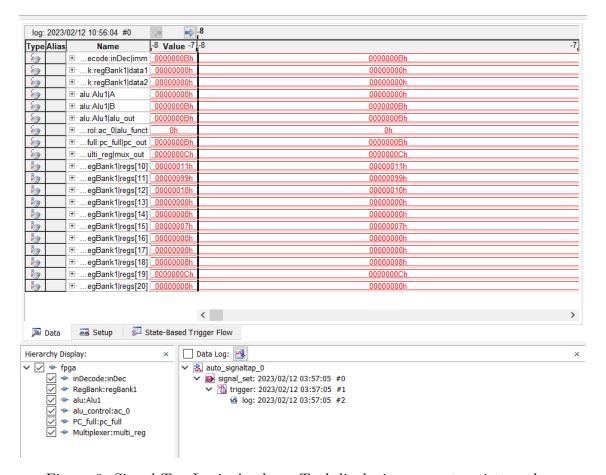


Figure 9: Signal Tap Logic Analyser Tool displaying current register values

5 Conclusion

The RISC-V processor we designed can be used for a range of applications mainly based on integer arithmetic. With our testing we were able to verify the possibility of executing programs containing control loops, arrays, etc.

By extending this instruction set, this processor can be made to support system instructions and floating point numbers. Through optimization, the processor can be made to run at a higher clock. By implementing the datapath using pipe-lining instead of single cycle design, the CPU time can be greatly increased.



6 Appendix

Instruction Set

Mnemonic	Instruction	Description	
R type			
ADD rd, rs1, rs2	Addition	rd <= rs2 + rs1	
SUB rd, rs1, rs2	Subtraction	rd <= rs2 - rs1	
SLL rd, rs1, rs2	Shift Left Logic	rd <= rs1 <<< rs2 (only by lower 5 bits in rs2)	
SLT rd, rs1, rs2	Set Less Than	if rs1 < rs2: rd <= 1, if rs1 >= rs2: rd <= 0	
SLTU rd, rs1, rs2	Set Less Than Unsigned	if rs1 < unsigned(rs2): rd <= 1, if rs1 >= unsigned(rs2): rd <= 0	
XOR rd, rs1, rs2	XOR Logic	rd <= rs1 ^ rs2	
SRL rd, rs1, rs2	Shift Right Logic	rd <= rs1 >>> rs2 (only by lower 5 bits in rs2)	
SRA rd, rs1, rs2	Shift Right Arithmetic	rd <= rs1 >> rs2 (only by lower 5 bits in rs2)	
OR rd, rs1, rs2	OR Logic	rd <= rs1 rs2	
AND rd, rs1, rs2	AND Logic	rd <= rs1 & rs2	
I type			
ADDI rd, rs1, imm	Add Immediate	rd <= rs1 + imm	
SLTI rd, rs1, imm	Set Less Than Immediate	if rs1 < imm: rd <= 1, If rs1 >= imm: rd <= 0	
SLTIU rd, rs1, imm	Set Less Than Immediate Unsigned	if rs1 < unsigned(imm): rd <= 1, If rs1 >= unsigned(imm): rd <= 0	

