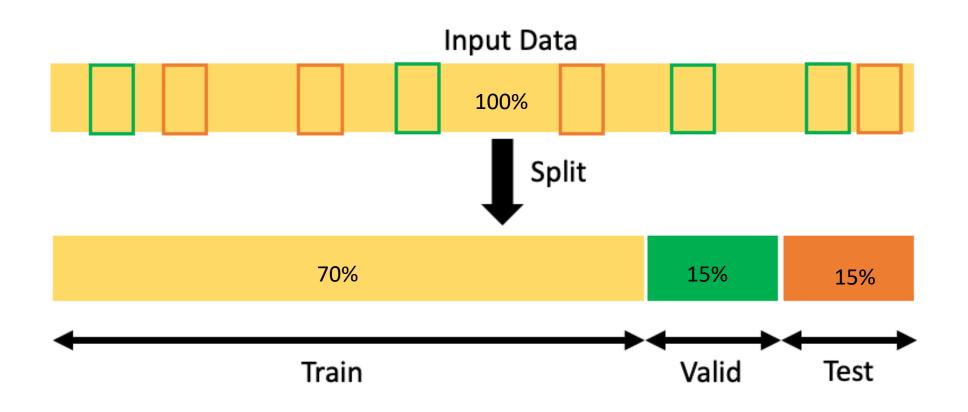
Today, Agenda!



- 1. Dataset splitting
- 2. Overfit and underfit concepts
- 3. Gradient descent
- 4. R2 Value
- 5. Concept of multi-variable LR

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Splitting Dataset



Splitting a dataset generally refers to the process of dividing the data into separate subsets for training, validation, and testing during the development of a predictive model. This is a critical practice in machine learning and statistics to evaluate the performance of models. Here's what each subset is used for:

- 1. Training Set: This subset is used to train the model, meaning that the model learns the patterns from this data. Typically, the training set is the largest portion of the data.
- 2. Validation Set: After the model is trained, you use this subset to tune the model's hyperparameters. The validation set is used to evaluate the model's performance during the training process and to prevent overfitting. It acts as a proxy for the test set during this tuning phase.
- 3. Test Set: This subset is used to evaluate the final model's performance after it has been trained and validated. The test set is crucial because it is used to estimate how well the model is expected to perform on unseen data. It should only be used once for this purpose to avoid biasing the model's performance metrics.

The Common starting point is 70% for training, 15% for validation, and 15% for testing, or 80% for training and 20% for testing if a separate validation set is not used.

Overfitting and Underfitting





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Overfitting and Underfitting

Overview



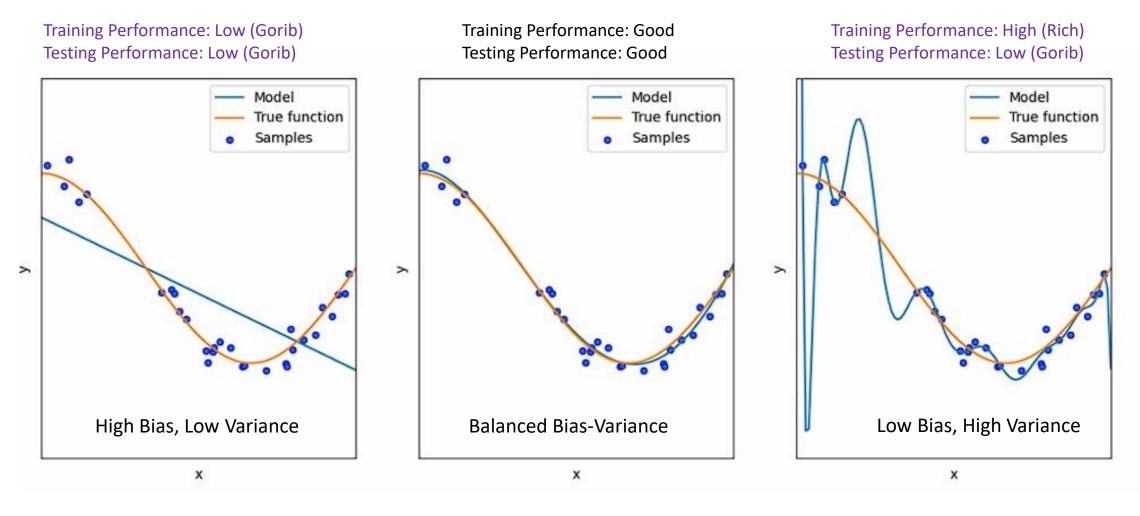


Fig 01: Underfitting Fig 02: Best fitting Fig 03: Overfitting

Overfitting and Underfitting Why?



