```
In [1]: import numpy as np
    import tensorflow
    from matplotlib import pyplot as plt
    from tensorflow.keras.models import Sequential, load_model
    from tensorflow.keras.layers import Conv2D, MaxPooling2D, Dense, Flatten, Batc
    hNormalization
    from tensorflow.keras.callbacks import ReduceLROnPlateau, EarlyStopping
    from tensorflow.keras.regularizers import 12
    from tensorflow.keras.datasets import cifar100
```

```
In [2]: (trainX, trainY), (testX, testY) = cifar100.load_data()
```

```
In [3]: # Target classes: numbers to text
         # Source: https://github.com/keras-team/keras/issues/2653#issuecomment-4501339
         96
         classes = [
           'apple',
           'aquarium_fish',
           'baby',
           'bear',
           'beaver',
           'bed',
           'bee',
           'beetle',
           'bicycle',
           'bottle',
           'bowl',
           'boy',
           'bridge',
           'bus',
           'butterfly',
           'camel',
           'can',
           'castle',
           'caterpillar',
           'cattle',
           'chair',
           'chimpanzee',
           'clock',
           'cloud',
           'cockroach',
           'couch',
           'crab',
           'crocodile',
           'cup',
           'dinosaur',
           'dolphin',
           'elephant',
           'flatfish',
           'forest',
           'fox',
           'girl',
           'hamster',
           'house',
           'kangaroo',
           'computer_keyboard',
           'lamp',
           'lawn_mower',
           'leopard',
           'lion',
           'lizard',
           'lobster',
           'man',
           'maple_tree',
           'motorcycle',
           'mountain',
           'mouse',
           'mushroom',
```

```
'oak_tree',
  'orange',
  'orchid',
  'otter',
  'palm_tree',
  'pear',
  'pickup_truck',
  'pine_tree',
  'plain',
  'plate',
  'poppy',
  'porcupine',
  'possum',
  'rabbit',
  'raccoon',
  'ray',
  'road',
  'rocket',
  'rose',
  'sea',
  'seal',
  'shark',
  'shrew',
  'skunk',
  'skyscraper',
  'snail',
  'snake',
  'spider',
  'squirrel',
  'streetcar',
  'sunflower',
  'sweet_pepper',
  'table',
  'tank',
  'telephone',
  'television',
  'tiger',
  'tractor',
  'train',
  'trout',
  'tulip',
  'turtle',
  'wardrobe',
  'whale',
  'willow_tree',
  'wolf',
  'woman',
  'worm',
]
```

```
In [4]: # Visualize firt 9 images
    for i in range(9):
        plt.subplot(330 + 1 + i)
        image = trainX[i]
        target = trainY[i][0]
        plt.axis('off')
        plt.imshow(image)
        plt.title(f'{classes[target]}')
    plt.show()
```



```
In [5]: trainX = trainX.reshape(trainX.shape[0], 32,32,3)
    trainY = trainY.reshape(trainY.shape[0], 1)
    testX = testX.reshape(testY.shape[0], 32, 32, 3)
    testY = testY.reshape(testY.shape[0], 1)
```

```
In [6]: # Parse numbers as floats
    trainX = trainX.astype('float32')
    testX = testX.astype('float32')

# Normalize data
    trainX = trainX / 255.0
    testX = testX / 255.0
```

```
In [7]:
         model = Sequential()
         model.add(Conv2D(32, (3, 3), input\_shape = (32, 32, 3), kernel\_regularizer = 1
         2(0.005), activation = 'elu'))
         model.add(BatchNormalization())
         model.add(MaxPooling2D(pool size = (2, 2)))
         model.add(Conv2D(128, (3, 3), kernel_regularizer = 12(0.005), activation = 'el
