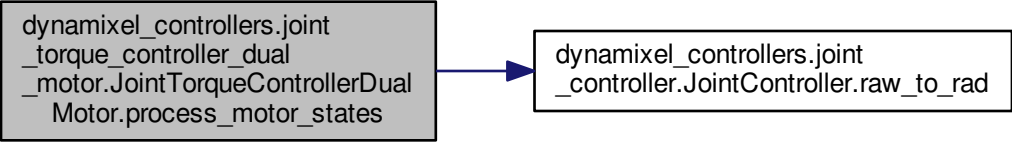


dynamixel\_controllers.joint  
\_torque\_controller\_dual  
\_motor.JointTorqueControllerDual  
Motor.process\_motor\_states



```
graph LR; A["dynamixel_controllers.joint_torque_controller_dual_motor.JointTorqueControllerDualMotor.process_motor_states"] --> B["dynamixel_controllers.joint_controller.JointController.raw_to_rad"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains the text 'dynamixel\_controllers.joint\_torque\_controller\_dual\_motor.JointTorqueControllerDualMotor.process\_motor\_states'. The right box has a white background and contains the text 'dynamixel\_controllers.joint\_controller.JointController.raw\_to\_rad'.

dynamixel\_controllers.joint  
\_controller.JointController.raw\_to\_rad