

به نام خدا



دانشگاه صنعتی خواجه نصیرالدین طوسی دانشکده برق

شبیه سازی و مدلسازی

گزارش تمرین شماره 1

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بهمن 1402

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بخش١: سوالات تحليلي

سوال اول

Input:
$$u = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$
 Output: $y = \begin{bmatrix} 4 \\ 5 \\ 7 \end{bmatrix}$

Design matrix:
$$U = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix}$$

$$\theta = (U^T U)^{-1} U^T y = \left(\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 4 \\ 5 \\ 7 \end{bmatrix}$$

$$= \begin{bmatrix} 3 & 6 \\ 6 & 14 \end{bmatrix}^{-1} \begin{bmatrix} 16 \\ 35 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 14 & -6 \\ -6 & 3 \end{bmatrix} \begin{bmatrix} 16 \\ 35 \end{bmatrix} = \begin{bmatrix} \frac{14}{6} \\ \frac{9}{6} \end{bmatrix} = \begin{bmatrix} 2.34 \\ 1.5 \end{bmatrix}$$

$$\theta_1 = 2.34 , \ \theta_2 = 1.5$$



```
% data points x = [1; 2; 3]; % input y = [4; 5; 7]; % output X = [ones(size(x)),x]; % design matrix % method 1 coefficients = X \setminus y; m = coefficients(2); b = coefficients(1); % method 2 theta = (inv(X'*X))*X'*y; theta_1 = theta(1); theta_2 = theta(2); fprintf('theta_{1} = %.2f\n',theta_1) fprintf('theta_{2} = %.2f\n',theta_2)
```

code 1:

1. Data Points and Design Matrix:

- I've defined two vectors, x and y, representing input and output data points.
- The design matrix X is created by adding a column of ones to x.

2. **Method 1: Solving Using Backslash Operator** (\):

- You've used the backslash operator to solve the linear system X
 * coefficients = y.
- The coefficients m and b represent the slope and intercept of the regression line, respectively.

3. Method 2: Using Matrix Inversion:

- Alternatively, you've computed the coefficients using matrix inversion.
- theta_1 and theta_2 correspond to the intercept and slope, respectively.

Predict y for a specific x (e.g., x = 4)

```
x_new = 4;

y_predicted = m * x_new + b;

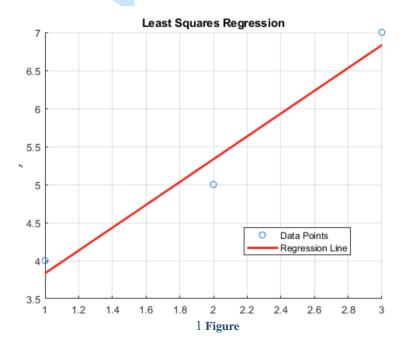
fprintf('Predicted y for x = %.2f is y = %.2f\n', x_new, y_predicted);

% Plot the data points and the regression line figure;
scatter(x, y, 'o', 'DisplayName', 'Data Points');
hold on;
x_fit = linspace(min(x), max(x), 100);
y_fit = m * x_fit + b;
plot(x_fit, y_fit, 'r-', 'LineWidth', 2, 'DisplayName', 'Regression Line');
xlabel('x');
ylabel('y');
title('Least Squares Regression');
legend('Location', 'best');
grid on;
```

Predicted y for x = 4.00 is y = 8.33

Code 2: **Prediction for a Specific** x:

- o I've predicted the value of y for a new x (in this case, $x_n = 4$).
- The predicted y value is calculated as $y_predicted = m * x_new + b$.



Plotting the Regression Line:

I've visualized the data points and the regression line.

The red line represents the least squares regression fit.

