



Dimitrios Vlachos

Senior Software Engineer Algorithms, R&D , Robotics & Embedded devices

Websites: <http://dvlachos.dev> / <http://vira.works>

LinkedIN: <https://www.linkedin.com/in/dimitris-vlachos-mt/>

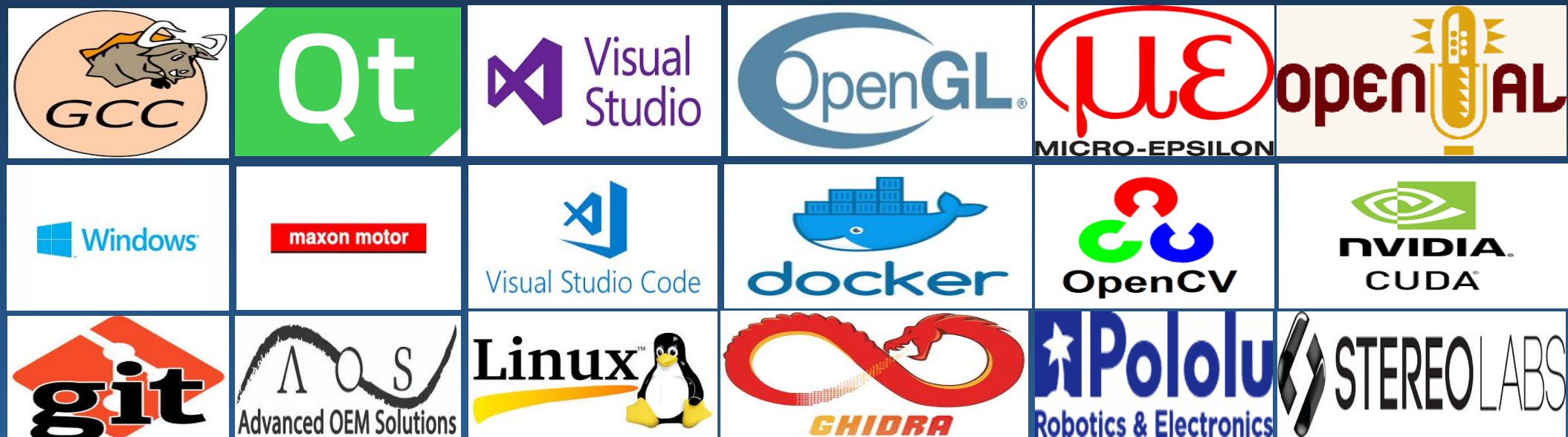
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Skillset

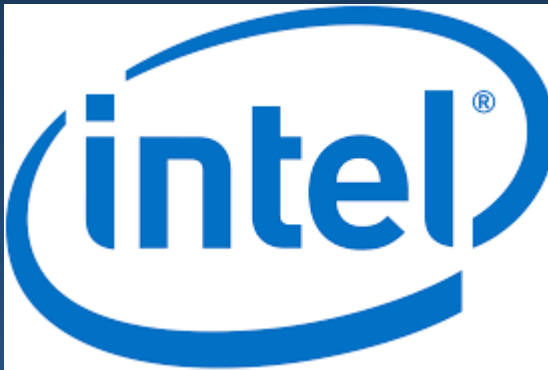
- 23+ Years of programming experience (C,C++,Assembly,Scripting)
 - Deep learning / Computer Vision
- Embedded devices / Robotics (full stack implementation / Fanuc robots / MAXON&Roboclaw controllers/encoders)
 - Sensors (eg : profilometers like Microepsilon's 1mm accuracy profilometers , Phased Array AOS C++ SDK)
 - Algorithms & Optimization (CPU parallelization/GPU:CUDA)
 - Data compression (Including a proprietary symbol sequence predictor)
 - Networking (protocol implementation)
 - OpenGL/OpenAL/OpenCV
- QT Creator / Visual Studio / Visual Studio Code / Atom / GCC Compiler/Debugger toolset
 - Experience with Linux kernel driver / module implementation
 - Motor controller programming (Maxon / Roboclaw / etc)
 - Containers/VMS:Docker/etc
 - Reversing (eg: Ghidra...etc)



Competitions

**2nd place at Intel's worldwide competition
"Accelerate your code" out of 130+ submissions.**

**Solution page:
<https://github.com/DimitrisVlachos/INTEL-AYC-2013SUMMER--2ND-PLACE-SOLUTION>**



Completed Projects

Project name : "Minotaur-R"

Website: <http://www.esmera-project.eu/minotaur-r/>

Video: https://www.youtube.com/watch?v=Jn_fYlvK5YU

Description: "A pick and place robot placed in Radio active environment that uses various tools and computer vision/Deep Learning to separate radio active springs from trash."