There are several reasons why a model might get overfitted, and it's helpful to understand the specifics of the situation to give you the most accurate answer. However, I can share some general causes and solutions:

- Limited training data: When you don't have enough data, the model can't learn the underlying patterns well enough to generalize to unseen data.
- Model complexity: Models with too many parameters or layers can easily overfit, memorizing specific details in the training data instead of learning generalizable rules.
- Training for too long: Overtraining makes the model focus on irrelevant details and noise in the training data, which leads to poor performance on new data.
- Noisy data: Data with errors or inconsistencies can mislead the model and cause overfitting.
- Inappropriate features: Using irrelevant or redundant features can increase the model's complexity and contribute to overfitting.

Overfitting and Underfitting

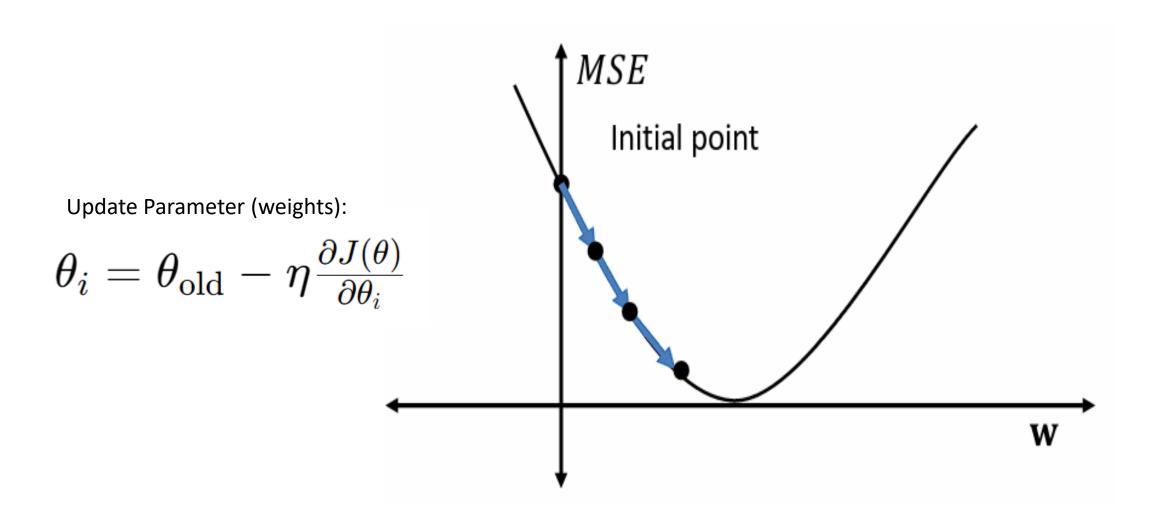
Solution?



- Increase the training data size: Collect more data or use data augmentation techniques to create more samples from your existing data.
- Simplify the model: Reduce the number of parameters, layers, or features in your model.
- Use regularization techniques: L1 and L2 regularization penalize complex models, forcing them to learn simpler patterns.
- Early stopping: Stop training the model before it starts to overfit by monitoring its performance on a validation set.
- Data cleaning and preprocessing: Correct errors and inconsistencies in your data to avoid misleading the model.
- Feature selection: Choose only the most relevant features for your model to reduce complexity.



