

# Vector Space over $\mathbb{R}$

# Vector Space over $\mathbb{R}$

A **vector space** is a nonempty set  $V$  of objects, called *vectors*, on which are defined two operations, called *addition* and *multiplication by scalars* (real numbers), subject to the ten axioms (or rules) listed below.<sup>1</sup> The axioms must hold for all vectors  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  in  $V$  and for all scalars  $c$  and  $d$ .

1. The sum of  $\mathbf{u}$  and  $\mathbf{v}$ , denoted by  $\mathbf{u} + \mathbf{v}$ , is in  $V$ .
2.  $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$ .
3.  $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$ .
4. There is a **zero** vector  $\mathbf{0}$  in  $V$  such that  $\mathbf{u} + \mathbf{0} = \mathbf{u}$ .
5. For each  $\mathbf{u}$  in  $V$ , there is a vector  $-\mathbf{u}$  in  $V$  such that  $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$ .
6. The scalar multiple of  $\mathbf{u}$  by  $c$ , denoted by  $c\mathbf{u}$ , is in  $V$ .
7.  $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$ .
8.  $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$ .
9.  $c(d\mathbf{u}) = (cd)\mathbf{u}$ .
10.  $1\mathbf{u} = \mathbf{u}$ .



# A Subspace Spanned by a Set

For  $v_1, v_2, \dots, v_p \in V$

$\text{Span}\{v_1, v_2, \dots, v_p\}$  = set of all linear combinations of  $v_1, v_2, \dots, v_p$ .

# A Subspace Spanned by a Set

For  $v_1, v_2, \dots, v_p \in V$

$\text{Span}\{v_1, v_2, \dots, v_p\}$  = set of all linear combinations of  $v_1, v_2, \dots, v_p$ .

# Linear transformation

Let  $V_1, V_2$  be two vector spaces over  $\mathbb{R}$ . A function  $T : V_1 \rightarrow V_2$  is called linear transformation if

$$\begin{aligned}T(u + v) &= T(u) + T(v) \\ T(c.u) &= c.T(u)\end{aligned}$$

for all  $u, v \in V_1$  and  $c \in \mathbb{R}$ .

# Linear transformation

Let  $V_1, V_2$  be two vector spaces over  $\mathbb{R}$ . A function  $T : V_1 \rightarrow V_2$  is called linear transformation if

$$\begin{aligned}T(u + v) &= T(u) + T(v) \\ T(c \cdot u) &= c \cdot T(u)\end{aligned}$$

for all  $u, v \in V_1$  and  $c \in \mathbb{R}$ .

Kernel of  $T = \{u \in V_1 \mid T(u) = 0\}$

Range of  $T = \{v \in V_2 \mid v = T(u) \text{ for some } u \in V_1\}$

# Linear transformation

Let  $V_1, V_2$  be two vector spaces over  $\mathbb{R}$ . A function  $T : V_1 \rightarrow V_2$  is called linear transformation if

$$\begin{aligned}T(u + v) &= T(u) + T(v) \\ T(c \cdot u) &= c \cdot T(u)\end{aligned}$$

for all  $u, v \in V_1$  and  $c \in \mathbb{R}$ .

Kernel of  $T = \{u \in V_1 \mid T(u) = 0\}$

Range of  $T = \{v \in V_2 \mid v = T(u) \text{ for some } u \in V_1\}$

Both are subspaces.



# Linear transformation

Let  $V_1, V_2$  be two vector spaces over  $\mathbb{R}$ . A function  $T : V_1 \rightarrow V_2$  is called linear transformation if

$$\begin{aligned}T(u + v) &= T(u) + T(v) \\ T(c.u) &= c.T(u)\end{aligned}$$

for all  $u, v \in V_1$  and  $c \in \mathbb{R}$ .

Kernel of  $T = \{u \in V_1 \mid T(u) = 0\}$

Range of  $T = \{v \in V_2 \mid v = T(u) \text{ for some } u \in V_1\}$

Both are subspaces.

$V_1, V_2$ -two vector spaces over  $\mathbb{R}$  are said to be isomorphic if there exists a linear transformation  $T : V_1 \rightarrow V_2$  such that  $T$  is bijective.

# Basis

A set of vectors  $B = \{v_1, v_2, \dots, v_p\}$  is said to be basis of a vector space  $V$  if  $B$  is linearly independent and  $\text{Span}(B) = V$ .

A set of vectors  $B = \{v_1, v_2, \dots, v_p\}$  is said to be basis of a vector space  $V$  if  $B$  is linearly independent and  $\text{Span}(B) = V$ .

## Theorem

*Every vector space has a basis.*

A set of vectors  $B = \{v_1, v_2, \dots, v_p\}$  is said to be basis of a vector space  $V$  if  $B$  is linearly independent and  $\text{Span}(B) = V$ .

## Theorem

*Every vector space has a basis.*

### The Spanning Set Theorem

Let  $S = \{v_1, \dots, v_p\}$  be a set in  $V$ , and let  $H = \text{Span}\{v_1, \dots, v_p\}$ .

- If one of the vectors in  $S$ —say,  $v_k$ —is a linear combination of the remaining vectors in  $S$ , then the set formed from  $S$  by removing  $v_k$  still spans  $H$ .
- If  $H \neq \{0\}$ , some subset of  $S$  is a basis for  $H$ .

A set of vectors  $B = \{v_1, v_2, \dots, v_p\}$  is said to be basis of a vector space  $V$  if  $B$  is linearly independent and  $\text{Span}(B) = V$ .

## Theorem

*Every vector space has a basis.*

### The Spanning Set Theorem

Let  $S = \{v_1, \dots, v_p\}$  be a set in  $V$ , and let  $H = \text{Span}\{v_1, \dots, v_p\}$ .

- a. If one of the vectors in  $S$ —say,  $v_k$ —is a linear combination of the remaining vectors in  $S$ , then the set formed from  $S$  by removing  $v_k$  still spans  $H$ .
- b. If  $H \neq \{0\}$ , some subset of  $S$  is a basis for  $H$ .

**Dimension of a vector space**  $V$  is the number of elements in any basis of  $V$ .