Role: Full stack lead software engineer

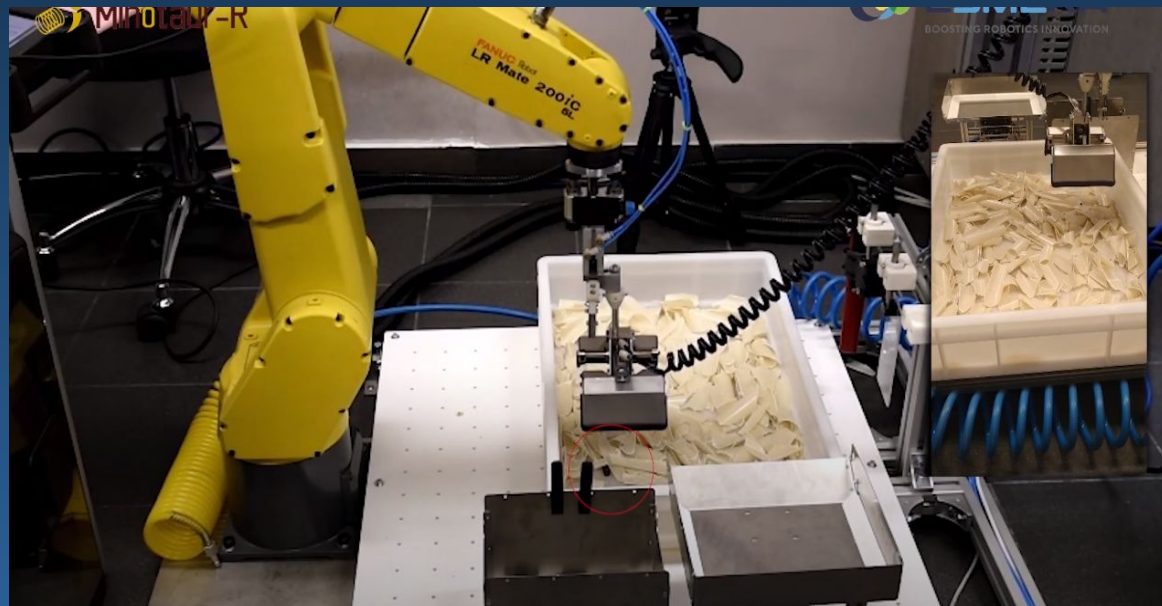
Developed the entire software stack & drivers for the project from scratch including:

- 6-Axis robot control driver
- CNNs for computer vision to detect springs/predict orientation
- Custom 2d->3d Mapping tool to calibrate inspection area
- Camera calibration tools
- Rendering engine / Graphs
- Network protocol for communication
- RGBD camera algorithms for depth estimation / Tiling / Calibration
- Tool support (depth sensor / gripper and so on)
- Software to implement sequences once and then adapt(\approx stretch/fit) within any environment at runtime
- Multithread/GPU optimizations
- 3D world partitioning editor
- GUI
- Graphs

Code size : Approx 350KB +

*Total Separate modules : 4 (Controller on the robot service , Robot Hub router , Computer Vision Service, GUI)
(all communicate through tcp low-level optimized protocol)*

The entire project is written in C/C++ and some tools in C#/CUDA.

