Runtime Environments

CIS*4650 (Winter 2020)

Review

- Front-end analysis: scanning, parsing, and static semantic analysis
 - Language-specific and machine-independent
 - Most of the error-checking captured
- Back-end synthesis: machine-specific and relying on coding solutions
 - <u>Runtime environments</u>: organization of registers and memory for program execution
 - Code generation: convert intermediate code to target machine/assembly code
 - Code optimization: transform code for efficiency in time and space

Three Kinds of Environments

Fully-static environments:

- All data are statically allocated in memory before execution
- o e.g., FORTRAN77

Stack-based environments:

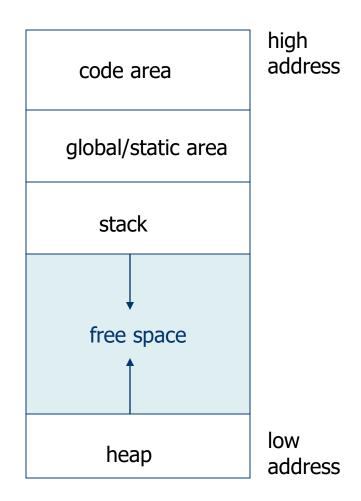
- Memory for recursive calls can't be allocated statically, but can be maintained as a stack
- o e.g., C/C++, Pascal, and Ada

Fully-dynamic environments:

- Allowing the reference to a local variable in a procedure (usually resulting in a dangling reference in a stack-based environment)
- o e.g., LISP

Memory Organization

- Entries to procedures and addresses to global data can be computed at compile time
- Data are often allocated at the execution time in the form of stack and/or heap
- Stack and heap can compete for the same free space or be given with separate spaces



Global/Static Data Area

- Global data can be allocated statically at compile time
 - In FORTRAN77, all data belong to this class
 - In Pascal, only global variables are in this class
 - In C, external and static variables as well as global variables are in this class
- ➤ Small constants such as 0 and 1 are inserted directly into the code
- Large constants, especially strings, are stored in the global area

Activation Records

Unit of memory allocated to a procedure, which should contain at least the following sections:

Space for arguments (parameters)

Space for bookkeeping info such as return address

Space for local variables

Space for local temporaries

Activation records are also called stack frames in a stack-based environment

Registers

Registers are part of the runtime environment and may be used to store temporaries, local variables, and even global data.

- Special-purpose registers:
 - program counter (pc): keep track of the current instruction during execution
 - stack pointer (sp): points to the top (lowest address) of the stack area
 - frame pointer (fp): points to the current activation record
 - argument pointer (ap): points to the argument area of an activation record

- Sequence of operations that must occur when a function is called:
 - Call sequence: operations performed during a call such as allocating memory for activation record, computing argument values, and setting the necessary registers.
 - Return sequence: operations performed on return such as placing the return value for the caller, adjusting register values, and possibly releasing memory for the called activation record.
- Caller vs. Callee: how to divide the tasks between the two?

Fully-Static Runtime Environments

Example FORTRAN77 program:

PROGRAM TEST
COMMON MAXSIZE
INTEGER MAXSIZE
REAL TABLE(10), TEMP
MAXSIZE = 10
READ *, TABLE(1), TABLE(2), TABLE(3)
CALL QUADMEAN(TABLE, 3, TEMP)
PRINT *, TEMP
END

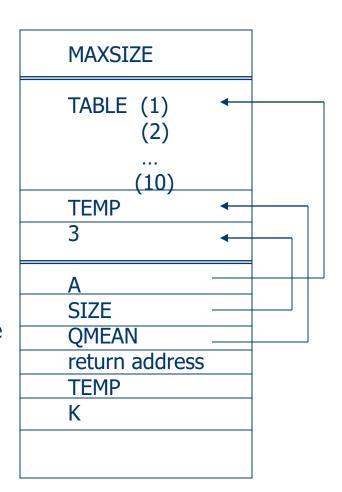
```
SUBROUTINE QUADMEAN(A, SIZE, QMEAN)
COMMON MAXSIZE
INTEGER MAXSIZE, SIZE
REAL A(SIZE), QMEAN, TEMP
INTEGER K
TEMP = 0.0
IF ((SIZE.GT.MAXSIZE).OR.(SIZE.LT.1)) GOTO 99
DO 10 K = 1, SIZE
TEMP = TEMP + A(K)*A(K)
10 CONTINUE
99 QMEAN = SORT(TEMP/SIZE)
RETURN
END
```

Fully-Static Runtime Environments

Global area

Activation record of main procedure

Activation record of QUADMEAN procedure

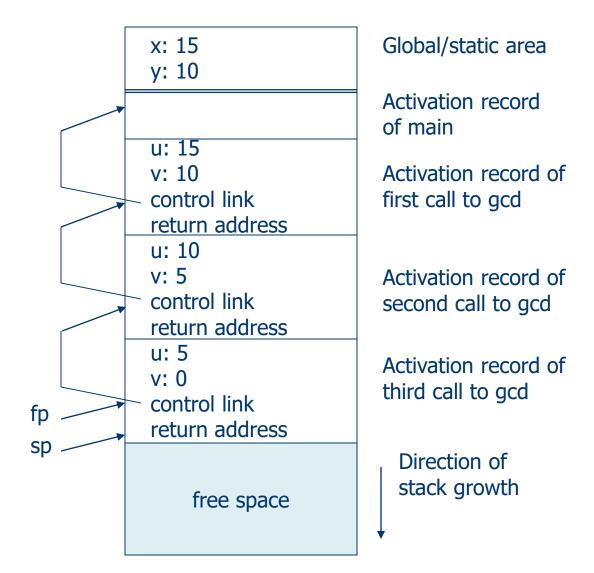


Fully-Static Runtime Environments

- Each procedure has only a single activation record (no recursive calls allowed)
- All variables, either local or global, can be accessed directly via fixed addresses (no pointers or dynamic allocation)
- Calling sequence:
 - o call sequence: compute arguments and store their values to the activation record, save the return address, and jump to new procedure
 - o return sequence: jump to the return address in the caller
- Parameters are passed by references and arrays don't need to be copied
- Constant arguments such as 3 must be stored so that its location can be passed to the procedure
- > Temporaries are placed at the end of the activation record

Activation records for recursive calls can't be allocated statically, but can be maintained as a stack if the caller doesn't reference local variables in the callee

```
#include <stdio.h>
int x, y;
int gcd( int u, int v ) {
  if( v == 0 ) return u;
  else return gcd( v, u%v );
}
int main( ) {
  scanf( "%d%d", &x, &y );
  printf( "%d\n", gcd(x, y) );
  return 0;
}
```



Example with indirect recursion and a static variable:

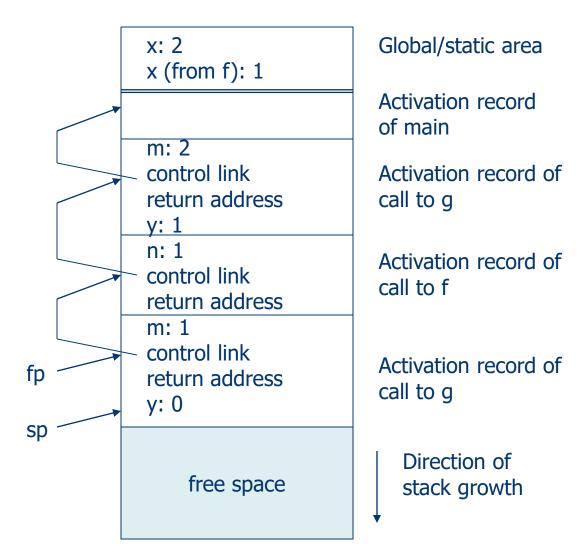
```
int x = 2;

void g( int );  /* prototype */

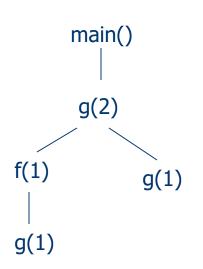
void f( int n ) {
    static int x = 1;
    g( n );
    x--;
}
```

