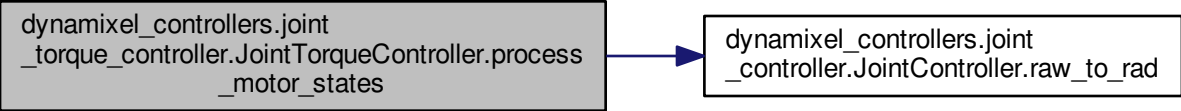


dynamixel_controllers.joint
_torque_controller.JointTorqueController.process
_motor_states



```
graph LR; A["dynamixel_controllers.joint_torque_controller.JointTorqueController.process_motor_states"] --> B["dynamixel_controllers.joint_controller.JointController.raw_to_rad"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'dynamixel_controllers.joint_torque_controller.JointTorqueController.process_motor_states'. The right box is white with a black border and contains the text 'dynamixel_controllers.joint_controller.JointController.raw_to_rad'. A blue arrow points from the right side of the left box to the left side of the right box.

dynamixel_controllers.joint
_controller.JointController.raw_to_rad