

Table of contents

3 - 1
4 - 1
5 - 1
6 - 1
7 - 1
8 - 1
9 - 1
10 - 1
11 - 1
12 - 1
13 - 1
14 - 1
15 - 1
16 - 1
17 - 1

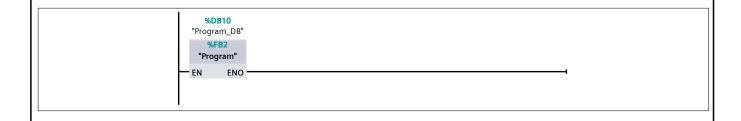
Totally Integrated Automation Portal		
---	--	--

Main [OB1]

Main Propert	ies				
General					
Name	Main	Number	1	Туре	OB
Language	LAD	Numbering	Automatic		
Information					
Title	"Main Program Sweep (Cycle)"	Author		Comment	
Family		Version	0.1	User-defined ID	

Name	Data type	Default value	Comment
▼ Input			
Initial_Call	Bool		Initial call of this OB
Remanence	Bool		=True, if remanent data are available
Temp			
Constant			

Network 1:



otally Integrated	
Automation Portal	
	l

BinarySearch [FB1]

BinarySearch	Properties				
General					
Name	BinarySearch	Number	1	Туре	FB
Language	SCL	Numbering	Automatic		
Information					
Title		Author		Comment	
Family		Version	0.1	User-defined ID	

Name	Data type	Default value	Retain	sible from HMI/OP C UA/We b API	ta- ble fro m	ing		Super- vision	Comment
✓ Input									
S_State	DInt	0	Non-retain	True	Tru e	True	False		
▼ Output									
Action	Int	0	Non-retain	True	Tru e	True	False		
▼ InOut									
▼ ArEtat	Array[*] of DInt			False	Fals e	False	False		
ArEtat[*]	DInt			False	Fals e	False	False		
▼ ArAction	Array[*] of Int			False	Fals e	False	False		
ArAction[*]	Int			False	Fals e	False	False		
Static									
▼ Temp									
max	DInt								
min	DInt								
mid	DInt								
Constant									

```
0001 #min := 0;
0002 #max:=UPPER_BOUND(ARR := #ArEtat, DIM := 1);
0003
0004 WHILE #min < #max DO
0005  #mid := (#min + #max) / 2;
0006  IF #ArEtat[#mid] = #S_State THEN
0007  #Action := #ArAction[#mid];
0008  RETURN
0009  ;
0010  ELSIF #ArEtat[#mid] < #S_State THEN
0011  #min := #mid + 1;</pre>
```

Symbol	Address	Type	Comment
#Action		Int	
#ArAction[*]		Int	
#ArEtat		Array	
#ArEtat[*]		DInt	
#max		DInt	
#mid		DInt	
#min		DInt	
#S_State		DInt	

Program [FB2]

Program Prop	erties				
General					
Name	Program	Number	2	Type	FB
Language	SCL	Numbering	Automatic		
Information					
Title		Author		Comment	
Family		Version	0.1	User-defined ID	

me	Data type	Default value	Retain	from HMI/OP C UA/We b API	ta- ble fro m	in HMI engi-		Comment
Input								
Output								
InOut								
Static								
▼ task	Ar- ray[013] of Struct		Non-retain		е	True	False	
▼ task[0]	Struct		Non-retain	True	Tru e	True	False	
AUT	Bool	false	Non-retain		Tru e	True	False	
AUTf	Bool	false	Non-retain		Tru e	True	False	
IC	Bool	false	Non-retain		Tru e	True	False	
IS	Bool	false	Non-retain		Tru e	True	False	
▼ task[1]	Struct		Non-retain		Tru e	True	False	
AUT	Bool	false	Non-retain	True		True	False	
AUTf	Bool	false	Non-retain	True		True	False	
IC	Bool	false	Non-retain	True	Tru e	True	False	
IS	Bool	false	Non-retain			True	False	
▼ task[2]	Struct		Non-retain		Tru e	True	False	
AUT	Bool	false	Non-retain	True		True	False	
AUTf	Bool	false	Non-retain			True	False	
IC	Bool	false	Non-retain			True	False	

Totally Integrated Automation Portal									
ame	Data type	Default value	Retain	Acces- sible from HMI/OP C UA/We b API	ta- ble fro m	ing		Super- vision	Comment
IS	Bool	false	Non-retain	True	Tru e	True	False		
▼ task[3]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True	Tru	True	False		
AUTf	Bool	false	Non-retain	True		True	False		
IC	Bool	false	Non-retain	True		True	False		
IS	Bool	false	Non-retain	True		True	False		
▼ task[4]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True		True	False		
AUTf	Bool	false	Non-retain	True		True	False		
IC	Bool	false	Non-retain	True		True	False		
IS	Bool	false	Non-retain	True		True	False		
▼ task[5]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True		True	False		
AUTf	Bool	false	Non-retain	True		True	False		
IC	Bool	false	Non-retain	True		True	False		
IS	Bool	false	Non-retain	True		True	False		
▼ task[6]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True		True	False		
AUTf	Bool	false	Non-retain	True		True	False		
IC	Bool	false	Non-retain	True		True	False		
IS	Bool	false	Non-retain	True		True	False		
▼ task[7]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True		True	False		
AUTf	Bool	false	Non-retain	True		True	False		
IC	Bool	false	Non-retain	True	e Tru	True	False		

Totally Integrated Automation Portal									
Name	Data type	Default value	Retain	from HMI/OP C UA/We b API	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
IS	Bool	false	Non-retain	True	Tru e	True	False		
▼ task[8]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True		True	False		
AUTf	Bool	false	Non-retain	True	_	True	False		
IC	Bool	false	Non-retain	True		True	False		
IS	Bool	false	Non-retain	True		True	False		
▼ task[9]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True		True	False		
AUTf	Bool	false	Non-retain	True		True	False		
IC	Bool	false	Non-retain	True		True	False		
IS	Bool	false	Non-retain	True	_	True	False		
▼ task[10]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True	_	True	False		
AUTf	Bool	false	Non-retain	True	Tru e	True	False		
IC	Bool	false	Non-retain	True	Tru e	True	False		
IS	Bool	false	Non-retain	True	Tru e	True	False		
▼ task[11]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True		True	False		
AUTf	Bool	false	Non-retain	True	Tru e	True	False		
IC	Bool	false	Non-retain	True	Tru e	True	False		
IS	Bool	false	Non-retain	True	_	True	False		
▼ task[12]	Struct		Non-retain	True		True	False		
AUT	Bool	false	Non-retain	True	Tru e	True	False		
AUTf	Bool	false	Non-retain	True	Tru e	True	False		
IC	Bool	false	Non-retain	True	Tru e	True	False		

Totally Integrated Automation Portal								
ame		Default value	Retain	Acces- sible from HMI/OP C UA/We b API	ta- ble fro m HM I/O PC UA/ We b	in HMI engi- neer- ing	point	Comment
IS	Bool	false	Non-retain	True	Tru e	True	False	
▼ task[13]	Struct		Non-retain	True	Tru e	True	False	
AUT	Bool	false	Non-retain	True		True	False	
AUTf	Bool	false	Non-retain	True	_	True	False	
IC	Bool	false	Non-retain	True		True	False	
IS	Bool	false	Non-retain	True		True	False	
FTX10	Bool	false	Non-retain	True		True	False	
FTX11	Bool	false	Non-retain	True	Tru	True	False	
FTX20	Bool	false	Non-retain	True	e Tru e	True	False	
FTX21	Bool	false	Non-retain	True		True	False	
FTX30	Bool	false	Non-retain	True	Tru	True	False	
FTX31	Bool	false	Non-retain	True	e Tru e	True	False	
FTX40	Bool	false	Non-retain	True	_	True	False	
FTX41	Bool	false	Non-retain	True	Tru	True	False	
FTX50	Bool	false	Non-retain	True	e Tru e	True	False	
FTX51	Bool	false	Non-retain	True	_	True	False	
FTX52	Bool	false	Non-retain	True	_	True	False	
FTX53	Bool	false	Non-retain	True	_	True	False	
FTX54	Bool	false	Non-retain	True	_	True	False	
FTX55	Bool	false	Non-retain	True	_	True	False	
FTX60	Bool	false	Non-retain	True	_	True	False	
FTX61	Bool	false	Non-retain	True	_	True	False	
FTX70	Bool	false	Non-retain	True	_	True	False	
FTX71	Bool	false	Non-retain	True	Tru	True	False	
FTX80	Bool	false	Non-retain	True	e Tru	True	False	