Predict y-values using the model

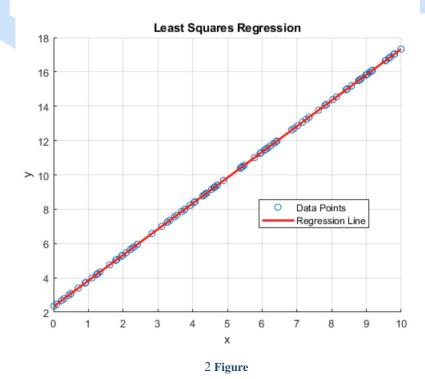
```
mdl = fitlm(x, y);

% Predict y-values using the model
x_new = 10 * rand(1,100)'; % New x-values for prediction
y_pred = predict(mdl, x_new);

% Plot
figure()
scatter(x_new,y_pred,'DisplayName', 'Data Points');
hold on;
plot(x_new, y_pred, 'r-', 'LineWidth', 2, 'DisplayName', 'Regression Line');
xlabel('x');
ylabel('y');
title('Least Squares Regression');
legend('Location', 'best');
grid on;
```

code 3:

- I've also used the fitlm function to create a linear regression model (mdl).
- Next, I've predicted y values for new x values.



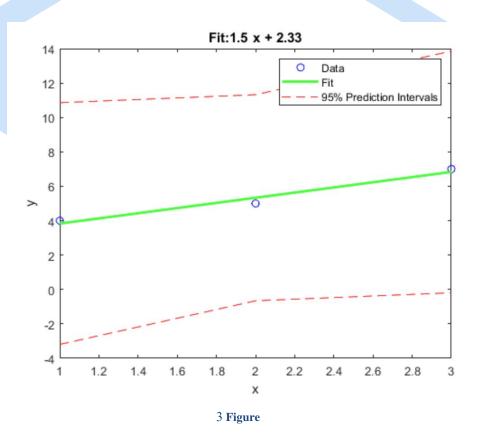
95% Prediction Intervals

```
degree = 1; % Degree of the fit
[p,S] = polyfit(x,y,degree);
alpha = 0.05; % Significance level
[yfit,delta] = polyconf(p,x,S,'alpha',alpha);

figure()
plot(x,y,'bo')
hold on
plot(x,yfit,'g-','LineWidth',2)
plot(x,yfit-delta,'r--',x,yfit+delta,'r--')
legend('Data','Fit','95% Prediction Intervals')
xlabel('x');
ylabel('y');
title(['Fit:',texlabel(polystr(round(p,2)))])
hold off
```

code 4 : Confidence band around linear least-squares line

I've found the the band by using p 'polytool' and defined a polystr function



بخش۲: سوالات شبیه سازی

سوال اول

import data

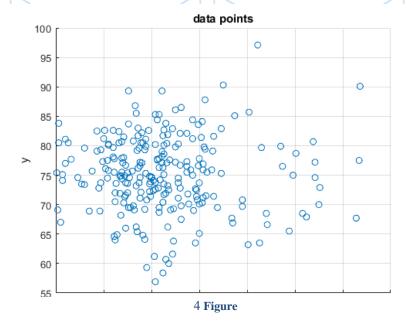
```
A=readmatrix('batch-yield-and-purity.csv');

x=A(:,2);
y=A(:,1);
X=[ones(size(x)),x];

figure()
scatter(x,y)
title('data points')
xlabel('x');
ylabel('y');
grid on
hold on
```

Data Import and Visualization:

- I've imported data from a CSV file named "batch-yield-andpurity.csv."
- The data consists of two columns: x (input) and y (output).
- o I've plotted the data points using a scatter plot.



```
% without command
Theta_ncmd1=(inv(X'*X))*X'*y

Theta_ncmd2=pinv(X)*y

% with command
Theta_cmd=lsqr(X,y)

% curve fitting
ytilda = X*Theta_cmd;
plot(x,ytilda,'r',LineWidth=3)
xlabel('x');
ylabel('y');
title('curve fitting')

% error
error = y - ytilda;
J = error' * error;
```

```
Theta_ncmd1 = 76.7595 -0.0251

Theta_ncmd2 = 76.7595 -0.0251

Theta_cmd = 76.7595 -0.0251
```

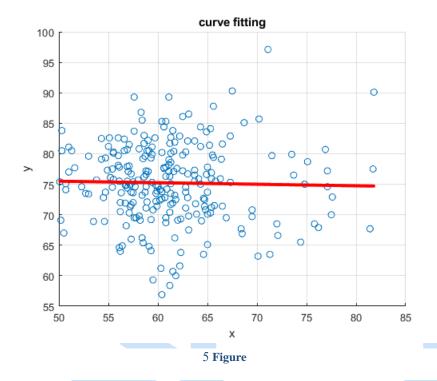
Estimating Coefficients:

I've calculated the coefficients using different methods:

- Without Commands: Theta_ncmd1 and Theta_ncmd2 represent the coefficients obtained without specific MATLAB commands.
- With Command: Theta_cmd represents the coefficients obtained using the lsqr command.

