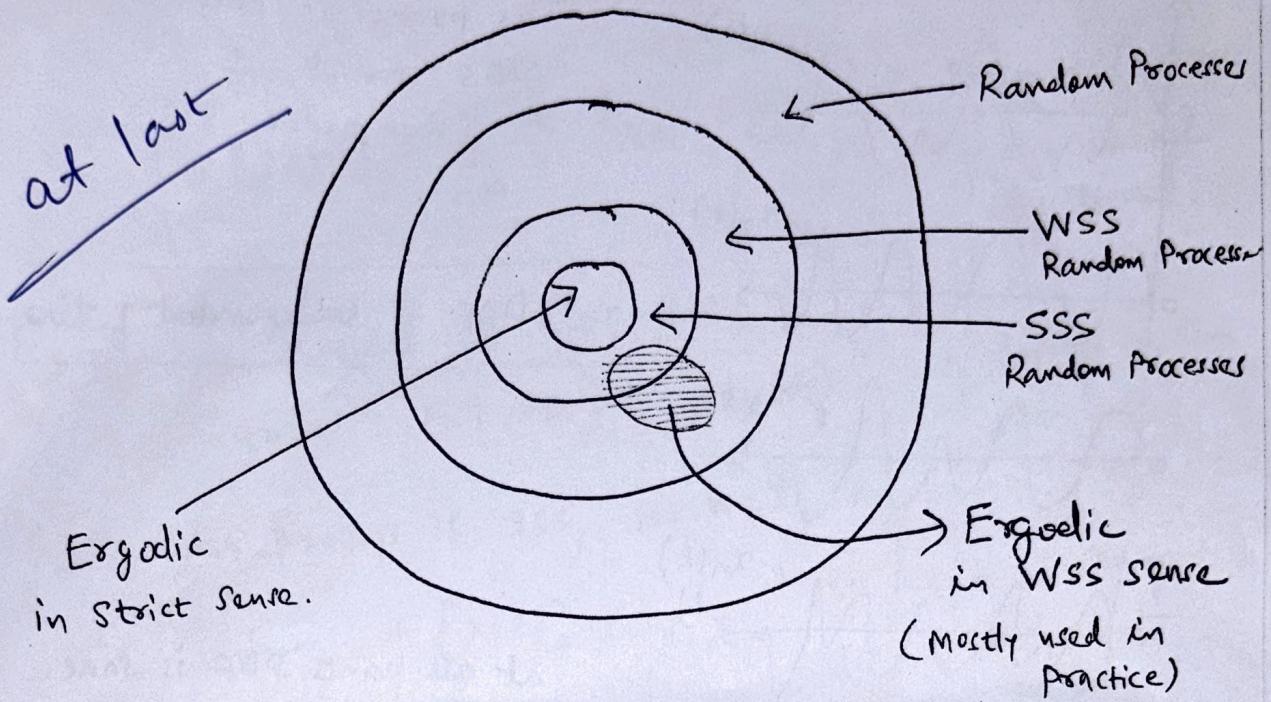


20.11.24
WST

* Types of Random Processes *



* Strict sense stationary (SSS) Random Process *

$$f_{X(t_1), X(t_2), \dots, X(t_n)}^{(x_1, x_2, x_3, \dots, x_n)} = f_{X(t_1+T), \dots, X(t_n+T)}^{(x_1, x_2, \dots, x_n)}$$

n-th order joint PDF

∴ joint PDF is independent of time origin.
 means everywhere, joint pdf is the same.

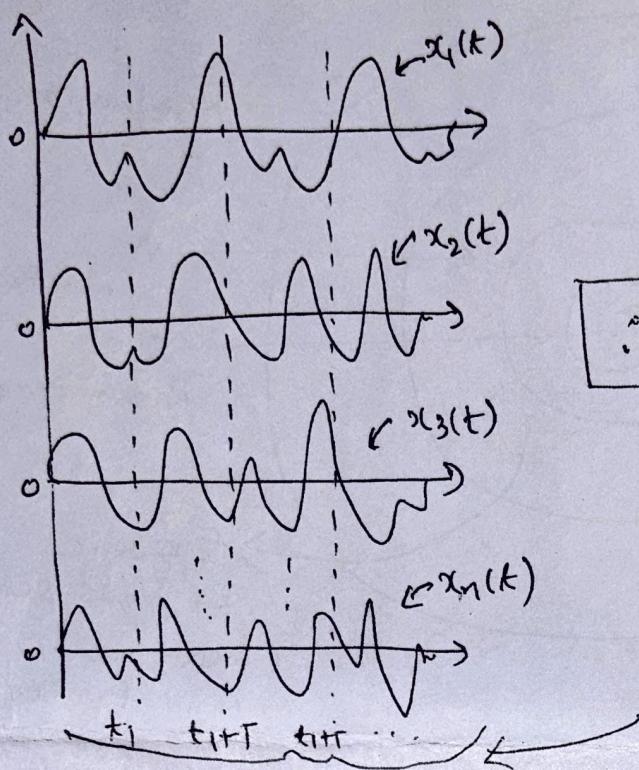
Note: 1. Mostly random processes are NOT SSS (in practice).

2. Practically, some random processes found stationary upto some time interval.

Ex: Consider, $n=1$

$$f_{X(t_1)}(x_1) = f_{X(t_1+T)}(x)$$

The process is said to be SSS for $n=1$ (first order SSS).



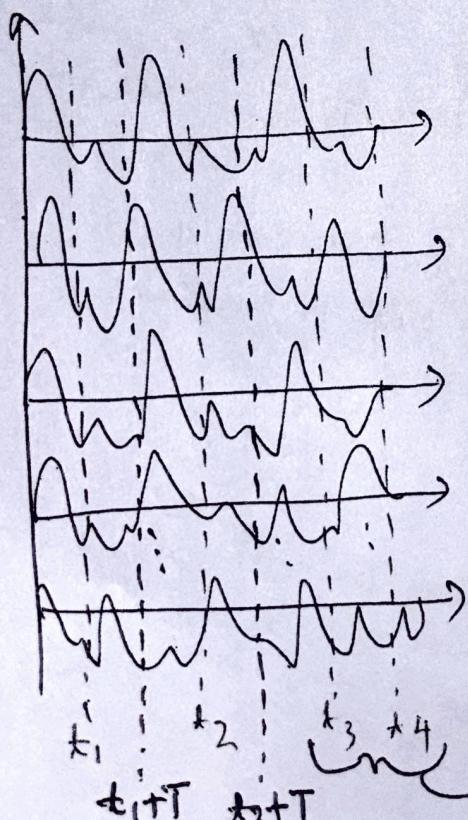
∴ PDF is independent of time

at all points PDF is same.

Ex: Consider $n=2$

$$f_{X(t_1) X(t_2)}(x_1, x_2; t_1, t_2)$$

$$= f_{X(t_1+T) X(t_2+T)}(x_1, x_2; t_1+T, t_2+T)$$



Joint PDF

Joint PDF is dependent on time difference (t_2-t_1)

If this time interval is same as $(t_1 \rightarrow t_2)$

Then the Joint PDF at t_3, t_4 will be same as t_1, t_2 .

* Gross Characterization of Random Process *

\Rightarrow Consider $n=1$

$$E[X(t)] = \int_{-\infty}^{\infty} x \cdot f_{X(t)}(x) \cdot dx$$

\Rightarrow Ensemble average
 \therefore taking average
at a time t .

If the process is NOT SSS,
then $E[X(t)] = \mu_x(t)$ \therefore depend on time.

If the process is SSS, for $n=1$,

then $E[X(t)] = \mu_x$ \therefore Mean is constant
i.e., independent of time.

\Rightarrow Consider $n=2$

$$E[X(t_1)X(t_2)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1 x_2 f_{X(t_1)X(t_2)}(x_1, x_2) \cdot dx_1 \cdot dx_2$$

This is called Auto correlation function of RP
denoted as, $R_X(t_1, t_2)$

If the process is SSS
then $E[X(t_1)X(t_2)] = E[X(t_1+T)X(t_2+T)]$
 $= R_X(t_2 - t_1)$

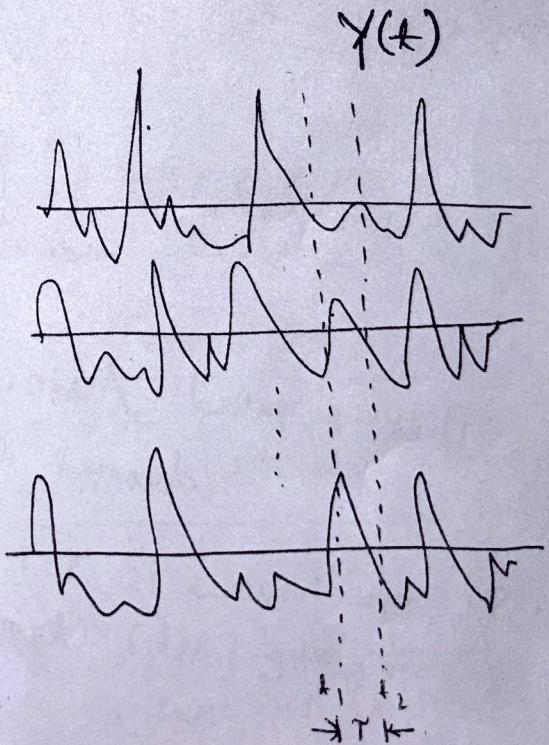
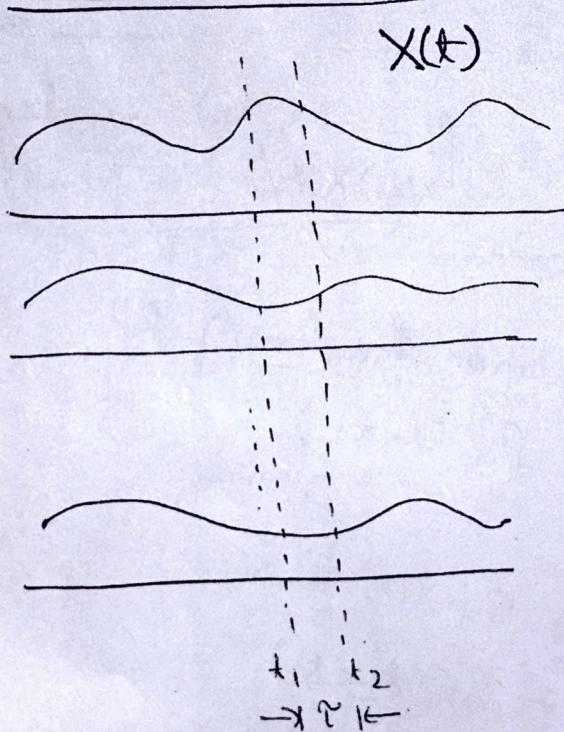
$\therefore R_X(t_1, t_2) = R_X(t_2 - t_1) \Rightarrow$ Auto correlation func.
is func. of time difference.

Note: For a random process, if expectation is independent of time (constant) and Autocorrelation func. is func. of time difference then such a random process is called Wide-sense Stationary (WSS)

This is applicable in practical situations.

WSS Random Process Conditions	$\begin{aligned} (1) \quad E[X(t)] &= \bar{X} \\ (2) \quad E[X(t_1)X(t_2)] &= R_X(t_1, t_2) \\ &= R_X(t_2 - t_1) \\ &= R_X(\tau) \end{aligned}$
-------------------------------------	---

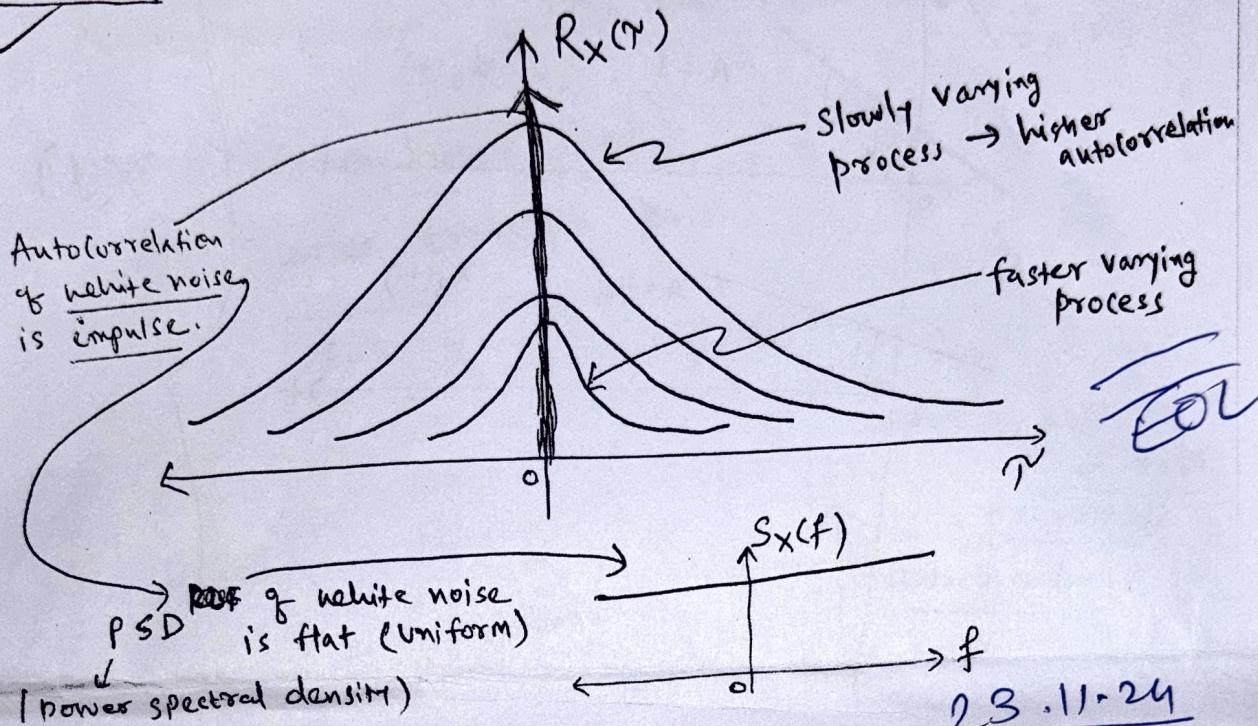
Intuitive illustration:



$X(t)$ autocorrelation is higher compared to autocorrelation of $Y(t)$
i.e., $R_X(\tau) \gg R_Y(\tau)$, for same τ .

Practical point

Remark: Autocorrelation gives us how a random process overall behaves or works like; without explicitly observing the random process.



Example: Sketch ensemble of random process,

$$X(t) = At + b,$$

where, b is constant

A is a random variable uniformly distributed betw $(-2, 2)$

(a) Just by looking at the ensemble, comment on the stationarity of the process.

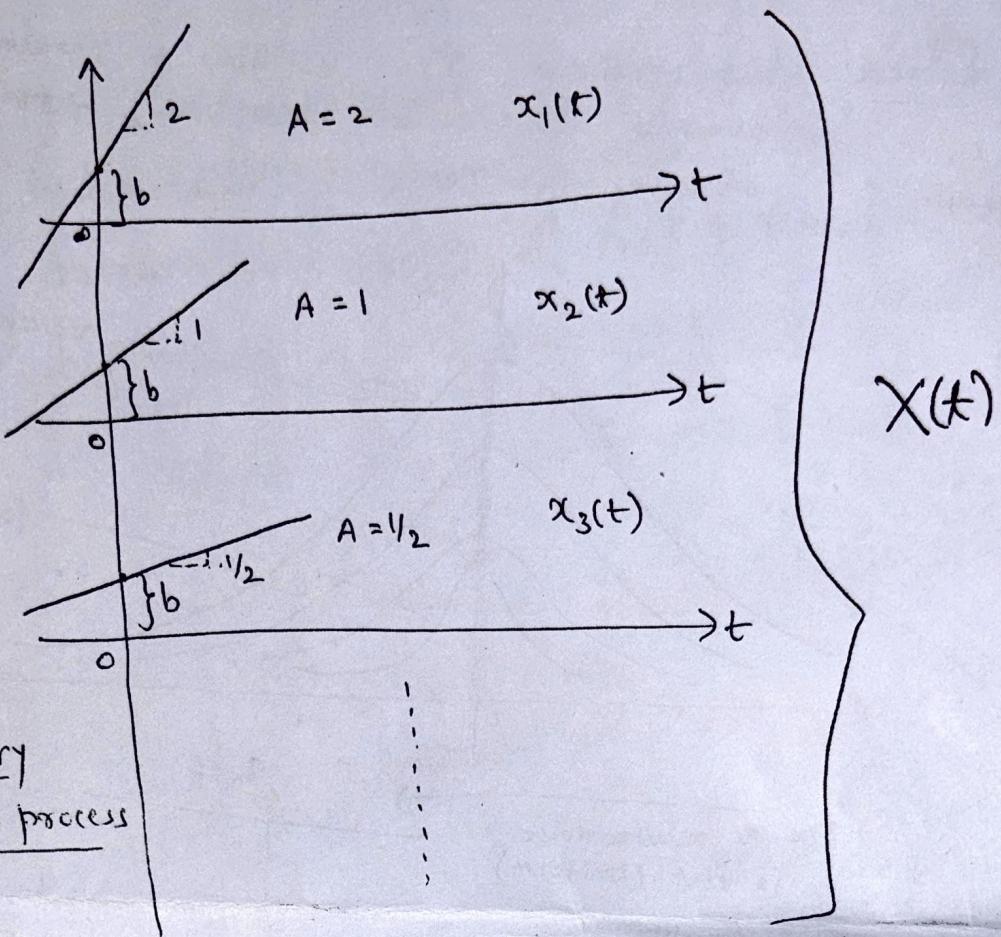
(b) Find autocorrelation function $R_{XX}(\tau)$.

