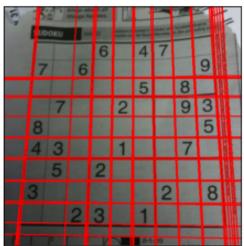
```
In [ ]: import numpy as np
   import matplotlib.pyplot as plt
   import cv2 as cv
   %matplotlib inline
```

```
In [ ]: | #1
         sudukoimage=cv.imread(r'sudoku.png',cv.IMREAD_COLOR)
         assert sudukoimage is not None
         gray=cv.cvtColor(sudukoimage,cv.COLOR_BGR2GRAY)
         edges=cv.Canny(gray,50,150,apertureSize=3)
         lines=cv.HoughLines(edges,1,np.pi/180,175)
         for line in lines:
             rho,theta=line[0]
             a=np.cos(theta)
             b=np.sin(theta)
             x0,y0=a*rho,b*rho
             x1,y1=int(x0+1000*(-b)),int(y0+1000*a)
             x2,y2=int(x0-1000*(-b)),int(y0-1000*a)
             cv.line(sudukoimage,(x1,y1),(x2,y2),(0,0,255),2)
         cv.namedWindow("Image",cv.WINDOW_NORMAL)
         cv.imshow("Image",gray)
         cv.waitKey(0)
         cv.imshow("Image",edges)
         cv.waitKey(0)
         cv.imshow("Image", sudukoimage)
         cv.waitKey(0)
         cv.destroyAllWindows()
         plt.imshow(cv.cvtColor(gray,cv.COLOR_BGR2RGB))
         plt.xticks([]),plt.yticks([])
         plt.show()
         plt.imshow(cv.cvtColor(edges,cv.COLOR_BGR2RGB))
         plt.xticks([]),plt.yticks([])
         plt.imshow(cv.cvtColor(sudukoimage,cv.COLOR_BGR2RGB))
         plt.xticks([]),plt.yticks([])
         plt.show()
```





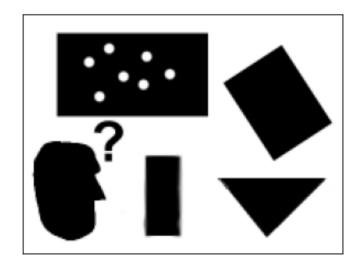


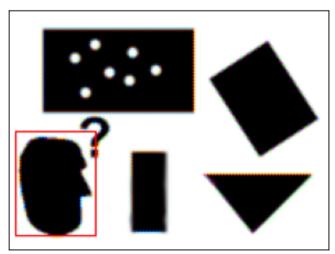
```
In [ ]:
        coinsimage=cv.imread(r'coins.jpg',cv.IMREAD_COLOR)
        assert coinsimage is not None
        gray=cv.cvtColor(coinsimage,cv.COLOR_BGR2GRAY)
        circles=cv.HoughCircles(gray,cv.HOUGH_GRADIENT,1,50,param1=150,param2=20,
        circles=np.uint16(np.around(circles))
        for i in circles[0,:]:
            cv.circle(coinsimage,(i[0],i[1]),i[2],(0,255,0),2)
            cv.circle(coinsimage,(i[0],i[1]),2,(0,0,255),3)
        #cv.namedWindow("Image",cv.WINDOW_NORMAL)
        cv.imshow("Detected circles",coinsimage)
        cv.waitKey(0)
        cv.destroyAllWindows()
        plt.imshow(cv.cvtColor(coinsimage,cv.COLOR_BGR2RGB))
        plt.xticks([]),plt.yticks([])
        plt.show()
```