Error Calculation:

 You've computed the error between the actual y values and the predicted y values. The objective function J quantifies the error



Curve Fitting:

I've fitted a curve to the data using the estimated coefficients.

The red line represents the fitted curve.

BLUE

```
theta = X \setminus y;
theta_0 = theta_1;
theta_1 = theta(2)
% Display the estimated linear model
fprintf('Estimated linear model: y = \%.4f + \%.4fx\n', theta_0, theta_1);
% Plot the data points and the fitted line
figure;
scatter(x, y, 'o', 'DisplayName', 'Data Points');
hold on;
x_{fit} = linspace(min(x), max(x), 100);
y_fit = theta_0 + theta_1 * x_fit;
plot(x_fit, y_fit, 'r-', 'LineWidth',2, 'DisplayName', 'Fitted Line');
xlabel('x');
ylabel('y');
title('Best Linear Unbiased Estimation (BLUE)');
legend('Location', 'best');
grid on;
```

theta 1 = -0.0251

Estimated linear model: y = 76.7595 + -0.0251x

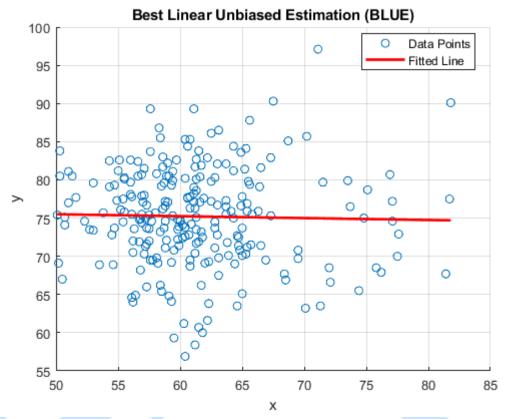


Figure 6.

Best Linear Unbiased Estimation (BLUE):

- You've also estimated the linear model using the backslash operator (\).
- \circ The estimated model is given by $y = \text{theta}_0 + \text{theta}_1 * x$.

Plotting the Fitted Line:

• The scatter plot shows the data points, and the red line represents the fitted regression line.

