# Homework #3 A

Spring 2020, CSE 446/546: Machine Learning Dino Bektesevic

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## Conceptual Questions

A1. The answers to these questions should be answerable without referring to external materials. Briefly justify your answers with a few word

- a. [2 points] True or False: Given a data matrix  $X \in \mathbb{R}^{n \times d}$  where dis much smaller than n, if we project our data onto a k dimensional subspace using PCA where  $k = \operatorname{rank} X$ , our projection will have 0 reconstruction error (we find a perfect representation of our data, with no information loss)
- b. [2 points] True or False: The maximum margin decision boundaries that support vector machines construct have the lowest generalization error among all linear classifiers.
- c. [2 points] True or False: An individual observation  $x_i$  can occur multiple times in a single bootstrap sample from a dataset X, even if  $x_i$  only occurs once in X.
- d. [2 points] True or False: Suppose that the SVD of a square  $n \times n$  matrix X is  $USV^T$ , where S is a diagonal  $n \times n$  matrix. Then the rows of V are equal to the eigenvectors of  $X^TX$ .
- e. [2 points] True or False: Performing PCA to reduce the feature dimensionality and then applying the Lasso results in an interpretable linear model.
- f. [2 points] True or False: choosing k to minimize the k-means objective (see Equation (1) below) is a good way to find meaningful clusters.
- g. [2 points] Say you trained an SVM classifier with an RBF kernel  $(K(u, v) = \exp(\frac{-||u-v||_2^2}{2\sigma^2}))$ . It seems to under-fit the training set: should you increase or decrease  $\sigma$ ?

# Kernels and the Bootstrap

A2. [5 points] Suppose that our inputs x are one-dimensional and that our feature map is infinite-dimensional:  $\psi(x)$  is a vector whose i-th component is

$$\frac{1}{\sqrt{i!}}e^{\frac{-x^2}{2}}x^i$$

for all nonnegative integers i. (Thus,  $\psi$  is an infinite-dimensional vector.) Show that  $K(x, x') = e^{-1/2(x-x')^2}$  is a kernel function for this feature map, i.e.,  $\psi(x) \cdot \psi(x') = e^{-1/2(x-x')^2}$ . Hint:Use the Taylor expansion of e. (This is the one dimensional version of the Gaussian (RBF) kernel).

A3. This problem will get you familiar with kernel ridge regression using the polynomial and RBF kernels. First, let's generate some data. Let n=30 and  $f_*(x)=4\sin(\pi x)\cos(6\pi x^2)$ . For  $i=1,\ldots,n$  let each  $x_i$  be drawn uniformly at random on [0,1] and  $y_i=f_*(x_i)+i$  where  $i\approx \mathcal{N}(0,1)$ . For any function f, the true error and the train error are respectively defined as

$$\varepsilon_{\text{true}}(f) = E_{XY}[(f(X) - Y)^2]$$

$$\varepsilon_{\text{train}}(f) = \frac{1}{n} \sum_{i=1}^{n} = (f(x_i) - y_i)$$

Using kernel ridge regression, construct a predictor

$$\alpha = \underset{\alpha}{\operatorname{argmin}} ||K\alpha - y||^2 + \lambda \alpha^T K\alpha$$

$$\hat{f}(x) = n \sum_{i=1}^{k} \widehat{\alpha}_i k(x_i, x)$$

where  $K_{i,j} = k(x_i, x_j)$  is a kernel evaluation and  $\lambda$  is the regularization constant. Include any code you use for your experiments in your submission.

- a. [10 points] Using leave-one-out cross validation, find a good  $\lambda$  and hyperparameter settings for the following kernels:
  - (a)  $k_{poly}(x,z) = (1+x^Tz)^d$  where  $d \in \mathcal{N}$  is a hyperparameter,
  - (b)  $k_{rbf}(x,z) = \exp(-\gamma ||x-z||^2)$  where  $\gamma > 0$  is a hyperparameter,

Report the values of  $d,\gamma$ , and the  $\lambda$  values for both kernels.

For polynomial kernel I find optimal lambda: 0.56, degree: 16.0 sampled @ minimal error: 3.165 (log(Err)=1.152). For RBF kernel I find optimal 0.071, gamma: 10.85 sampled @ minimal error: 1.58 (log(Err)=0.4577).

