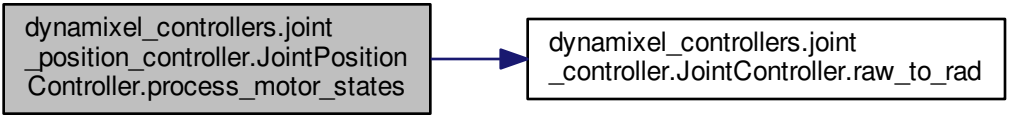
dynamixel_controllers.joint
_position_controller.JointPosition
Controller.process_motor_states
dynamixel_controllers.joint
_controller.JointController.raw_to_rad