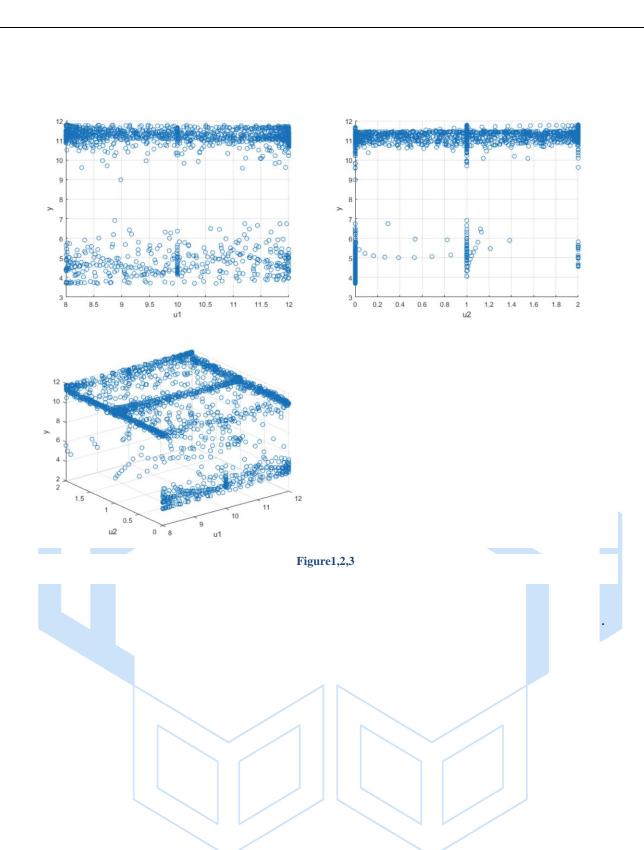
سوال دوم

setup

```
A=importdata("pHdata.dat");
%data Columns
timeSteps=A(:,1);
u1=A(:,2); %input
u2=A(:,3); %input
y=A(:,4); %output
figure()
scatter(u1,y)
xlabel('u1')
ylabel('y')
grid on
figure()
scatter(u2,y)
xlabel('u2')
ylabel('y')
grid on
figure()
scatter3(u1,u2,y)
xlabel('u1')
ylabel('u2')
zlabel('y')
% normalizing data
u1 = (u1 - min(u1)) / (max(u1) - min(u1));
u2 = (u2 - min(u2)) / (max(u2) - min(u2));
y = (y - min(y)) / (max(y) - min(y));
U=[ones(size(y)),u1,u2];
```

Data Import and Normalization:

- The code starts by importing data from a file named "pHdata.dat."
- The data includes columns for timeSteps, u1 (input 1), u2 (input 2), and y (output).
- The u1, u2, and y values are normalized to the range [0, 1]



Least square

```
x = [u1, u2];
X=[ones(size(y))];
theta=zeros(9,4);
for n=1:4
  X=[X,x.^n];
  for i=1:2*n+1
     LS=lsqr(X,y);
     theta(i,n)=(LS(i,1));
  end
  intercept=theta(1,n);
  slope 11=theta(2,n);
  slope21=theta(3,n);
  slope12=theta(4,n);
  slope22 = theta(5,n);
  slope13=theta(6,n);
  slope23=theta(7,n);
  slope14=theta(8,n);
  slope24=theta(9,n);
  yFit = intercept + slope11*u1 + slope21*u2 + slope12*u1.^2 + slope22*u2.^2 ...
      + slope13*u1.^3 + slope23*u2.^3 + slope14*u1.^4 + slope24*u2.^4;
  e_LS = y - yFit;
  %plot
  figure(4)
  subplot(2,2,n)
  scatter3(u1,u2,yFit)
  hold on
  scatter3(u1,u2,y,'filled')
  title( num2str(n), 'order')
  xlabel('u1')
  ylabel('u2')
  zlabel('v')
  legend('Fitted', 'Data')
  figure(5)
  subplot(2,2,n)
  plot(e_LS)
  title( num2str(n), 'order')
  xlabel('Sample Index')
  ylabel('Residual')
  grid on
end
```