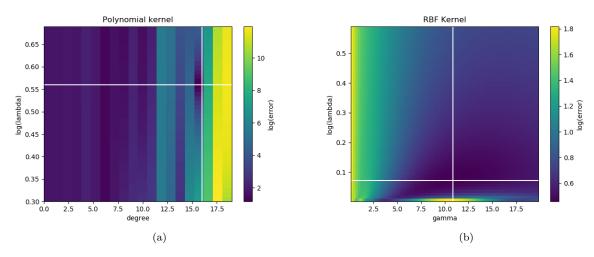


Figure 1: Cross validated error sampled at different pairs of regularization (y-axis) and hyper (x-axis) parameters. White cross marks the minimal sampled cross validation error.

b. [10 points] Let  $\widehat{f}_{poly}(x)$  and  $\widehat{f}_{rbf}(x)$  be the functions learned using the hyperparameters you found in part a. For a single plot per function  $\widehat{f} \in \{\widehat{f}_{poly}(x), \widehat{f}_{poly}(x)\}$ , plot the original data  $\{(x_i, y_i)\}_{i=1}^n$ , the true f(x), and  $\widehat{f}(x)$  (i.e., define a fine grid on [0, 1] to plot the functions).

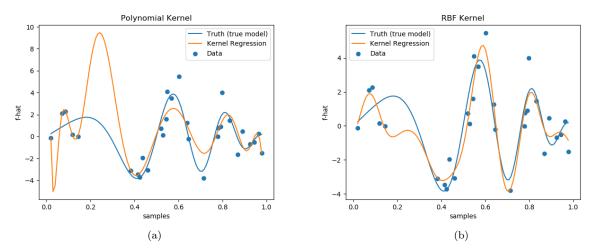


Figure 2: Kernels evaluated on [0,1] using the best fit values of regularization and hyper parameters.

c. [5 points] We wish to build bootstrap percentile confidence intervals for  $\widehat{f}_{\text{poly}}(x)$  and  $\widehat{f}_{\text{rbf}}(x)$  for all  $x \in [0,1]$  from part b. Use the non-parametric bootstrap with B = 300 bootstrap iterations to find 5% and 95% percentiles at each point x on a fine grid over [0,1].

Specifically, for each bootstrap sample  $b \in \{1, ..., B\}$ , draw uniformly at randomly with replacement n samples from  $\{(x_i, y_i)\}_{i=1}^n$ , train an  $\widehat{f}_n$  using the b-th resampled dataset, compute  $\widehat{f}_b(x)$  for each x in your fine grid; let the 5th percentile at point x be the largest value  $\nu$  such that  $B \sum_{b=1}^{B} \mathbf{1}\{\widehat{f}_b(x) \leq \nu\} leq.05$ , define the 95% analogously. Plot the 5 and 95 percentile curves on the plots from part b.

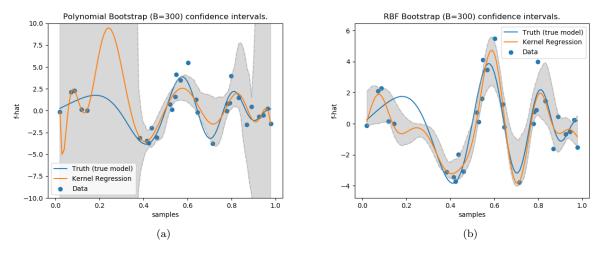


Figure 3: Bootstrapped 5th and 95th percentile confidence interval.

d. [5 points] Repeat parts a, b, and c with n = 300, but use 10-fold CV instead of leave-one-out for part a.

For polynomial kernel I find optimal lambda: 0.33, degree: 17.0 sampled @ minimal error: 1.059 (log(Err)=0.05697). For RBF kernel I find optimal lambda: 0.061, gamma: 6.1 sampled @ minimal error: 1.03 (log(Err)=0.02964). These numbers indicate that the RBF fits in a) are not the best because there are significant changes between the fitted parameters, but the ones for the polynomial fit seem to be stable.

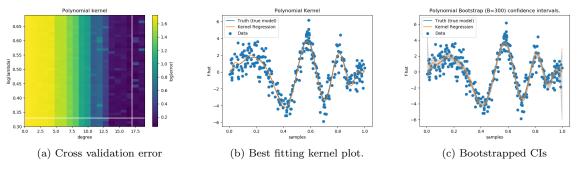


Figure 4: Part a-c using Polynomial kernel

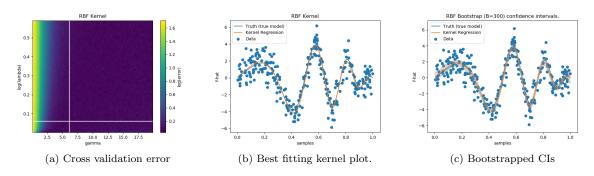


Figure 5: Part a-c using RBF kernel

e. [5 points] For this problem, use the  $\hat{f}_{\text{poly}}$  and  $\hat{f}_{\text{rbf}}$  learned in part d. Suppose m=1000 additional samples  $(x'_1, y'_1), \ldots, (x'_m, y'_m)$  are drawn i.i.d. the same way the first n samples were drawn. Use the non-parametric bootstrap with B=300 to construct a confidence interval on  $E[(Y-\hat{f}_{\text{poly}}(X))^2-(Y-\hat{f}_{\text{rbf}})^2]$  (i.e. randomly draw with replacement m samples denoted as  $\{(\tilde{x}'_i, \tilde{y}'_i)\}_{i=1}^m$  from  $\{(\tilde{x}'_i, \tilde{y}'_i)\}_{i=1}^m$  and compute

