

Calibration results

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Camera-system parameters:

cam0 (/image_cropped):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.84922604 -0.16323755 0.1550282 -0.0784892] +- [0.34509922 0.44266801 0.02766657 0.03578619]

projection: [768.00107827 734.33222101 770.69085668 42.51272615] +- [7.3414496 8.26888609 31.35313963 31.01197365]

reprojection error: [-0.000015, -0.000009] +- [0.192115, 0.099788]

Target configuration

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Type: checkerboard

Rows

Count: 6

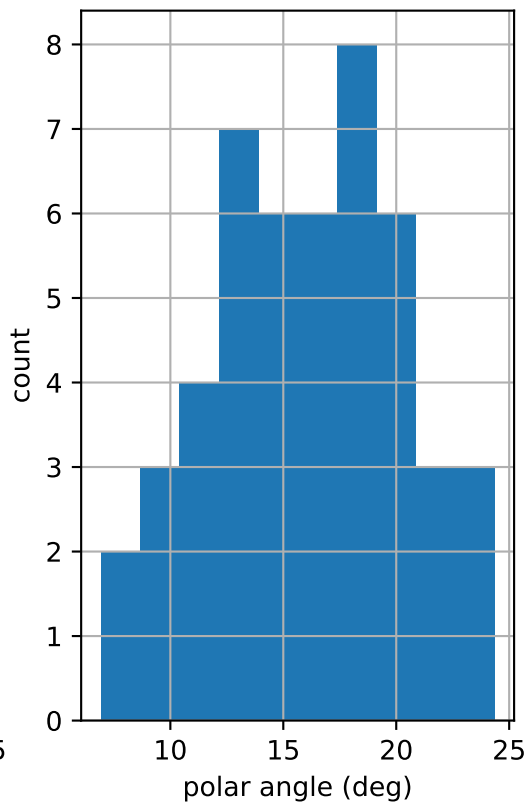
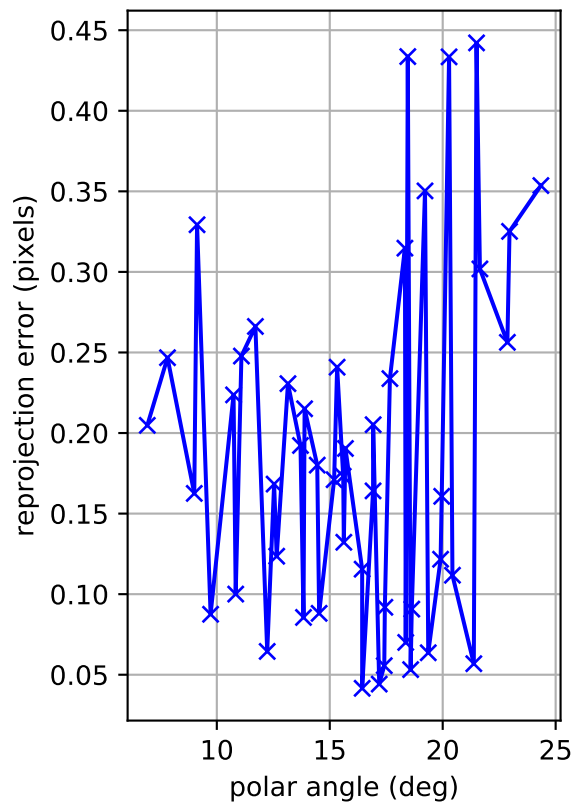
Distance: 0.034 [m]

Cols

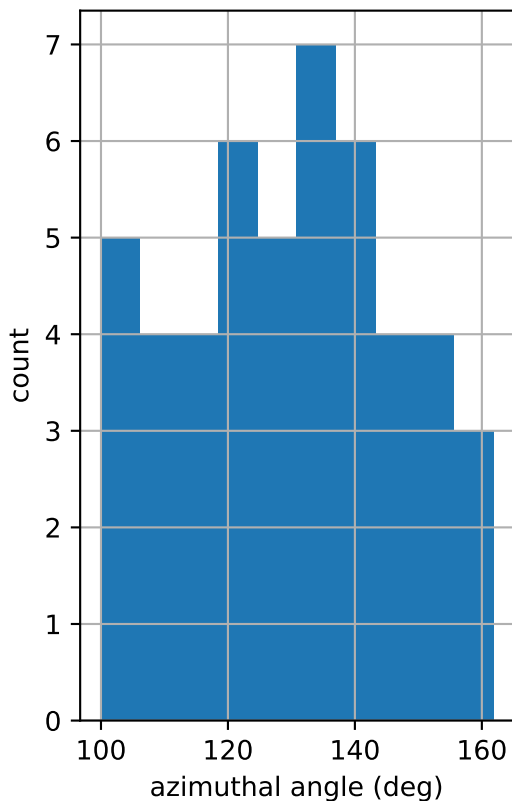
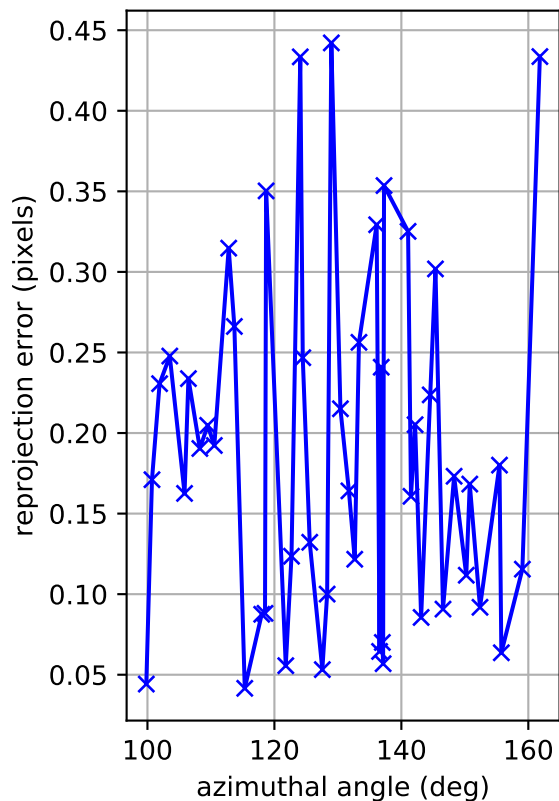
Count: 8

Distance: 0.034 [m]

cam0: polar error



cam0: azimuthal error



cam0: reprojection errors

