## **AC – Aprendizagem Computacional / Machine Learning**

# P4a – Perceptron

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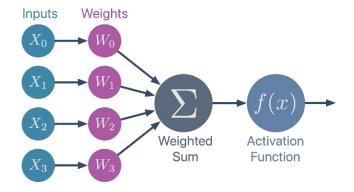
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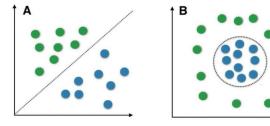




- 1 Objectives
- 2 | Train a Perceptron (by hand)
- 3 | Train a perceptron (Automatically)
  - Datasets
- 4 Conclusions

## Objectives – Network with one Layers of neurons

- Concepts
- Datasets/problems
  - Linearly separable
  - Not linearly separable



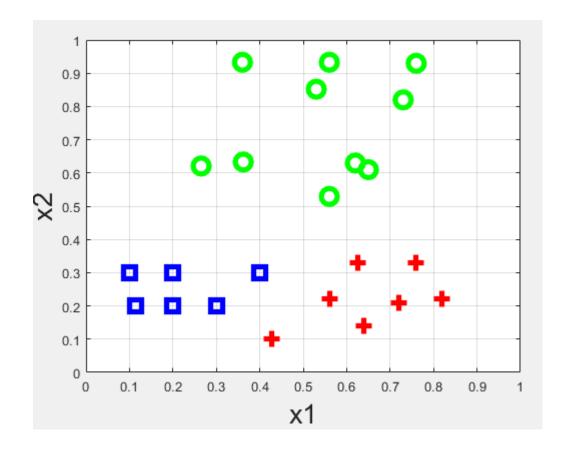
- Structures
  - Perceptron
  - Adaline
  - Sigmoidal activation

- Implement perceptron training rule

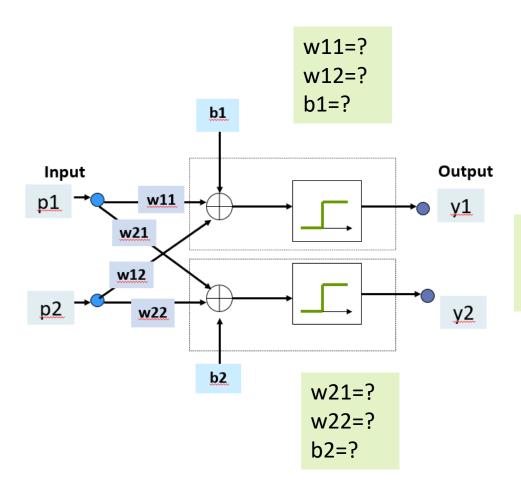
  By hand and automatically
- use of pseudo-inverse
- Implement Recursive Least squares

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- Train a perceptron network (one layer)
  - Define the structure (number of perceptrons)
  - Train the network (parameters w, b)



Training a perceptron network

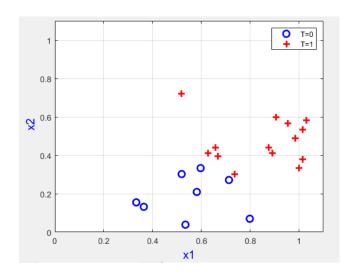


```
If y1=1 AND y2=1 Y=?
If y1=1 AND y2=0 Y=?
```

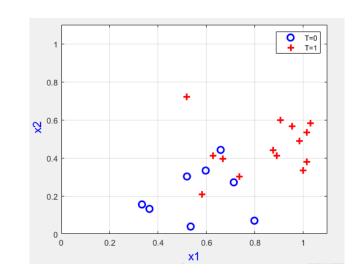
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## Datasets

- Dataset 1 linearly separable
- P4\_data1.csv

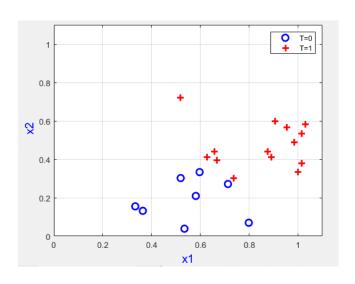


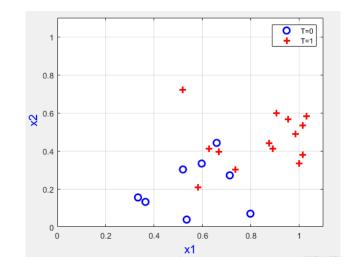
- Dataset 2 non-linearly separable
- P4\_data2.csv



# Three algorithms

- 1 | Perceptron
  - Perceptron Training rule (on-line)
- 2 | Adaline
  - Pseudo-inverse (off-line)
- 3 | Sigmoidal
  - RLMSE (on-line)