$$\frac{1}{m} \sum_{i=1}^{m} \left[ (\tilde{y}_i' - \hat{f}_{\text{poly}}(\tilde{x}_i'))^2 - (\tilde{y}_i' - \hat{f}_{\text{rbf}}(\tilde{x}_i'))^2 \right]$$

repeat this B times) and find 5% and 95% percentiles. Report these values. Using this confidence interval, is there statistically significant evidence to suggest that one of  $\hat{f}_{poly}$   $\hat{f}_{rbf}$  is better than the other at predicting Y from X? (Hint: does the confidence interval contain 0?)

I retrieve the 5th and 95th percentile interval of the given expression to be from 0.001955 to 0.023875. The interval does not contain zero, therefore we conclude we are 95% confident that there is a statistically significant evidence in favor of fitting with the RBF kernel.

The above plots and numbers were produced by the attached code. Note that the values of searched parameters were retrieved by manually scanning smaller and smaller intervals, using a finer and finer grid. This is generally considered bad (there are no guarantees that there are no other local minima accidentally "skipped" over during gridding). I froze the random seed at 0 so that I could at least compare the results with my colleagues.

```
import numpy as np
import matplotlib.pyplot as plt
import itertools
 import multiprocessing as mp
np.random.seed(0)
class Kernel:
    """Base class used to define a generic, actionless, kernel (KO) to use in
        ridge regression defined as:
       Attributes
       x: 'np.array', optional
Feature space.
y: 'np.array', optional
       Labels.
lambd: 'float', optional
       Regularization parameter
hyperparams: 'dict', optional
A dictionary of hyperparameters.
       alpha: 'dict'
Lerned predictor (learned weights).
       Fitting/training the kernel will update, replace, its features and labels
        with the ones given for training.
       Hyperparameters must be registered in the hyperparameters dictionary when
        inheriting.
       def __init__(self, x=None, y=None, lambd=None, **kwargs):
    self.update(x=x, y=y, lambd=lambd, **kwargs)
    self.alpha = None
       def update(self, **kwargs):
    """Update given class attributes (x, y, lambd, hyperparams)."""
    x = kwargs.pop("x", None)
    y = kwargs.pop("y", None)
    lambd = kwargs.pop("lambd", None)
    hyperparams = kwargs
              self._mean = None
self._std = None
              if x is not None:
                      self.x = x
              self.x = x
if y is not None:
    self.y = y
if lambd is not None:
    self.lambd = lambd
if len(hyperparams) != 0:
    self.hyperparams = hyperparams
       def eval(self, *args, **kwargs):
    """Defines kernel action, i.e. given an x_i, x_j evaluates the kernel.
Needs to be an vectorized operation, such that supplying two vectors
with dimensions n and m returns n-by-m matrix.
"""
               raise NotImplementedError
       def standardize(self, x, mean=None, std=None):
    """Returns a standardized copy of the array using the given weights.
"""
               if mean is None:
              if mean is None:
    self._mean = np.mean(x)
    mean = self._mean
if std is None:
    self._std = np.std(x)
    std = self._std
return (x-mean)/std
        \begin{array}{ll} \text{def fit(self, x, y):} \\ \text{"""Given features x and labels y, updates the class attributes and} \\ \text{preforms ridge regression. Stores the learned predictor in the alpha attribute.} \end{array} 
              Parameters
              x: 'np.array'
              .. up.array
Features to train on.
y: 'np.array'
Labels for corresponding features.
""
              self.update(x=x, y=y)
x = self.standardize(x)
K = self.eval(x, x)
self.alpha = np.linalg.solve(K + self.lambd * np.eye(len(K)), y)
       def predict(self, x):
    """Using learned weights and given features predicts the labels.
               Parameters
              x: 'np.array'
               Returns
              y: 'np.array'
Predicted labels
              Raises
```

```
AttributeError

When Kernel has not been trained and thus has no alpha attributed.

Call fit with the features and associated labels to train the
                  kernel.
            if self.alpha is None:
            if self.alpha is None:
    raise AttributeError("Kernel has not been trained.")
sx = self.standardize(self.x, self._mean, self._std)
xx = self.standardize(x, self._mean, self._std)
kernel = self.eval(sx, xx)
return np.dot(self.alpha, kernel)
      def score(self, x, y):
    """Predicts the labels of the given features and compares them to the
    given truth (true labels). Associates a score to the \"goodness\" of
    prediction.
            Parameters
            r: 'np.array'
Features for which labels will be predicted.
            y: 'np.array'
Truth, true labels for the corresponding features.
            Score: 'float'
Mean of the square of differences in predicitons, the score of the goodness of predictions.
"""
             return np.mean((self.predict(x) - y)**2)
class PolynomialKernel(Kernel):
    """Class implementing the polynomial kernel."""
      def __init__(self, lambd, degree, **kwargs):
    """Instantiate a polynomial kernel.
           lambd: 'float'
Regularization parameter
degree: 'int'
Degree of the polynomial
            super().__init__(lambd=lambd, degree=degree, **kwargs)
      @property
def d(self):
            return self.hyperparams["degree"]
      def eval(self, x, z):
    """Evaluate the kernel on given points. Kenrel action is defined as
                  K(x,z) = (1 + x*z)**d
            A column vector of features.

z: 'np.array'
A column vector of ''n'' points at which to evaluate the kernel.
            Returns
            An n-by-d matrix where each column is the kernel evaluated at a single point.
            return (1 + np.outer(x, z))**self.d
class RBFKernel(Kernel):
         "Class implementing the RBF kernel."""
      def __init__(self, lambd, gamma, **kwargs):
    """Instantiate an RBF kernel.
            Parameters
            lambd: 'float'
           Regularization parameter gamma: 'int'
Degree of the polynomial
            super().__init__(lambd=lambd, gamma=gamma, **kwargs)
      @property
def gamma(self):
    return self.hyperparams["gamma"]
      def eval(self, x, z):
    """Evaluate the kernel on given points. Kernel action is defined as
                  K(x,z) = \exp(-gamma*(x-z)^2)
            Parameters
            x: 'np.array'
A column vector of features.
            z: 'np.array'
A column vector of ''n'' points at which to evaluate the kernel.
            Returns
            eval: 'np.array'

An n-by-d matrix where each column is the kernel evaluated at a
                   single point.
```

```
return np.exp(-self.gamma * np.subtract.outer(x, z)**2)
class KernelFactory:
    """Kernel factory."""
       @staticmethod
       wstaticmethod
def create(kernelType, *args, **kwargs):
    """Given either ''poly'' or 'rbf'' kernel types and arguments returns
an instance of PolynomialKernel or RBFKernel.
             A string containing either ''poly'' or ''rbf'' targeting which kernel to isntantiate
              All other arguments are passed to the class instntiation call.
              if "poly" in kernelType.lower():
              return RolfynenialKernel(*args, **kwargs)
elif "rbf" in kernelType.lower():
    return RBFKernel(*args, **kwargs)
def truth(x):
    """The truth, the true model that we are trying to reconstruct. A function
             f(x) = 4*sin(pi*x) * cos(6*pi*x^2)
       Returns
      y: 'np.array'
Function values (i.e. labels in this context)
       return 4 * np.sin(np.pi * x) * np.cos(6 * np.pi * x**2)
def cross_validate(kernel, x, y, foldSize):
    """Performs cross validation of the kernel on the given dataset by randomly
    permuting the order of features, training on the fold-sized subsets of the
    total dataset {x_i, y_i} and then scoring the predictions of the trained
    kernel.
      kernel: 'object'
A Kernel subclass.
x: 'np.array'
Features
      y: 'np.array'
Labels
foldSize: 'int'
             The size of the selected subsets of data to train on
       meanScore: 'float'
The mean of all of the scores scored after training on random subsets.
       idxs = np.random.permutation(np.arange(0, n))
       if foldSize == 0:
              kernel.fit(x, y)
scores = np.array([kernel.score(x, y)])
              scores = np.zeros(foldSize)
              for i in range(foldSize):
lower = int(n/foldSize * i)
upper = int(n/foldSize * (i+1))
                   xPredict = x[idxs[lower:upper]]
yPredict = y[idxs[lower:upper]]
xFit = np.concatenate([x[idxs[0:lower]], x[idxs[upper:]]])
yFit = np.concatenate([y[idxs[0:lower]], y[idxs[upper:]]]))
                    kernel.fit(xFit, yFit)
scores[i] = kernel.score(xPredict, yPredict)
       return np.mean(scores)
def sampler(x, y, lambdas, hyperparams, foldSize, kernelType):
    """Preforms grid sampling of cross evaluated scores over all pairs of
    given lambdas and hyperparameters.
       Parameters
       x: 'np.array'
              Features
       rearures
y: 'mp.array'
Labels
lambdas: 'np.array'
Regularization parameters at which to preform cross validation.
       Regularization parameters at which so preson the supportance in array'
Hyperparameter values at which to preform cross validation.
foldSize: 'int'
Cross validation folding size.
       kernelType: 'str'
Which kernel type to use.
       Returns
```

```
samples: 'np.array'
A structured numpy array containing the cross validation error, log
                of regularization parameters and hyperparameter values at which the error was measured.

Fit: 'dict'
                A dictionary containing the minimal sampled cross validation error and
the values of lambda and hyperparameter at that error.
        """
Combinations = len(lambdas)*len(hyperparams)
dt = [("lambda", float), ("hyperparams", float), ("error", float)]
samples = np.zeros((nCombinations, ), dtype=dt)
        for i, (lambd, hparam) in enumerate(itertools.product(lambdas, hyperparams)):
    k = KernelFactory.create(kernelType, lambd, hparam)
    samples["error"][i] = cross_validate(k, x, y, foldSize)
    samples["lambd"][i] = lambd
    samples["hyperparams"][i] = hparam
        idxMinErr = np.where(samples['error'] == samples['error'].min())[0][0]
minErr = samples['error'][idxMinErr]
optimLanbda = samples['lanbda'][idxMinErr]
optimHParam = samples['hyperparams'][idxMinErr]
         print(f"Using {kernelType} with fold size={foldSize}: ")
         print(f" Optimal lambda: (optimLambda: .4), hyperparam: {optimHParam: .4} "
    f"sampled @ minimal error: {minErr: .4} (log(Err)={np.log(minErr): .4}).")
        Parameters
        fig: 'matplotlib.pyplot.Figure'
              Figure to which a colorbar will be attached.

'matplotlib.pyplot.Axes'

Axis on which to plot
         x: 'np.array'
        x: np.array
Features, a vector of length n
y: 'np.array'
Labels, a vector of length m
z: 'np.array'
       z: 'np.array'
An m*n lenght array of cross-validation errors.
bestFit: 'dict'
dictionary containing the minimal error, and the values of regularization and hyper-parameters at that point.
xlabel: 'str', optional
X axis label. Defaults to hyperparameter
ylabel: 'str', optional
Y axis label. Defaults to log(lambda)
cbarlbl: 'str', optional
Colorbar label. Defaults to log(error)
title: 'str', optional
Axis title. Defaults to "Kernel".
        ax: 'matplotlib.pyplot.Axes'
Modified axis containing the plot.
cbar: 'matplotlib.pyplot.Axes'
        cbar: 'matplotlib.pyplot.Axes'
Axis containing the colorbar.
         smpls = z.reshape(len(y), len(x))
        \label{eq:continuous} \begin{split} & \text{img = ax.imshow(smpls, interpolation=None, aspect="auto",} \\ & & \text{extent=}(x[0], \ x[-1], \ y[0], \ y[-1]), \ \text{origin="lower"}) \\ & \text{cbar = fig.colorbar(ing, ax=ax, orientation='vertical')} \\ & \text{ax.axvline(bestFit['hyperparam'], color="white")} \end{split}
         ax.axhline(bestFit['lambda'], color="white")
         cbar.set_label(cbarlbl)
         ax.set_xlabel(xlabel)
         ax.set_ylabel(ylabel)
ax.set_title(title)
def A3a(kernelType, x, y, foldSize, lambdas, hyperparams, xlabel="", title=""):
    """Samples the cross validation error on a grid for both polynomial and RBF
    kernels. Reports the minimal found error values and plots the errors.
        Kernel type (''poly'' or ''rbf'')
x: 'np.array'
                Features
        y: 'np.array'
Labels
foldSize: 'int'
        Cross validationsubset size
lambdas: 'np.array'
Regularization parameters at which to calculate cross validation error.
        Regularization parameters at which to calculate cross validation error. 
X axis label title: 'str'

X axis label title: 'str'
                Axis title
```

```
fig, axes = plt.subplots()
        plotA3a(fig, axes, hyperparams, lambdas, np.log(samples['error']), best, xlabel=xlabel, title=title)
def A3b(kernelType, x, y, bestFit, axis=None, title=None, xlabel="samples", ylabel="f-hat"):
    """Using best fit parameters plots the data, the truth (true model) and the
    best fitting kernel.
       KernelType: 'str'
Kernel type to use (''poly'' or ''rbf'')
x: 'np.array'
Features (train data set)
        y: 'np.array'
Labels (train data set)
bestFit: 'dict'
        A dictionary containing the minimal sampled cross validation e the values of lambda and hyperparameter at that error.

axis: 'matplotlib.pyplot.Axes'

Axis on which to plot, otherwise a new figure will be created.

title: 'str'

Title to use.

"""
                 A dictionary containing the minimal sampled cross validation error and
        kernel = KernelFactory.create(kernelType, bestFit['lambda'], bestFit['hyperparam'])
kernel.fit(x, y)
         if title is None:
title = ""
         if axis is None:
                 fig, axis = plt.subplots()
         # we need more evenly spaced arrays for plots, otherwise ugly
xTest = np.linspace(x.min(), x.max(), 100)
yHat = kernel.predict(xTest)
         axis.scatter(x, y, label="Data")
axis.plot(xTest, truth(xTest), label="Truth (true model)")
axis.plot(xTest, yHat, label="Kernel Regression")
         axis.set_title(title)
         axis.set_xlabel(xlabel)
axis.set_ylabel(ylabel)
axis.legend()
         return axis
def bootstrap(x, y, B, kernel):
    """Performs a non-parametric bootstrap on the given dataset. Selects,
    with replacement, a subset of given features and labels, trains a kernel
    and creates new predictions on a (min(x), max(x)) range. Returns all made
         predictions.
        x: 'np.array'
Features
        y: 'np.array
Labels
         B: 'int'
Number of bootstrap iterations.
         Returns
        predictions: 'np.array'

Array each element of which is a set of predictions on a min(x)-max(x)

range, i.e. each element are that bootstrap iterations predictions.

percentile5: 'np.array'

Array each element of which is the 5th percentile of corresponding