(c) Find Expectation $E[X(t)]$.

(d) Based on (b) and (c), comment whether the process is WSS?

Solution:

(a)



$$(C) E[x(t)] = E[Akt + b] = t E(A) + b = \boxed{b} \quad \begin{matrix} \text{CONSTANT} \\ \text{Ans. Expectation} \end{matrix}$$

$\because A \sim U(-2, 2)$
 $\therefore E(A) = 0$.

$$(b) R_X(\tau) = R_X(t_1, t_2) = E\{x(t_1)x(t_2)\}$$

$$= E[(At_1 + b)(At_2 + b)]$$

$$= E[A^2 t_1 t_2 + At_1 b + At_2 b + b^2]$$

$$= E[A^2] t_1 t_2 + E[A] t_1 b + E[A] t_2 b + b^2$$

Autocorrelation
fun \approx is NOT
dependent on
time diff ($t_2 - t_1$)
but depend on
 t_1, t_2 itself.

$$= b^2 + E[A^2] t_1 t_2 \quad \left| \begin{array}{l} t_1 t_2 \int_{-2}^2 \frac{A^2}{4} da + b^2 \\ = \frac{4}{3} t_1 t_2 + b^2 \end{array} \right.$$

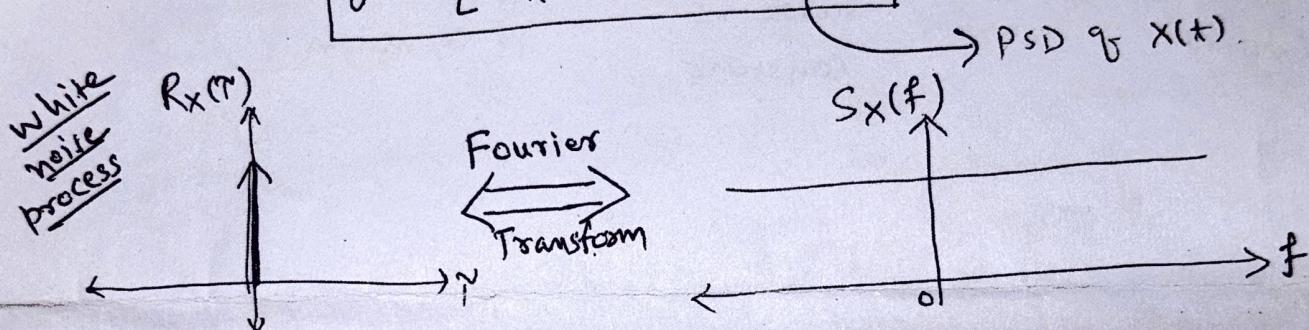
\therefore The $X(t)$ is "NOT" a WSS. \rightarrow Ans (d) (\because (b) and (c))

* Wiener - Khinchine Theorem " (without proof)

AutoCorrelation fun $\cong R_x(\tau)$ and Power Spectral density (PSD)
 $S_x(f)$

(of a random process $X(t)$)
 are Fourier transform pair.