Totally Integrated Automation Portal									
lame	Data type	Default value	Retain	Acces- sible from HMI/OP C UA/We b API	ta- ble fro m	in HMI engi-		Super- vision	Comment
FTX81	Bool	false	Non-retain	True		True	False		
FTX82	Bool	false	Non-retain	True		True	False		
FTX83	Bool	false	Non-retain	True		True	False		
FTX90	Bool	false	Non-retain	True		True	False		
FTX91	Bool	false	Non-retain	True		True	False		
FTX100	Bool	false	Non-retain	True		True	False		
FTX101	Bool	false	Non-retain	True		True	False		
FTX110	Bool	false	Non-retain	True	Tru	True	False		
FTX111	Bool	false	Non-retain	True	e Tru e	True	False		
FTX120	Bool	false	Non-retain	True	Tru	True	False		
FTX121	Bool	false	Non-retain	True		True	False		
FTX122	Bool	false	Non-retain	True		True	False		
FTX123	Bool	false	Non-retain	True		True	False		
FTX130	Bool	false	Non-retain	True		True	False		
FTX131	Bool	false	Non-retain	True		True	False		
FTX132	Bool	false	Non-retain	True		True	False		
FTX133	Bool	false	Non-retain	True		True	False		
position	Real	0.0	Non-retain	True		True	False		
X10	Bool	false	Non-retain	True		True	False		
X11	Bool	false	Non-retain	True		True	False		
X20	Bool	false	Non-retain	True		True	False		
X21	Bool	false	Non-retain	True		True	False		
X30	Bool	false	Non-retain	True		True	False		
X31	Bool	false	Non-retain	True		True	False		
X40	Bool	false	Non-retain	True	e Tru e	True	False		

e

Totally Integrated Automation Portal								
ame		Default value	Retain	Acces- sible from HMI/OP C UA/We b API	ta- ble fro m HM I/O PC UA/ We b	in HMI engi- neer- ing	point	Comment
X41	Bool	false	Non-retain	True	Tru e	True	False	
X50	Bool	false	Non-retain	True	Tru e	True	False	
X51	Bool	false	Non-retain	True		True	False	
X52	Bool	false	Non-retain	True		True	False	
X53	Bool	false	Non-retain	True		True	False	
X54	Bool	false	Non-retain	True		True	False	
X55	Bool	false	Non-retain	True		True	False	
X60	Bool	false	Non-retain	True		True	False	
X61	Bool	false	Non-retain	True		True	False	
X70	Bool	false	Non-retain	True		True	False	
X71	Bool	false	Non-retain	True		True	False	
X80	Bool	false	Non-retain	True	-	True	False	
X81	Bool	false	Non-retain	True	_	True	False	
X82	Bool	false	Non-retain	True		True	False	
X83	Bool	false	Non-retain	True		True	False	
X90	Bool	false	Non-retain	True		True	False	
X91	Bool	false	Non-retain	True		True	False	
X100	Bool	false	Non-retain	True		True	False	
X101	Bool	false	Non-retain	True		True	False	
X110	Bool	false	Non-retain	True		True	False	
X111	Bool	false	Non-retain	True		True	False	
X120	Bool	false	Non-retain	True	_	True	False	
X121	Bool	false	Non-retain	True	_	True	False	
X122	Bool	false	Non-retain	True		True	False	
X123	Bool	false	Non-retain	True		True	False	