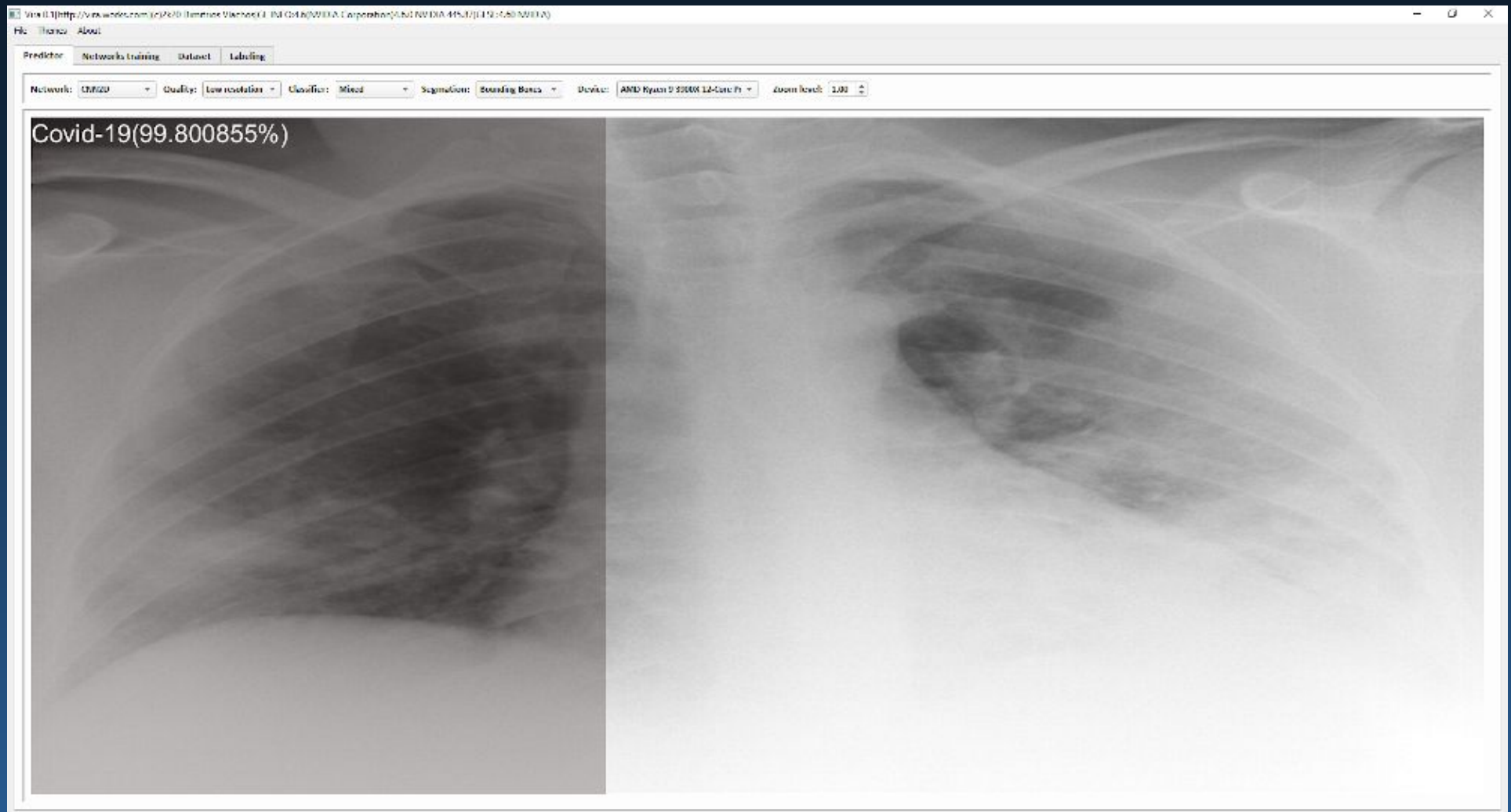


Completed Projects

Project name : "Vira"

Vira is a proof of concept software that uses Deep Learning to detect various lung infection types including Covid19.

The entire project is written in C++ & Qt for GUI.