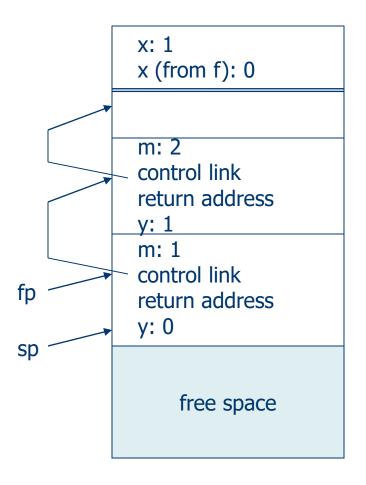
```
void g( int m ) {
  int y = m - 1;
  if(y > 0) {
   f( y );
    X--;
    g( y );
int main( ) {
  g(x);
  return 0;
```

 Stack environment during the second call to g



 Stack environment during the third call to g





Global/static area

Activation record of main

Activation record of call to g

Activation record of call to g

Direction of stack growth

Access to Names

- Dynamically allocated parameters and local variables can't be accessed by fixed addresses
 - Solution: use offsets from the current frame pointer (fp).

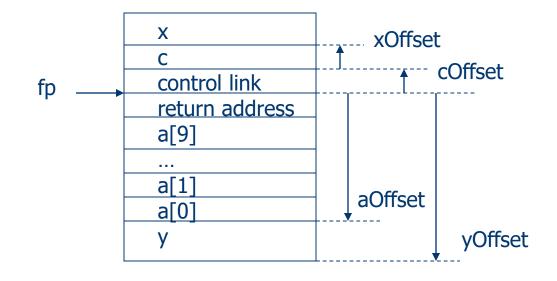


o e.g., assuming that integer requires 2 bytes and address requires 4 bytes, then we have: mOffset = +4(fp) and yOffset = -6(fp).

Access to Names

```
void f( int x, char c ) {
  int a[10];
  double y;
  ...
}
```

Name	Offset
X	+5
С	+4
a	-24
У	-32



a[i] offset: (-24+2*i)(fp)

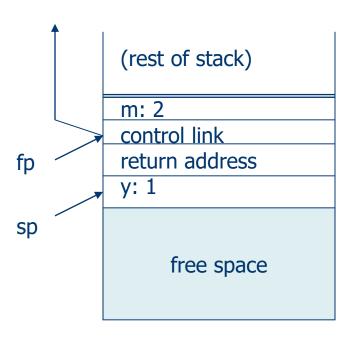
Call Sequence:

- 1. Compute arguments and push values to the activation record of callee
- 2. Push the current fp as the control link
- 3. Copy current sp to fp so that it points to the current activation record
- 4. Push the return address to the new activation record
- 5. Perform a jump to the code of the callee
- 6. Move down sp for all local variables in the callee

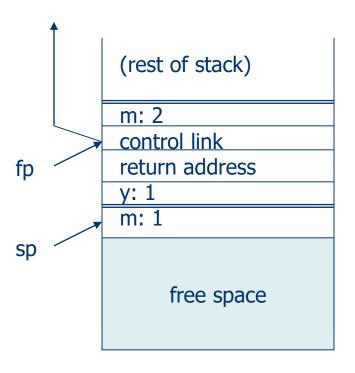
Return Sequence:

- 1. Copy the current fp to sp
- 2. Load the control link to fp
- 3. Perform a jump to the return address
- 4. Change sp to pop the arguments

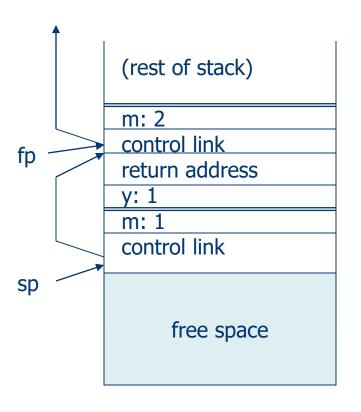
- before the last call to g:



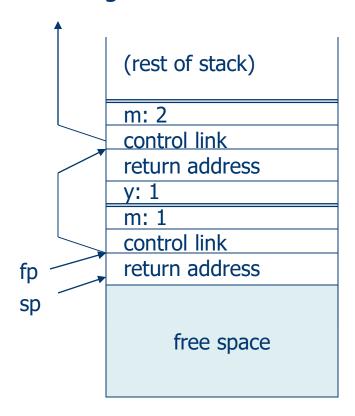
- as new call to g is made:



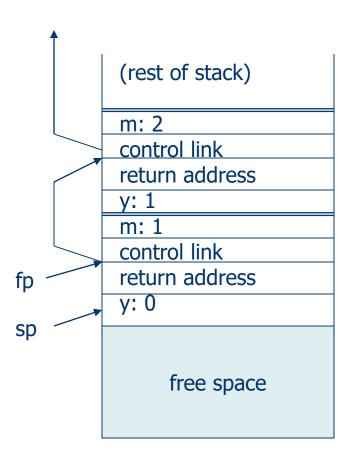
- fp is pushed onto stack:



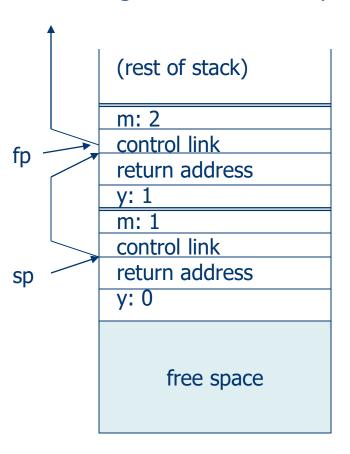
- sp is copied to fp, return address is pushed onto stack, jump to new call to g is made:



- new y is allocated and initialized



- On exit, after copying fp to sp and loading control link to fp

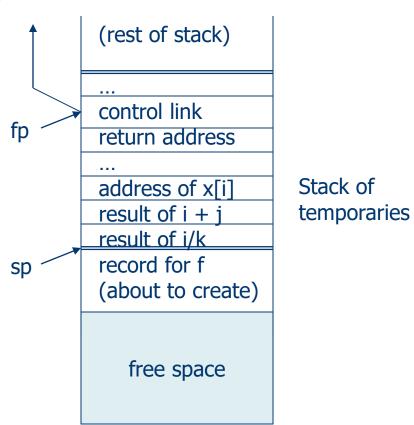


Local Temporaries

Computing partial results:

$$x[i] = (i + j) + (i/k + f(j))$$

-The calling sequence using sp works without change.



Nested Blocks

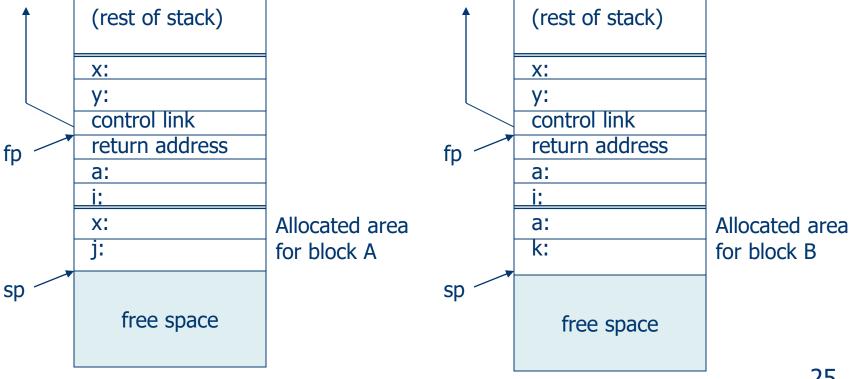
New activation records could be created for each block and discarded on exit

- ➤ Why not efficient?
 - No parameters
 - No return address
 - Always executed immediately

```
void p( int x, double y ) {
  char a;
  int i;
  A: { double x;
       int j;
  B: { char * a;
       int k;
```