Name	Data type	Default value	Retain	Accessible from HMI/OF C UA/We b API	ta- ble fro m	in HMI engi- neer- ing		Comment
					b API			
X130	Bool	false	Non-retain	True	Tru e	True	False	
X131	Bool	false	Non-retain	True	Tru e	True	False	
X132	Bool	false	Non-retain	True	Tru e	True	False	
X133	Bool	false	Non-retain	True	Tru e	True	False	
retracted	Bool	false	Non-retain	True	Tru e	True	False	
sorti	Bool	false	Non-retain	True	Tru e	True	False	
ир	Bool	false	Non-retain	True	Tru e	True	False	
bas	Bool	false	Non-retain	True	Tru e	True	False	
i	Int	0	Non-retain	True	Tru e	True	False	
State	DInt	0	Non-retain	True	Tru e	True	False	
ActionFound	Int	0	Non-retain	True	Tru e	True	False	
Temp								
Constant								

```
0001 "R TRIG movingX"(CLK := "movingX");
0002 "R TRIG movingZ"(CLK := "movingZ");
0003 "R TRIG rotating"(CLK := "rotating");
0004
0005 "F TRIG movingX" (CLK := "movingX");
0006 "F TRIG movingZ"(CLK := "movingZ");
0007 "F TRIG rotating"(CLK := "rotating");
0008 "F TRIG sortie_piece"(CLK := "sortie_piece");
0009
0010 IF "init" THEN
0011 #up := True;
0012 #bas := False;
0013 #retracted := True;
0014
     #sorti := False;
      "MoveX" := False;
0015
      "MoveZ" := False;
0016
      "CCW" := False;
0017
0018 "CW" := False;
0019 "Grab" := False;
0020 "Conv1" := False;
0021
      "Conv2" := False;
     "Output_Conv" := False;
"GripperCCW" := False;
0022
0023
0024
      #position := 0;
```

```
0025 END IF;
0026
0027
0028 IF "MoveX" AND "R TRIG movingX".Q THEN
0029
     #retracted := False;
0030
      #sorti := False;
0031 END IF;
0032 IF "MoveX" AND "F TRIG movingX".Q THEN
0033 #retracted := False;
0034 #sorti := True;
0035 END IF;
0036 IF NOT "MoveX" AND "R_TRIG_movingX".Q THEN
0037
      #retracted := False;
0038
      #sorti := False;
0039 END IF;
0040 IF NOT "MoveX" AND "F TRIG movingX".Q THEN
0041 #retracted := True;
0042 #sorti := False;
0043 END IF;
0044 IF "MoveZ" AND "R TRIG movingZ".Q THEN
0045
      #up := False;
0046
      #bas := False;
0047 END IF;
0048 IF "MoveZ" AND "F TRIG movingZ".Q THEN
0049 #up := False;
0050 #bas := True;
0051 END IF;
0052 IF NOT "MoveZ" AND "R TRIG_movingZ".Q THEN
     #up := False;
0054
     #bas := False;
0055 END_IF;
0056 IF NOT "MoveZ" AND "F TRIG movingZ".Q THEN
0057 #up := True;
0058 #bas := False;
0059 END IF;
0060
0061 \#task[1].IS := \#X10;
0062 \#task[2].IS := \#X20;
0063 \text{ #task[3].IS} := \text{#X30};
0064 \text{ #task}[4].IS := \text{#X40};
0065 \text{ #task}[5].IS := \text{#X50};
0066 #task[6].IS := #X60;
0067 #task[7].IS := #X70;
0068 #task[8].IS := #X80;
0069 \#task[9].IS := \#X90;
0070 \text{ #task}[10].IS := \text{#X100};
0071 #task[11].IS := #X110;
0072 \text{ #task}[12].IS := \text{#X120};
0073 #task[13].IS := #X130;
0074
0075 #task[1].IC := NOT "wait1";
0076 #task[2].IC := NOT "wait2";
0077 #task[3].IC := (#position = 0) AND #retracted AND "wait1" AND #up AND NOT "de-
     tected";
0078 #task[4].IC := #up AND #retracted AND "detected" AND (#position = 1);
0079 #task[5].IC := #up AND #retracted AND "detected" AND (#position = 2);
0080 #task[6].IC := (#position = 0) AND #retracted AND "wait2" AND #up AND NOT "de-
     tected";
0081 #task[7].IC := #up AND #retracted AND "detected" AND (#position = 3);
```

```
Totally Integrated Automation Portal
```

```
0082 #task[8].IC := #up AND #retracted AND NOT "detected" AND (#position = 2);
0083 #task[9].IC := "p exit";
0084 #task[10].IC := (#position = 2) AND #retracted AND #up AND NOT "detec-
     ted" AND "wait1";
0085 #task[11].IC := (#position = 2) AND #retracted AND #up AND NOT "detec-
     ted" AND "wait2";
0086 #task[12].IC := #retracted AND "wait1" AND #up AND NOT "detected" AND (#posi-
     tion = 1);
0087 #task[13].IC := #retracted AND "wait2" AND #up AND NOT "detected" AND (#posi-
     tion = 3);
0088
0089 #State := 0;
0090 FOR #i := 0 TO 13 DO
      #State := #State + BOOL TO INT(#task[13-#i].IS) * 2 ** (#i * 2);
0092
      #State := #State + BOOL TO INT(#task[13-#i].IC) * 2 ** ((#i * 2) + 1);
0093 END FOR;
0094
0095 "State Action DB" (S State:=#State,
0096
              Action=>#ActionFound,
0097
              ArEtat:="Control Table".State,
0098
              ArAction:="Control Table".Action);
0099
0100
0101 FOR #i := 0 TO 13 DO
0102 #task[#i].AUTf := 0;
0103 END FOR;
0104 #task[#ActionFound].AUTf := 1;
0105
0106 #task[1].AUT := #task[12].IS AND #task[1].AUTf;
0107 #task[2].AUT := #task[13].IS AND #task[2].AUTf;
0108 #task[3].AUT := #task[6].IS AND #task[3].AUTf;
0109 #task[4].AUT := #task[12].IS AND #task[4].AUTf;
0110 #task[5].AUT := #task[8].IS AND #task[9].IS AND #task[10].IS AND #task[11].IS
     AND #task[5].AUTf;
0111 #task[6].AUT := #task[3].IS AND #task[6].AUTf;
0112 #task[7].AUT := #task[8].IS AND #task[13].IS AND #task[7].AUTf;
0113 #task[8].AUT := #task[5].IS AND #task[7].IS AND #task[10].IS AND #task[11].IS
     AND #task[8].AUTf;
0114 #task[9].AUT := #task[5].IS AND #task[9].AUTf;
0115 #task[10].AUT := #task[5].IS AND #task[8].IS AND #task[11].IS AND
     #task[10].AUTf;
0116 #task[11].AUT := #task[5].IS AND #task[8].IS AND #task[10].IS AND
     #task[11].AUTf;
0117 #task[12].AUT := #task[1].IS AND #task[4].IS AND #task[8].IS AND
     #task[12].AUTf;
0118 #task[13].AUT := #task[2].IS AND #task[7].IS AND #task[8].IS AND
     #task[13].AUTf;
0120 (*Transition : GConv1 T1*)
0121 #FTX10 := #task[1].IS AND #task[1].AUT AND #task[1].IC;
0122 #FTX11 := #X11 AND "wait1";
0123
0124 (*Transition : GConv2 T2*)
0125 #FTX20 := #X20 AND #task[2].AUT AND #task[2].IC;
0126 #FTX21 := #X21 AND "wait2";
0127
0128 (* Transition : GCCW0 1 T3*)
0129 #FTX30 := #X30 AND #task[3].AUT AND #task[3].IC;
0130 #FTX31 := #X31 AND "F_TRIG_rotating".Q;
```

```
0131
0132 (* Transition : GCCW1 2 T4*)
0133 #FTX40 := #X40 AND #task[4].AUT AND #task[4].IC;
0134 #FTX41 := #X41 AND "F TRIG rotating".Q;
0135
0136 (* Transition : GDEPOSER T5*)
0137 #FTX50 := #X50 AND #task[5].AUT AND #task[5].IC;
0138 #FTX51 := #X51 AND "F_TRIG_movingX".Q;
0139 #FTX52 := #X52 AND "F TRIG movingZ".Q;
0140 #FTX53 := #X53;
0141 #FTX54 := #X54 AND "F TRIG movingZ".Q;
0142 #FTX55 := #X55 AND "F_TRIG_movingX".Q;
0143
0144 (* Transition : GCW0 3 T6*)
0145 #FTX60 := #X60 AND #task[6].AUT AND #task[6].IC;
0146 #FTX61 := #X61 AND "F TRIG rotating".Q;
0147
0148 (* Transition : GCW3 2 T7*)
0149 #FTX70 := #X70 AND #task[7].AUT AND #task[7].IC;
0150 #FTX71 := #X71 AND "F TRIG rotating".Q;
0151
0152 (* Transition : GCCW2 0 T8*)
0153 #FTX80 := #X80 AND #task[8].AUT AND #task[8].IC;
0154 #FTX81 := #X81 AND "F TRIG rotating".Q;
0155 #FTX82 := #X82;
0156 #FTX83 := #X83 AND "F TRIG rotating".Q;
0157
0158 (* Transition : GConv Sortie T9*)
0159 #FTX90 := #X90 AND #task[9].AUT AND #task[9].IC;
0160 #FTX91 := #X91 AND "F TRIG sortie piece".Q;
0161
0162 (* Transition : GCW3 2 T10*)
0163 #FTX100 := #X100 AND #task[10].AUT AND #task[10].IC;
0164 #FTX101 := #X101 AND "F TRIG rotating".Q;
0165
0166 (* Transition : GCCW2 3 T11*)
0167 #FTX110 := #X110 AND #task[11].AUT AND #task[11].IC;
0168 #FTX111 := #X111 AND "F TRIG rotating".Q;
0169
0170 (* Transition : GPRENDRE 1 T12*)
0171 #FTX120 := #X120 AND #task[12].AUT AND #task[12].IC;
0172 #FTX121 := #X121 AND "F_TRIG_movingZ".Q;
0173 #FTX122 := #X122;
0174 #FTX123 := #X123 AND "F_TRIG_movingZ".Q;
0175
0176 (* Transition : GPRENDRE 2 T13*)
0177 #FTX130 := #X130 AND #task[13].AUT AND #task[13].IC;
0178 #FTX131 := #X131 AND "F TRIG movingZ".Q;
0179 #FTX132 := #X132;
0180 #FTX133 := #X133 AND "F TRIG movingZ".Q;
0182 IF "CCW" AND "R TRIG rotating".Q THEN
0184 END IF;
0185 IF (#X31 OR #X41 OR #X81 OR #X83 OR #X111) AND "F TRIG rotating".Q THEN
     \#position := \#position + 0.5;
0186
0187 END IF;
0188
0189 IF "CW" AND "R TRIG rotating".Q THEN
```

```
#position := #position - 0.5;
0190
0191 END IF;
0192 IF (#X61 OR #X71 OR #X101) AND "F TRIG rotating".Q THEN
     \#position := \#position - 0.5;
0194 END IF;
0195
0196 IF #position = 4 THEN
0197
     #position := 0;
0198 END IF;
0199 IF #position < 0 THEN
0200 #position := 3.5;
0201 END IF;
0202
0203 (*# Task 1 : GConv1 T1*)
0204 #X10 := #FTX11 OR #X10 AND NOT #FTX10 OR "init";
0205 #X11 := (#FTX10 OR #X11 AND NOT #FTX11) AND NOT "init";
0206
0207 (*# Etape : GConv2 T2*)
0208 #X20 := #FTX21 OR #X20 AND NOT #FTX20 OR "init";
0209 #X21 := (#FTX20 OR #X21 AND NOT #FTX21) AND NOT "init";
0210
0211 (*# Etape : GCCW0 1 T3*)
0212 #X30 := #FTX31 OR #X30 AND NOT #FTX30 OR "init";
0213 #X31 := (#FTX30 OR #X31 AND NOT #FTX31) AND NOT "init";
0214
0215 (*# Etape : GCCW1 2 T4*)
0216 #X40 := #FTX41 OR #X40 AND NOT #FTX40 OR "init";
0217 #X41 := (#FTX40 OR #X41 AND NOT #FTX41) AND NOT "init";
0218
0219 (*# Etape : GDEPOSER T5*)
0220 #X50 := #FTX55 OR #X50 AND NOT #FTX50 OR "init";
0221 #X51 := (#FTX50 OR #X51 AND NOT #FTX51) AND NOT "init";
0222 #X52 := (#FTX51 OR #X52 AND NOT #FTX52) AND NOT "init";
0223 #X53 := (#FTX52 OR #X53 AND NOT #FTX53) AND NOT "init";
0224 #X54 := (#FTX53 OR #X54 AND NOT #FTX54) AND NOT "init";
0225 #X55 := (#FTX54 OR #X55 AND NOT #FTX55) AND NOT "init";
0227 (*# Etape : GCW0_3_T6*)
0228 #X60 := #FTX61 OR #X60 AND NOT #FTX60 OR "init";
0229 #X61 := (#FTX60 OR #X61 AND NOT #FTX61) AND NOT "init";
0230
0231 (*# Etape : GCW3 2 T7*)
0232 #X70 := #FTX71 OR #X70 AND NOT #FTX70 OR "init";
0233 #X71 := (#FTX70 OR #X71 AND NOT #FTX71) AND NOT "init";
0234
0235 (*# Etape : GCCW2 0 T8*)
0236 #X80 := #FTX83 OR #X80 AND NOT #FTX80 OR "init";
0237 #X81 := (#FTX80 OR #X81 AND NOT #FTX81) AND NOT "init";
0238 #X82 := (#FTX81 OR #X82 AND NOT #FTX82) AND NOT "init";
0239 #X83 := (#FTX82 OR #X83 AND NOT #FTX83) AND NOT "init";
0240
0241 (*# Etape : GConv_Sortie_T9*)
0242 #X90 := #FTX91 OR #X90 AND NOT #FTX90 OR "init";
0243 #X91 := (#FTX90 OR #X91 AND NOT #FTX91) AND NOT "init";
0245 (*# Etape : GCW3_2 T10*)
0246 #X100 := #FTX101 OR #X100 AND NOT #FTX100 OR "init";
0247 #X101 := (#FTX100 OR #X101 AND NOT #FTX101) AND NOT "init";
0248
```

```
0249 (*# Etape : GCCW2 3 T11*)
0250 #X110 := #FTX111 OR #X110 AND NOT #FTX110 OR "init";
0251 #X111 := (#FTX110 OR #X111 AND NOT #FTX111) AND NOT "init";
0253 (*# Etape : GPRENDRE 1 T12*)
0254 #X120 := #FTX123 OR #X120 AND NOT #FTX120 OR "init";
0255 #X121 := (#FTX120 OR #X121 AND NOT #FTX121) AND NOT "init";
0256 #X122 := (#FTX121 OR #X122 AND NOT #FTX122) AND NOT "init";
0257 #X123 := (#FTX122 OR #X123 AND NOT #FTX123) AND NOT "init";
0258
0259 (*# Etape : GPRENDRE 2 T13*)
0260 #X130 := #FTX133 OR #X130 AND NOT #FTX130 OR "init";
0261 #X131 := (#FTX130 OR #X131 AND NOT #FTX131) AND NOT "init";
0262 #X132 := (#FTX131 OR #X132 AND NOT #FTX132) AND NOT "init";
0263 #X133 := (#FTX132 OR #X133 AND NOT #FTX133) AND NOT "init";
0264
0265 (*# Action*)
0266 IF #FTX52 THEN
0267
     "Grab" := False;
0268 END IF;
0269 IF #FTX121 THEN
0270 "Grab" := True;
0271 END IF;
0272 IF #FTX131 THEN
0273 "Grab" := True;
0274 END IF;
0275 "Conv1" := #X11;
0276 "Conv2" := #X21;
0277 IF #FTX30 OR #FTX40 OR #FTX80 OR #FTX82 OR #FTX110 THEN
0278
     "CCW" := True;
0279 END_IF;
0280 IF (#X31 OR #X41 OR #X81 OR #X83 OR #X111) AND "R TRIG rotating".Q THEN
0281 "CCW" := False;
0282 END IF;
0283 "MoveX" := #X51 OR #X52 OR #X53 OR #X54;
0284 "Movez" := #X52 OR #X53 OR #X121 OR #X122 OR #X131 OR #X132;
0285 IF #FTX60 OR #FTX70 OR #FTX100 THEN
0286 "CW" := True;
0287 END IF;
0288 IF (#X61 OR #X71 OR #X101) AND "R TRIG rotating".Q THEN
0289 "CW" := False;
0290 END_IF;
0291 "Output Conv" := #X91;
0292 "Feeding1" := #X11 OR NOT "debut arrivee1";
0293 "Feeding2" := #X21 OR NOT "debut arrivee2";
0294 "GripperCCW" := #X51;
```

Symbol	Address	Type	Comment
"CCW"	%Q0.3	Bool	
"Control Table".Action		Array	
"Control Table".State		Array	
"Conv1"	%Q0.1	Bool	
"Conv2"	%Q0.2	Bool	
"CW"	%Q0.6	Bool	
"debut_arrivee1"	%10.4	Bool	
"debut_arrivee2"	%10.5	Bool	
"detected"	%I1.0	Bool	
"F_TRIG_movingX".Q		Bool	
"F_TRIG_movingZ".Q		Bool	