predictions element.

Array each element of which is the 95th percentile of corresponding

predictions element.
         n = len(x)
        xTest = np.linspace(x.min(), x.max(), 100)
predictions = np.zeros((B, len(xTest)))
         indices = np.arange(n)
         lndices = np.arange(n)
for i in range(B):
    idxs = np.random.choice(indices, size=n, replace=True)
    kernel.fit(x[idxs], y[idxs])
    predictions[i] = kernel.predict(xTest)
         return (predictions,
                         np.percentile(predictions, 5, axis=0, interpolation="lower"),
np.percentile(predictions, 95, axis=0, interpolation="higher"))
def A3c(kernelType, x, y, bestFit, B=300, title=""):
    """Bootstraps and estimates 5th and 95th percentile and then overplots it
    on data, true model and best fit estimate model.
         Parameters
         kernelType: 'str'
Kernel type (''poly'' or 'rbf')
        x: 'np.array
Features
       Features
y: 'np.array'
Labels
bestFit: 'dict'
A dictionary containing the minimal sampled cross validation error and
the values of lambda and hyperparameter at that error.
```

```
fig, ax = plt.subplots()
ax = A3b(kernelType, x, y, bestFit, axis=ax, title=title)
         kernel = KernelFactory.create(kernelType, bestFit['lambda'], bestFit['hyperparam'])
predictions, percentile5, percentile95 = bootstrap(x, y, B, kernel)
         xTest = np.linspace(x.min(), x.max(), 100)
        xtest = np.linspace(x.min(), x.max(), 100)
ax.fill_between(xTest, percentile5, percentile95, alpha=0.3, color="gray")
ax.plot(xTest, percentile95, color="darkgray", ls="--", alpha=0.5)
ax.plot(xTest, percentile5, color="darkgray", ls="--", alpha=0.5)
ax.set_ylim((y.min()-1, y.max()+1))
def A3e(bestPoly, bestRbf, n=1000, B=300):
    """Using the given kernel parameters fits olynomial and RBF kernels to
    the data, created according to the same truth, and calculates the mean
    difference of the squared errors of the kernels predictions via
    non-parametric bootstrap approach.
         Prints the 5th and 95th percentile of the confidence interval squared
         errors differences.
        DestPoly: 'dict'

A dictionary containing the minimal sampled cross validation error and the values of lambda and hyperparameter at that error. bestRbf: 'dict'
         A dictionary containing the minimal sampled cross validation error and the values of lambda and hyperparameter at that error.

1. 'int', optional

Number of newly generated data points, default: 1000.
        Number of newly generated data points, defaul
B: 'int', optional
number of bootstrap iterations, default: 300.
         x = np.random.uniform(size=n)
         y = truth(x) + np.random.normal(size=n)
         poly = KernelFactory.create("poly", bestPoly['lambda'], bestPoly['hyperparam'])
rbf = KernelFactory.create("rbf", bestRbf['lambda'], bestRbf['hyperparam'])
         poly.fit(x, y)
rbf.fit(x, y)
         sqErr = []
indices = np.arange(n)
for i in range(B):
   idxs = np.random.choice(indices, size=n, replace=True)
                 predictPoly = poly.predict(x[idxs])
predictRbf = rbf.predict(x[idxs])
sqErr.append( np.mean((y[idxs]-predictPoly)**2 - (y[idxs]-predictRbf)**2) )
         percentile5 = np.percentile(sqErr, 5, axis=0, interpolation="lower")
percentile95 = np.percentile(sqErr, 95, axis=0, interpolation="higher")
         print(f"Confidence interval difference: {percentile5} to {percentile95}")
 def A3(n=30, foldSize=30, doPoly=True, doRBF=True, doA3e=False):
        ASIN=30, Toldsize=30, dopoly=irue, dokbr=irue, dokse=alse):
"""Problem A3 from a-d: creates data and labels based on truth and adds
gaussian noise, performs a grid search for best regularization and
hyperparameter values by minimizing the cross validation error, plots the
fits, uses reported values to fit kernels accross the range of the given
data, plots the kernel basis functions, the best fit kernels and boostraps
5th and 95th percentile confidence intervals over the data range.
         Parameters
        """

"""

"int', optional
Number of data points to create, default: 30.
foldSize: 'int', optional
Cross validation set size, default: 30.
doPoly: 'bool', optional
Use polynomial kernel, default: True.
doRBF: 'bool', optional
Use RBF kernel, default: True.
"""
         x = np.random.uniform(size=n)
y = truth(x) + np.random.normal(size=n)
         if doPoly:
                lambdas = np.arange(0.001, 0.6, 0.01)
                if doA3e:
                A3e(bestPoly, bestRdf)
         plt.show()
 def A3parallel(nprocs=None):
    """Runs A3 with 30 and 300 data points and 30 and 10 cross validation
    folding size in a parallel manner to amortize the total serial execution
         args = [(30, 30, True, False), (30, 30, False, True), (300, 10, True, False), (300, 10, False, True),
```

```
(300, 10, True, True, True)

]
nprocs = len(args) if nprocs is None else nprocs
with mp.Pool(nprocs) as p:
p.starmap(A3, args)

if __name__ == "__main__":
A3parallel()
```

