	Uitedh
Name:	
Roll No.:	To Owner by Exercising and Explained
Invigilator's Signature :	

# PROCESS INSTRUMENTATION & CONTROL

Time Allotted: 3 Hours Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

#### **GROUP - A**

# ( Multiple Choice Type Questions )

- 1. Choose the correct alternatives for any ten of the following:  $10 \times 1 = 10$ 
  - i) Macleod gauge is used to measure
    - a) pressure
- b) vacuum
- c) flow rate
- d) temperature.
- ii) The transfer operation of the first order system is
  - a)  $1/T_{S} + 1$
  - b)  $1/T_{S}$
  - c)  $S/T_S+1$
  - d) None of these.

6424 [ Turn over

B. Teen (BT NEW)/ SEM O/ CITE 010/ 2010					
iii)	Whi	ich of the following is	not	a mechanical pressure	
	sensing element ?				
	a)	U-tube	b)	Burdon tube	
	c)	Diaphragm	d)	Bellons.	
iv)	Erro	or caused by the act of	meas	urement on the physical	
	system being tested is				
	a)	Hysteresis error	b)	Random error	
	c)	Systematic error	d)	Loading error.	
v)	Opt	ical pyrometer is used	to m	neasure the temperature	
	of				
	a)	furnace			
	b)	low temperature			
	c)	moderate temperature	<b>)</b>		
	d)	liquid.			
vi)	Rati	io control system is a sp	oecial	type of	
	a)	open loop system			
	b)	feedback system			
	c)	on-off system			
	d)	feed forward system.			



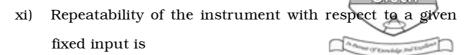
- vii) In proportional-plus-integral control action, tim required for oscillations to stop is
  - a) larger

- b) considerable
- c) shortest
- d) none of these.
- viii) The Laplace transform of sint is
  - a)  $1/S^2 + 1$
  - b)  $S/S^2 + 1$
  - c)  $1/S^2 1$
  - d)  $S/S^2-1$ .
- ix) The frequency at which the maximum amplitude ratio is attained is known as
  - a) resonant frequency
  - b) radian frequency
  - c) corner frequency
  - d) cross-over frequency.
- x) Which has maximum offset in P, P I, P D, PID controller?
  - a) *P*

b) PID

c) PD

d) PI.



- accuracy a)
- precision b)
- c) systematic error
- d) loading error.

xii) Critically damped system means damping coefficient is

1 a)

b) > 1

< 1 c)

d) 0.

#### **GROUP - B**

# (Short Answer Type Questions)

Answer any *three* of the following.

 $3 \times 5 = 15$ 

- 2. Derive the transfer function of a first order system.
- 5

A step change of magnitude 4 is introduced into a system 3. having transfer function

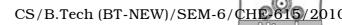
$$\frac{Y(s)}{X(s)} = \frac{1}{s^2 + 1 \cdot 6s + 4}$$

Determine overshoot, decay ratio and period of oscillation. 5

operating principle 4. Write down the resistance thermometer.

5

6424



5. Calculate C/R for the following control loop:

5

5

6. What are cascade control & adaptive control?

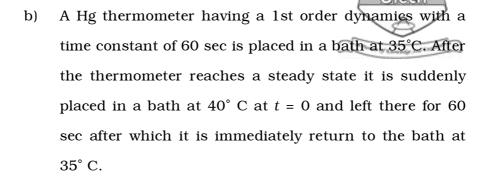
#### **GROUP - C**

# (Long Answer Type Questions)

Answer any *three* of the following.  $3 \times 15 = 45$ 

- 7. a) Explain the working principle of gas chromatography and polarography with suitable diagram.
  - b) Explain Seebeck, Peltier and Thomson effects. Define a thermocouple and explain how it generates e.m.f. 7 + 8
- 8. a) Describe the behaviour of a typical feedback control system using different kinds of control action when it is subject to a permanent disturbance with sketch.

5 [ Turn over



- i) Calculate the thermometer reading at time t = 30 sec & 120 sec.
- ii) Draw a sketch showing the variation of thermometer with time.
- iii) What would be the reading at t=6 sec if the thermometer had only been immersed in  $40^{\circ}$ C bath for less than 1 sec before being returned to  $35^{\circ}$  C bath. 5+10
- 9. a) Define proportional band.
  - b) Describe ON-OFF control.
  - c) Analyse the stability of the system having the following characteristic equation :

$$3s^4 + 10s^3 + 5s^2 + 5s + 2 = 0$$

d) State why PD control action referred as anticipatory control. 1 + 2 + 10 + 2

6



10. State the Bode stability criteria. Plot the Bode diagram for the system whose open loop transfer function is

$$G_s = \frac{1}{(s+1)(s+5)}$$

- 11. Write short notes on any *three* of the following:  $3 \times 5$ 
  - a) Static characteristics of instruments
  - b) PID controller
  - c) Static & Dynamic errors
  - d) Digital & Analog controller.