XORI rd, rs1, imm	XOR Immediate	rd <= rs1 ^ imm	
ORI rd, rs1, imm	OR Immediate	rd <= rs1 imm	
ANDI rd, rs1, imm	AND Immediate	rd <= rs1 & imm	
SLLI rd, rs1, shamt	Shift Left Logic Immediate	rd <= rs1 <<< shamt	
SRLI rd, rs1, shamt	Shift Right Logic Immediate	rd <= rs1 >>> shamt	
SRAI rd, rs1, shamt	Shift Right Arithmetic Immediate	rd <= rs1 >> shamt	
JALR rd, imm(rs1)	Jump And Link Register	Rd <= PC + 4 PC <= rs1 + imm	
Load Instructions (I type)			
LW rd, imm(rs1)	Load word	rd <= mem[rs1 + imm]	
LBU rd, imm(rs1)	Load Byte Unsigned	rd <= mem[rs1 + imm] The fetched value from memory is zero	
LHU rd, imm(rs1)	Load Halfword Unsigned	rd <= mem[rs1 + imm] The fetched value from memory is zero extended to make it as 32 bit	
S type			
SW rs2, imm(rs1)	Store Word	rs2[31:0] <= mem[rs1 + imm]	
SB type			
BEQ rs1, rs2, imm	Branch Equal	if rs1 = rs2: PC <= PC + imm*4 else: PC <= PC + 4	
BNE rs1, rs2, imm	Branch Not Equal	if rs1 != rs2: PC <= PC + imm*4 else: PC <= PC + 4	
S type SW rs2, imm(rs1) SB type BEQ rs1, rs2, imm	Store Word Branch Equal	rd <= mem[rs1 + imm] The fetched value from memory is zero extended to mak it as 32 bit rs2[31:0] <= mem[rs1 + imm] if rs1 = rs2: PC <= PC + imm*4 else: PC <= PC + 4 if rs1! = rs2: PC <= PC + imm*4	

BLT rs1, rs2, imm	Branch Less Than	if rs1 < rs2: PC <= PC + imm*4 else: PC <= PC + 4	
BGE rs1, rs2, imm	Branch Greater Than or Equal	if rs1 >= rs2: PC <= PC + imm*4 else: PC <= PC + 4	
BLTU rs1, rs2, imm	Branch Less Than Unsigned	if unsigned(rs1) < unsigned(rs2): PC <= PC + imm*4 else: PC <= PC + 4	
BGEU rs1, rs2, imm	Branch Greater Than or Equal Unsigned	if unsigned(rs1) >= unsigned(rs2): PC <= PC + imm*4 else: PC <= PC + 4	
U type			
LUI rd, imm	Load Upper Immediate	rd[31:12] <= imm rd[11:0] <= 12'b0	
AUIPC rd, imm	Add Upper Immediate to PC	rd <= PC + offset (offset[32] = imm[20] + zero[12])	
UJ type			
JAL rd, imm	Jump And Link	rd <= PC + 4 PC = PC + imm	



Verilog codes

Program counter

```
`timescale 1ns / 1ps
module PC(
        input clk,
        input reset, //reset
    input [31:0] pc_in,
    output reg [31:0] pc_out
    );
initial begin
        pc_out<=0;</pre>
        end
always @(posedge clk)
                       //Assigns pc_out equal to pc_in at every clock cycle
        begin
                 if(reset==1)
                 begin
                         pc_out<=0;</pre>
                 end
                 else
                 begin
                         pc_out<=pc_in;</pre>
                 end
        end
endmodule
PC Incrementor Adder
`timescale 1ns / 1ps
module PC_incrementor(
    input [31:0] pc_in,
    output [31:0] pc_out
    );
```