         u'))
         model.add(BatchNormalization())
         model.add(MaxPooling2D(pool size = (2, 2)))
         model.add(Conv2D(128, (3, 3), kernel_regularizer = 12(0.005), activation = 'el
         u'))
         model.add(BatchNormalization())
         model.add(Conv2D(256, (3, 3), kernel_regularizer = 12(0.005), activation = 'el
         u'))
         model.add(BatchNormalization())
         model.add(MaxPooling2D(pool_size = (2, 2)))
         model.add(Flatten())
         model.add(Dense(units = 128, activation = 'elu'))
         model.add(Dense(units = 256, activation = 'elu'))
         model.add(Dense(units = 100, activation = 'softmax'))
In [8]: model.compile(optimizer = 'adam', loss = 'sparse categorical crossentropy', me
         trics = ['accuracy'])
In [9]: | rlrop = ReduceLROnPlateau(monitor = 'val_loss', factor = 0.1, patience = 10)
In [10]: | early stop = EarlyStopping(monitor = 'val loss',
                                    mode = 'min',
                                    verbose = 1,
                                    patience = 30)
```

```
Train on 40000 samples, validate on 10000 samples
Epoch 1/100
- accuracy: 0.1828 - val_loss: 5.2625 - val_accuracy: 0.0700
Epoch 2/100
40000/40000 [============= ] - 104s 3ms/sample - loss: 3.2391
- accuracy: 0.2998 - val loss: 4.1788 - val accuracy: 0.1761
Epoch 3/100
40000/40000 [============== ] - 104s 3ms/sample - loss: 3.0300
- accuracy: 0.3465 - val loss: 4.3409 - val accuracy: 0.1775
Epoch 4/100
40000/40000 [============= ] - 106s 3ms/sample - loss: 2.9066
- accuracy: 0.3832 - val loss: 3.3714 - val accuracy: 0.2982
Epoch 5/100
40000/40000 [================ ] - 107s 3ms/sample - loss: 2.8178
- accuracy: 0.4107 - val loss: 3.2840 - val accuracy: 0.3373
Epoch 6/100
40000/40000 [================ ] - 107s 3ms/sample - loss: 2.7530
- accuracy: 0.4304 - val loss: 3.5828 - val accuracy: 0.2937
Epoch 7/100
40000/40000 [============= ] - 109s 3ms/sample - loss: 2.6902
- accuracy: 0.4507 - val_loss: 3.6019 - val_accuracy: 0.2947
Epoch 8/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 2.6293
- accuracy: 0.4685 - val_loss: 3.5475 - val_accuracy: 0.3119
Epoch 9/100
- accuracy: 0.4820 - val_loss: 3.2323 - val_accuracy: 0.3699
Epoch 10/100
40000/40000 [============= ] - 109s 3ms/sample - loss: 2.5296
- accuracy: 0.4986 - val_loss: 3.4871 - val_accuracy: 0.3417
Epoch 11/100
- accuracy: 0.5110 - val_loss: 3.4263 - val_accuracy: 0.3437
Epoch 12/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 2.4410
- accuracy: 0.5217 - val_loss: 3.5240 - val_accuracy: 0.3458
Epoch 13/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 2.3977
- accuracy: 0.5376 - val_loss: 3.7135 - val_accuracy: 0.3152
Epoch 14/100
40000/40000 [=============== ] - 110s 3ms/sample - loss: 2.3695
- accuracy: 0.5473 - val_loss: 3.5284 - val_accuracy: 0.3522
Epoch 15/100
- accuracy: 0.5572 - val loss: 4.1948 - val accuracy: 0.2615
Epoch 16/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 2.2837
- accuracy: 0.5714 - val_loss: 3.6979 - val_accuracy: 0.3291
Epoch 17/100
40000/40000 [=============== ] - 108s 3ms/sample - loss: 2.2457
- accuracy: 0.5809 - val loss: 3.6579 - val accuracy: 0.3471
Epoch 18/100
40000/40000 [============= ] - 109s 3ms/sample - loss: 2.2117
- accuracy: 0.5953 - val_loss: 3.4908 - val_accuracy: 0.3743
Epoch 19/100
40000/40000 [=============== ] - 109s 3ms/sample - loss: 2.1848
```