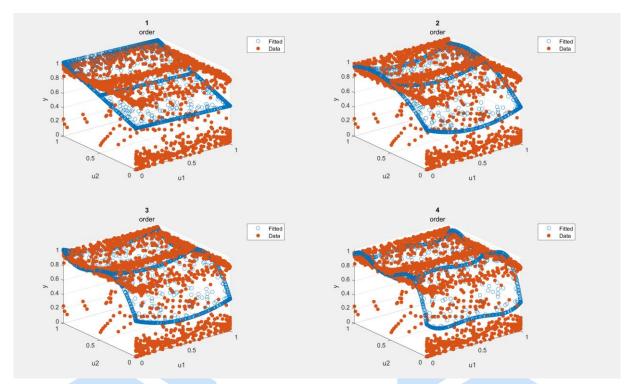


Figure 4

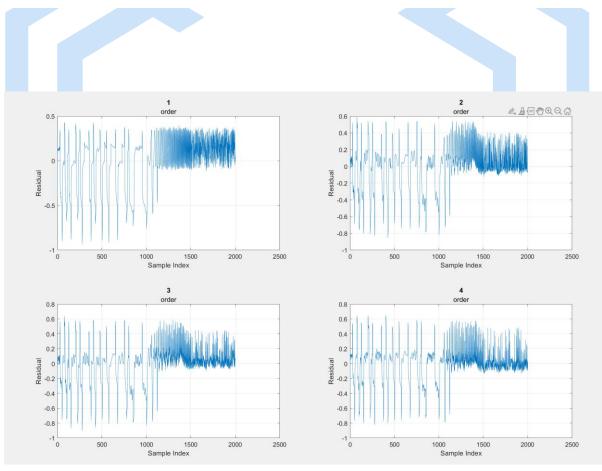
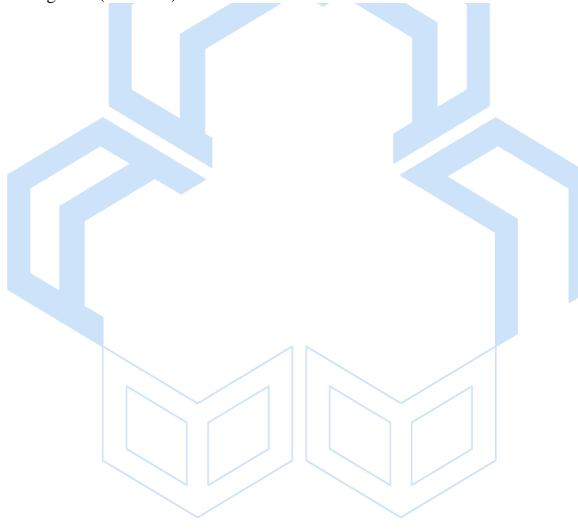


Figure 5

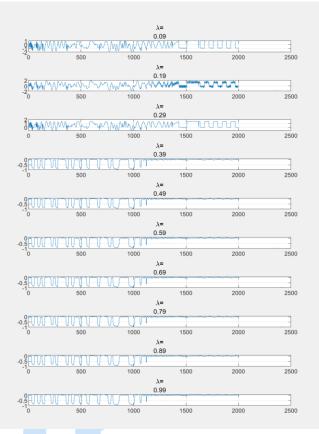
Least Squares Polynomial Fitting:

- o The code performs polynomial fitting using least squares.
- For each polynomial order (from 1 to 4), it constructs a design matrix X with powers of u1 and u2.
- o The coefficients (theta) are estimated using the lsqr function.
- o The fitted values (yFit) are calculated based on the polynomial model.
- Residuals (e_LS) are obtained by subtracting the fitted values from the actual y values.
- The results are plotted in Figure 4 (scatter plot of fitted vs. actual y) and Figure 5 (residuals).



forgetting factor

```
n=0;
for lambda = 0.09:0.05:0.99
  n=n+1;
  theta = zeros(size(U,2),1);
  P = eye(size(U,2)) / lambda;
  for i=1:length(y)
    u_i = U(i,:)';
    y_predict = u_i'*theta;
    e = y(i) - y_predict;
    K = P*u_i/(lambda + u_i'*P*u_i);
    theta = theta + K^*e;
    P = (P - K*u_i'*P)/lambda;
  end
% error
intercept=theta(1);
slope_u1=theta(2);
slope_u2=theta(3);
yFit_ff = intercept + slope_u1*u1 + slope_u2*u2;
e_ff = y - yFit_ff;
figure(6)
subplot(10,2,n)
plot(e_ff)
grid on
title('\lambda=',num2str(lambda))
end
```



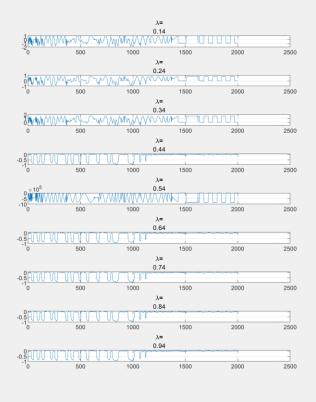


Figure 6

Forgetting Factor Recursive Estimation:

- The code then performs recursive estimation with a forgetting factor (lambda).
- The parameters (theta) are updated iteratively using the recursive least squares (RLS) algorithm.
- o The fitted values with the forgetting factor (yFit_ff) are calculated.
- Residuals (e_ff) are obtained by subtracting the fitted values from the actual y values.
- The results are plotted in Figure 6 (residuals for different forgetting factors).

