Calibration results
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Camera-system parameters:
cam0 (/image_cropped):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-1.11328917 -0.54314621 0.24707519 -0.09080968] +- [0.33639084 0.77082358 0.03457058 0.0277952]
projection: [855.41862525 782.9387218 762.18047084   9.34546596] +- [4.53173253 5.16811925 18.63155395 13.67107129]
reprojection error: [0.000015, 0.000012] +- [0.200490, 0.122647]

Target configuration
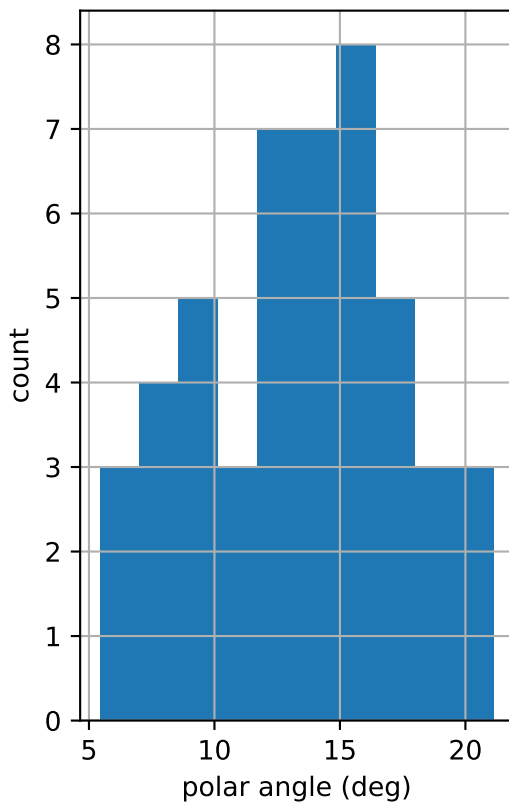====================

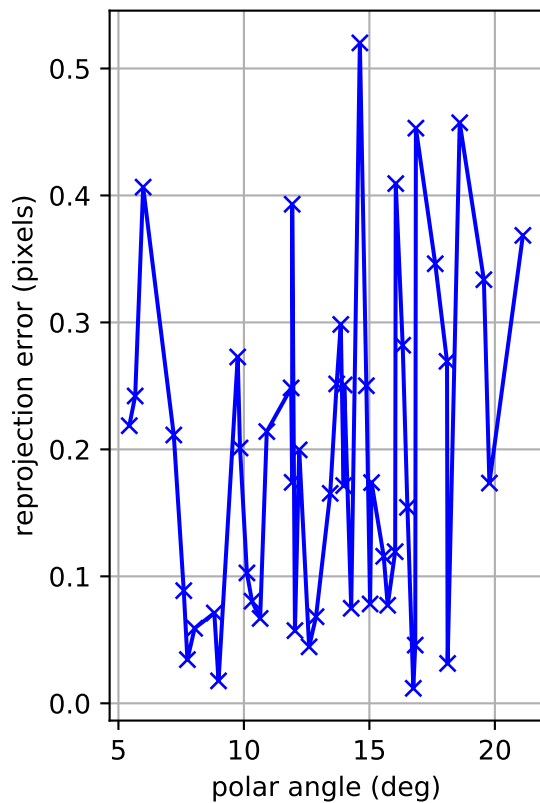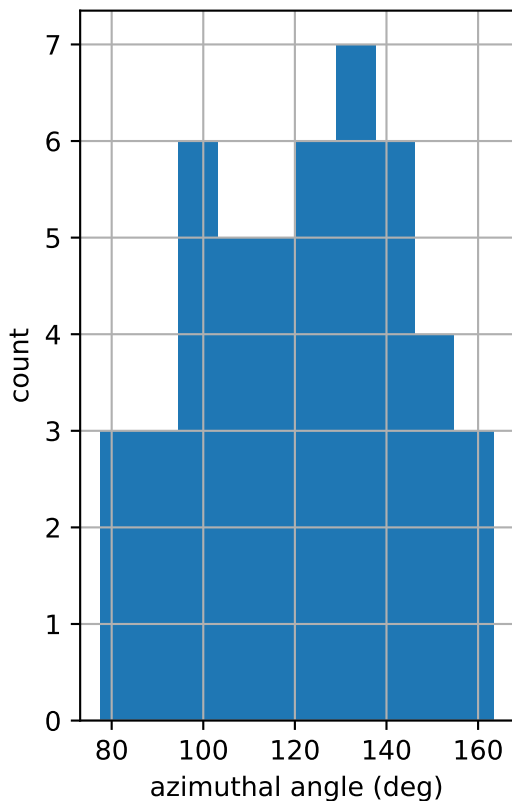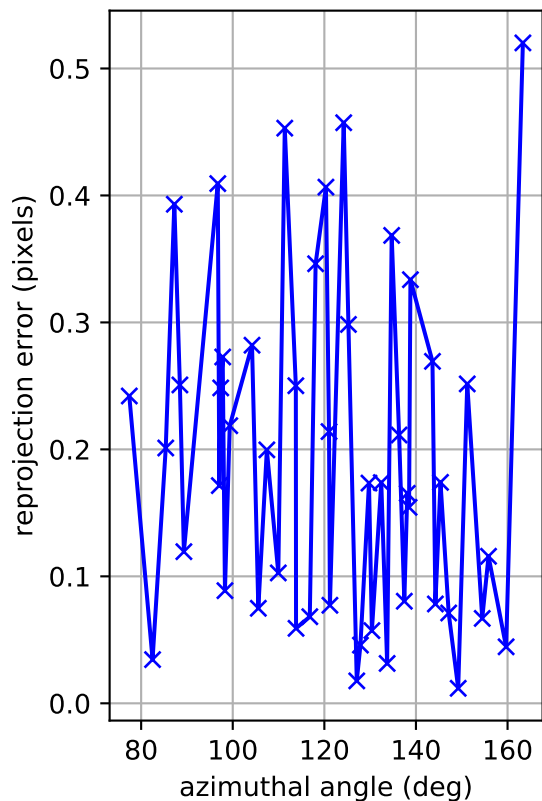Type: checkerboard
Rows
Count: 6
Distance: 0.034 [m]
Cols
Count: 8
Distance: 0.034 [m]

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors