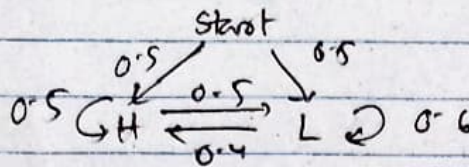
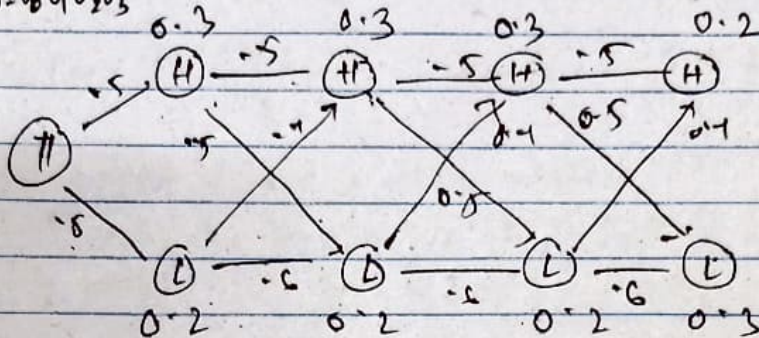


Soln

(Q)

GGCA  
0.0090203

(i)



$$\alpha_0(H) = 0.5 \times 0.2 = 0.1 \quad \alpha_0(L) = 0.5 \times 0.3 = 0.15$$

$$\text{For } T=1 \quad \alpha_1(H) = 0.15 \times 0.5 \times 0.3 + 0.1 \times 0.4 \times 0.3 = 0.0345$$

$$\alpha_1(L) = 0.1 \times 0.6 \times 0.2 + 0.15 \times 0.5 \times 0.2 = 0.027$$

$$\text{For } T=2 \quad \alpha_2(H) = 0.0345 \times 0.5 \times 0.3 + 0.027 \times 0.4 \times 0.3 = 0.008415$$

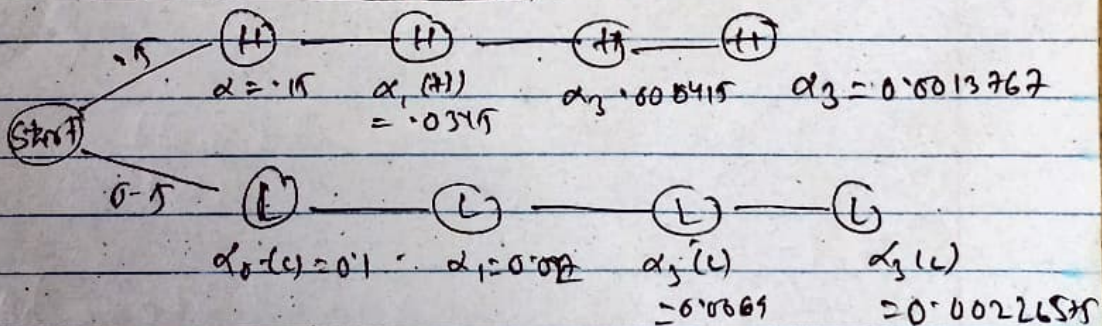
$$\alpha_2(L) = 0.027 \times 0.6 \times 0.2 + 0.0345 \times 0.5 \times 0.2 = 0.00669$$

$$\text{For } T=3 \quad \alpha_3(H) = 0.008415 \times 0.5 \times 0.3 + 0.00669 \times 0.4 \times 0.3 = 0.0013767$$

$$\alpha_3(L) = 0.00669 \times 0.5 \times 0.3 + 0.008415 \times 0.4 \times 0.3 = 0.00226575$$

$$P(0/x) = \sum_{i=0}^{\infty} \alpha_i(L) = 0.0036 \quad = 0.0026575$$

(ii)



For most likely state seq. we backtrack from higher  $\alpha_i$  value of every state.

For  $T_3 = \max = L$

state seq

$T_2 = \max = H$

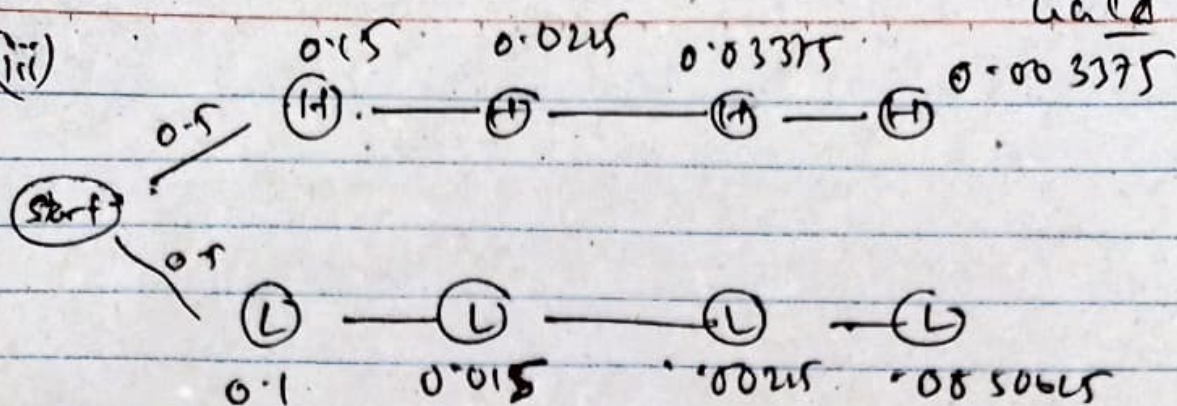
$= H H H L$

$T_1 = \max = H$

$T_0 = \max = H$



(iii)



$$V_0(H) = .5 \times 3 = .15$$

$$V_0(L) = .5 \times 2 = 0.1$$

for  $V_1$ 

$$H \rightarrow H \quad .15 \times .5 \times 3 = .0225$$

$$H \rightarrow L \quad .15 \times .5 \times 2 = .015$$

$$L \rightarrow H \quad 0.1 \times .4 \times 3 = 0.012$$

$$L \rightarrow L \quad 0.1 \times .6 \times 2 = 0.012$$

for  $V_2$ 

$$H \rightarrow H \quad .0225 \times .5 \times 3 = .03375$$

$$H \rightarrow L \quad .0225 \times .5 \times 2 = .00225$$

$$L \rightarrow H \quad .015 \times .4 \times 3 = .009$$

$$L \rightarrow L \quad .015 \times .6 \times 2 = .0018$$

for  $V_3$ 

$$H \rightarrow H \quad .03375 \times .5 \times 2 = .003375$$

$$H \rightarrow L \quad .03375 \times .5 \times .3 = .0050625$$

$$L \rightarrow H \quad .00225 \times .4 \times 2 = .00018$$

$$L \rightarrow L \quad .0018 \times .6 \times 3 = .000405$$

Optimal path = HHHL