Completed Projects

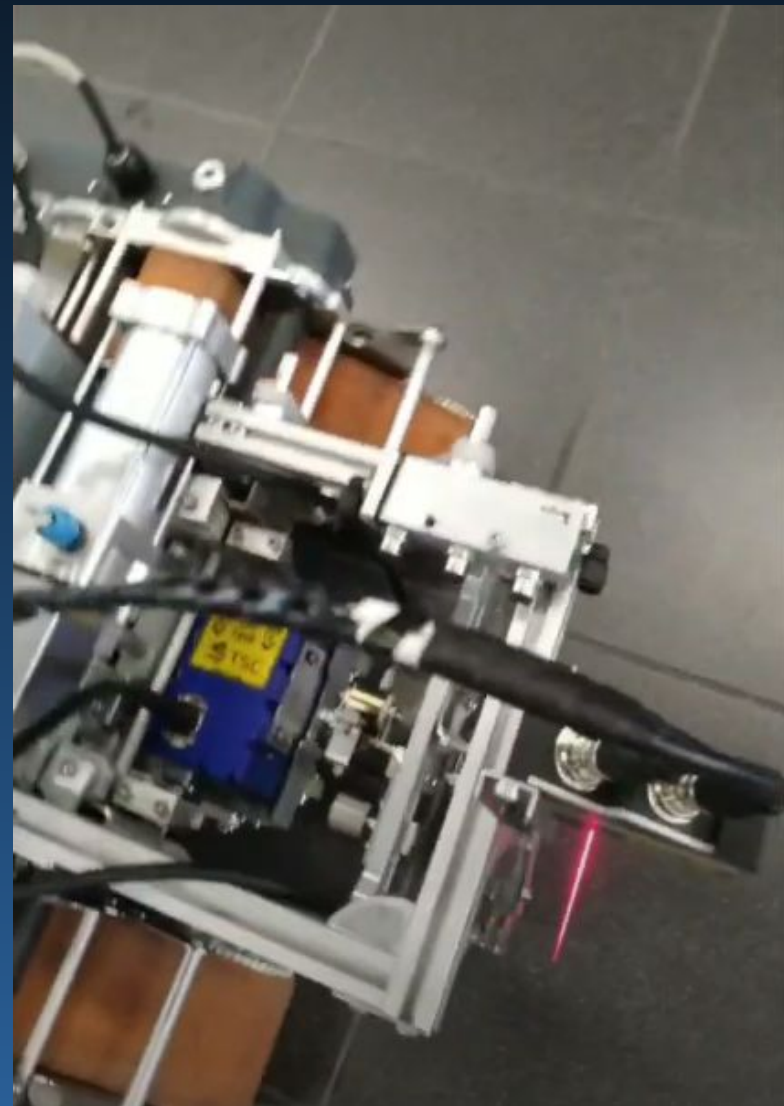
Project name : "Shiptest"

Website : <http://www.shiptest.eu/>

Description: Shiptest is a Robotic crawler designed for Automated NDT inspection using various sensors(Olympus Phased Array , MicroEpsilon's profilometer) and algorithms(A/B/C/S Scan , Automatic Weld Detection / Classifier and so on).

Role : Full stack lead software engineer

The entire project is written in C++ & Qt (gui). Code size : Approx 1MB

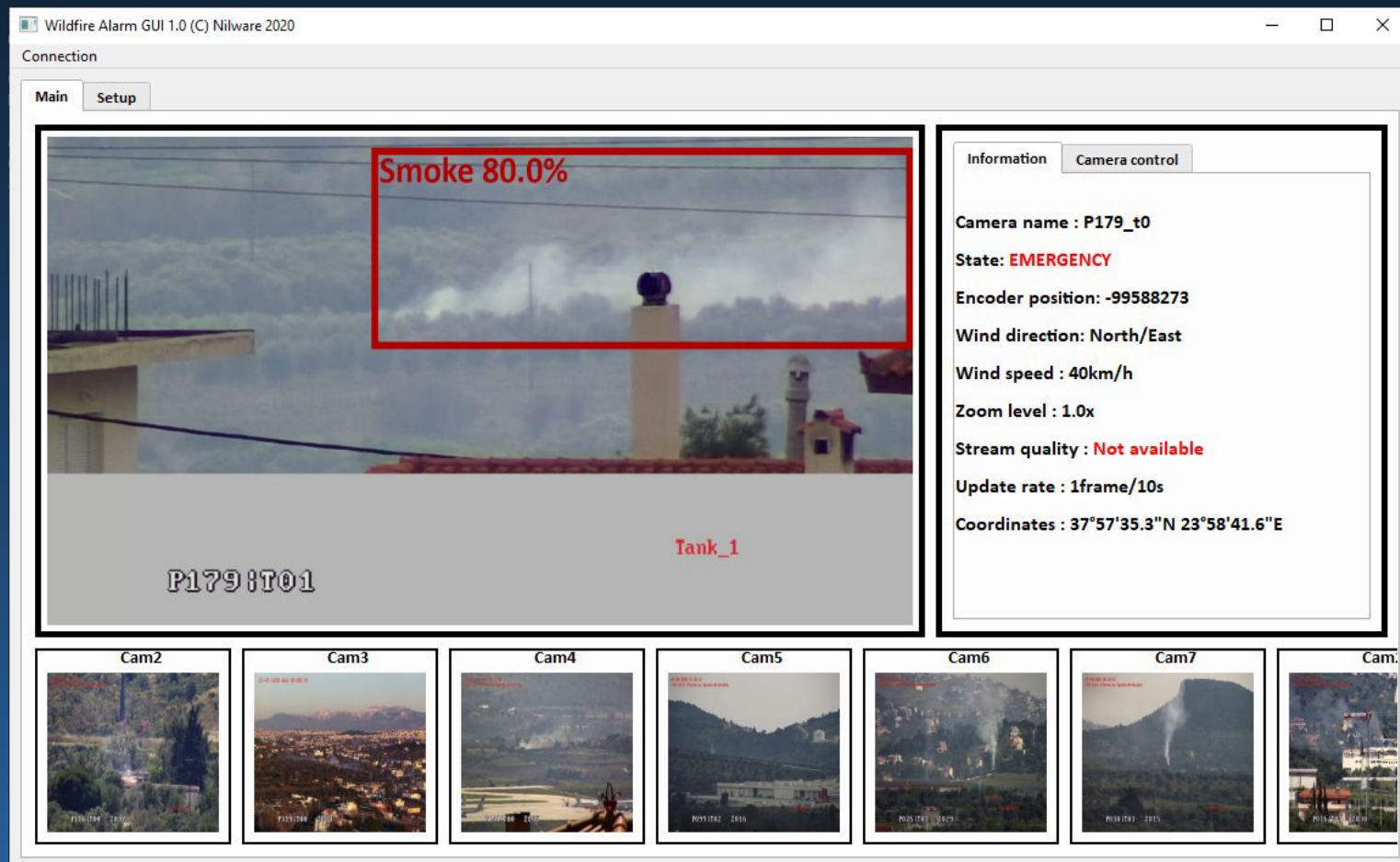


Completed Projects

Project name : "Wildfire alarm"

Description : Neural network based smoke detection from video footage

The entire project is written in C/C++/Qt/Python.



Completed Projects

Project name : "Friction Harmonics"

Website : <http://www.frictionharmonics.com/>

Description : Friction harmonics is a robotic solution for Kissing Bond defects detection.

Role :

Full stack lead software engineer

Developed the entire software stack & drivers for the

project including:

- GUI Development
- FFT & Harmonics solver/detector
- TDMS loader
- Dynamic playback of sequences
- Graph display

(The entire project is written in C/C++ & QT.)



