Calibration results
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Camera-system parameters:
cam0 (/image_cropped):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.58069055 0.03797048 -0.10257308 0.14278965] +- [0.18683421 0.07513533 0.03777213 0.14073175]
projection: [541.74272006 593.78268149 515.2440718 308.15854142] +- [49.79576743 59.37219594 139.14635308 60.12250921]
reprojection error: [-0.000006, 0.000004] +- [0.086467, 0.120312]

Target configuration
====================

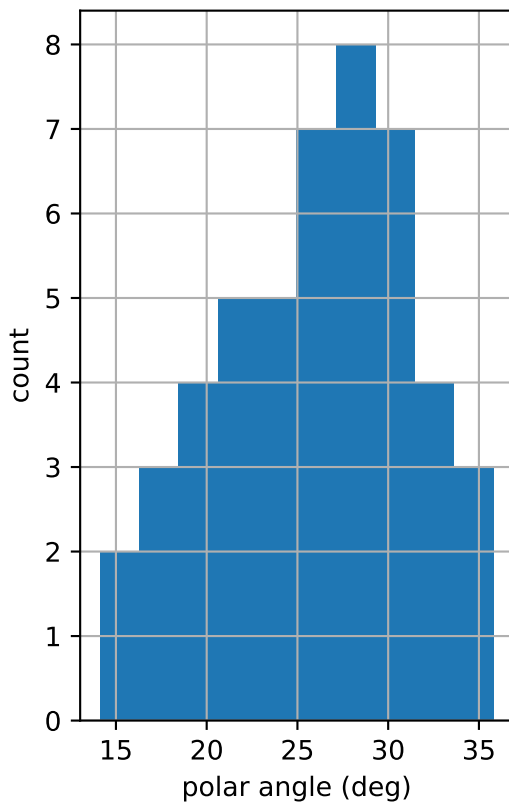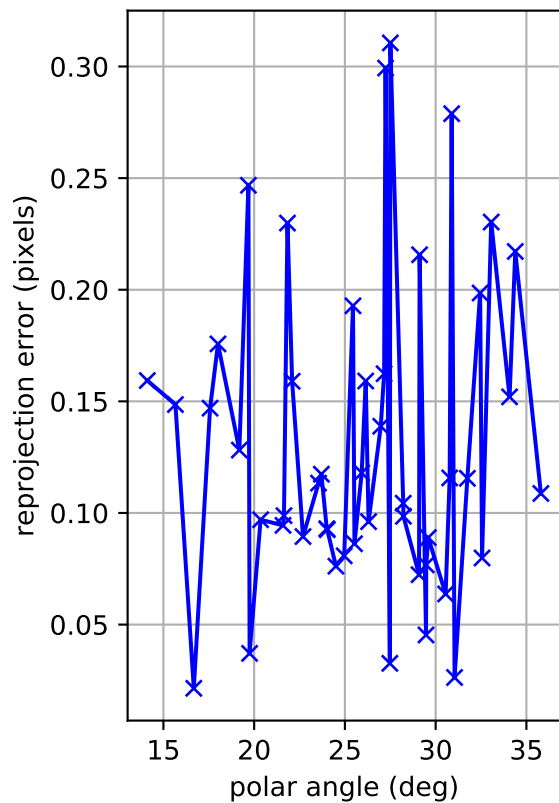Type: checkerboard
Rows
  Count: 6
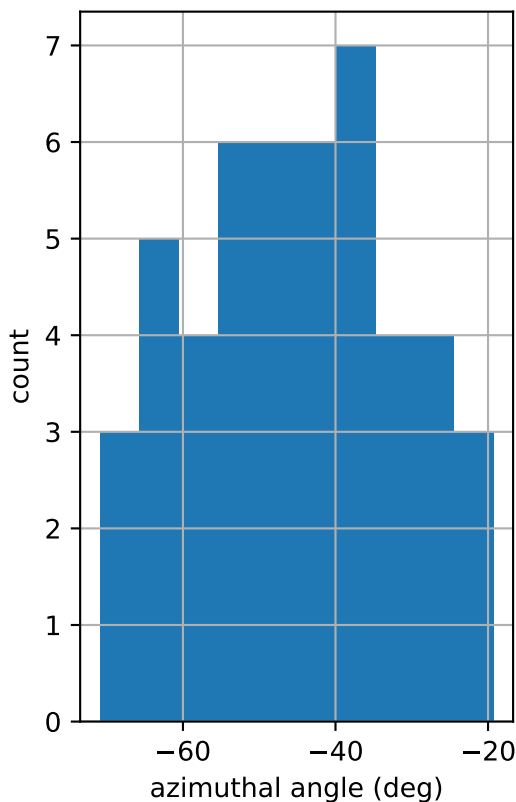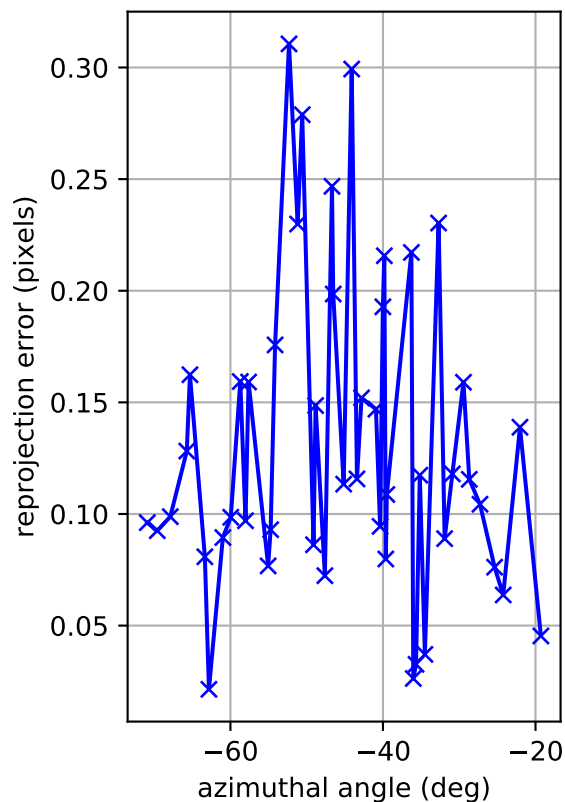 Distance: 0.034 [m]
Cols
  Count: 8
  Distance: 0.034 [m]

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors