

Gaussian Elimination: Matrix form $AX=b$

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Note that the last column is the RHS column vector b .

$$\left(\begin{array}{ccc|c} 2 & 1 & 1 & 5 \\ 4 & -6 & 0 & -2 \\ -2 & 7 & 2 & 9 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ 0 & 8 & 3 & 14 \end{array} \right) \rightarrow$$

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 $z = 2,$
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Gaussian Algorithm

For Row Echelon Form

1. Find the leftmost nonzero column.
2. Select a nonzero entry in that column (**pivot**). Bring it on top by interchanging rows
3. Use Elementary row operations to make all entries below that nonzero entry 0.
4. Ignore that row and columns before (including of leading entry) above found column. Apply steps 1-3 for remaining submatrix. Go on till all rows are exhausted.

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For Reduced Row Echelon Form

5. Make all leading entries 1 by elementary row operation ($R_i \rightarrow cR_i$)
6. Make all entries in a column above leading 1 zero by elementary row operation ($R_i \rightarrow R_i - cR_j$)

$$A = \begin{bmatrix} 0 & 3 & -6 & 6 \\ 3 & -7 & 8 & -5 \\ 3 & -9 & 12 & -9 \end{bmatrix}$$

Reduced Row Echelon Form (RREF) of A is

$$A' = \begin{bmatrix} 1 & 0 & -2 & 3 \\ 0 & 1 & -2 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

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Theorem

1. A linear system is inconsistent if and only if REF or RREF of its augmented matrix has a row of the form $0 \ 0 \ \cdots \ 0 \ b$, for some nonzero b .
2. A linear system has unique solution if and only if no. of nonzero rows and no. of columns of REF or RREF of its augmented matrix are same.

Triangular factorization: $A = LU$ Given a square matrix A , we can find L a lower Triangular matrix with 1s on the diagonal and U upper Triangular matrix such that $A = LU$.

For $A = \begin{bmatrix} 1 & 2 \\ 3 & 8 \end{bmatrix}$, $L = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$ and $U = \begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix}$

Calculation of A^{-1} : Gauss-Jordan Method

Let $AA^{-1} = I$

If X_1 is a first column of A^{-1} then $AX_1 = e_1$, where $e_1 = [1 \ 0 \ \cdots \ 0]^T$.

We can use Gaussian Elimination to find X_1 —first column of A^{-1} .

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Let $A = \begin{bmatrix} 1 & 2 \\ 3 & 8 \end{bmatrix}$.

Consider

$$[A|I] = \left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 3 & 8 & 0 & 1 \end{array} \right]$$

Perform elementary row operations on $[A|I]$ to convert A into I .
Then I will change to A^{-1} .

Vectors in \mathbb{R}^n :

$$\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$$

where $a_1, a_2, \dots, a_n \in \mathbb{R}$.

$$\begin{bmatrix} 2 \\ 3 \end{bmatrix} \text{ is a vector in } \mathbb{R}^2.$$

$$\begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \text{ is a vector in } \mathbb{R}^3.$$

Vector addition and scalar multiplication are done like matrices.

Algebraic Properties of \mathbb{R}^n

For all $\mathbf{u}, \mathbf{v}, \mathbf{w}$ in \mathbb{R}^n and all scalars c and d :

- | | |
|---|--|
| (i) $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$ | (v) $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$ |
| (ii) $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$ | (vi) $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$ |
| (iii) $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$ | (vii) $c(d\mathbf{u}) = (cd)\mathbf{u}$ |
| (iv) $\mathbf{u} + (-\mathbf{u}) = -\mathbf{u} + \mathbf{u} = \mathbf{0}$,
where $-\mathbf{u}$ denotes $(-1)\mathbf{u}$ | (viii) $1\mathbf{u} = \mathbf{u}$ |

Linear Combinations

Consider a linear system

$$\begin{aligned}x_2 - 4x_3 &= 8 \\2x_1 - 3x_2 + 2x_3 &= 1 \\5x_1 - 8x_2 + 7x_3 &= 1\end{aligned}$$

It can be written as

$$x_1 \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ -3 \\ -8 \end{bmatrix} + x_3 \begin{bmatrix} -4 \\ 2 \\ 7 \end{bmatrix} = \begin{bmatrix} 8 \\ 1 \\ 1 \end{bmatrix}$$

LHS of $=$ is called linear combination of

$$u = \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix}, v = \begin{bmatrix} 1 \\ -3 \\ -8 \end{bmatrix} \& w = \begin{bmatrix} -4 \\ 2 \\ 7 \end{bmatrix}$$

Above equation is called **vector equation**.



Linear system and Vector Equation

A linear system $AX = b$ is same as $x_1 C_1 + x_2 C_2 + \cdots + x_n C_n = b$ where C_i is i^{th} column of A .

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Hence we need to study linear combination of columns of A .

Column space of A = set of all linear combinations of columns of A .

$$Col(A) = \{x_1 C_1 + x_2 C_2 + \cdots + x_n C_n \mid x_i \in \mathbb{R} \text{ for all } i\}$$

$\therefore AX = b$ has a solution iff $b \in Col(A)$.

If $v_1, v_2, \dots, v_p \in \mathbb{R}^n$, then

$\text{Span} \{v_1, v_2, \dots, v_p\} = \{c_1 v_1 + c_2 v_2 + \dots + c_p v_p \mid c_1, c_2, \dots, c_p \in \mathbb{R}\}$,
the set of all linear combinations of v_1, v_2, \dots, v_p .

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Let

$$u = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, v = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{Span} \{v\} = \{c.v \mid c \in \mathbb{R}\} = \left\{ \begin{bmatrix} c \\ 0 \end{bmatrix} \mid c \in \mathbb{R} \right\}$$

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$\text{span}\{u\} = \{x.u \mid x \in \mathbb{R}\}$.

Geometrically it is a line passing through origin and point u .

Let $u, v \in \mathbb{R}^2$. Then $\text{span}\{u, v\} = \{x.u + y.v \mid x, y \in \mathbb{R}\} = \mathbb{R}^2$

Geometrically, what will it be?

Let $\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \in \mathbb{R}^2$

$xu + yv = b$

$\begin{bmatrix} 2 & 1 & | & b_1 \\ 3 & 0 & | & b_2 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 1 & | & b_1 \\ 0 & -3 & | & b_2 - \frac{3}{2}b_1 \end{bmatrix}$

Navigation icons: back, forward, search, etc.

If $v_1, v_2, \dots, v_p \in \mathbb{R}^n$, then

$\text{Span} \{v_1, v_2, \dots, v_p\} = \{c_1 v_1 + c_2 v_2 + \dots + c_p v_p \mid c_1, c_2, \dots, c_p \in \mathbb{R}\}$,
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Let $u, v \in \mathbb{R}^2$. Then $\text{span}\{u, v\} = \{x.u + y.v \mid x, y \in \mathbb{R}\}$.

Geometrically, what will it be?

For a matrix A ,

$\text{Col}(A) := \text{span}\{C_1, C_2, \dots, C_n\} \subseteq \mathbb{R}^m$

The equation $Ax = b$ has a solution if and only if b is a linear combination of the columns of A .

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Theorem

Let A be an $m \times n$ matrix. Then the following statements are logically equivalent

- 1. For each $b \in \mathbb{R}^m$, the equation $AX = b$ has a solution.*
- 2. Each $b \in \mathbb{R}^m$, is a linear combination of the columns of A .*
- 3. $\text{Col}(A) = \mathbb{R}^m$.*
- 4. A has a pivot position in every row.*

Homogeneous Linear System

$$\left\{ c \begin{bmatrix} 4 \\ 0 \\ 3 \end{bmatrix} \mid c \in \mathbb{R} \right\}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = c \begin{bmatrix} 4/3 \\ 0 \\ 1 \end{bmatrix} \in \mathbb{R}^3$$

The homogeneous equation $AX = 0$ has a nontrivial solution if and only if the $\text{REF}(A)$ has at least one free variable.