sliding window

```
window_size=1000;
step_size=1;
num_points=length(y);
num_windows = floor((num_points - window_size) / step_size) + 1;
intercept_sw = zeros(num_windows,1);
slope1_sw = zeros(num_windows,1);
slope2_sw = zeros(num_windows,1);
e sw = zeros(num windows,window size);
for i=1:num_windows
  Start = (i-1) * step size + 1;
  End = Start + window_size - 1;
  u1_inWindow = u1(Start:End);
  u2_{in}Window = u2(Start:End);
  y_inWindow = y(Start:End);
 U_window = [ones(size(y_inWindow)),u1_inWindow,u2_inWindow];
  theta_window = pinv(U_window) * y_inWindow;
  intercept sw(i)=theta window(1);
  slope1_sw(i)=theta_window(2);
  slope2 sw(i)=theta window(3);
  yFit_window = U_window * theta_window;
  e_sw(i,:) = y_inWindow - yFit_window;
end
%plot
figure(7)
for i=1:num windows
  Start = (i-1) * step\_size + 1;
  End = (i-1) * step_size + window_size;
  u1_inWindow = u1(Start:End);
  u2 inWindow = u2(Start:End);
 yFit_sw = intercept_sw(i) + slope1_sw(i)*u1_inWindow + slope2_sw(i)*u2_inWindow;
  scatter3(u1,u2,y,'filled','k')
  hold on
  plot3(u1_inWindow,u2_inWindow,yFit_sw)
end
figure(8)
plot(e_sw)
grid on:
```

1. Sliding Window Parameters:

- o window_size is set to 1000 data points.
- step_size is set to 1, meaning the window moves one data point at a time.

2. Window Initialization:

- The total number of data points (num_points) is determined from the length of the y vector.
- The number of windows (num_windows) is calculated based on the window size and step size.

3. Initialization of Variables:

Arrays are initialized to store results for each window:

- intercept_sw: Intercept of the linear regression model for each window.
- slope1_sw: Slope coefficient for u1 in the linear regression model for each window.
- slope2_sw: Slope coefficient for u2 in the linear regression model for each window.
- o e sw: Residuals (errors) for each window.

4. Sliding Window Loop:

For each window:

- Determine the start and end indices of the current window.
- Extract the corresponding data points (u1_inWindow, u2_inWindow, y_inWindow).
- Create a design matrix U_window by adding a column of ones to u1_inWindow and u2_inWindow.
- Calculate the coefficients (theta_window) using the pseudo-inverse (pinv) method.
- Store the intercept and slopes in the respective arrays.
- Compute the fitted values (yFit_window) using the estimated coefficients.
- Calculate the residuals (e_sw) by subtracting the fitted values from the actual y values.

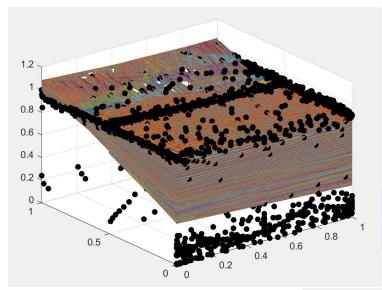
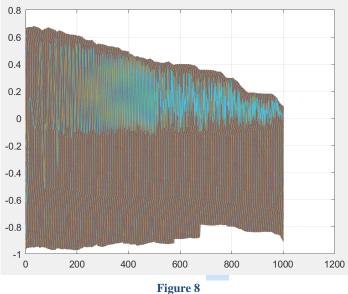


Figure 7



5. Plotting Results:

- Figure 7:
 - For each window, scatter plot the actual data points (u1, u2, y) in black.
 - Overlay the regression line (yFit_sw) for the current window.
- Figure 8:
 - Plot the residuals (e sw) for all windows.
 - The grid is turned on for clarity.

6. Interpretation:

- The sliding window analysis allows you to perform local linear regression on subsets of the data.
- o It estimates regression coefficients within each window and visualizes the results.

