view_frames Result Recorded at time: 102.230 world Broadcaster: /elfin_arm/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (102.230 sec old) Buffer length: 0.000 sec elfin_base_link Broadcaster: /elfin_arm/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (102.230 sec old) Buffer length: 0.000 sec elfin_base Broadcaster: /elfin_arm/robot_state_publisher Average rate: 50.202 Hz Most recent transform: 102.229 (0.001 sec old) Buffer length: 4.960 sec elfin_link1 Broadcaster: /elfin_arm/robot_state_publisher Average rate: 50.202 Hz Most recent transform: 102.229 (0.001 sec old) Buffer length: 4.960 sec elfin_link2 Broadcaster: /elfin_arm/robot_state_publisher Average rate: 50.202 Hz Most recent transform: 102.229 (0.001 sec old) Buffer length: 4.960 sec elfin_link3 Broadcaster: /elfin_arm/robot_state_publisher Average rate: 50.202 Hz Most recent transform: 102.229 (0.001 sec old) Buffer length: 4.960 sec elfin_link4 Broadcaster: /elfin_arm/robot_state_publisher Average rate: 50.202 Hz Most recent transform: 102.229 (0.001 sec old) Buffer length: 4.960 sec elfin_link5 Broadcaster: /elfin_arm/robot_state_publisher Average rate: 50.202 Hz Most recent transform: 102.229 (0.001 sec old) Buffer length: 4.960 sec elfin_link6 Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (102.230 sec old) Most recent transform: 0.000 (102.230 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec elfin_end_link elfin_dummy_gripper Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (102.230 sec old) Most recent transform: 0.000 (102.230 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_link robotiq_robotiq_arg2f_base_link Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 0.000 (102.230 sec old) Most recent transform: 102.229 (0.001 sec old) Most recent transform: 102.229 (0.001 sec old) Most recent transform: 102.229 (0.001 sec old) Most recent transform: 102.229 (0.001 sec old) Buffer length: 0.000 sec Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.960 sec robotiq_left_inner_knuckle robotiq_left_outer_knuckle robotiq_right_outer_knuckle robotiq_right_inner_knuckle camera_bottom_screw_frame Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (102.230 sec old) Most recent transform: 0.000 (102.230 sec old) Most recent transform: 0.000 (102.230 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera_link robotiq_left_outer_finger robotiq_right_outer_finger Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 102.229 (0.001 sec old) Most recent transform: 102.229 (0.001 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec robotiq_left_inner_finger robotiq_right_inner_finger Broadcaster: /elfin_arm/robot_state_publisher Broadcaster: /elfin_arm/robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (102.230 sec old) Most recent transform: 0.000 (102.230 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec robotiq_right_inner_finger_pad robotiq_left_inner_finger_pad