endmodule



PC Branching Adder

```
`timescale 1ns / 1ps
module adder(
    input [31:0] PC_current,
    input [31:0] imm,
    output [31:0] branched_PC
    );
assign branched_PC=PC_current+imm; //add PC and immediate
//(assumed imm incremented by 4)
endmodule
Register Bank
`timescale 1ns / 1ps
module RegBank(
    input
                      clk,
    input
               [ 4:0] r_addr1,
               [ 4:0] r_addr2,
    input
               [ 4:0] w_addr,
    input
                      write_en,
    input
         input
                                                reset,
               [31:0] write_data,
    input
    output reg [31:0] data1, //to alu directly
    output reg [31:0] data2 // send to the input selector between imm or reg
    );
    reg [31:0] regs[31:0]; // registers, there are 32 total.
   //Initially make all registers 0
    //writing data in the address.
    always @(posedge clk) // will execute on next pc update. same clock
        begin
                  if (reset) begin
                        regs[0]=32'b0;
                                                       regs[16]=32'b0;
            regs[1]=32'b0;
                                           regs[17]=32'b0;
            regs[2]=32'b0;
                                           regs[18]=32'b0;
            regs[3]=32'b0;
                                           regs[19]=32'b0;
            regs[4]=32'b0;
                                           regs[20]=32'b0;
            regs[5]=32'b0;
                                           regs[21]=32'b0;
            regs[6]=32'b0;
                                           regs[22]=32'b0;
```



```
regs[7]=32'b0;
                                           regs[23]=32'b0;
            regs[8]=32'b0;
                                           regs[24]=32'b0;
            regs[9]=32'b0;
                                           regs[25]=32'b0;
            regs[10]=32'b0;
                                            regs[26]=32'b0;
            regs[11]=32'b0;
                                            regs[27]=32'b0;
            regs[12]=32'b0;
                                            regs[28]=32'b0;
            regs[13]=32'b0;
                                            regs[29]=32'b0;
            regs[14]=32'b0;
                                            regs[30]=32'b0;
            regs[15]=32'b0;
                                            regs[31]=32'b0;
                  end
        else begin
                           if ((write_en == 1'b1) && (w_addr != 5'b00000))
                                         begin
                                                   regs[w_addr] = write_data;
                           end
                          end
        end
    always @(*)
        begin
            data1 = regs[r_addr1];
            data2 = regs[r_addr2];
        end
endmodule
```

Memory multiplexer

```
`timescale 1ns / 1ps
module Multiplexer(
    input [31:0] Read_data,
    input [31:0] Address,
    input [31:0] PC4,
    input [1:0] MemtoReg,
    output reg [31:0] mux_out
    );
    always @(*) begin
        case (MemtoReg)
          2'b00: mux_out = Address;
          2'b01: mux_out = Read_data;
          2'b11: mux_out = PC4;
          default: mux_out = 32'b0;
```



