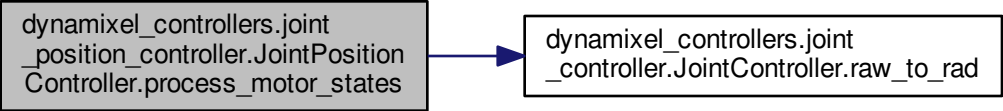


```
dynamixel_controllers.joint  
_position_controller.JointPosition  
Controller.process_motor_states
```



A diagram showing a call to the process_motor_states method of the JointPositionController class. The call is represented by a grey rectangular box on the left, containing the code snippet. A blue arrow points from this box to a white rectangular box on the right, which contains the code snippet for the raw_to_rad property of the JointController class.

```
dynamixel_controllers.joint  
_controller.JointController.raw_to_rad
```