Totally Integrated Automation Portal			
Symbol	Address	Туре	Comment
'F_TRIG_rotating".Q		Bool	
'F_TRIG_sortie_piece".Q		Bool	
'Feeding1"	%Q1.0	Bool	
'Feeding2"	%Q1.1	Bool	
"Grab"	%Q0.0	Bool	
'GripperCCW"	%Q1.2	Bool	
'init"	%I1.2	Bool	
'MoveX"	%Q0.4	Bool	
'MoveZ"	%Q0.5	Bool	
'movingX"	%10.0	Bool	
movingZ"	%10.1	Bool	
'Output_Conv"	%Q0.7	Bool	
p_exit"	%I1.1	Bool	
R_TRIG_movingX".Q		Bool	
'R_TRIG_movingZ".Q		Bool	
'R_TRIG_rotating".Q		Bool	
'rotating"	%10.6	Bool	
'sortie_piece"	%10.7	Bool	
'wait1"	%10.2	Bool	
'wait2"	%10.3	Bool	
#ActionFound		Int	
#bas		Bool	
#FTX10		Bool	
#FTX11		Bool	
#FTX20		Bool	
#FTX21		Bool	
#FTX30		Bool	
#FTX31		Bool	
#FTX40		Bool	
#FTX41		Bool	
#FTX50		Bool	
#FTX51		Bool	
#FTX52		Bool	
#FTX53		Bool	
#FTX54		Bool	
FTX55		Bool	
#FTX60		Bool	
#FTX61		Bool	
#FTX70		Bool	
#FTX71		Bool	
#FTX80		Bool	
#FTX81		Bool	
#FTX82		Bool	
#FTX83		Bool	
#FTX90		Bool	
#FTX91		Bool	
#FTX100			
		Bool	
#FTX101		Bool	
#FTX110		Bool	
#FTX111		Bool	
#FTX120		Bool	
#FTX121		Bool	
#FTX122		Bool	
#FTX123		Bool	
#FTX130		Bool	
#FTX131		Bool	
#FTX132		Bool	

	ı		
Symbol	Address	Туре	Comment
FTX133		Bool	
‡i		Int	
position #position		Real	
retracted		Bool	
#sorti		Bool	
#State		DInt	
task[*].AUTf		Bool	
task[*].IC		Bool	
task[*].IS		Bool	
task[1].AUT		Bool	
task[1].AUTf		Bool	
task[1].IC		Bool	
		Bool	
#task[1].IS			
task[2].AUT		Bool	
task[2].AUTf		Bool	
task[2].IC		Bool	
#task[2].IS		Bool	
#task[3].AUT		Bool	
#task[3].AUTf		Bool	
#task[3].IC		Bool	
#task[3].IS		Bool	
#task[4].AUT		Bool	
#task[4].AUTf		Bool	
#task[4].IC		Bool	
#task[4].IS		Bool	
#task[5].AUT		Bool	
#task[5].AUTf		Bool	
#task[5].IC		Bool	
#task[5].IS		Bool	
#task[6].AUT		Bool	
#task[6].AUTf		Bool	
#task[6].IC		Bool	
#task[6].IS		Bool	
#task[7].AUT		Bool	
#task[7].AUTf		Bool	
#task[7].IC		Bool	
#task[7].IS		Bool	
#task[8].AUT		Bool	
#task[8].AUTf		Bool	
#task[8].IC		Bool	
task[8].IS		Bool	
task[9].AUT		Bool	
#task[9].AUTf		Bool	
task[9].IC		Bool	
task[9].IS		Bool	
task[10].AUT		Bool	
task[10].AUTf		Bool	
task[10].IC		Bool	
#task[10].IS		Bool	
task[11].AUT		Bool	
task[11].AUTf		Bool	
#task[11].IC		Bool	
task[11].IS		Bool	
task[11].AUT		Bool	
task[12].AUTf task[12].IC		Bool Bool	
		ROOL	The state of the s

Symbol #task[13].AUT #task[13].AUTf	Address	Туре	Comment
task[13].AUTf		Bool	
		Bool	
task[13].IC		Bool	
task[13].IS		Bool	
up		Bool	
X10		Bool	
#X11		Bool	
‡X20		Bool	
‡X21			
		Bool	
X30		Bool	
X31		Bool	
‡X40		Bool	
X41		Bool	
X50		Bool	
ŧX51		Bool	
#X52		Bool	
#X53		Bool	
#X54		Bool	
#X55		Bool	
#X60		Bool	
#X61		Bool	
#X70		Bool	
#X71		Bool	
#X80		Bool	
#X81		Bool	
‡X82		Bool	
#X83		Bool	
#X90		Bool	
#X91		Bool	
#X100		Bool	
X101		Bool	
X110		Bool	
‡X111		Bool	
‡X120		Bool	
X121		Bool	
‡X122		Bool	
#X123		Bool	
#X130		Bool	
#X131		Bool	
#X132		Bool	
¥X133		Bool	

Program_DB [DB10]

Program_DB	Properties				
General					
Name	Program_DB	Number	10	Туре	DB
Language	DB	Numbering	Automatic		
Information					
Title		Author		Comment	
Family		Version	0.1	User-defined ID	

lame	Data type	Start value	Retain	Acces- sible		Visible in HMI		Super- vision	Comment
				from HMI/O PC UA/We b API	ble fro m	engi-			
Input									
Output									
InOut									
▼ Static									
▼ task	Ar- ray[013] of Struct		False	True	е		False		
▼ task[0]	Struct		False	True	e		False		
AUT	Bool	false	False	True	Tru e	True	False		
AUTf	Bool	false	False	True	Tru e	True	False		
IC	Bool	false	False	True	Tru e	True	False		
IS	Bool	false	False	True	Tru e	True	False		
▼ task[1]	Struct		False	True	Tru e	True	False		
AUT	Bool	false	False	True	Tru e	True	False		
AUTf	Bool	false	False	True	Tru e	True	False		
IC	Bool	false	False	True	Tru e	True	False		
IS	Bool	false	False	True	Tru e	True	False		
▼ task[2]	Struct		False	True	Tru e	True	False		
AUT	Bool	false	False	True	Tru e	True	False		
AUTf	Bool	false	False	True	_	True	False		
IC	Bool	false	False	True		True	False		

ame	Data type	Start value	Retain	Acces- sible from HMI/O PC UA/We b API	ta- ble fro m	ing		Super- vision	Comment
IS	Bool	false	False	True		True	False		
▼ task[3]	Struct		False	True		True	False		
AUT	Bool	false	False	True		True	False		
AUTf	Bool	false	False	True	_	True	False		
IC	Bool	false	False	True		True	False		
IS	Bool	false	False	True		True	False		
▼ task[4]	Struct		False	True		True	False		
AUT	Bool	false	False	True	Tru	True	False		
AUTf	Bool	false	False	True		True	False		
IC	Bool	false	False	True		True	False		
IS	Bool	false	False	True		True	False		
▼ task[5]	Struct		False	True		True	False		
AUT	Bool	false	False	True		True	False		
AUTf	Bool	false	False	True		True	False		
IC	Bool	false	False	True		True	False		
IS	Bool	false	False	True		True	False		
▼ task[6]	Struct		False	True		True	False		
AUT	Bool	false	False	True		True	False		
AUTf	Bool	false	False	True		True	False		
IC	Bool	false	False	True		True	False		
IS	Bool	false	False	True		True	False		
▼ task[7]	Struct		False	True	e Tru	True	False		
AUT	Bool	false	False	True	e Tru	True	False		
AUTf	Bool	false	False	True	e Tru	True	False		
IC	Bool	false	False	True	e Tru	True	False		

lame	Data type	Start value	Retain	Accessible from HMI/O PC UA/We b API	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
IS	Bool	false	False	True	Tru e	True	False		
▼ task[8]	Struct		False	True		True	False		
AUT	Bool	false	False	True		True	False		
AUTf	Bool	false	False	True	Tru	True	False		
IC	Bool	false	False	True		True	False		
IS	Bool	false	False	True		True	False		
▼ task[9]	Struct		False	True		True	False		
AUT	Bool	false	False	True		True	False		
AUTf	Bool	false	False	True		True	False		
IC	Bool	false	False	True		True	False		
IS	Bool	false	False	True	e Tru	True	False		
▼ task[10]	Struct		False	True	e Tru	True	False		
AUT	Bool	false	False	True	e Tru	True	False		
AUTf	Bool	false	False	True	e Tru	True	False		
IC	Bool	false	False	True	e Tru	True	False		
IS	Bool	false	False	True	e Tru	True	False		
▼ task[11]	Struct		False	True	e Tru	True	False		
AUT		false	False	True	е	True	False		
AUTf		false	False	True	e	True	False		
IC		false	False	True	е	True	False		
IS	Bool	false	False	True	e	True	False		
		Igi2c			е				
▼ task[12]	Struct		False	True	е	True	False		
AUT		false	False	True	е	True	False		
AUTf		false	False	True	е	True	False		
IC	Bool	false	False	True	Tru e	True	False		

Name		Start value		Acces- sible from HMI/O PC UA/We b API	ta- ble fro m		point	Super- vision	Comment
IS	Bool	false	False	True	Tru e	True	False		
▼ task[13]	Struct		False	True	Tru e	True	False		
AUT	Bool	false	False	True	Tru e	True	False		
AUTf	Bool	false	False	True		True	False		
IC	Bool	false	False	True		True	False		
IS	Bool	false	False	True		True	False		
FTX10	Bool	false	False	True	Tru	True	False		
FTX11	Bool	false	False	True		True	False		
FTX20	Bool	false	False	True		True	False		
FTX21	Bool	false	False	True		True	False		
FTX30	Bool	false	False	True	e Tru	True	False		
FTX31	Bool	false	False	True	e Tru	True	False		
FTX40	Bool	false	False	True	e Tru	True	False		
FTX41	Bool	false	False	True	e Tru	True	False		
FTX50		false	False	True	е		False		
FTX51	Bool	false	False	True	e		False		
FTX52	Bool	false	False	True	е		False		
				True	е				
FTX53	Bool	false	False		е	True	False		
FTX54	Bool	false	False	True	е		False		
FTX55	Bool	false	False	True	e	True	False		
FTX60	Bool	false	False	True	е	True	False		
FTX61	Bool	false	False	True	Tru e		False		
FTX70	Bool	false	False	True	Tru e	True	False		
FTX71	Bool	false	False	True	Tru e	True	False		
FTX80	Bool	false	False	True	_	True	False		

