



IASD 2023/24 Project Assignment #2: Autonomous shared vehicle transportation system

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1 Introduction

The project for this assignment remains the same. The system receives as input a set of transportation requests from users, and schedules a fleet of autonomous vehicles to drive users from their pickup points to the desired destinations. Each vehicle has a pre-defined amount of seats. The goal is to maximize efficiency in passenger transportation.

2 Second Assignment and Deliverable

This assignment is a followup of the Assignment #1, where the problem was properly formalized. This second assignment aims at obtaining optimal solutions to the problem using uninformed search methods.

Associated with the IASD course book, there is a Python code repository with many Python files for the different chapters of the book¹. In the repository you have the file search.py where you can find the definition of the class Problem, the superclass of the class FleetProblem, examples for other problems, and the functions that implement each one of the search algorithms mentioned in the IASD lectures. For this assignment, you only need to import search.py, which in turn imports utils.py. Both files are available in the repository. Copy both files to your work directory while developing and testing on your computer. Nothing else is needed.

The Python program to be delivered should be called solution.py and include (at least) a class with name FleetProblem containing (at least) the following methods (see Annex A for the class template):

result(state, action) returns the state that results from executing the given action in the given state.

actions (state) returns the list of actions that can be executed in the given state.

goal_test(state) returns True if the given state is a goal.

load(fh) loads a problem from an opened file object fh (same as in Assignment #1)

solve() calls an uninformed search algorithm from search.py to solve the problem; this function should return a plan in the same format as defined in Assignment #1, i.e., a list of tuples representing actions.

In order to solve a problem one needs to:

- read the problem from a file object like you did for Assignment #1,
- decide and implement a representation for the state of the problem. You may change the representation used for Assignment #1 if you find a better one, and represent the initial state with that representation, and saved in the object FleetProblem (self.initial),
- (re)implement the methods result, actions, goal_test, and solve as specified above,
- choose one uninformed search algorithm that the group considers best fits the problem at hand, and use it in method solve. See search.py for the set of uninformed search algorithms available.

¹The link for the repository is https://github.com/aimacode/aima-python.

3 Evaluation

The deliverable for this assignment is shown through DEEC Moodle, with the submission of a single python file, called solution.py, implementing the modules mentioned above. Instructions for this platform are available on the course webpage. Finally, the grade is computed in the following way:

- 50% from the public tests;
- 50% from the private tests; and
- -10% from the code structure, quality and readability.

Deadline: 13-October-2023.

Projects submitted after the deadline will not be considered for evaluation.

Closing Remarks on Ethics:

- Any kind of sharing code outside your group is considered plagiarism;
- Developing your code in any open software development tool is considered sharing code;
- You can use GitHub. Make sure you have private projects and remove them afterward;
- If you get caught in any plagiarism, either by copying the code/ideas or sharing them with others, you will not be graded; and
- The scripts and other supporting materials produced by the instructors cannot be made public!

A Class Template

```
import search
""" For this assignment, you just need to import search.py,
which in turn imports utils.py; both files are available
in the repository mentioned on page 2 of the Assignment"""

class FleetProblem(search.Problem):

    def result(self, state, action):
        """Return the state that results from executing
        the given action in the given state."""
        pass
```