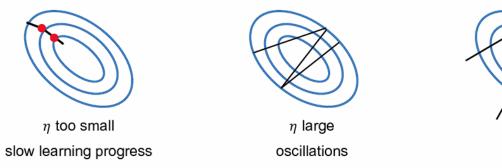




Overview



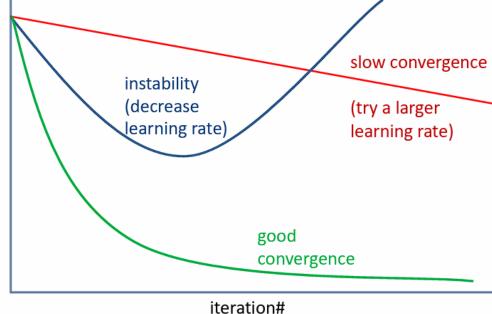
The speed of the local/global minimum is affected from the learning rate.



 η too large instability

MSE

The training curve could be used to monitor the effect of the learning rate value and observe the convergence. We plot the training loss against the number of training iterations.



Overview



The update rule for each parameter θ_i (where i indexes the parameters) in gradient descent can be represented as:

$$heta_i = heta_i - lpha rac{\partial J(heta)}{\partial heta_i} \left/
ight. \; heta_i = heta_{
m old} - \eta rac{\partial J(heta)}{\partial heta_i}$$

Where:

- ullet lpha is the learning rate, a hyperparameter that controls the size of the steps taken during optimization.
- $J(\theta)$ is the cost function.
- $\frac{\partial J(\theta)}{\partial \theta_i}$ is the partial derivative of the cost function with respect to θ_i , which gives the gradient of the cost function with respect to that parameter.

Gradient descent continues to update the parameters until convergence, where the algorithm finds parameter values that minimize the cost function.

Mathematics



The Mean Squared Error (MSE) is calculated as the squared difference between the actual values ($y^{(i)}$) and the predicted values ($h_{\theta}(x^{(i)})$):

$$ext{MSE} = rac{1}{m} \sum_{i=1}^m (h_{ heta}(x^{(i)}) - y^{(i)})^2$$

1. Mean Squared Error (MSE):

- MSE quantifies the average of the squared differences between predicted values and actual values across the dataset.
- The formula is expressed as: $ext{MSE} = rac{1}{n} \sum_{i=0}^n (y_i \hat{y}_i)^2$, where:
 - ullet y_i represents the actual value from the dataset.
 - \hat{y}_i denotes the predicted value by the model.
 - ullet n signifies the total number of data points.

2. Substitution of \hat{y}_i with mx_i+c :

- In linear regression, predictions (\hat{y}_i) can be computed using the equation of a straight line, y=mx+c.
- ullet Here, m denotes the slope of the line, x_i is the input feature value, and c represents the y-intercept.

3. Revised MSE Formula:

 ullet After replacing \hat{y}_i with the linear equation mx_i+c , the MSE is recalculated as:

• MSE =
$$\frac{1}{n} \sum_{i=0}^{n} (y_i - (mx_i + c))^2$$

 ullet This adjusted formulation is utilized to evaluate the performance of a linear regression model, aiming to minimize the MSE by identifying optimal values for m and c through model training.

Mathematics

Algorithm



Step: 01

Gradient (m) = 0 Intercept (c) = 0 Learning Rate (L) = \sim 0.001 Step: 02

Calculate the partial derivative of the Cost function with respect to m. Let the partial derivative of the Cost function with respect to m be Dm.

$$D_{m} = \frac{\partial (Cost Function)}{\partial m} = \frac{\partial}{\partial m} \left(\frac{1}{n} \sum_{i=0}^{n} (y_{i} - y_{i pred})^{2} \right)$$

$$= \frac{1}{n} \frac{\partial}{\partial m} \left(\sum_{i=0}^{n} (y_{i} - (mx_{i} + c))^{2} \right)$$

$$= \frac{1}{n} \frac{\partial}{\partial m} \left(\sum_{i=0}^{n} (y_{i}^{2} + m^{2}x_{i}^{2} + c^{2} + 2mx_{i}c - 2y_{i}mx_{i} - 2y_{i}c) \right)$$

$$= \frac{-2}{n} \sum_{i=0}^{n} x_{i} (y_{i} - (mx_{i} + c))$$

$$= \frac{-2}{n} \sum_{i=0}^{n} x_{i} (y_{i} - y_{i pred})$$

Algorithm



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Step: 03

Similarly, let's find the partial derivative with respect to c. Let the partial derivative of the Cost function with respect to c be Dc.