Name		pe Start value		Accessible from HMI/O PC UA/We b API	ta- ble fro m		point	Super- vision	Comment
FTX81	Bool	false	False	True	Tru e	True	False		
FTX82	Bool	false	False	True	Tru e	True	False		
FTX83	Bool	false	False	True	Tru e	True	False		
FTX90	Bool	false	False	True		True	False		
FTX91	Bool	false	False	True		True	False		
FTX100	Bool	false	False	True	_	True	False		
FTX101	Bool	false	False	True	Tru	True	False		
FTX110	Bool	false	False	True		True	False		
FTX111	Bool	false	False	True		True	False		
FTX120	Bool	false	False	True		True	False		
FTX121	Bool	false	False	True		True	False		
FTX122	Bool	false	False	True		True	False		
FTX123	Bool	false	False	True		True	False		
FTX130	Bool	false	False	True		True	False		
FTX131	Bool	false	False	True		True	False		
FTX132	Bool	false	False	True		True	False		
FTX133	Bool	false	False	True		True	False		
position	Real	0.0	False	True		True	False		
X10	Bool	false	False	True	e Tru	True	False		
X11	Bool	false	False	True	e Tru	True	False		
X20	Bool	false	False	True	e Tru	True	False		
X21	Bool	false	False	True	e Tru	True	False		
X30	Bool	false	False	True	e Tru	True	False		
X31	Bool	false	False	True	e Tru	True	False		
X40	Bool	false	False	True	е	True	False		

ame	Data type	Start value		Accessible from HMI/O PC UA/We b API	ta- ble fro m HM I/O PC UA/ We b API	in HMI engi- neer- ing	point	Super- vision	Comment
X41	Bool	false	False	True	Tru e	True	False		
X50	Bool	false	False	True	Tru e	True	False		
X51	Bool	false	False	True		True	False		
X52	Bool	false	False	True		True	False		
X53	Bool	false	False	True		True	False		
X54	Bool	false	False	True	Tru	True	False		
X55	Bool	false	False	True		True	False		
X60	Bool	false	False	True		True	False		
X61	Bool	false	False	True		True	False		
X70	Bool	false	False	True		True	False		
X71	Bool	false	False	True	e Tru	True	False		
X80	Bool	false	False	True		True	False		
X81	Bool	false	False	True		True	False		
X82	Bool	false	False	True		True	False		
X83	Bool	false	False	True		True	False		
X90	Bool	false	False	True		True	False		
X91	Bool	false	False	True		True	False		
X100	Bool	false	False	True		True	False		
X101	Bool	false	False	True		True	False		
X110	Bool	false	False	True		True	False		
X111	Bool	false	False	True		True	False		
X120	Bool	false	False	True		True	False		
X121	Bool	false	False	True		True	False		
X122	Bool	false	False	True		True	False		
X123	Bool	false	False	True	e Tru	True	False		

Totally Integrated	
Automation Portal	

Control Table [DB1]

Control Table	Properties				
General					
Name	Control Table	Number	1	Туре	DB
Language	DB	Numbering	Automatic		
Information					
Title		Author		Comment	
Family		Version	0.1	User-defined ID	

ame	рата туре	Start value	Retain	Accessible from HMI/O PC UA/We b API	ta- ble fro m	Visible in HMI engi- neer- ing		Super- vision	Comment
Static									
▼ State	Ar- ray[0235] of DInt		False	True	Tru e	True	False		
State[0]	DInt	0	False	True	Tru e	True	False		
State[1]	DInt	3528021	False	True	Tru e	True	False		
State[2]	DInt	5592151	False	True	Tru e	True	False		
State[3]	DInt	5592407	False	True	Tru e	True	False		
State[4]	DInt	5594613	False	True	Tru e	True	False		
State[5]	DInt	5594869	False	True		True	False		
State[6]	DInt	5723477	False	True		True	False		
State[7]	DInt	6116693	False	True		True	False		
State[8]	DInt	7705941	False	True		True	False		
State[9]	DInt	7722325	False	True		True	False		
State[10]	DInt	9789141	False	True		True	False		
State[11]	DInt	9789397	False	True		True	False		
State[12]	DInt	9794901	False	True		True	False		
State[13]	DInt	9917781	False	True		True	False		
State[14]	DInt	10310997	False	True		True	False		

Totally Integrate Automation Port									
Name	Data type	Start value	Retain	sible from	ta- ble fro m			Super- vision	Comment
State[15]	DInt	11883605	False	True	Tru e	True	False		
State[16]	DInt	11883861	False	True	Tru e	True	False		
State[17]	DInt	13976661	False	True		True	False		
State[18]	DInt	13988949	False	True	_	True	False		
State[19]	DInt	13989205	False	True	-	True	False		
State[20]	DInt	14112085	False	True	Tru e	True	False		
State[21]	DInt	16078165	False	True	Tru e	True	False		
State[22]	DInt	18174805	False	True	Tru e	True	False		
State[23]	DInt	18175069	False	True	-	True	False		
State[24]	DInt	18175325	False	True	Tru e	True	False		
State[25]	DInt	18177525	False	True		True	False		
State[26]	DInt	18183509	False	True	Tru e	True	False		
State[27]	DInt	18306389	False	True	Tru e	True	False		
State[28]	DInt	19256661	False	True	Tru e	True	False		
State[29]	DInt	20305237	False	True	_	True	False		
State[30]	DInt	20305493	False	True		True	False		
State[31]	DInt	21321045	False	True	Tru e	True	False		
State[32]	DInt	22304085	False	True	Tru e	True	False		
State[33]	DInt	22304597	False	True	Tru e	True	False		
State[34]	DInt	22306805	False	True	Tru e	True	False		
State[35]	DInt	22353237	False	True	Tru e	True	False		
State[36]	DInt	22368341	False	True	Tru e	True	False		
State[37]	DInt	22368343	False	True	Tru e	True	False		
State[38]	DInt	22369109	False	True	Tru e	True	False		
State[39]	DInt	22369111	False	True	Tru e	True	False		

Totally Integrate Automation Port									
Name	Data type	Start value	Retain	sible from	ta- ble fro m			Super- vision	Comment
State[40]	DInt	22369301	False	True	Tru e	True	False		
State[41]	DInt	22369349	False	True	Tru e	True	False		
State[42]	DInt	22369361	False	True		True	False		
State[43]	DInt	22369364	False	True		True	False		
State[44]	DInt	22369367	False	True	-	True	False		
State[45]	DInt	22369373	False	True	Tru e	True	False		
State[46]	DInt	22369617	False	True	Tru e	True	False		
State[47]	DInt	22369620	False	True	Tru e	True	False		
State[48]	DInt	22369623	False	True	Tru e	True	False		
State[49]	DInt	22369629	False	True	Tru e	True	False		
State[50]	DInt	22369813	False	True	Tru e	True	False		
State[51]	DInt	22369879	False	True	Tru e	True	False		
State[52]	DInt	22369885	False	True	Tru e	True	False		
State[53]	DInt	22370069	False	True	Tru e	True	False		
State[54]	DInt	22370117	False	True	Tru e	True	False		
State[55]	DInt	22370129	False	True	Tru e	True	False		
State[56]	DInt	22370135	False	True	Tru e	True	False		
State[57]	DInt	22370141	False	True	Tru e	True	False		
State[58]	DInt	22370805	False	True	Tru e	True	False		
State[59]	DInt	22371317	False	True	Tru e	True	False		
State[60]	DInt	22371573	False	True	е	True	False		
State[61]	DInt	22371813	False	True	е	True	False		
State[62]	DInt	22371829	False	True	е	True	False		
State[63]	DInt	22372085	False	True	Tru e	True	False		
State[64]	DInt	22372277	False	True	Tru e	True	False		

Totally Integrate Automation Port									
Name	Data type	Start value	Retain	sible from	ta- ble fro m			Super- vision	Comment
State[65]	DInt	22372325	False	True	Tru e	True	False		
State[66]	DInt	22372341	False	True	Tru e	True	False		
State[67]	DInt	22373717	False	True	Tru	True	False		
State[68]	DInt	22377813	False	True		True	False		
State[69]	DInt	22500693	False	True	Tru	True	False		
State[70]	DInt	22631765	False	True	Tru e	True	False		
State[71]	DInt	23450965	False	True	Tru e	True	False		
State[72]	DInt	23451221	False	True	Tru	True	False		
State[73]	DInt	24483157	False	True	Tru e	True	False		
State[74]	DInt	24499285	False	True	Tru e	True	False		
State[75]	DInt	24499541	False	True	Tru e	True	False		
State[76]	DInt	25515349	False	True	Tru e	True	False		
State[77]	DInt	25515861	False	True	Tru e	True	False		
State[78]	DInt	26498389	False	True	Tru e	True	False		
State[79]	DInt	26498901	False	True	Tru e	True	False		
State[80]	DInt	26501077	False	True	Tru e	True	False		
State[81]	DInt	26559829	False	True		True	False		
State[82]	DInt	26562645	False	True	Tru e	True	False		
State[83]	DInt	26563413	False	True	Tru e	True	False		
State[84]	DInt	26563677	False	True	Tru e	True	False		
State[85]	DInt	26563921	False	True	Tru e	True	False		
State[86]	DInt	26563933	False	True	Tru e	True	False		
State[87]	DInt	26564189	False	True	Tru e	True	False		
State[88]	DInt	26564373	False	True	Tru e	True	False		
State[89]	DInt	26564433	False	True	Tru e	True	False		

Totally Integrated Automation Porta									
lame	Data type	Start value	Retain	Acces- sible from HMI/O PC UA/We b API	ta- ble fro m	ing		Super- vision	Comment
State[90]	DInt	26564445	False	True	Tru	True	False		
State[91]	DInt	26565333	False	True	e Tru e	True	False		
State[92]	DInt	26565589	False	True		True	False		
State[93]	DInt	26565845	False	True	e Tru e	True	False		
State[94]	DInt	26566101	False	True	Tru e	True	False		
State[95]	DInt	26566357	False	True	-	True	False		
State[96]	DInt	26566549	False	True	Tru e	True	False		
State[97]	DInt	26566613	False	True	-	True	False		
State[98]	DInt	26568021	False	True	e	True	False		
State[99]	DInt	26571861	False	True	Tru e	True	False		
State[100]	DInt	26572117	False	True	_	True	False		
State[101]	DInt	26694741	False	True	Tru e	True	False		
State[102]	DInt	26694997	False	True	Tru e	True	False		
State[103]	DInt	26826069	False	True		True	False		
State[104]	DInt	27612245	False	True	Tru e	True	False		
State[105]	DInt	27612501	False	True		True	False		
State[106]	DInt	27613013	False	True	Tru e	True	False		
State[107]	DInt	28660821	False	True	Tru e	True	False		
State[108]	DInt	28661077	False	True	Tru e	True	False		
State[109]	DInt	28661333	False	True	Tru e	True	False		
State[110]	DInt	28661589	False	True	e	True	False		
State[111]	DInt	29709653	False	True	е	True	False		
State[112]	DInt	30692693	False	True	е	True	False		
State[113]	DInt	30693205	False	True	е	True	False		
State[114]	DInt	30695381	False	True	Tru e	True	False		

Totally Integrated Automation Portal									
Name	Data type	Start value	Retain	Acces- sible from HMI/O PC UA/We b API	ta- ble fro m			Super- vision	Comment
State[115]	DInt	30753877	False	True	Tru e	True	False		
State[116]	DInt	30754133	False	True		True	False		
State[117]	DInt	30756949	False	True	Tru	True	False		
State[118]	DInt	30757461	False	True		True	False		
State[119]	DInt	30758225	False	True		True	False		
State[120]	DInt	30758228	False	True	e Tru	True	False		
State[121]	Dlnt	30758237	False	True	e Tru	True	False		
State[122]	Dlnt	30759637	False	True	e Tru	True	False		
State[123]	Dlnt	30760661	False	True	e Tru	True	False		
State[124]	Dlnt	30760917	False	True	e	True	False		
State[121]	Dint	30762069	False	True	e	True	False		
					e				
State[126]	DInt	30762325	False	True	e	True	False		
State[127]	DInt	30766165	False	True	Tru e	True	False		
State[128]	DInt	30766421	False	True	Tru e	True	False		
State[129]	DInt	30889045	False	True	Tru e	True	False		
State[130]	DInt	30889301	False	True		True	False		
State[131]	DInt	31806805	False	True		True	False		
State[132]	DInt	32855125	False	True	Tru	True	False		
State[133]	DInt	32855381	False	True		True	False		
State[134]	DInt	34954869	False	True		True	False		
State[135]	DInt	34955125	False	True		True	False		
State[136]	DInt	34985045	False	True		True	False		
State[137]	DInt	34985301	False	True		True	False		
State[138]	Dlnt	35083605	False	True	e Tru	True	False		
State[139]	DInt	35476821	False	True	e Tru	True	False		

Totally Integrated Automation Portal									
Name	Data type	Start value	Retain	Acces- sible from HMI/O PC UA/We b API	ta- ble fro m			Super- vision	Comment
State[140]	DInt	38884693	False	True	Tru e	True	False		
State[141]	DInt	39081301	False	True	Tru e	True	False		
State[142]	DInt	39081813	False	True		True	False		
State[143]	DInt	39083893	False	True	-	True	False		
State[144]	DInt	39145557	False	True	-	True	False		
State[145]	DInt	39145559	False	True		True	False		
State[146]	DInt	39146325	False	True		True	False		
State[147]	DInt	39146327	False	True	_	True	False		
State[148]	DInt	39146583	False	True		True	False		
State[149]	DInt	39146836	False	True	-	True	False		
State[150]	DInt	39146839	False	True		True	False		
State[151]	DInt	39148405	False	True		True	False		
State[152]	DInt	39148661	False	True	_	True	False		
State[153]	DInt	39148917	False	True		True	False		
State[154]	DInt	39149157	False	True		True	False		
State[155]	DInt	39149173	False	True		True	False		
State[156]	DInt	39149413	False	True		True	False		
State[157]	DInt	39149429	False	True		True	False		
State[158]	DInt	39163221	False	True		True	False		
State[159]	DInt	39179349	False	True		True	False		
State[160]	DInt	39179605	False	True		True	False		
State[161]	DInt	39179861	False	True		True	False		
State[162]	DInt	39277653	False	True		True	False		
State[163]	DInt	39277909	False	True		True	False		
State[164]	DInt	39408981	False	True	_	True	False		

Totally Integrate Automation Por									
Name	Data type	Start value	Retain	sible from	ta- ble fro m			Super- vision	Comment
State[165]	DInt	39670869	False	True	Tru e	True	False		
State[166]	DInt	39671125	False	True		True	False		
State[167]	DInt	43078997	False	True	-	True	False		
State[168]	DInt	43337045	False	True		True	False		
State[169]	DInt	43340629	False	True	Tru e	True	False		
State[170]	DInt	43340885	False	True	Tru e	True	False		
State[171]	DInt	43341141	False	True	Tru e	True	False		
State[172]	DInt	43341653	False	True	Tru e	True	False		
State[173]	DInt	43342677	False	True	Tru e	True	False		
State[174]	DInt	43342933	False	True	Tru e	True	False		
State[175]	DInt	43343189	False	True	Tru e	True	False		
State[176]	DInt	43343445	False	True	Tru e	True	False		
State[177]	DInt	43343701	False	True	Tru e	True	False		
State[178]	DInt	43349077	False	True	Tru e	True	False		
State[179]		43349333	False	True	e	True	False		
State[180]		43471957	False	True	e	True	False		
State[181]		43472213	False	True	e	True	False		
State[182]		43865173	False	True	е	True	False		
State[183]		43865429	False	True	e	True	False		
State[184]		47469909	False	True	е	True	False		
State[185]		47470421	False	True	e	True	False		
State[186]		47472469	False	True	е	True	False		
State[187]		47531093	False	True	е	True	False		
State[188]		47531349	False	True	e	True	False		
State[189]	DInt	47535444	False	True	Tru e	True	False		

Totally Integrated Automation Portal									
Name	Data type	Start value	Retain	Acces- sible from HMI/O PC UA/We b API	ta- ble fro m			Super- vision	Comment
State[190]	DInt	47535445	False	True	Tru e	True	False		
State[191]	DInt	47537749	False	True	Tru e	True	False		
State[192]	DInt	47538005	False	True		True	False		
State[193]	DInt	47539285	False	True	-	True	False		
State[194]	DInt	47539541	False	True	-	True	False		
State[195]	DInt	47543381	False	True		True	False		
State[196]	DInt	47543637	False	True	Tru	True	False		
State[197]	DInt	47666517	False	True	e Tru e	True	False		
State[198]	DInt	51762517	False	True		True	False		
State[199]	DInt	51860821	False	True	-	True	False		
State[200]	DInt	51991893	False	True		True	False		
State[201]	DInt	52253781	False	True		True	False		
State[202]	DInt	52254037	False	True	_	True	False		
State[203]	DInt	55661653	False	True		True	False		
State[204]	DInt	55661909	False	True	Tru	True	False		
State[205]	DInt	55858517	False	True	e Tru e	True	False		
State[206]	DInt	55907669	False	True		True	False		
State[207]	DInt	55923793	False	True		True	False		
State[208]	DInt	55924049	False	True		True	False		
State[209]	DInt	55924055	False	True	Tru	True	False		
State[210]	DInt	55940437	False	True	e Tru e	True	False		
State[211]	DInt	55956821	False	True		True	False		
State[212]	DInt	56055125	False	True		True	False		
State[213]	DInt	56185941	False	True		True	False		
State[214]	DInt	56186197	False	True	_	True	False		

me	Data type	Start value	Retain	Acces- sible from HMI/O PC UA/We b API	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
State[215]	DInt	56448085	False	True	е	True	False		
State[216]	DInt	56448341	False	True	Tru e	True	False		
State[217]	DInt	59855957	False	True	Tru e	True	False		
State[218]	DInt	59856213	False	True	Tru e	True	False		
State[219]	DInt	60052821	False	True	Tru e	True	False		
State[220]	DInt	60053333	False	True	Tru e	True	False		
State[221]	DInt	60055381	False	True	Tru e	True	False		
State[222]	DInt	60118353	False	True	Tru e	True	False		
State[223]	DInt	60118357	False	True	Tru e	True	False		
State[224]	DInt	60118865	False	True	Tru e	True	False		
State[225]	DInt	60120917	False	True	_	True	False		
State[226]	DInt	60249173	False	True		True	False		
State[227]	DInt	60249429	False	True	_	True	False		
State[228]	DInt	60380245	False	True		True	False		
State[229]	DInt	60380501	False	True	_	True	False		
State[230]	DInt	60642389	False	True	_	True	False		
State[231]	DInt	60642645	False	True		True	False		
State[232]	DInt	60642901	False	True		True	False		
State[233]	DInt	60643153	False	True	-	True	False		
State[234]	DInt	64312661	False	True		True	False		
State[235]	DInt	67108865	False	True		True	False		
▼ Action	Ar- ray[0235] of Int		False	True	-	True	False		
Action[0]	Int	2	False	True	Tru e	True	False		
Action[1]	Int	0	False	True	Tru e	True	False		