endcase

```
end
endmodule
Branching multiplexer
`timescale 1ns / 1ps
module mux(
    input [31:0] in0,
    input [31:0] in1,
    input sel,
    output [31:0] out
    );
assign out=sel?in1:in0; //if sel is 1, choose in1 else choose in0
endmodule
Main control
`timescale 1ns / 1ps
module main_control(
                        input [6:0]
                                                            opcode,
                        output reg
                                                           alu_src_1,
                        output reg
                                                           alu_src_2,
                        output reg[1:0]
                                              mem_to_reg,
                        output reg
                                                           reg_write,
                        output reg
                                                           mem_read,
                        output reg
                                                           mem_write,
                        output reg
                                                           branch,
                        output reg[1:0]
                                                alu_op,
                        output reg[1:0]
                                                next_pc_sel
                                                         );
        always @ (*) begin
                if (opcode == 7'b0110011) begin
                        /*Control signals for R-type & I-type(immediate)*/
                                                  = 1'b0;
                        alu_src_1
                        alu_src_2
                                                  = 1'b0;
                        mem_to_reg
                                                   = 2'b00;
                                                   = 1'b1;
                        reg_write
                                                         = 1'b0;
                        mem\_read
                                                 = 1'b0;
                        mem_write
                                                       = 1'b0;
                        branch
                                                       = 2'b10;
                        alu_op
                                                    = 2'b00;
                        next_pc_sel
```



```
end else if (opcode == 7'b0010011) begin
        /*I-type(immediate)*/
        alu_src_1
                                   = 1'b0;
                                  = 1'b1;
        alu_src_2
                                    = 2'b00;
        mem_to_reg
        reg_write
                                   = 1'b1;
        mem_read
                                         = 1'b0;
                                  = 1'b0;
        mem_write
        branch
                                       = 1'b0;
        alu_op
                                       = 2'b10;
        next_pc_sel
                                    = 2'b00;
end else if (opcode == 7'b0000011) begin
        /*Control signals for I-type(load)*/
                                   = 1'b0;
        alu_src_1
                                  = 1'b1;
        alu_src_2
                                    = 2'b01;
        mem_to_reg
                                   = 1'b1;
        reg_write
        mem_read
                                         = 1'b1;
                                  = 1'b0;
        mem_write
                                       = 1'b0;
        branch
        alu_op
                                       = 2'b00;
                                    = 2'b00;
        next_pc_sel
end else if (opcode == 7'b0100011) begin
        /*Control signals for S-type*/
                                   = 1'b0;
        alu_src_1
                                  = 1'b1;
        alu_src_2
        mem_to_reg
                                    = 2'b00;
                                                     /*don't care*/
                                   = 1'b0;
        reg_write
        mem_read
                                 = 1'b0;
        mem_write
                                  = 1'b1;
                                       = 1'b0;
        branch
                                       = 2'b00;
        alu_op
        next_pc_sel
                                    = 2'b00;
end else if (opcode == 7'b1100011) begin
        /*Control signals for SB-type*/
        alu_src_1
                                   = 1'b0;
        alu_src_2
                                  = 1'b0;
                                    = 2'b00;
        mem_to_reg
        reg_write
                                   = 1'b0;
                                 = 1'b0;
        mem_read
        mem_write
                                  = 1'b0:
        branch
                                       = 1'b1;
                                       = 2'b01;
        alu_op
        next_pc_sel
                                    = 2'b00;
end else if (opcode == 7'b1101111) begin
        /*JAL instrution (UJ-type)*/
        alu_src_1
                                   = 1'b0;
```



```
alu_src_2
                                 = 1'b0;
                                   = 2'b11;
        mem_to_reg
        reg_write
                                   = 1'b1;
                                 = 1'b0;
        mem_read
                                  = 1'b0;
        mem_write
                                       = 1'b0;
        branch
                                       = 2'b11;
        alu_op
                                    = 2'b01;
        next_pc_sel
end else if (opcode == 7'b1100111) begin
        /*JALR instruction (I-type)*/
        alu_src_1
                                   = 1'b0;
                                  = 1'b1;
        alu_src_2
                                    = 2'b11;
        mem_to_reg
                                   = 1'b1;
        reg_write
                                 = 1'b0;
        mem_read
        mem_write
                                  = 1'b0;
        branch
                                       = 1'b0;
                                       = 2'b11;
        alu_op
                                    = 2'b10;
        next_pc_sel
end else if (opcode == 7'b0110111) begin
        /*LUI instruction (U-type)*/
        alu_src_1
                                   = 1'b0;
                                  = 1'b1;
        alu_src_2
        mem_to_reg
                                    = 2'b00;
                                   = 1'b1;
        reg_write
                                 = 1'b0;
        mem_read
        mem_write
                                  = 1'b0;
        branch
                                       = 1'b0;
                                       = 2'b11;
        alu_op
        next_pc_sel
                                    = 2'b00;
end else if (opcode == 7'b0010111) begin
        /*AUIPC instuction (U-type)*/
        alu_src_1
                                   = 1'b1;
        alu_src_2
                                  = 1'b1;
                                    = 2'b00;
        mem_to_reg
        reg_write
                                   = 1'b1;
        mem_read
                                 = 1'b0;
                                  = 1'b0;
        mem_write
        branch
                                       = 1'b0;
                                       = 2'b11;
        alu_op
                                    = 2'b00;
        next_pc_sel
end else begin
        /*Keep high impedence for any other input*/
        alu_src_1
                                   = 1'bz;
        alu_src_2
                                  = 1'bz;
                                    = 2'bzz;
        mem_to_reg
                                   = 1'bz;
        reg_write
```



```
= 1'bz;
                        mem_read
                        mem_write
                                                 = 1'bz;
                        branch
                                                      = 1'bz;
                                                      = 2'bzz;
                        alu_op
                        next_pc_sel
                                                   = 2'bzz;
                end
        end
endmodule
Instruction Memory
`timescale 1ns / 1ps
module Ins_Mem (
    //input clk,
    input [4:0] addr,
    output reg [31:0] instruction
    //output wire [31:0] instruction
);
  reg [31:0] memory[31:0]; //chnage as you like later.
  initial begin
    memory[0] = 32'b000000000011000000000010110011; //add x1, x0, x3
    memory[1] = 32'b000000000110000000000010110011;
    memory[2] = 32'b000000000110000000000010110011;
    memory[3] = 32'b00000001010110100000100100110011; //add x18, x20, x21
    memory[4] = 32'b0000000101111011000010010110011; //add x17, x22, x23
    memory[5] = 32'b000000000000000000000001101111; //jal x0, 0
    memory[6] = 32'b0;
    memory[7] = 32'b0;
    memory[8] = 32'b0;
    memory[9] = 32'b0;
    memory[10] = 32'h000;
    memory[11] = 32'h000;
    memory[12] = 32'h000;
    memory[13] = 32'h000;
    memory[14] = 32'h000;
    memory[15] = 32'h000;
    memory[16] = 32'h000;
    memory[17] = 32'h0012;
    memory [18] = 32'h0013;
    memory [19] = 32'h0014;
    memory[20] = 32'h0015;
    memory[21] = 32'h0016;
```



```
memory[22] = 32'h0017;
    memory[23] = 32'h0018;
    memory[24] = 32'h0019;
    memory[25] = 32'h001a;
    memory[26] = 32'h001b;
    memory[27] = 32'h001c;
    memory[28] = 32'h001d;
    memory[29] = 32'h0013;
    memory[30] = 32'h001f;
    memory[31] = 32'h0;
  end
  // Retriving the instruction code based on the PC count
  //assign instruction = memory[addr[3:0]];
  always @(*)
  begin
    instruction = memory[addr[4:0]];
  end
endmodule
Input Sel 1 multiplexer
`timescale 1ns / 1ps
module INPUT_SEL(
                  ALUSrc1, // ALUSrc is Control unit flag to select the Input, IMMval, // IF 1, select imm value
    input
    input [31:0] IMMval,
    input [31:0] reg_val,
                               // If 0, select register out put
    output [31:0] AluInput2
    );
    assign AluInput2 = ALUSrc1 ? IMMval:reg_val;
endmodule
```