$$D_{c} = \frac{\partial(Cost Function)}{\partial c} = \frac{\partial}{\partial c} \left(\frac{1}{n} \sum_{i=0}^{n} (y_{i} - y_{i pred})^{2} \right)$$

$$= \frac{1}{n} \frac{\partial}{\partial c} \left(\sum_{i=0}^{n} (y_{i} - (mx_{i} + c))^{2} \right)$$

$$= \frac{1}{n} \frac{\partial}{\partial c} \left(\sum_{i=0}^{n} (y_{i}^{2} + m^{2}x_{i}^{2} + c^{2} + 2mx_{i}c - 2y_{i}mx_{i} - 2y_{i}c) \right)$$

$$= \frac{-2}{n} \sum_{i=0}^{n} (y_{i} - (mx_{i} + c))$$

$$\frac{-2}{n} \sum_{i=0}^{n} (y_{i} - y_{i pred})$$

Calculus



Derivative	Integral (Antiderivative)
$\frac{d}{dx}n=0$	$\int 0 dx = C$
$\frac{d}{dx}x = 1$	$\int 1 dx = x + C$
$\frac{d}{dx}x^n=nx^{n-1}$	$\int x^n dx = \frac{x^{n+1}}{n+1} + C$
$\frac{d}{dx}e^{x}=e^{x}$	$\int \mathbf{e}^{x} dx = \mathbf{e}^{x} + C$
$\frac{d}{dx}\ln x = \frac{1}{x}$	$\int \frac{1}{x} dx = \ln x + C$
$\frac{d}{dx}n^x = n^x \ln x$	$\int n^x dx = \frac{n^x}{\ln n} + C$
$\frac{d}{dx}\sin x = \cos x$	$\int \cos x \ dx = \sin x + C$
$\frac{d}{dx}\cos x = -\sin x$	$\int \sin x \ dx = -\cos x + C$

$\frac{d}{dx}\tan x = \sec^2 x$	$\int \sec^2 x \ dx = \tan x + C$
$\frac{d}{dx}\cot x = -\csc^2 x$	$\int \csc^2 x \ dx = -\cot x + C$
$\frac{d}{dx}\sec x = \sec x \tan x$	$\int \tan x \sec x \ dx = \sec x + C$
$\frac{d}{dx}\csc x = -\csc x \cot x$	$\int \cot x \csc x \ dx = -\csc x + C$
$\frac{d}{dx}\arcsin x = \frac{1}{\sqrt{1-x^2}}$	$\int \frac{1}{\sqrt{1-x^2}} dx = \arcsin x + C$
$\frac{d}{dx}\arccos x = -\frac{1}{\sqrt{1-x^2}}$	$\int -\frac{1}{\sqrt{1-x^2}} dx = \arccos x + C$
$\frac{d}{dx}\arctan x = \frac{1}{1+x^2}$	$\int \frac{1}{1+x^2} dx = \arctan x + C$
$\frac{d}{dx} \operatorname{arc} \cot x = -\frac{1}{1+x^2}$	$\int -\frac{1}{1+x^2} dx = \operatorname{arc} \cot x + C$
$\frac{d}{dx} \arccos x = \frac{1}{x\sqrt{x^2 - 1}}$	$\int \frac{1}{x\sqrt{x^2 - 1}} dx = arc \sec x + C$
$\frac{d}{dx} \arccos x = -\frac{1}{x\sqrt{x^2 - 1}}$	$\int -\frac{1}{x\sqrt{x^2-1}} dx = arc \csc x + C$

Algorithm



Step: 04

Update the value of the gradient and intercept.

$$\operatorname{new}_m = \operatorname{old}_m - \operatorname{Learning\ rate} \times D_m$$
 $\operatorname{new}_c = \operatorname{old}_c - \operatorname{Learning\ rate} \times D_c$

