

```
dynamixel_controllers.joint  
_position_controller_dual  
_motor.JointPositionControllerDual.process  
_motor_states
```

A diagram showing a call to the `process` method of the `JointPositionControllerDual` class. The call is made on the `_motor` attribute of the `joint_position_controller_dual` object, passing `_motor_states` as an argument. The call is represented by a blue arrow pointing from the left box to the right box.

```
dynamixel_controllers.joint  
_controller.JointController.raw_to_rad
```

A diagram showing a call to the `raw_to_rad` method of the `JointController` class. The call is made on the `joint_controller` attribute of the `dynamixel_controllers` object. The call is represented by a blue arrow pointing from the left box to the right box.