RLS sliding window

```
window_size=1000; step_size=1;
num_points=length(y);
intercept swR = zeros(num windows,1);
slope1_swR = zeros(num_windows,1);
slope2_swR = zeros(num_windows,1);
e_swR = zeros(num_windows,window_size);
for i = 1: num_points - window_size + 1
  Start = (i-1) * step\_size + 1;
  End = Start + window_size - 1;
  u1 inWindow = u1(Start:End);
  u2 inWindow = u2(Start:End);
  y_inWindow = y(Start:End);
  P = eye(3);
  theta_window = zeros (3,1);
  window_errors = zeros(1,window_size);
  for j =1:window_size
    u=[1; u1 inWindow(j); u2 inWindow(j)];
    e = y_inWindow(j) - u' * theta_window;
    K = (P*u) / (1 + u'*P*u);
    theta_window = theta_window + K*e;
    P = P - K*u'*P;
    window_errors(j) = e;
  e_swR(i,:) = window_errors;
end
%plot
figure(9)
for i=1:num_windows
  Start = (i-1) * step\_size + 1;
  End = (i-1) * step_size + window_size;
  u1_Window = u1(Start:End);
  u2_Window = u2(Start:End);
  yFit_swR = intercept_swR(i) + slope1_swR(i)*u1_Window + slope2_swR(i)*u2_Window;
  plot3(u1_Window,u2_Window,yFit_swR)
  hold on
end
scatter3(u1,u2,y,'filled','b')
figure(10)
plot(e_swR)
grid on
```

1. Sliding Window Parameters:

- o window_size is set to 1000 data points.
- step_size is set to 1, meaning the window moves one data point at a time.

2. Initialization of Variables:

- num_points represents the total number of data points in the vector v.
- Arrays are initialized to store results for each window:
 - intercept_swR: Intercept of the linear regression model for each window.
 - slope1_swR: Slope coefficient for u1 in the linear regression model for each window.
 - slope2_swR: Slope coefficient for u2 in the linear regression model for each window.
 - e_swR: Residuals (errors) for each window.

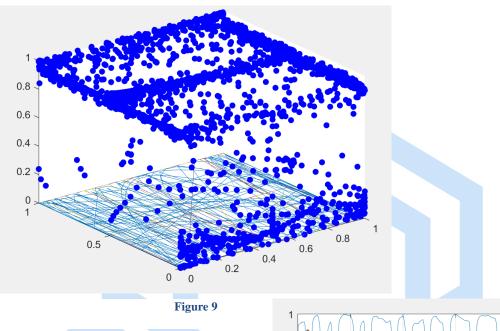
3. Sliding Window Loop:

For each window:

- o Determine the start and end indices of the current window.
- Extract the corresponding data points (u1_inWindow, u2_inWindow).
- Initialize the covariance matrix P and the parameter vector theta window.
- Iterate over each data point within the window:
 - Compute the Kalman gain K.
 - Update the parameter vector theta_window.
 - Update the covariance matrix P.
 - Calculate the error (e) and store it in window_errors.
- Store the window errors in e_swR.

4. Interpretation:

- The sliding window analysis with recursive estimation allows you to adaptively estimate regression coefficients within each window.
- The Kalman gain (K) adjusts the parameter estimates based on the observed errors.
- The results are useful for tracking changes in the regression model over time.



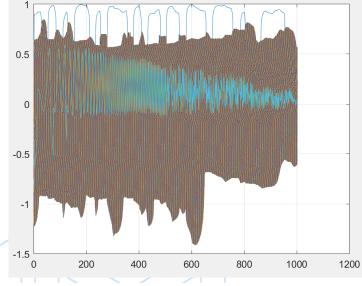


Figure 10

5. Plotting Results:

- o Figure 9:
 - For each window, compute the fitted values (yFit_swR) using the estimated coefficients.
 - Plot the regression line (yFit_swR) for the current window.
 - Overlay the actual data points (u1, u2, y) in blue.
- o Figure 10:
 - Plot the residuals (e_swR) for all windows.
 - The grid is turned on for clarity.

مراجع

 $[1] \qquad \underline{https://www.mathworks.com/matlabcentral/answers/392636\text{-}confidence-band-around-linear-least-squares-line}$