Input sel 2 multiplexer

```
`timescale 1ns / 1ps
module INPUT_SEL_2(
        t ALUSrc2, // ALUSrc is Control unit flag to select the Input, input [31:0] Pc, // IF 1, select imm value
    input
        input [31:0] reg_val,
                                    // If 0, select register out put
        output [31:0] AluInput1
        );
        assign AluInput1 = ALUSrc2 ? Pc:reg_val;
endmodule
Decoder
`timescale 1ns / 1ps
module inDecode (
    input [31:0] inst,
    output reg [ 6:0] opcode,
    output reg [ 4:0] rsAddr,
                                  //rs1
    output reg [ 4:0] rdAddr,  //rd
output reg [ 4:0] shamt,  //SHIFT VAL AND RS2
    output reg [ 3:0] alu_func, // FOR ALU_contoller
    //func_3 + 1 bit for add sub chaage like things
    output reg [31:0] imm // i TYPE imm and branching //output reg [31:0] label // for braching
);
  always @(*) begin
    opcode = inst[6:0]; //Opcode is always the first 7 bits
    if(opcode==7'b0110011) //Arithmetic and Shift Operations
                begin
      rsAddr = inst[19:15];
      rdAddr = inst[11:7];
      shamt = inst[24:20];
      alu_func = {inst[30], inst[14:12]};
      imm = 32'b0;
      //label = 32'b0;
    end
        else if(opcode==7'b0010011) //Immediate Operations
                begin
      rsAddr = inst[19:15];
      rdAddr = inst[11:7];
```



```
= 5'b00000; // no need second address
 alu_func = {1'b0, inst[14:12]};
       = $signed(inst[31:20]);
 imm
 //label = 32'b0; //only for U and UJ
end
   else if(opcode==7'b0000011)
           begin
 rsAddr = inst[19:15]; //rs1
 rdAddr = inst[11:7]; //rd
       = 5'b00000;
 shamt
 alu_func = {1'b0, inst[14:12]};
        = $signed(inst[31:20]);
 // label = 32'b0;
end
else if(opcode==7'b0100011)
           begin
 rsAddr = inst[19:15]; //rs1
 rdAddr = 5'b00000; //inst[23:19];
 shamt = inst[24:20]; // We need this
 alu_func = {1'b0, inst[14:12]};
 imm = $signed({inst[31:25], inst[11:7]});
 // label = 32'b0; //No need this
end
   else if(opcode==7'b1100011) //Branch/Jump Operations
           begin
 rsAddr = inst[19:15]; // rs1 adddress
 rdAddr = 5'b0;
 shamt = inst[24:20];
 alu_func = {1'b0, inst[14:12]};
        = $signed({ inst[31], inst[7], inst[30:25], inst[11:8], 1'b0});
 // label = 32'b0;
end
   else if(opcode==7'b1101111) //J - JAL
          begin
          = 5'b0;
 rsAddr
        = inst[11:7];
 rdAddr
 shamt
         = 5'b0;
 alu_func = 4'b0;
        = {inst[31], inst[19:12], inst[20], inst[30:21], 1'b0};
 imm
 // imm
            = 32'b0:
 // label
           = {inst[31], inst[19:12], imm[20], imm[30:21], 1'b0};
end
```



```
else if(opcode==7'b1100111) //I-type JALR
             begin
   rsAddr = inst[19:15];
   rdAddr = inst[11:7];
   shamt = 5'b00000; // no need second address
   alu_func = {1'b0, inst[14:12]};
          = $signed(inst[31:20]);
   // label = 32'b0; //only for U and UJ
 end
 else if(opcode==7'b0110111)
                              //Upper LUI
             begin
            = 5'b0;
   rsAddr
   rdAddr = inst[11:7];
   shamt
          = 5'b0;
   alu_func = 4'b0;
   imm
          = $signed({inst[31:12], 12'b0});
             = 32'b0;
   // imm
   // label = $signed({inst[31:12], 12'b0});
 end
 else if(opcode==7'b0010111) //Upper AUIPC
             begin
   rsAddr
            = 5'b0;
   rdAddr = inst[11:7];
   shamt
           = 5'b0;
   alu_func = 4'b0;
          = $signed({inst[31:12], 12'b0});
   imm
             = 32'b0;
   // imm
   // label = $signed({inst[31:12], 12'b0});
 end
 else //invalid instruction0
 begin
   rsAddr = 5'b0;
   rdAddr = 5'b0;
   shamt = 5'b0;
   alu_func = 4'b0;
   imm = 32'b0;
   //label = 32'b0;
 end
end
```