Suppose augmented form $[A|0]$ is

$$\left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ -3 & -2 & 4 & 0 \\ 6 & 1 & -8 & 0 \end{array} \right] \xrightarrow[R_3 \rightarrow R_3 - 2R_1]{R_2 \rightarrow R_2 + R_1} \left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & -9 & 0 & 0 \end{array} \right] \quad x = 0$$

$$x_1 = \frac{4}{3}c, \quad x_2 = 0, \quad x_3 = c$$

$$A(0) = 0$$

$$R_3 \rightarrow R_3 + 3R_2 \quad \left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$\Rightarrow 0$ is always

a solⁿ to $AX = 0$

x_1, x_2 are dependent variables
 x_3 is free variable.

$$3x_2 = 0, \quad 3x_1 + 5x_2 - 4x_3 = 0$$

$$x_3 = c, \quad x_1 = \frac{4}{3}c$$

Homogeneous Linear System

solⁿ space for $AX=0$
is $\text{span}\{u, v\}$

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$$A = \begin{bmatrix} 1 & 3 & -3 & 7 \\ 0 & 1 & -4 & 5 \end{bmatrix}$$

$AX=0$

$$c \begin{bmatrix} -9 \\ 4 \\ 1 \\ 0 \end{bmatrix} + d \begin{bmatrix} 8 \\ -5 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -9c+8d \\ 4c-5d \\ c \\ d \end{bmatrix}$$

x_3, x_4
 c, d

$$x_2 - 4x_3 + 5x_4 = 0 \Rightarrow x_2 = 4c - 5d$$

$$x_1 + 3x_2 - 3x_3 + 7x_4 = 0$$

$$x_1 = -3(4c-5d) + 3c - 7d = -9c + 8d$$

Non homogeneous linear system

Theorem

Suppose the equation $Ax = b$ is consistent for some given b , and let p be a solution (i.e., $Ap = b$). Then the solution set of $Ax = b$ is the set of all vectors of the form $w = p + v_h$, where v_h is any solution of the homogeneous equation $Ax = 0$.

$Ap = b$
 $Aq = b$
 $A(p - q) = 0$

Let q be any solⁿ to $Ax = b$
 $A(q - p) = 0$, $\underline{q - p} \in \text{Sol}^n(Ax = 0)$
 $\underline{v_h}$
 $q = p + v_h$

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WRITING A SOLUTION SET (OF A CONSISTENT SYSTEM) IN PARAMETRIC VECTOR FORM

1. Row reduce the augmented matrix to reduced echelon form.
2. Express each basic variable in terms of any free variables appearing in an equation. *dependent.*
3. Write a typical solution \mathbf{x} as a vector whose entries depend on the free variables, if any.
4. Decompose \mathbf{x} into a linear combination of vectors (with numeric entries) using the free variables as parameters.

Write down the solutions of $AX = 0$ in parametric form where $A =$

$$\begin{bmatrix} 1 & -4 & -2 & 0 & 3 & -5 \\ 0 & 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & -4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix}$$

$$x_5 = 4x_6^{+3}$$

$$x_3 = x_6^{+2}, x_4 = 4x_2 + 2x_3^{+1} - 3x_5 + 5x_6$$

$$x_2 = c, x_4 = d, x_6 = e$$

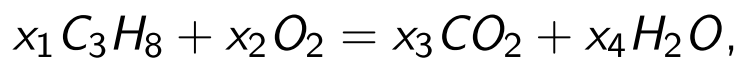
$$AX = b$$

$$\begin{bmatrix} 1 \\ 0 \\ 2 \\ 0 \\ 3 \\ 0 \end{bmatrix} + e \begin{bmatrix} -5 \\ 0 \\ 1 \\ 0 \\ 4 \\ 1 \end{bmatrix} + c \begin{bmatrix} 4 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4c - 5e \\ c \\ e \\ 0 \\ 4e \\ e \end{bmatrix} = e \begin{bmatrix} -5 \\ 0 \\ 1 \\ 0 \\ 4 \\ 1 \end{bmatrix} + c \begin{bmatrix} 4 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Chemical Equations

Consider a chemical reaction of propane gas with oxygen to form carbon dioxide and water.



where x_i are the no. of molecules

$$x_1 \begin{bmatrix} 3 \\ 8 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix} - x_3 \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} - x_4 \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Network flow