Completed Projects

Project name : "Winspector"

Website : <http://www.winspector.eu/>

Description : Winspector is a robotic platform for advanced non-destructive testing (NDT) to in-situ blade defect detection.

Role :

Full stack lead software engineer

Developed the entire software stack & drivers for the project including:

- GUI Development
- Robot Controller programming
- Motor controller programming
- Kinematics
- Editor for capturing motion sequences and stretch/fit them in any environment
- Network protocol implementation

Code size: 400KB+

Total Separate modules : 3 (Robot hub , GUI controller , robot controller)

The entire project is written in C/C++.



Completed Projects

Project name : "SocketMaster"

Website : <http://www.socketmaster.eu/>

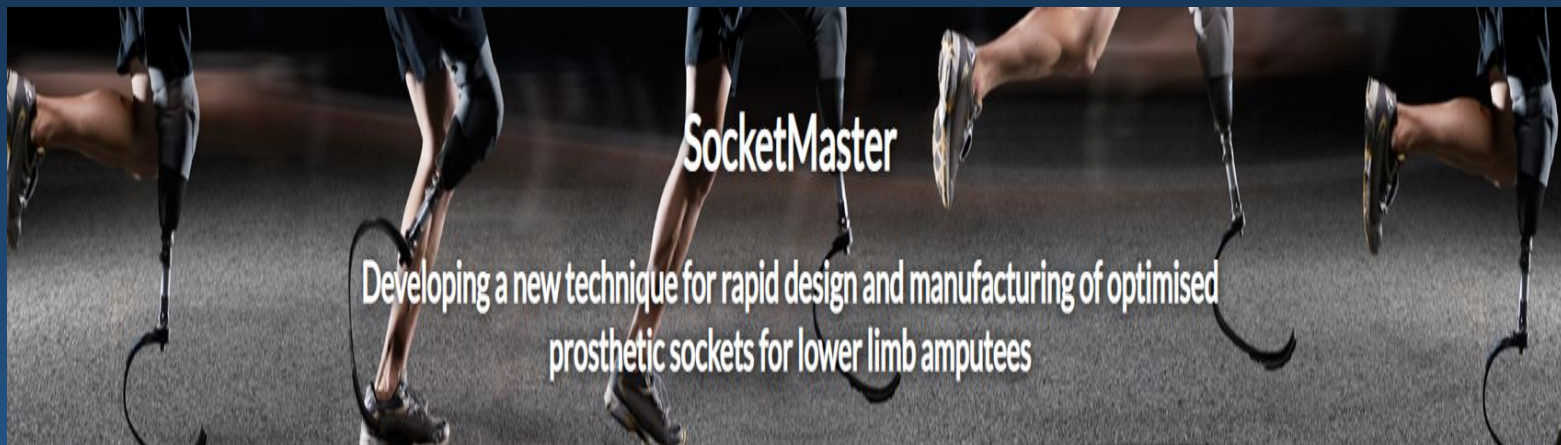
Description :