## k-means clustering

A4. Given a dataset  $x_1, \ldots, x_n \in \mathbb{R}^d$  and an integer  $1 \le k \le n$ , recall the following k-means objective function

$$\min_{p_{i_1,\dots,\pi_k}} \sum_{i=1}^k \sum_{j \in \pi_i} ||x_j - \mu_i||_2^2$$

$$\mu_i = \frac{1}{\pi_i} \sum_{j \in \pi_i} x_j$$

Above,  $\{\pi_i\}_{i=1}^k$  is a partition of  $\{1, 2, \dots, n\}$ . The objective is NP-hard to find a global minimizer of. Nevertheless Lloyd's algorithm, the commonly-used heuristic which we discussed in lecture, typically works well in practice.

- a. [5 points] Implement Lloyd's algorithm for solving the k-means objective. Do not use any off-the-shelf implementations, such as those found in scikit-learn. Include your code in your submission.
- b. [5 points] Run the algorithm on the training dataset of MNIST with k=10, plotting the objective function as a function of the iteration number. Visualize (and include in your report) the cluster centers as  $a28 \times 28$  image.
- c. [5 points] For  $k = \{2, 4, 8, 16, 32, 64\}$  run the algorithm on the training dataset to obtain centers  $\{\mu_i\}_{i=1}^k$ . If  $\{(x_i, y_i)\}_{i=1}^n$  and  $\{(x_i', y_i')\}_{i=1}^m$  denote the training and test sets, respectively, plot the training error  $\frac{1}{n} \sum_{i=1}^n \min_{j=1,\dots,k} ||\mu_j x_i||_2^2$  and test error  $\frac{1}{m} \sum_{i=1}^m \min_{j=1,\dots,k} ||\mu_j x_i'||_2^2$  as a function of k on the same plot.

### Neural Networks for MNIST

A5. In Homework 1, we used ridge regression for training a classifier for the MNIST data set. Students who did problem B.2 also used a random feature transform. In Homework 2, we used logistic regression to distinguish between the digits 2 and 7. Students who did problem B.4 extended this idea to multinomial logistic regression to distinguish between all 10 digits. In this problem, we will use PyTorch to build a simple neural network classifier for MNIST to further improve our accuracy. We will implement two different architectures: a shallow but wide network, and a narrow but deeper network. For both architectures, we used to refer to the number of input features (in MNIST,  $d = 28^2 = 784$ ),  $h_i$  to refer to the dimension of the *i*-th hidden layer and k for the number of target classes (in MNIST, k = 10). For the non-linear activation, use ReLU. Recall from lecture that

$$ReLU(x) = \begin{cases} x & \text{if } x \ge 0\\ 0 & \text{if } x < 0 \end{cases}$$

#### Weight Initialization

Consider a weight matrix  $W \in \mathbb{R}^{n \times m}$  and  $b \in \mathbb{R}^n$ . Note that here m refers to the input dimension and n to the output dimension of the transformation Wx + b. Define  $\alpha = 1/\sqrt{m}$ . Initialize all your weight matrices and biases according to  $Unif(-\alpha, \alpha)$ .