Nested Blocks

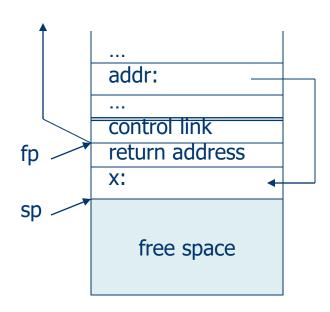
> A simpler solution is to allocate temporaries on entry to a block and de-allocate them on exit



Fully-Dynamic Environments

Dangling references in a stack-based environment:

```
int * dangle( void ) {
  int x;
  return &x;
}
...
int * addr = dangle();
```



- Fully-dynamic environment will de-allocate activation records only when all references to them have disappeared
 - Finding and de-allocating inaccessible areas of memory during execution is called *garbage collection*.

Heap Management

- Even a stack-based environment may need dynamic allocations/de-allocations through pointers.
- A heap can grow linearly while interfering as little as possible with the stack.
- Users are responsible for allocating and freeing heap spaces.
 - A heap supports two operations (e.g., in C language):
 void * malloc(unsigned int nbytes);
 void free(void * ptr);

Heap Management

> A circular linked list for available spaces:

- Structure of a memory block

- Initial header (never deleted)

Header

next
usedsize
freesize
used space

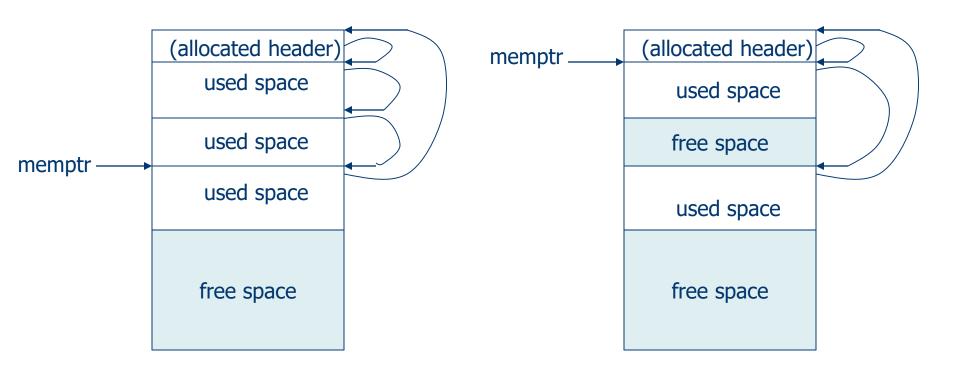
free space

free space

Heap Management

- After three calls to malloc:

- After middle block is freed:



Parameter Passing

Parameters correspond to locations in the activation record of a procedure call

- Parameter passing: bind parameters to their arguments (different forms such as addresses and values)
- Parameter passing methods:
 - Pass by value (or call by value)
 - Pass by reference (or call by reference)
 - Pass by value-result

Pass By Value

- Arguments are expressions whose values are computed and copied to parameters
 - The only parameter passing mechanism in C

```
/* incorrect. Why? */
void inc2( int x ) {
    ++x;
    ++x;
}

/* correct solution */
void inc2( int * x ) {
    ++(*x);
    ++(*x);
}
```

```
/* will x[] be initialized correctly? */
void init( int x[], int size ) {
  int i = 0;
  for( i = 0; i < size; i++ )
    x[i] = 0;
}</pre>
```

Pass By Reference

- Arguments must be variables (at least in principle) so that their addresses can be copied to parameters
 - The only parameter passing mechanism in FORTRAN77
 - Parameters are essentially aliases for their arguments

```
/* C++ solution */
void inc2( int & x ) {
    ++x;
    ++x;
}
```

Pass By Value-Result

- Similar to pass by reference except that no actual alias is established
 - The argument value is copied and used in the procedure and the final value of the parameter is copied back to the argument.

```
/* what is the value of a after p(a, a) if different parameter passing
  methods are used? */
void p( int x, int y ) {
    ++x;
    ++y;
}

int main( ) {
    int a = 1;
    p(a, a);
    return 0;
}
```