Linear Regression using Gradient Descent Algorithm



Repeat the steps! 500-1000 times

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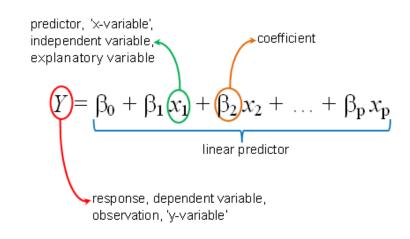
Linear Regression with Multiple Variables

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Linear Regression with Multiple Variables

Mathematical Representation





$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_p x_{ip}$$

where, for i = n observations:

 $y_i = \text{dependent variable}$

 $x_i = \text{expanatory variables}$

 $\beta_0 = \text{y-intercept (constant term)}$

 β_p = slope coefficients for each explanatory variable

Linear Regression with Single Vs. Multiple Variables

Mathematical Representation



$$y = b_0 + b_1 x_1$$

Dependent variable (DV) Independent variables (IVs)

Multiple
$$y = b_0 + b_1^* x_1 + b_2^* x_2 + ... + b_n^* x_n$$

R Squared Value / Model Accuracy

Mathematical Calculation



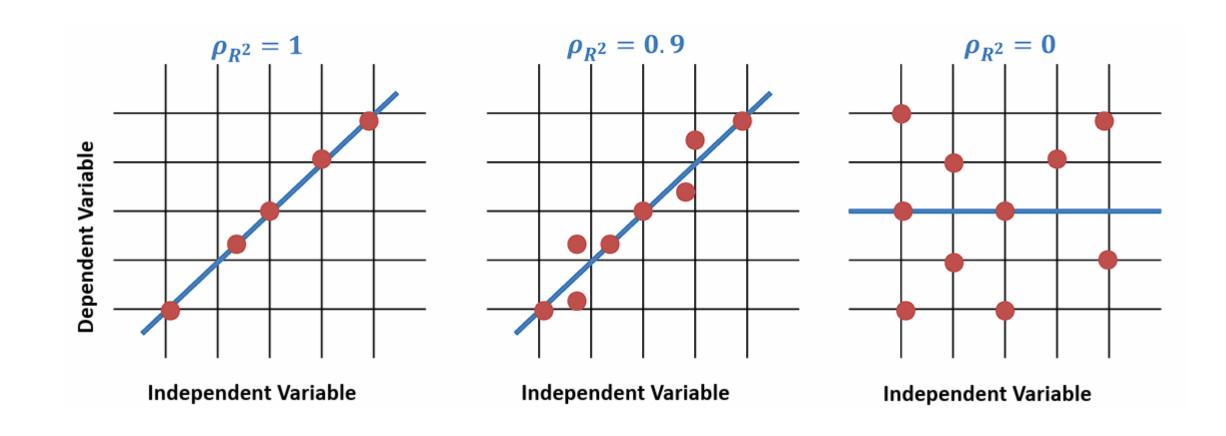
$$R^{2} = 1 - \frac{SS_{RES}}{SS_{TOT}} = 1 - \frac{\sum_{i} (y_{i} - \hat{y}_{i})^{2}}{\sum_{i} (y_{i} - \overline{y})^{2}}$$

- Residual sum of squared errors of our regression model (SSres)
- Total sum of squared errors (SStot)

R Squared Value / Model Accuracy

Mathematical Calculation





R Squared Value / Model Accuracy

Python Implementation



Way no: 01

reg.score(xtest, ytest)

Way no: 02

y_pred = reg.predict(xtest) #Predicted y
from sklearn.metrics import r2_score
Score = r2_score(ytest, y_pred)

Measures for Classification: MCE & ACC

Mathematical Calculation



1. Misclassification Error (MCE):

- Misclassification Error measures the proportion of incorrectly classified instances in a classification problem.
- It is calculated as the total number of misclassified instances divided by the total number of instances.
- Mathematically, MCE can be expressed as:

$$MCE = \frac{\text{Number of misclassified instances}}{\text{Total number of instances}}$$

2. Accuracy (ACC):

- Accuracy measures the proportion of correctly classified instances in a classification problem.
- It is calculated as the total number of correctly classified instances divided by the total number of instances.
- * Mathematically, Accuracy can be expressed as:

$$ACC = \frac{\text{Number of correctly classified instances}}{\text{Total number of instances}}$$