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```
- accuracy: 0.6023 - val loss: 3.8797 - val accuracy: 0.3349
Epoch 20/100
40000/40000 [=============== ] - 109s 3ms/sample - loss: 1.6245
- accuracy: 0.7621 - val loss: 2.8346 - val accuracy: 0.4920
Epoch 21/100
40000/40000 [============== ] - 110s 3ms/sample - loss: 1.3456
- accuracy: 0.8293 - val loss: 2.7888 - val accuracy: 0.4940
Epoch 22/100
40000/40000 [============== ] - 110s 3ms/sample - loss: 1.1831
- accuracy: 0.8631 - val loss: 2.7597 - val accuracy: 0.4916
Epoch 23/100
40000/40000 [============= ] - 109s 3ms/sample - loss: 1.0601
- accuracy: 0.8828 - val loss: 2.7660 - val accuracy: 0.4902
Epoch 24/100
40000/40000 [=============== ] - 109s 3ms/sample - loss: 0.9537
- accuracy: 0.9054 - val_loss: 2.7583 - val_accuracy: 0.4861
Epoch 25/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 0.8592
- accuracy: 0.9222 - val loss: 2.8006 - val accuracy: 0.4859
Epoch 26/100
40000/40000 [=============== ] - 110s 3ms/sample - loss: 0.7780
- accuracy: 0.9370 - val loss: 2.8942 - val accuracy: 0.4713
Epoch 27/100
40000/40000 [============= ] - 109s 3ms/sample - loss: 0.7146
- accuracy: 0.9471 - val_loss: 2.9108 - val_accuracy: 0.4803
Epoch 28/100
- accuracy: 0.9561 - val_loss: 2.9620 - val_accuracy: 0.4747
Epoch 29/100
40000/40000 [=============== ] - 110s 3ms/sample - loss: 0.6076
- accuracy: 0.9629 - val_loss: 2.9858 - val_accuracy: 0.4788
Epoch 30/100
40000/40000 [============= ] - 108s 3ms/sample - loss: 0.5648
- accuracy: 0.9691 - val loss: 3.0552 - val accuracy: 0.4682
Epoch 31/100
40000/40000 [============= ] - 109s 3ms/sample - loss: 0.5256
- accuracy: 0.9735 - val_loss: 3.0819 - val_accuracy: 0.4673
Epoch 32/100
- accuracy: 0.9735 - val_loss: 3.1257 - val_accuracy: 0.4728
Epoch 33/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 0.4754
- accuracy: 0.9768 - val_loss: 3.1471 - val_accuracy: 0.4680
40000/40000 [================ ] - 109s 3ms/sample - loss: 0.4442
- accuracy: 0.9816 - val_loss: 3.2416 - val_accuracy: 0.4683
Epoch 35/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 0.3966
- accuracy: 0.9916 - val_loss: 3.1433 - val_accuracy: 0.4812
Epoch 36/100
40000/40000 [============= ] - 110s 3ms/sample - loss: 0.3803
- accuracy: 0.9952 - val loss: 3.1494 - val accuracy: 0.4813
Epoch 37/100
40000/40000 [=============== ] - 110s 3ms/sample - loss: 0.3728
- accuracy: 0.9965 - val_loss: 3.1493 - val_accuracy: 0.4798
Epoch 38/100
40000/40000 [================ ] - 108s 3ms/sample - loss: 0.3674
```

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```
- accuracy: 0.9967 - val loss: 3.1642 - val accuracy: 0.4828
        Epoch 39/100
        40000/40000 [=============== ] - 108s 3ms/sample - loss: 0.3614
        - accuracy: 0.9972 - val loss: 3.1652 - val accuracy: 0.4828
        Epoch 40/100
        40000/40000 [============== ] - 108s 3ms/sample - loss: 0.3565
        - accuracy: 0.9970 - val loss: 3.1896 - val accuracy: 0.4803
        Epoch 41/100
        40000/40000 [=============== ] - 108s 3ms/sample - loss: 0.3501
        - accuracy: 0.9978 - val loss: 3.1823 - val accuracy: 0.4812
        Epoch 42/100
        40000/40000 [============= ] - 108s 3ms/sample - loss: 0.3453
        - accuracy: 0.9975 - val loss: 3.1954 - val accuracy: 0.4819
        Epoch 43/100
        40000/40000 [=============== ] - 109s 3ms/sample - loss: 0.3405
        - accuracy: 0.9979 - val_loss: 3.1892 - val_accuracy: 0.4806
        Epoch 44/100
        40000/40000 [============= ] - 110s 3ms/sample - loss: 0.3357
        - accuracy: 0.9980 - val loss: 3.2206 - val accuracy: 0.4770
        Epoch 45/100
        40000/40000 [============= ] - 108s 3ms/sample - loss: 0.3297
        - accuracy: 0.9985 - val loss: 3.2055 - val accuracy: 0.4814
        Epoch 46/100
        40000/40000 [============= ] - 109s 3ms/sample - loss: 0.3293
        - accuracy: 0.9988 - val_loss: 3.2074 - val_accuracy: 0.4809
        Epoch 47/100
        - accuracy: 0.9987 - val_loss: 3.2057 - val_accuracy: 0.4813
        Epoch 48/100
        40000/40000 [=============== ] - 110s 3ms/sample - loss: 0.3279
        - accuracy: 0.9987 - val_loss: 3.2077 - val_accuracy: 0.4806
        Epoch 49/100
        40000/40000 [============= ] - 110s 3ms/sample - loss: 0.3263
        - accuracy: 0.9987 - val loss: 3.2090 - val accuracy: 0.4803
        Epoch 50/100
        40000/40000 [============= ] - 108s 3ms/sample - loss: 0.3267
        - accuracy: 0.9987 - val_loss: 3.2099 - val_accuracy: 0.4807
        Epoch 51/100
        - accuracy: 0.9987 - val loss: 3.2109 - val accuracy: 0.4812
        Epoch 52/100
        40000/40000 [============= ] - 109s 3ms/sample - loss: 0.3251
        - accuracy: 0.9985 - val_loss: 3.2109 - val_accuracy: 0.4821
        40000/40000 [================ ] - 109s 3ms/sample - loss: 0.3247
        - accuracy: 0.9986 - val loss: 3.2120 - val accuracy: 0.4811
        Epoch 54/100
        40000/40000 [============= ] - 108s 3ms/sample - loss: 0.3242
        - accuracy: 0.9986 - val loss: 3.2163 - val accuracy: 0.4820
        Epoch 00054: early stopping
In [12]: model.save('Version Final.h5')
```

```
In [13]: model.summary()
```