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endmodule



Flag Logic module flag_logic(input eq, input 1t, input ltu, input branch, output branch_flag); assign branch_flag = branch & (eq | lt | ltu); endmodule **Data Memory** `timescale 1ns / 1ps module Data_memory(input clk, input [31:0] Address, input [31:0] Write_data, input MemRead, input MemWrite, output reg [31:0] Read_data); reg [31:0] mem [1023:0]; // 1024 32-bit words of memory initial begin for (int i = 0; i < 1024; i++) begin mem[i] = 0;end //mem[6] =32'b11101; end always @(*) begin if (MemRead == 1) begin Read_data = mem[Address[9:0]]; end end always @(posedge clk)



```
begin
      if (MemWrite == 1) begin
        mem[Address[9:0]] <= Write_data;</pre>
      end
    end
endmodule
ALU Control
`timescale 1ns / 1ps
module alu_control (
                            input
                                         [1:0]
                                                                       alu_op,
                                                 input
                                                              [3:0]
                                                 output reg
                                                                   [3:0]
                    [5:0]
        wire
                                 temp;
        assign temp = {alu_op, alu_funct};
        always Q(*) begin
                if (temp == 6'b10_0000 | temp == 6'b00_0010 | temp == 6'b11_0000) beg
                        /* ADD for add, addi, lw, sw instructions */
                        alu\_ctrl = 4'b0000;
                end else if (temp == 6'b10_1000) begin
                        /* SUB */
                        alu_ctrl = 4'b0001;
                end else if (temp == 6'b01_0001) begin
                        /* SLL */
                        alu_ctrl = 4'b0010;
                end else if (temp == 6'b10_0010) begin
                        /* SLT -> slt & slti*/
                        alu_ctrl = 4'b0011;
                end else if (temp == 6'b10_0011) begin
                        /* ALU SLTU */
                        alu_ctrl = 4'b0100;
                end else if (temp == 6'b10_0100) begin
                        /* XOR */
                        alu\_ctrl = 4'b0101;
                end else if (temp == 6'b10_0101) begin
                        /* SRL */
                        alu_ctrl = 4'b0110;
```



```
end else if (temp == 6'b10_1101) begin
                        /* SRA */
                        alu_ctrl = 4'b0111;
                end else if (temp == 6'b10_0110) begin
                        /* OR */
                        alu_ctrl = 4'b1000;
                end else if (temp == 6'b10_0111) begin
                        /* AND */
                        alu_ctrl = 4'b1001;
                end else if (temp == 6'b01_0000) begin
                        /* BEQ */
                        alu_ctrl = 4'b1011;
                end else if (temp == 6'b01_0100) begin
                        /* BLT */
                        alu\_ctrl = 4'b1100;
                end else if (temp == 6'b01_0110) begin
                        /* BLTU */
                        alu_ctrl = 4'b1101;
                end else begin
                        alu_ctrl = 4'bzzzz;
                end
        end
endmodule
```

PC Incrementor selecting multiplexer

```
module mux_4(
    input [31:0] jal,
    input [31:0] br_pc,
    input [31:0] jalr,
    input [1:0] sel,
    output reg [31:0] y
    );

always @(*) begin
    case (sel)
        2'b00: y = br_pc;
        2'b01: y = jal;
        2'b10: y = jalr;
        endcase
end
```