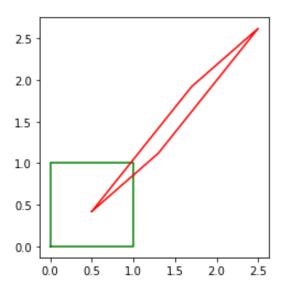
```
In [ ]:
                    #3
                    im = cv.imread(r'pic1.png', cv.IMREAD_REDUCED_GRAYSCALE_2)
                    temp1 = cv.imread(r'templ.png', cv.IMREAD REDUCED GRAYSCALE 2)
                    assert im is not None
                    assert temp1 is not None
                    im_edges = cv.Canny(im,50,250)
                    temp1_edges = cv.Canny(temp1,50,250)
                    alg = cv.createGeneralizedHoughGuil()
                    alg.setTemplate(temp1_edges)
                    alg.setAngleThresh(100000)
                    alg.setScaleThresh(40000)
                    alg.setPosThresh(1000)
                    alg.setAngleStep(1)
                    alg.setScaleStep(0.1)
                    alg.setMinScale(0.9)
                    alg.setMaxScale(1.1)
                    positions, votes = alg.detect(im_edges)
                    out = cv.cvtColor(im,cv.COLOR_BAYER_BG2BGR)
                    for x,y,scale,orientation in positions[0]:
                              halfHeight = temp1.shape[0]/ 2.* scale
                              halfWidth = temp1.shape[1]/ 2.* scale
                              p1 = (int(x - halfWidth),int(y - halfHeight))
                              p2 = (int(x + halfWidth), int(y + halfHeight))
                              print("x = {}, y= {},scale = {},orientation = {}, p1 = {}, p2 = {}".
                              cv.rectangle(out,p1,p2,(0,0,255))
                    cv.namedWindow("Image",cv.WINDOW_NORMAL)
                    cv.imshow("Image",im)
                    cv.waitKey(0)
                    cv.imshow("Image",out)
                    cv.waitKey(0)
                    cv.destroyAllWindows()
                    plt.imshow(cv.cvtColor(im,cv.COLOR_BGR2RGB))
                    plt.xticks([]),plt.yticks([])
                    plt.imshow(cv.cvtColor(out,cv.COLOR_BGR2RGB))
                    plt.xticks([]),plt.yticks([])
                    plt.show()
                    x = 29.0, y = 109.0, scale = 1.0, rightarrow or initial value of <math>x = 29.0, y = 109.0, y = 109.0
```

4, 141)





```
In [ ]: |#4
         a,b,c,d,=[0,0,1],[0,1,1],[1,1,1],[1,0,1]
         X=np.array([a,b,c,d]).T
         theta=np.pi*30/180
         s=1
         tx, ty=0.5, 0.42
         #H=np.array([[s*np.cos(theta),-s*np.sin(theta),tx],[s*np.sin(theta),s*np.
         #Y=H@X
         a11, a12, a21, a22=0.8, 1.2, 0.7, 1.5
         A=np.array([[a11,a12,tx],[a21,a22,ty],[0,0,1]])
         Y=A@X
         x=np.append(X[0,:],X[0,0])
         y=np.append(X[1,:],X[1,0])
         fig,ax=plt.subplots()
         ax.plot(x,y,color='g')
         ax.set_aspect('equal')
         x=np.append(Y[0,:],Y[0,0])
         y=np.append(Y[1,:],Y[1,0])
         ax.plot(x,y,color='r')
         ax.set_aspect('equal')
         plt.show()
```



```
#5
In [ ]:
        im1=cv.imread(r'D:\4th sem uom\machine vision\coding\ex6\graftar\img1.ppm
        im4=cv.imread(r'D:\4th sem uom\machine vision\coding\ex6\graftar\img4.ppm
        H=np.array([6.6378505e-01, 6.8003334e-01, -3.1230335e+01],
        [-1.4495500e-01,9.7128304e-01,1.4877420e+02],
        [4.2518504e-04,-1.3930359e-05,1.0000000e+00]])
        im1to4=cv.warpPerspective(im4,np.linalg.inv(H),(2000,2000))
        cv.namedWindow('Image 1',cv.WINDOW_AUTOSIZE)
        cv.imshow('Image 1',im1)
        cv.waitKey(0)
        cv.namedWindow('Image 2',cv.WINDOW_AUTOSIZE)
        cv.imshow('Image 2',im4)
        cv.waitKey(0)
        cv.namedWindow('Image 3',cv.WINDOW_AUTOSIZE)
        cv.imshow('Image 3',im1to4)
        cv.waitKey(0)
        cv.destroyAllWindows()
        plt.imshow(cv.cvtColor(im1,cv.COLOR_BGR2RGB))
        plt.xticks([]),plt.yticks([])
        plt.show()
        plt.imshow(cv.cvtColor(im4,cv.COLOR_BGR2RGB))
        plt.xticks([]),plt.yticks([])
        plt.show()
        plt.imshow(cv.cvtColor(im1to4,cv.COLOR_BGR2RGB))
        plt.xticks([]),plt.yticks([])
        plt.show()
```