Lavar (tura)	Output Chara	Dansu #
Layer (type)	Output Shape ============	Param # ======
conv2d (Conv2D)	(None, 30, 30, 32)	896
batch_normalization (BatchNo	(None, 30, 30, 32)	128
max_pooling2d (MaxPooling2D)	(None, 15, 15, 32)	0
conv2d_1 (Conv2D)	(None, 13, 13, 128)	36992
batch_normalization_1 (Batch	(None, 13, 13, 128)	512
max_pooling2d_1 (MaxPooling2	(None, 6, 6, 128)	0
conv2d_2 (Conv2D)	(None, 4, 4, 128)	147584
batch_normalization_2 (Batch	(None, 4, 4, 128)	512
conv2d_3 (Conv2D)	(None, 2, 2, 256)	295168
batch_normalization_3 (Batch	(None, 2, 2, 256)	1024
max_pooling2d_2 (MaxPooling2	(None, 1, 1, 256)	0
flatten (Flatten)	(None, 256)	0
dense (Dense)	(None, 128)	32896
dense_1 (Dense)	(None, 256)	33024
dense_2 (Dense)	(None, 100)	25700
	=======================================	======

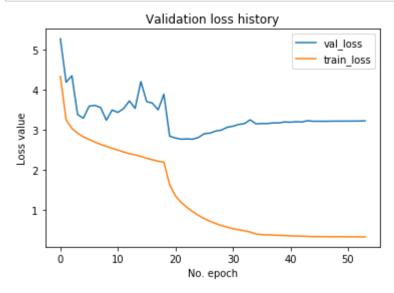
Total params: 574,436 Trainable params: 573,348 Non-trainable params: 1,088

```
In [14]: # Generate generalization metrics
    score = model.evaluate(testX, testY, verbose=0)
    print(f'Test loss: {score[0]} / Test accuracy: {score[1]}')
```

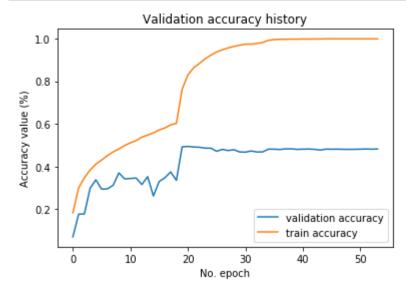
Test loss: 3.152114510726929 / Test accuracy: 0.4839000105857849

```
In [15]: testY_pred = model.predict(testX)
```

```
In [16]: # Visualize history
# Plot history: Loss
plt.plot(history.history['val_loss'], label = 'val_loss')
plt.plot(history.history['loss'], label = 'train_loss')
plt.title('Validation loss history')
plt.ylabel('Loss value')
plt.xlabel('No. epoch')
plt.legend()
plt.show()
```



```
In [17]: # Plot history: Accuracy
    plt.plot(history.history['val_accuracy'], label = 'validation accuracy')
    plt.plot(history.history['accuracy'], label = 'train accuracy')
    plt.title('Validation accuracy history')
    plt.ylabel('Accuracy value (%)')
    plt.xlabel('No. epoch')
    plt.legend()
    plt.show()
```



```
In [18]:
         import random
         fig=plt.figure(figsize=(10,7))
         columns = 3
         rows = 3
         # Visualize firt 9 images
         for i in range(1,10):
             fig.add_subplot(rows, columns, i)
             k = random.randrange(10000)
             image = testX[k]
             target_pred = testY_pred[k].tolist().index(testY_pred[k].max())
             target_actual = testY[k][0]
             plt.axis('off')
             plt.imshow(image)
             plt.title(classes[target_pred]+' ('+classes[target_actual]+')')
         plt.show()
```





rabbit (ray)



leopard (leopard)



motorcycle (motorcycle)



caterpillar (caterpillar)



fox (tiger)



sunflower (sunflower)



chair (chair)



plain (road)