endmodule

Full Processor

```
`timescale 1ns / 1ps
module Zigma_RISCV(
    input clk_max,
         input reset
    );
         wire clk;
                          //clock after dividing
         Clock_divider clk_div0(
                .clock_in
                                  (clk_max),
                .clock_out
                                   (clk)
         );
        wire [31:0] pc_number;
        wire [31:0] data = 32'h0;
        wire wren = 0;
                                       /*write enable*/
        wire [31:0]
                         inst_out_inst_Mem;
        // instruction memory
    Ins_Mem instmem(
      .addr(pc_number),
      .instruction(inst_out_inst_Mem)
    );
         /*instruction memory*/
         myTop instr_mem0(
                .address (pc_number[9:0]),
                .clock (clk_max),
                .data
                         (data),
                         (wren),
                .wren
                          (inst_out_inst_Mem)
                .q
                );
         //Instruction decoder
         wire [6:0] inDec_opcode;
    wire [4:0] inDec_rs1Add;
    wire [4:0] inDec_rs2Add;
    wire [ 4:0] inDec_rdAddr;
    wire [ 3:0] inDec_alu_func;
    wire [31:0] inDec_imm;
    inDecode inDec(
```



```
.inst(inst_out_inst_Mem),
  .opcode(inDec_opcode),
  .rsAddr( inDec_rs1Add),
  .rdAddr(inDec_rdAddr),
  .shamt(inDec_rs2Add),
  .alu_func(inDec_alu_func),
  .imm(inDec_imm)
);
    //wire [4:0] regB_r_addr1;
     //wire [ 4:0] regB_r_addr2;
     //wire [ 4:0] regB_w_addr;
/***********************************/
                regB_write_en;
wire [31:0] regB_write_data;
wire [31:0] regB_data1;
wire [31:0] regB_data2;
RegBank regBank1(
  .clk(clk),
  .r_addr1(inDec_rs1Add),
  .r_addr2(inDec_rs2Add),
  .w_addr(inDec_rdAddr),
  .write_en(regB_write_en),
            .reset(~reset),
  .write_data(regB_write_data),
  .data1(regB_data1),
  .data2(regB_data2)
);
     /********************/
 wire
             inp_ALUSrc_2;
 //wire [31:0] inp_IMMval;
 //wire [31:0] inp_reg_val;
 wire [31:0] inp_AluInput2;
 //select between register data or immediate data for alu
  INPUT_SEL input_sel1(
     .ALUSrc1(inp_ALUSrc_2),
     .IMMval(inDec_imm),
     .reg_val(regB_data2),
     .AluInput2(inp_AluInput2)
```



```
);
              inp\_ALUSrc1 ; // ALUSrc is Control unit flag to select the Input
 wire
 //wire [31:0] inp_Pc;
                              // IF 1, select imm value
 wire [31:0] inp_1_reg_val;
                                // If 0, select register out put
 wire [31:0] inp_AluInput1;
// select between register and pc for alu
INPUT_SEL_2 input_sel2(
  .ALUSrc2(inp_ALUSrc1),
  .Pc(pc_number),
  .reg_val(regB_data1),
  .AluInput1(inp_AluInput1)
);
//wire [3:0] alu_func;
//wire [31:0] alu_A;
//wire [31:0] alu_B;
wire[31:0] alu_alu_out;
wire alu_eq, alu_a_lt_b, alu_a_lt_ub;
wire [3:0] alu_ctrl;
// ALU connectivity
alu Alu1(
  .func(alu_ctrl),
  .A(inp_AluInput1),
  .B(inp_AluInput2),
  .alu_out(alu_alu_out),
  .eq(alu_eq),
  .a_lt_b(alu_a_lt_b),
  .a_lt_ub(alu_a_lt_ub)
);
    /************** Main contoler ***********/
    wire mem_read, mem_write, branch;
    wire [1:0] mem_to_reg, next_pc_sel;
    wire [1:0] alu_op;
      main_control mc_0 (
                    .opcode
                                                      (inDec_opcode),
                                               (inp_ALUSrc1),
                    .alu_src_1
                                               (inp_ALUSrc_2),
                    .alu_src_2
                                                (mem_to_reg),
                    .mem_to_reg
                    .reg_write
                                               (regB_write_en),
                                               (mem_read),
                    .mem_read
                    .mem_write
                                        (mem_write),
```



```
.branch
                                       (branch),
                                       (alu_op),
             .alu_op
             .next_pc_sel
                         (next_pc_sel)
);
/****************/
alu_control ac_0 (
             .alu_op
                                     (alu_op),
             .alu_funct
                                 (inDec_alu_func),
             .alu_ctrl
                                 (alu_ctrl)
);
wire [31:0] dat_mem_output;
Data_memory dat_mem(
 .clk(clk),
 .Address(alu_alu_out),
 .Write_data(regB_data2),
 .MemRead(mem_read),
 .MemWrite(mem_write),
 .Read_data(dat_mem_output)
);
/********************************/
/*
data_memory dm0(
      .address (alu_alu_out),
      .clock
              (clk_max),
                                       //clk_max or clk??
      .data
                       (regB_data2),
      .rden
                       (mem_read),
                       (mem_write),
      .wren
                           (dat_mem_output)
      . q
);
*/
/**************/
// Register input selector after the data memmory
wire [31:0] incr_pc; // use this one in Pc parts
Multiplexer multi_reg(
```



```
.Read_data(dat_mem_output),
  .Address(alu_alu_out),
                                           /*direct output from ALU*/
  .PC4(incr_pc),
  .MemtoReg(mem_to_reg),
  .mux_out(regB_write_data) //sending to register bank
);
PC_full pc_full(
  .clk(clk),
  .next_pc_sel(next_pc_sel),
  .imme(inDec_imm),
  .jalr(alu_alu_out),
  .eq(alu_eq),
  .a_lt_b(alu_a_lt_b),
  .a_lt_ub(alu_a_lt_ub),
  .branch(branch),
  .pc_out(pc_number),
  .reset(~reset),
  .pcinc_to_m2(incr_pc)
);
```

endmodule