## DATA

• X={x1,x2}

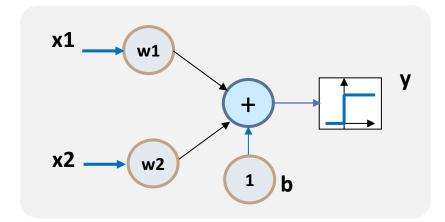
```
0.8147 0.1270 0.6324 0.2785 0.9575 0.1576 0.9572 0.8003 0.4218 0.7922 0.9058 0.9134 0.0975 0.5469 0.9649 0.9706 0.4854 0.1419 0.9157 0.9595 (R=2,N=10)
```

• 
$$x_0 = 0.8147$$
  $x_i = ....$ 

1 0 1 0 1 0 1 0 · (1,N=10)

## 1 | Perceptron learning rule (iterative)

• Activation function: hardlim



$$\theta = \begin{bmatrix} w & b \end{bmatrix} \quad z = \begin{bmatrix} x_i \\ 1 \end{bmatrix}$$

$$y = \text{hardlim}(\theta z)$$
(3,1)

(3,N)

$$W^{(new)} = W^{(old)} + E X^{T}$$
(1,2) (1,N) (N,2)

$$b^{(new)} = b^{(old)} + E I$$
(1,1)
(1,N)(N,1)

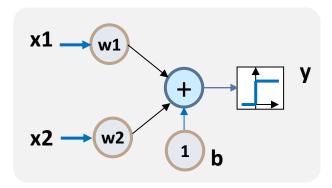
$$E = T - Y$$
 (1,N)  
 $\theta^{(new)} = \theta^{(old)} + E Z^{T}$ 

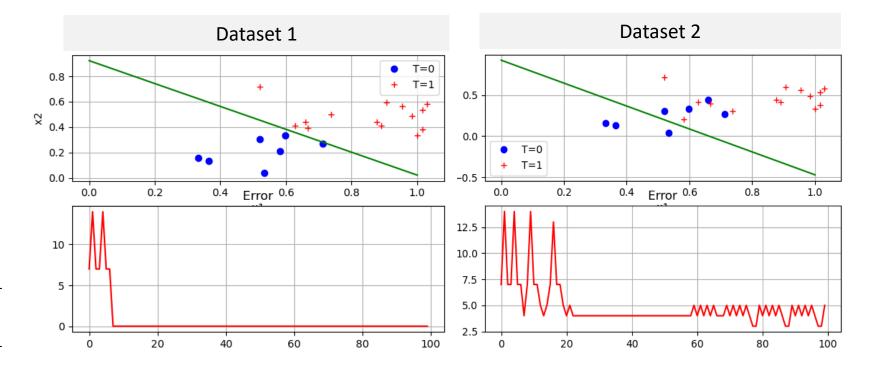
(1,3)

(1,N)

(N,3)

- 1 Perceptron iterative learning rule
  - Linearly / nonlinearly separable ?

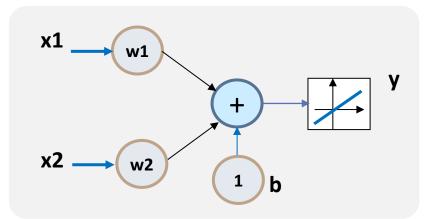






## 2 | Adaline – offline pseudoinverse

Activation function: purelin



$$\theta = \begin{bmatrix} w & b \end{bmatrix} \quad z = \begin{bmatrix} x_i \\ 1 \end{bmatrix} \\
y = \theta z$$
(3,1)

$$Z (3,N)$$

$$e = T - Y (1,N)$$

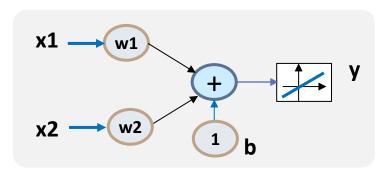
$$\theta = T \left[ Z^T Z \right]^{-1} Z^T$$

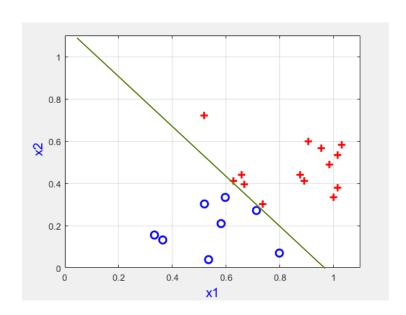
$$(1,3)$$
  $(1,N)$   $(N,3)$  $(3,N)$   $(N,3)$ 