e	Data type	Start value	Retain	Acces-	Wri	Visible	Set-	Super-	Comment
				sible from HMI/O PC UA/We b API	ta- ble fro m	in HMI engi- neer- ing		vision	
Action[2]	Int	13	False	True		True	False		
Action[3]	Int	13	False	True	Tru e	True	False		
Action[4]	Int	11	False	True	Tru e	True	False		
Action[5]	Int	0	False	True	e	True	False		
Action[6]	Int	5	False	True	e	True	False		
Action[7]	Int	4	False	True	е	True	False		
Action[8]	Int	0	False	True	е	True	False		
Action[9]	Int	3	False	True	е	True	False		
Action[10]	Int	8	False	True	e	True	False		
Action[11]	Int	10	False	True	e	True	False		
Action[12]	Int	7	False	True	e	True	False		
Action[13]	Int	5	False	True	e	True	False		
Action[14]	Int	4	False	True	е	True	False		
Action[15]	Int	3	False	True	e	True	False		
Action[16]	Int	3	False	True	e	True	False		
Action[17]	Int	0	False	True	е	True	False		
Action[18]	Int	2	False	True	e	True	False		
Action[19]	Int	7	False	True	е	True	False		
Action[20]	Int	5	False	True	e	True	False		
Action[21]	Int	3	False	True	e	True	False		
Action[22]	Int	0	False	True	e	True	False		
Action[23]	Int	12	False	True	e	True	False		
Action[24]	Int	12	False	True	е	True	False		
Action[25] Action[26]	Int	7	False False	True True	e	True True	False False		

	Data type	Start value	Retain	Accessible from HMI/O PC UA/We	ta- ble fro m HM	in HMI engi- neer- ing		Super- vision	Comment
				b API	I/O PC UA/ We b API				
Action[27]	Int	5	False	True	Tru e	True	False		
Action[28]	Int	0	False	True	Tru e	True	False		
Action[29]	Int	6	False	True	Tru e	True	False		
Action[30]	Int	3	False	True	Tru e	True	False		
Action[31]	Int	0	False	True	-	True	False		
Action[32]	Int	0	False	True	-	True	False		
Action[33]	Int	0	False	True		True	False		
Action[34]	Int	0	False	True	Tru	True	False		
Action[35]	Int	0	False	True		True	False		
Action[36]	Int	0	False	True		True	False		
Action[37]	Int	0	False	True		True	False		
Action[38]	Int	9	False	True	e Tru e	True	False		
Action[39]	Int	9	False	True		True	False		
Action[40]	Int	0	False	True		True	False		
Action[41]	Int	0	False	True	Tru	True	False		
Action[42]	Int	0	False	True		True	False		
Action[43]	Int	0	False	True		True	False		
Action[44]	Int	13	False	True		True	False		
Action[45]	Int	12	False	True		True	False		
Action[46]	Int	0	False	True		True	False		
Action[47]	Int	0	False	True	e Tru	True	False		
Action[48]	Int	13	False	True	e Tru	True	False		
Action[49]	Int	12	False	True	e Tru	True	False		
Action[50]	Int	0	False	True	e	True	False		
Action[51]	Int	0	False	True	e	True	False		

e	Data type	Start value	Retain	Acces-	Wri	Visible	Set-	Super-	Comment
				sible from HMI/O PC UA/We b API	ta- ble fro m	in HMI engi- neer- ing		vision	
Action[52]	Int	0	False	True		True	False		
Action[53]	Int	9	False	True	Tru e	True	False		
Action[54]	Int	9	False	True	Tru e	True	False		
Action[55]	Int	9	False	True	e	True	False		
Action[56]	Int	9	False	True	e	True	False		
Action[57]	Int	12	False	True	е	True	False		
Action[58]	Int	0	False	True	е	True	False		
Action[59]	Int	9	False	True	е	True	False		
Action[60]	Int	11	False	True	e	True	False		
Action[61]	Int	0	False	True	e	True	False		
Action[62]	Int	8	False	True	e	True	False		
Action[63]	Int	11	False	True	e	True	False		
Action[64]	Int	9	False	True	е	True	False		
Action[65]	Int	9	False	True	e	True	False		
Action[66]	Int	9	False	True	e	True	False		
Action[67]	Int	0	False	True	e	True	False		
Action[68]	Int	7	False	True	е	True	False		
Action[69]	Int	5	False	True	е	True	False		
Action[70]	Int	0	False	True	e	True	False		
Action[71]	Int	0	False	True	e	True	False		
Action[72]	Int	0	False	True	e	True	False		
Action[73]	Int	0	False	True	e	True	False		
Action[74]	Int	6	False	True	е	True	False		
Action[75] Action[76]	Int	0	False False	True True	e	True True	False False		

	Data type	Start value	Retain	Accessible from HMI/O PC UA/We b API	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
					PC UA/ We b API				
Action[77]	Int	9	False	True	е	True	False		
Action[78]	Int	0	False	True	Tru e	True	False		
Action[79]	Int	0	False	True	Tru e	True	False		
Action[80]	Int	0	False	True	Tru e	True	False		
Action[81]	Int	0	False	True	Tru	True	False		
Action[82]	Int	0	False	True	-	True	False		
Action[83]	Int	0	False	True		True	False		
Action[84]	Int	12	False	True		True	False		
Action[85]	Int	0	False	True		True	False		
Action[86]	Int	12	False	True	Tru	True	False		
Action[87]	Int	12	False	True		True	False		
Action[88]	Int	9	False	True	e Tru e	True	False		
Action[89]	Int	0	False	True		True	False		
Action[90]	Int	9	False	True		True	False		
Action[91]	Int	0	False	True	Tru	True	False		
Action[92]	Int	9	False	True		True	False		
Action[93]	Int	10	False	True		True	False		
Action[94]	Int	8	False	True		True	False		
Action[95]	Int	10	False	True		True	False		
Action[96]	Int	9	False	True		True	False		
Action[97]	Int	9	False	True		True	False		
Action[98]	Int	0	False	True		True	False		
Action[99]	Int	7	False	True		True	False		
Action[100]	Int	7	False	True	e Tru	True	False		
Action[101]	Int	0	False	True	e Tru	True	False		

Totally Integrated Automation Portal									
Name	Data type	Start value	Retain	Accessible from HMI/O PC UA/We b API	ta- ble fro m			Super- vision	Comment
Action[102]	Int	5	False	True	Tru e	True	False		
Action[103]	Int	0	False	True	Tru e	True	False		
Action[104]	Int	0	False	True		True	False		
Action[105]	Int	0	False	True		True	False		
Action[106]	Int	0	False	True		True	False		
Action[107]	Int	3	False	True		True	False		
Action[108]	Int	3	False	True	_	True	False		
Action[109]	Int	3	False	True	Tru	True	False		
Action[110]	Int	9	False	True	e Tru e	True	False		
Action[111]	Int	2	False	True		True	False		
Action[112]	Int	2	False	True		True	False		
Action[113]	Int	2	False	True	-	True	False		
Action[114]	Int	2	False	True	Tru	True	False		
Action[115]	Int	2	False	True	Tru	True	False		
Action[116]	Int	0	False	True		True	False		
Action[117]	Int	0	False	True		True	False		
Action[118]	Int	0	False	True		True	False		
Action[119]	Int	2	False	True		True	False		
Action[120]	Int	0	False	True		True	False		
Action[121]	Int	12	False	True		True	False		
Action[122]	Int	0	False	True		True	False		
Action[123]	Int	8	False	True		True	False		
Action[124]	Int	9	False	True		True	False		
Action[125]	Int	2	False	True		True	False		
Action[126]	Int	2	False	True		True	False		
					е				

e	Data type	Start value	Retain	sible from	ta- ble fro m	Visible in HMI engi- neer- ing		Super- vision	Comment
					UA/ We b API				
Action[127]	Int	7	False	True	Tru e	True	False		
Action[128]	Int	7	False	True	Tru e	True	False		
Action[129]	Int	2	False	True	Tru e	True	False		
Action[130]	Int	5	False	True	Tru e	True	False		
Action[131]	Int	0	False	True	Tru e	True	False		
Action[132]	Int	0	False	True	Tru e	True	False		
Action[133]	Int	2	False	True	Tru e	True	False		
Action[134]	Int	11	False	True	Tru e	True	False		
Action[135]	Int	11	False	True		True	False		
Action[136]	Int	0	False	True	Tru e	True	False		
Action[137]	Int	6	False	True	Tru e	True	False		
Action[138]	Int	0	False	True	Tru e	True	False		
Action[139]	Int	4	False	True	_	True	False		
Action[140]	Int	0	False	True		True	False		
Action[141]	Int	0	False	True		True	False		
Action[142]	Int	0	False	True		True	False		
Action[143]	Int	0	False	True	Tru e	True	False		
Action[144]	Int	0	False	True		True	False		
Action[145]	Int	0	False	True		True	False		
Action[146]	Int	9	False	True		True	False		
Action[147]	Int	9	False	True		True	False		
Action[148]	Int	13	False	True		True	False		
Action[149]	Int	0	False	True	_	True	False		
Action[150]	Int	13	False	True		True	False		
Action[151]	Int	9	False	True		True	False		