SocketMaster aims to provide amputees with personalized, optimized prosthetic sockets capable of being designed and manufactured in a short period of time.

Role:

In this project my task was to re-write completely from scratch the original code(C#) in C++ that handled the transformations & also to make it run on embedded device as fast as possible.

The entire project is written in C/C++.



Completed Projects

Project name : "CMDrive"

Website : <http://www.cmdrive.co.uk/>

Description :

The project goal is to establish the feasibility of the innovative use of a non-contact microphone array for structural health diagnostics by noise detection combined with active noise cancellation, for all the rotating machinery within an onshore wind turbine nacelle.

Role:

In this project I had to fix multiple bugs/issues present in the codebase along with optimizations.

The entire project is written in C/C++.



WELCOME TO THE PROJECT WEBSITE:

"Non-contact microphone array for structural health diagnostics combined with active noise and vibration cancellation for wind turbine nacelle machinery"

The project goal is to establish the feasibility of the innovative use of a non-contact microphone array for structural health diagnostics by noise detection combined with active noise cancellation, for all the rotating machinery within an onshore wind turbine nacelle.

Completed Projects

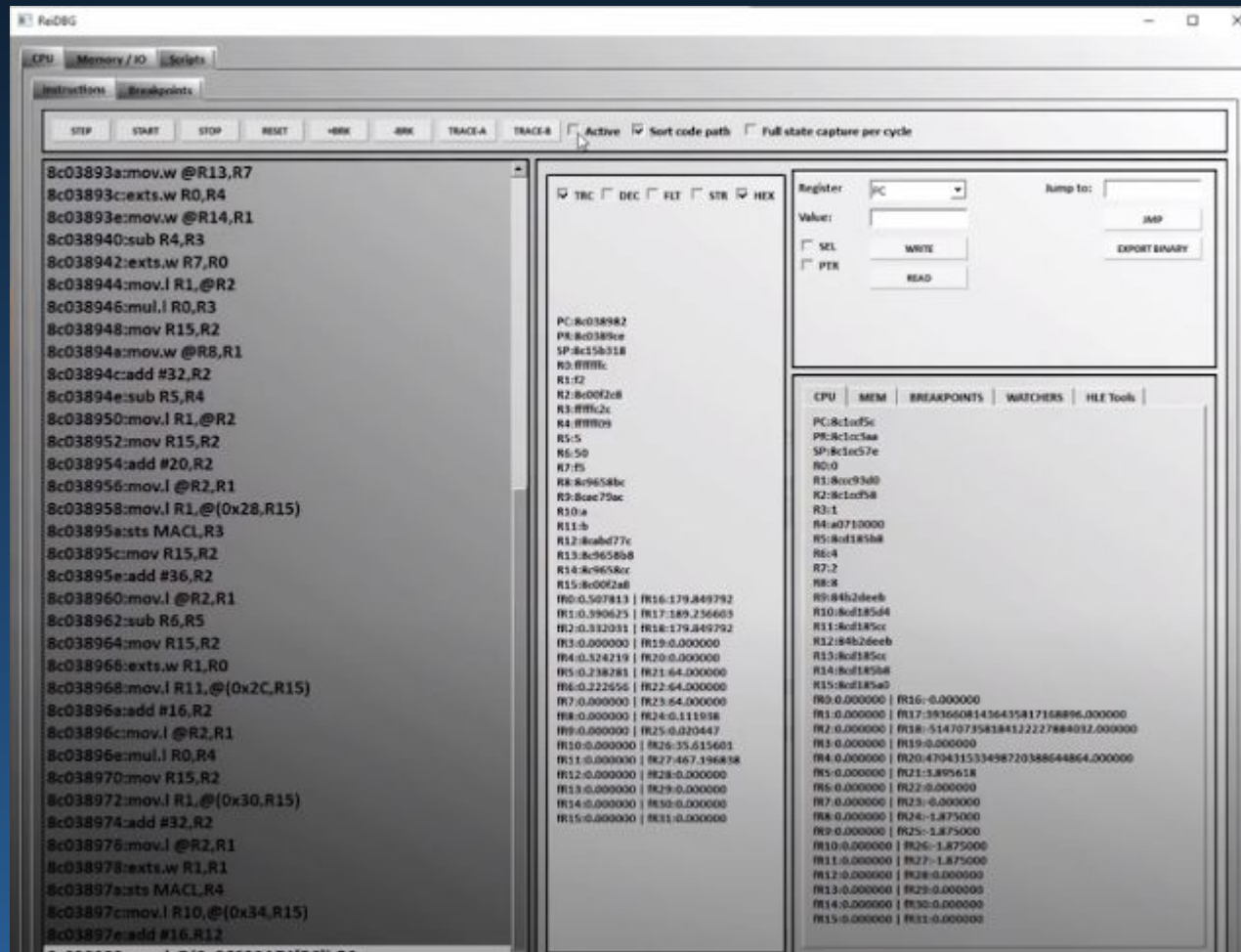
Project name : "ReiDBG"