### Training

For this assignment, use the Adam optimizer from torch.optim. Adam is a more advanced form of gradient descent that combines momentum and learning rate scaling. It often converges faster than regular gradient descent. You can use either Gradient Descent or any form of Stochastic Gradient Descent. Note that you are still using Adam, but might pass either the full data, a single datapoint or a batch of data to it. Use cross entropy for the loss function and ReLU for the non-linearity.

#### Implementing the Neural Networks

a. [10 points] Let  $W_0 \in \mathbb{R}^{h \times d}$ ,  $b_0 \in \mathbb{R}^h$ ,  $W_1 \in \mathbb{R}^{k \times h}$ ,  $b_1 \in \mathbb{R}^k$  and  $\sigma(z) : \mathbb{R} \to \mathbb{R}$  some non-linear activation function. Given some  $x \in \mathbb{R}^d$ , the forward pass of the wide, shallow network can be formulated as:

$$\mathbb{F}_1(x) = W_1 \sigma(W_0 x + b_0) + b + 1$$

Use h = 64 for the number of hidden units and choose an appropriate learning rate. Train the network until it reaches 99% accuracy on the training data and provide a training plot (loss vs. epoch). Finally evaluate the model on the test data and report both the accuracy and the loss.

b. [10 points] Let  $W_0 \in \mathbb{R}^{h_0 \times d}$ ,  $b_0 \in \mathbb{R}^{h_0}$ ,  $W_1 \in \mathbb{R}^{h_1 \times h_0}$ ,  $b_1 \in \mathbb{R}^{h_1}$ ,  $W_2 \in \mathbb{R}^{k \times h_2}$ ,  $b_2 \in \mathbb{R}^k$  and  $\sigma(z) : \mathbb{R} \to \mathbb{R}$  some non-linear activation function. Given some  $x \in \mathbb{R}^d$ , the forward pass of the network can be formulated as:

$$\mathbb{F}_2(x) = W_2 \sigma(W_1 \sigma(W_0 x + b_0) + b_1) + b_2$$

Use  $h_0 = h_1 = 32$  and perform the same steps as in part a.

c. [5 points] Compute the total number of parameters of each network and report them. Then compare the number of parameters as well as the test accuracies the networks achieved. Is one of the approaches (wide, shallow vs narrow, deeper) better than the other? Give an intuition for why or why not.

### **PCA**

Let's do PCA on MNIST dataset and reconstruct the digits in the dimensionality-reduced PCA basis. You will actually compute your PCA basis using the training dataset only, and evaluate the quality of the basis on the test set, similar to the k-means reconstructions of above. Because 50,000 training examples are size  $28 \times 28$  so begin by flattening each example to a vector to obtain  $X_{\text{train}} \in \mathbb{R}^{50,000 \times d}$  and  $X_{\text{test}} \in \mathbb{R}^{10,000 \times d}$  for d := 784 A6. Let  $\mu \in \mathbb{R}^d$  denote the average of the training examples in  $X_{\text{train}}$ , i.e.,  $\mu = \frac{1}{d}X_{\text{train}}^T$ . Now let  $\sum (X_{\text{train}} - \mathbf{1}\mu^T)^T (X_{\text{train}} - \mathbf{1}\mu^T)/50000$  denote the sample covariance matrix of the training examples, and let  $\sum = UDU^T$  denote the eigenvalue decomposition of  $\sum$ 

- a. [2 points] If  $\lambda_i$  denotes the i-th largest eigenvalue of  $\sum$ , what are the eigenvalues  $\lambda_1, \lambda_2, \lambda_{10}, \lambda_{30}$ , and  $\lambda_{50}$ ? What is the sum of eigenvalues  $\sum_{i=1}^{d} \lambda_i$ ?
- b. [5 points] Any example  $x \in \mathbb{R}^d$  (including those from either the training or test set) can be approximated using just  $\mu$  and the first k eigenvalue, eigenvector pairs, for any k = 1, 2, ..., d. For any k, provide a formula for computing this approximation.
- c. [5 points] Using this approximation, plot the reconstruction error from k = 1 to 100 (the X-axis is k and the Y-axis is the mean-squared error reconstruction error) on the training set and the test set (using the  $\mu$  and the basis learned from the training set). On a separate plot, plot

$$1 - \frac{\sum_{i=1}^{k} \lambda_i}{\sum_{i=1}^{d} \lambda_i}$$

from k = 1 to 100.

- d. [3 points] Now let us get a sense of what the top PCA directions are capturing. Display the first 10 eigenvectors as images, and provide a brief interpretation of what you think they capture.
- e. [3 points] Finally, visualize a set of reconstructed digits from the training set for different values of k. In particular provide the reconstructions for digits 2,6,7 with values k = 5, 15, 40, 100 (just choose an image from each digit arbitrarily). Show the original image side-by-side with its reconstruction. Provide a brief interpretation, in terms of your perceptions of the quality of these reconstructions and the dimensionality you used.