	Data type	Start value	Retain	Acces- sible from HMI/O PC UA/We b API	ta- ble fro m HM I/O PC UA/ We b			Super- vision	Comment
Action[152]	Int	11	False	True		True	False		
Action[153]	Int	0	False	True		True	False		
Action[154]	Int	0	False	True		True	False		
Action[155]	Int	11	False	True		True	False		
Action[156]	Int	9	False	True		True	False		
Action[157]	Int	9	False	True		True	False		
Action[158]	Int	0	False	True		True	False		
Action[159]	Int	6	False	True		True	False		
Action[160]	Int	6	False	True	e Tru	True	False		
Action[161]	Int	0	False	True		True	False		
Action[162]	Int	0	False	True		True	False		
Action[163]	Int	5	False	True	e Tru	True	False		
Action[164]	Int	0	False	True		True	False		
Action[165]	Int	4	False	True	e Tru	True	False		
Action[166]	Int	4	False	True	e Tru	True	False		
Action[167]	Int	0	False	True	e Tru	True	False		
Action[168]	Int	0	False	True		True	False		
Action[169]	Int	9	False	True		True	False		
Action[170]	Int	0	False	True		True	False		
Action[171]	Int	0	False	True	e Tru	True	False		
Action[172]	Int	9	False	True		True	False		
Action[173]	Int	9	False	True	e Tru	True	False		
Action[174]	Int	0	False	True	e Tru	True	False		
Action[175]	Int	8	False	True	e Tru	True	False		
Action[176]	Int	8	False	True	e Tru	True	False		

me	Data type	Start value	Retain	sible from	ta- ble fro m HM I/O PC UA/			Super- vision	Comment
					We b API				
Action[177]	Int	9	False	True	Tru e	True	False		
Action[178]	Int	7	False	True	Tru e	True	False		
Action[179]	Int	7	False	True	Tru e	True	False		
Action[180]	Int	0	False	True	Tru e	True	False		
Action[181]	Int	5	False	True	Tru e	True	False		
Action[182]	Int	0	False	True	Tru e	True	False		
Action[183]	Int	4	False	True		True	False		
Action[184]	Int	0	False	True		True	False		
Action[185]	Int	2	False	True		True	False		
Action[186]	Int	0	False	True		True	False		
Action[187]	Int	2	False	True	-	True	False		
Action[188]	Int	2	False	True		True	False		
Action[189]	Int	0	False	True	_	True	False		
Action[190]	Int	2	False	True		True	False		
Action[191]	Int	2	False	True	Tru	True	False		
Action[192]	Int	9	False	True		True	False		
Action[193]	Int	2	False	True		True	False		
Action[194]	Int	2	False	True		True	False		
Action[195]	Int	7	False	True		True	False		
Action[196]	Int	7	False	True		True	False		
Action[197]	Int	5	False	True		True	False		
Action[198]	Int	1	False	True		True	False		
Action[199]	Int	1	False	True		True	False		
Action[200]	Int	0	False	True		True	False		
Action[201]	Int	4	False	True	e Tru	True	False		

	Data type	Start value	Retain	Accessible from HMI/O PC UA/We b API	ta- ble fro m			Super- vision	Comment
Action[202]	Int	1	False	True		True	False		
Action[203]	Int	1	False	True	e Tru	True	False		
Action[204]	Int	1	False	True	e Tru	True	False		
	Int	1	False	True	e	True	False		
Action[205]					e				
Action[206]	Int	0	False	True	e	True	False		
Action[207]	Int	0	False	True	Tru e	True	False		
Action[208]	Int	0	False	True	Tru e	True	False		
Action[209]	Int	1	False	True	Tru	True	False		
Action[210]	Int	1	False	True	e Tru e	True	False		
Action[211]	Int	1	False	True		True	False		
Action[212]	Int	5	False	True		True	False		
Action[213]	Int	1	False	True		True	False		
Action[214]	Int	1	False	True	_	True	False		
Action[215]	Int	1	False	True	Tru e	True	False		
Action[216]	Int	4	False	True	Tru e	True	False		
Action[217]	Int	1	False	True		True	False		
Action[218]	Int	1	False	True		True	False		
Action[219]	Int	1	False	True		True	False		
Action[220]	Int	1	False	True	Tru e	True	False		
Action[221]	Int	0	False	True	Tru e	True	False		
Action[222]	Int	0	False	True	Tru e	True	False		
Action[223]	Int	1	False	True	Tru e	True	False		
Action[224]	Int	0	False	True	Tru e	True	False		
Action[225]	Int	1	False	True	Tru e	True	False		
Action[226]	Int	0	False	True		True	False		

				sible from HMI/O PC UA/We b API	ble fro m	ing	point	vision	Comment
Action[227]	Int	5	False	True		True	False		
Action[228]	Int	1	False	True	Tru e	True	False		
Action[229]	Int	1	False	True		True	False		
Action[230]	Int	4	False	True		True	False		
Action[231]	Int	4	False	True		True	False		
Action[232]	Int	0	False	True		True	False		
Action[233]	Int	9	False	True		True	False		
Action[234]	Int	2	False	True		True	False		
Action[235]	Int	0	False	True		True	False		

anguage DB nformation itle amily	te_Action_DB	Numberi	ng Autoi	matic			Type		
tle				Hatic					
							_		
allilly		Author Version	0.1				Comm User-d		
		Version	0.1				ID	eiiiieu	
ame	Data type	Start value	Retain	from	ta- ble fro m	in HMI engi- neer- ing			Comment
I nput									
S_State	DInt	0	False	True	Tru e	True	False		
▼ Output									
Action	Int	0	False	True	Tru e	True	False		
▼ InOut									
ArEtat	Array[*] of DInt		False	False	Fals e	False	False		
ArAction	Array[*] of Int		False	False		False	False		
Static	OI IIII				-				

General Name R_TRIG Language SCL Information Title Family BIT	ì		Number Numbering Author Version	1001 Automatic SIMATIC 1.0			Comm User-d		FB R_TRIC	5
Name	Data type	e Defa	ult value	Retain	from HMI/OP C UA/We b API	Wri ta- ble fro m	in HMI engi-			Comment
▼ Input	Dool	false		Non ratain	Tviia	Ти	Terra	False		
CLK	Bool	raise		Non-retain		e	True	raise		
▼ Output Q	Bool	false		Non-retain			True	False		
InOut						е				
▼ Static										
Stat_Bit	Bool	false		Non-retain		Tru e	True	False		

ime nguage	R_TRIG_m DB	ovingX		Number Numbering	4 Auto	omatic			Type		DB
nformation itle amily	BIT			Author Version	SIM. 1.0	ATIC			Commo User-do ID		R_TRIG
ame		Data type	Start	value	Retain	from HMI/O PC UA/We	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
▼ Input											
CLK		Bool	false		False	True	Tru e	True	False		
Output											
Q		Bool	false		False	True		True	False		
InOut							е				
▼ Static											
Stat_Bit		Bool	false		False	True	Tru e	True	False		

R_TRIG_movir General Name Language	R_TRIG_m			Number Numbering	3 Autor	natic			Туре		DB
nformation Fitle Family	BIT			Author Version	SIMA ⁻	ГІС			Comme User-de ID		R_TRIG
Name		Data type	Start	value	Retain	from HMI/O PC UA/We	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
✓ Input							AFI				
CLK	E	Bool	false		False	True	Tru e	True	False		
▼ Output											
Q	E	Bool	false		False	True	Tru e	True	False		
InOut											
▼ Static											
Stat_Bit	E	Bool	false		False	True	Tru e	True	False		

anguage nformation Fitle	F_TRIG SCL BIT			Number Numbering Author Version	1002 Automatic SIMATIC 1.0			Type Commo		FB F_TRIG	ì
Name		Data type	Defa	ult value	Retain	from HMI/OP C UA/We b API	Wri ta- ble fro m	in HMI engi-			Comment
▼ Input	-	2 1	£ 1.		N	T .	T .	T .	F 1.		
CLK	Ė	Bool	false		Non-retain		e e	True	False		
▼ Output Q	E	Bool	false		Non-retain	True	Tru	True	False		
InOut							е				
▼ Static											
Stat_Bit	E	Bool	false		Non-retain		Tru e	True	False		

inguage formation tle imily	DB			Author Version	SIMA 1.0				Commo User-do ID		F_TRIG
ame		Data type	Start	value	Retain	from HMI/O PC UA/We	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
► Input							AFI				
CLK		Bool	false		False	True	Tru e	True	False		
Output											
Q		Bool	false		False	True		True	False		
InOut							е				
Static											
Stat_Bit		Bool	false		False	True	Tru e	True	False		

nguage formation tle amily	F_TRIG_m DB BIT			Numbering Author Version	SIMA 1.0				Comme User-de ID		F_TRIG
ame		Data type	Start	value	Retain	from HMI/O PC UA/We	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
Input							AFI				
CLK		Bool	false		False	True	Tru e	True	False		
Output											
Q		Bool	false		False	True		True	False		
InOut							е				
Static											
Stat_Bit		Bool	false		False	True	Tru e	True	False		

inguage formation tle imily	F_TRIG_rd DB BIT	J		Numbering Author Version	SIMA ¹				Commo User-do ID		DB F_TRIG
ame		Data type	Start	value	Retain	from HMI/O PC UA/We	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
Input							AFI				
CLK		Bool	false		False	True	Tru e	True	False		
Output											
Q		Bool	false		False	True		True	False		
InOut							е				
Static											
Stat_Bit		Bool	false		False	True	Tru e	True	False		

R_TRIG_rotati General Name Language	R_TRIG_rc			Number Numbering	8 Autor	natic			Туре		DB
nformation Title Tamily	BIT			Author Version	SIMA ⁻	ГІС			Comme User-de		R_TRIG
Name		Data type	Start	value	Retain	sible from HMI/O PC UA/We	ta- ble fro m			Super- vision	Comment
✓ Input							AFI				
CLK		Bool	false		False	True	Tru e	True	False		
▼ Output											
Q		Bool	false		False	True	Tru e	True	False		
InOut											
▼ Static											
Stat_Bit		Bool	false		False	True	Tru e	True	False		

nguage formation tle mily	DB			Author Version	SIMA 1.0				Commo User-do ID		F_TRIG
ame		Data type	Start	value	Retain	from HMI/O PC UA/We	ta- ble fro m	in HMI engi- neer- ing		Super- vision	Comment
Input							AFI				
CLK		Bool	false		False	True	Tru e	True	False		
Output							-				
Q		Bool	false		False	True	Tru	True	False		
InOut							е				
Static											
Stat_Bit		Bool	false		False	True	Tru	True	False		