Website: <https://github.com/reicast/reicast-emulator/>

Video: <https://www.youtube.com/watch?v=SSOJEpYrsFM>

Description: "A complete system debugger for the Sega Dreamcast emulator NullDC/Reicast"

The entire project is written in C/C++/QT.



Completed Projects

Project name : "NullDC"

Website : <https://code.google.com/archive/p/nulldc/>

Company : Nilware

Description : The fastest Sega Dreamcast emulator to date for Windows x86-64

Role:

In the codebase I did took care of multiple reported issues , also implemented Caching system for the DirectX rendering engine along with JIT optimizations and some fixes.

The entire project is written in C/C++.

nullDC

Dreamcast



Completed Projects

Project name : "Reicast"

Website : <https://github.com/reicast/reicast-emulator>

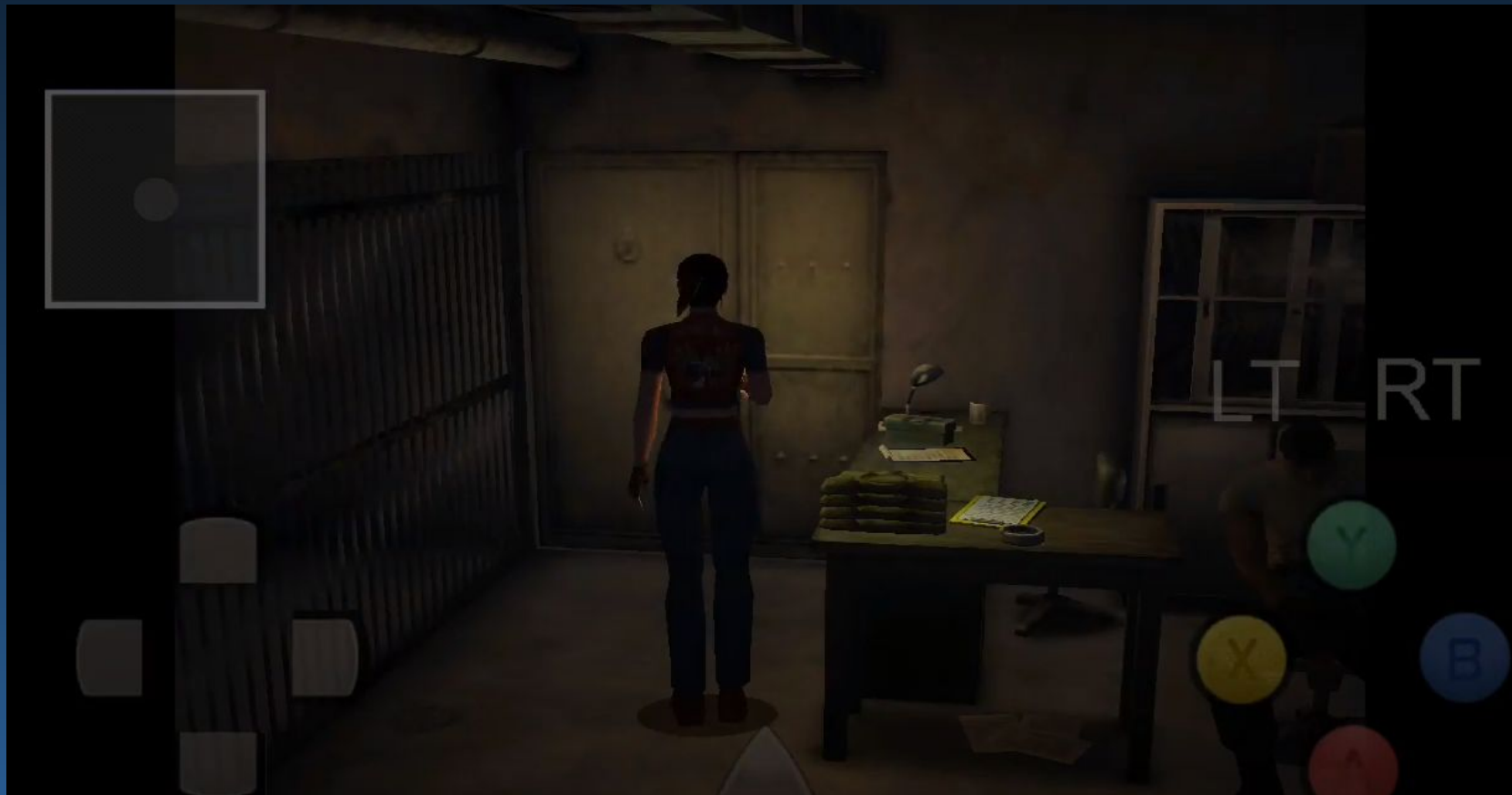
Company : Nilware

Description : A lightweight version of NullDC Dreamcast emulator running on Android, Windows, Linux, Mac.

Role:

Actively working on this project as maintainer. My tasks involve from basic fixes/porting to JIT Compiler / High level emulation & reversing.

The entire project is written in C/C++.



Completed Projects

Project name : "GNUBOY 64" - 2014

Website : <https://github.com/DimitrisVlachos/Gnuboy64>

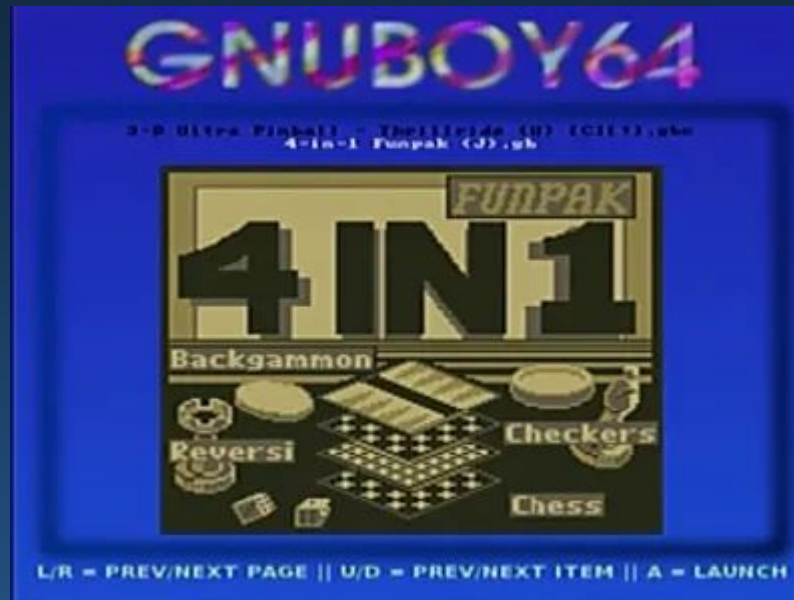
Company : Non profit

Description :

The official port for the Gameboy & Gameboy color emulator for the N64 running in full speed with 90% of the renderer code being written in pure mips32 assembly.

Role:

I'm the original author and maintainer of this port.



Thank you!

*Thanks for your time , you may check my website for more information.
<http://dvlachos.dev>*