Calibration results
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Camera-system parameters:
cam0 (/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [0.1391484 -0.37521469 0.009574   -0.00534517] +- [0.0116886 0.04714139 0.00131872 0.00169827]
projection: [639.52937597 646.18525108 302.05929698 257.4986989] +- [4.36357987 4.51646601 2.79461738 2.28794185]
reprojection error: [-0.000000, 0.000001] +- [0.359535, 0.507353]
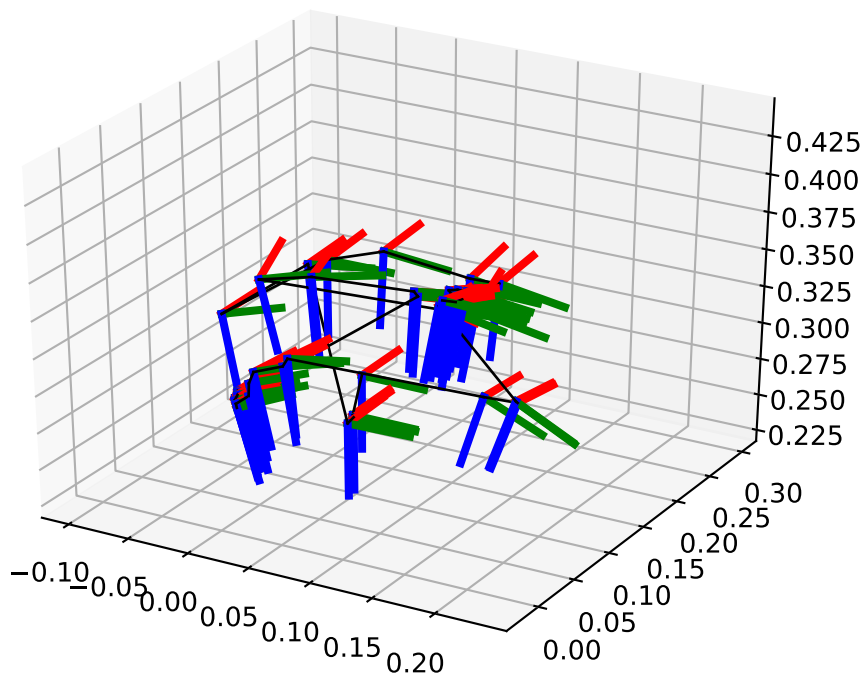

Target configuration
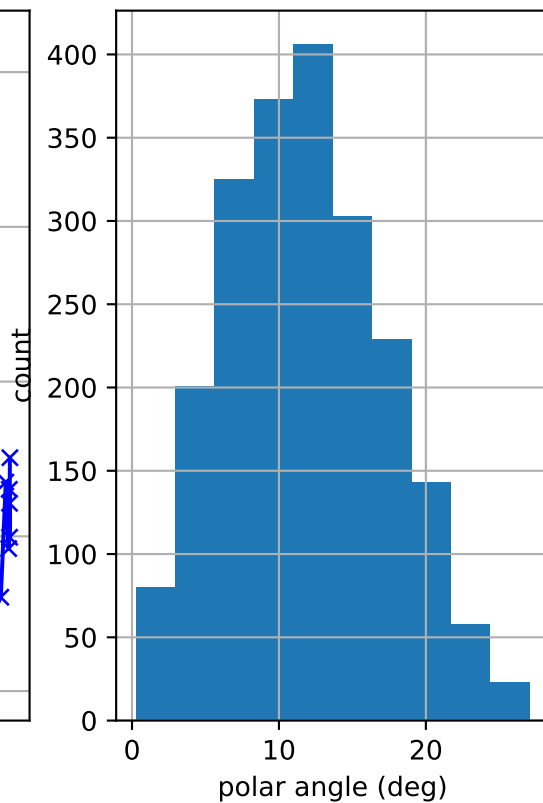====================

Type: checkerboard
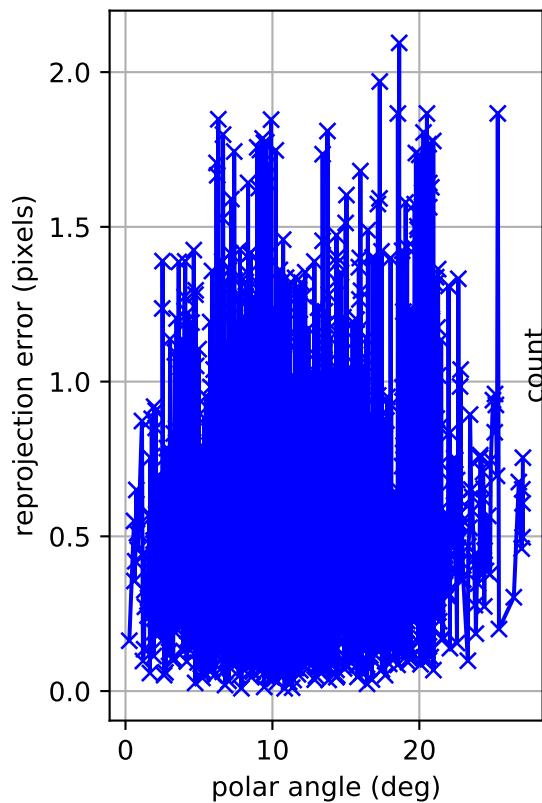Rows
Count: 6
Distance: 0.024 [m]
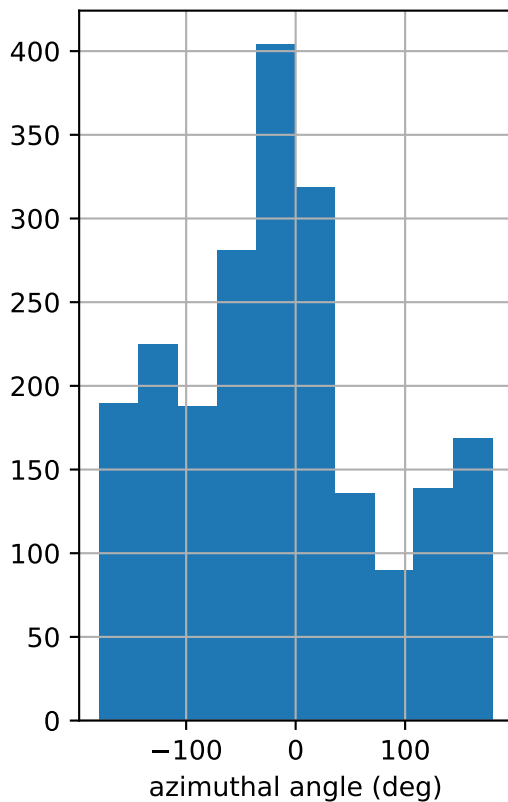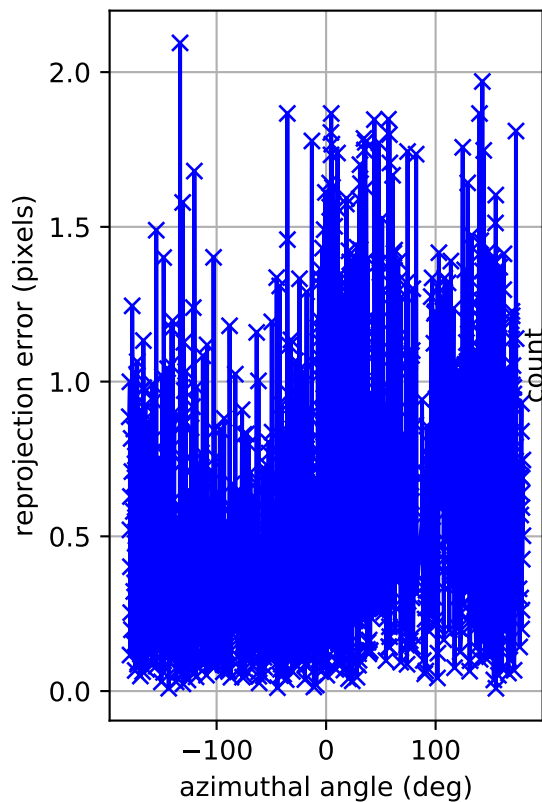Cols
Count: 8
Distance: 0.024 [m]
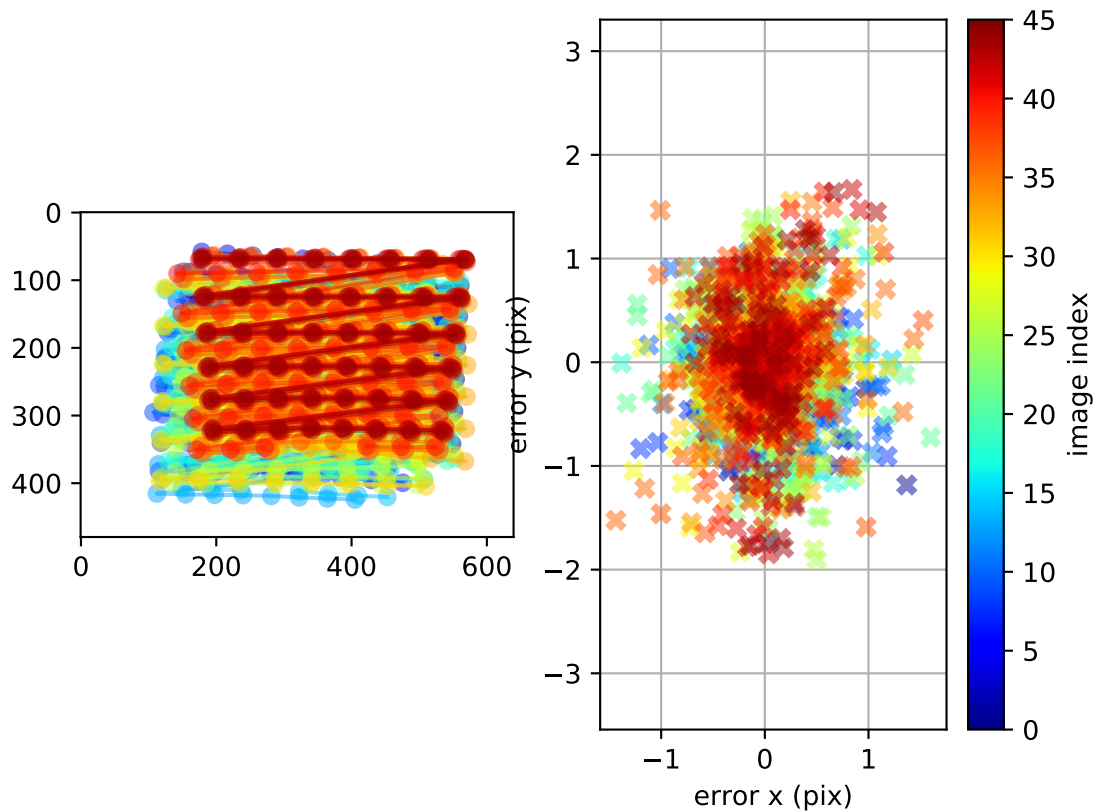
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0