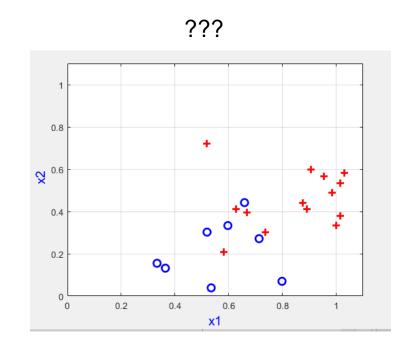
$$\theta = T Z^{+}$$
(1,N) (N,3)

## 2 Adaline - pseudoinverse

• Activation function: purelin



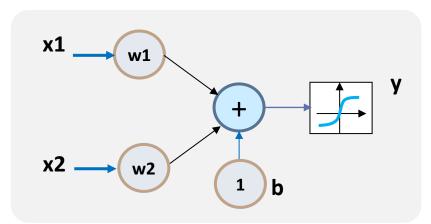






## 3 | Nonlinear – recursive least squares

• Activation function: sigmoidal



$$\theta = \begin{bmatrix} w & b \end{bmatrix} \quad z = \begin{bmatrix} X \\ 1 \end{bmatrix}$$

$$y = \log sig(\theta z)$$
(3,1)

$$W^{(new)} = W^{(old)} + \alpha \left( E \otimes F' \right) X^{T}$$
(1,2) (1,N)  $\otimes$  (1,N) (N,2)

$$b^{(new)} = b^{(old)} + (E \otimes F') I$$

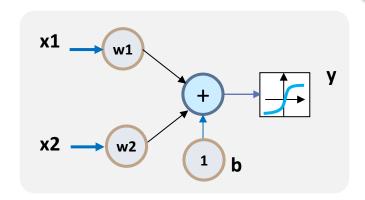
$$(1,1) \qquad (1,N) \otimes (1,N) (N,1)$$

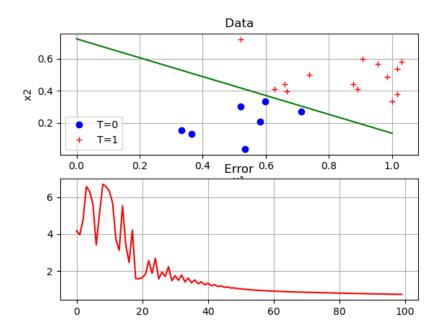
$$Z$$
 (3,N)  $\alpha$  learning rate
$$e = T - Y$$
 (1,N)
$$\theta^{(new)} = \theta^{(old)} + \alpha (E \otimes F') Z^{T}$$
(1,3) (1,N) $\otimes$ (1,N)(N,3)

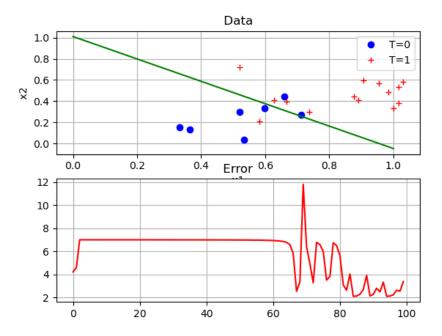


## 3 | Nonlinear – RLS

- Learning rate,  $\alpha$  ?
- Epochs?









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# 4 | Conclusions



#### Structure

- 1 Implement perceptron + perceptron learning rule
  - Epochs?
- 2 | Implement Adaline + pseudo-inverse
  - Right, Left
- 3 | Implement nonlinear neuron + recursive least squares
  - Epochs ?
  - $\alpha$  Learning rate value ?

#### Dataset

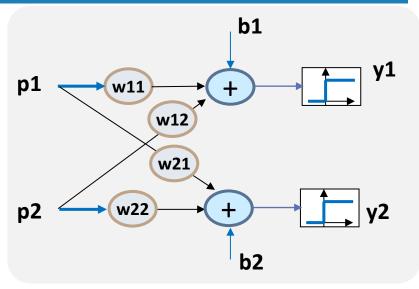
- Linearly separable
- Not linearly separable

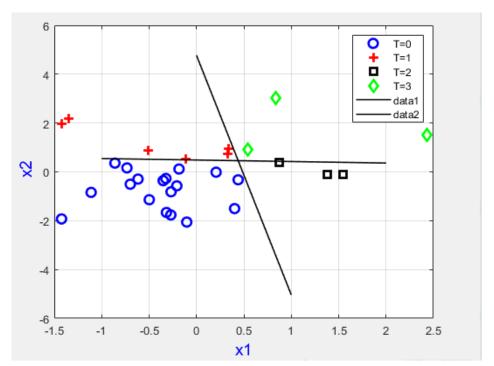
# 4 | Conclusions



# Other ideas - 1 | Multiclass

- 4 classes
- Layer of two perceptrons
- P4\_dataset3.csv
- [x1 x2 y1 y2]





# 4 | Conclusions



## Other ideas – 2 | nonlinear function

Non-linear function