$$\int_{-\infty}^{\infty} [R_x(\tau)] = S_x(f)$$

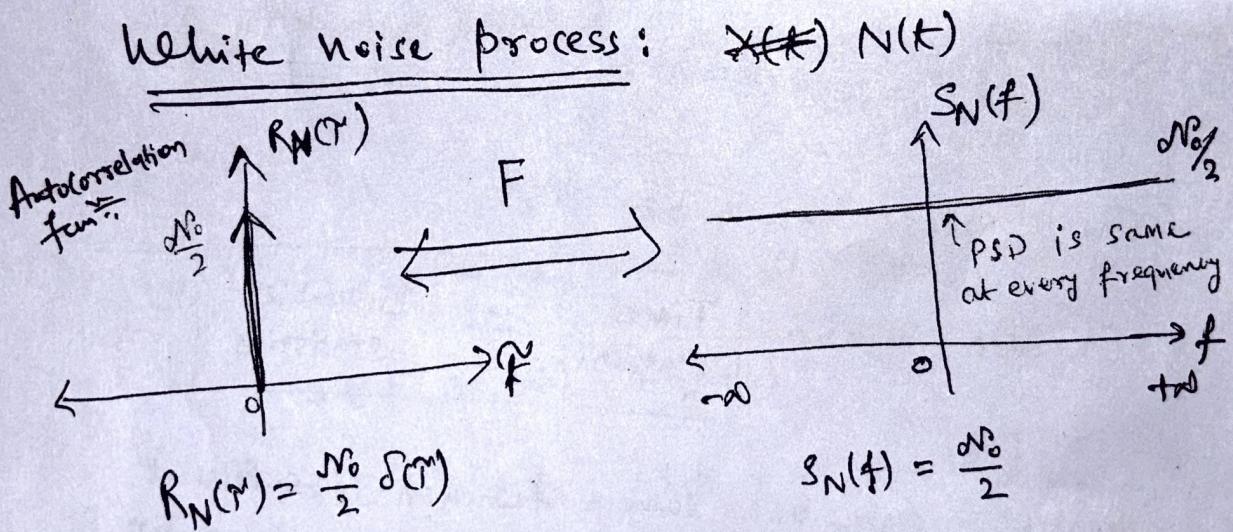
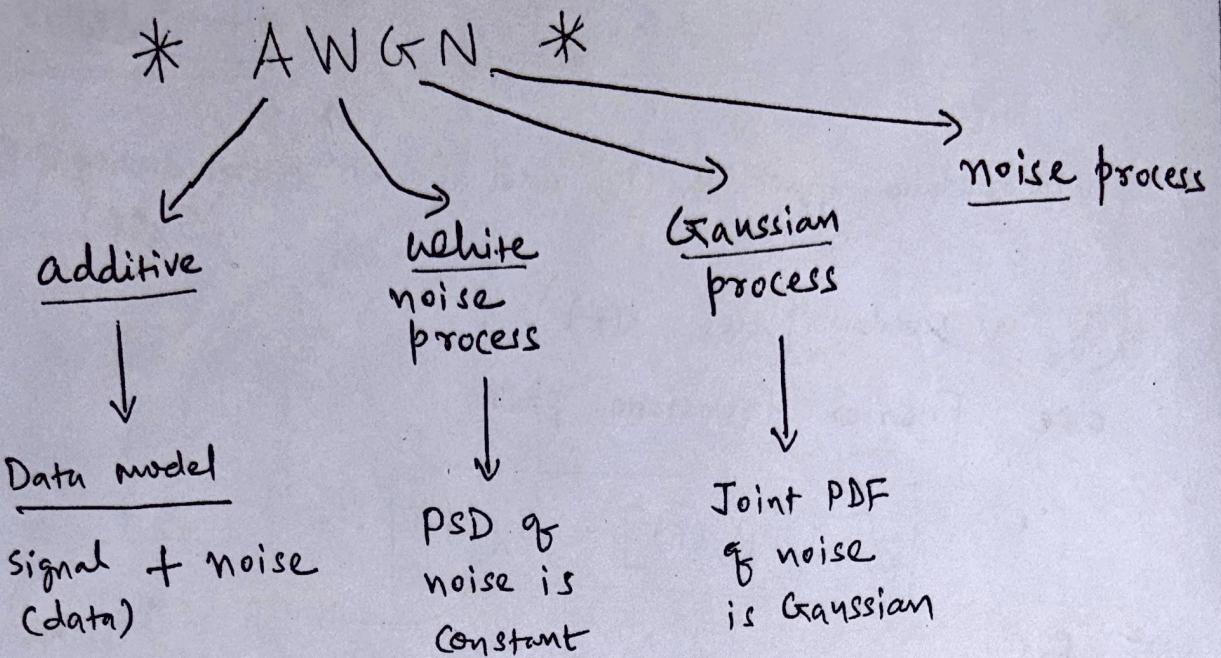


* Ergodic process * (just definition)

- The process has to be SSS.
- Ergodic means

$$\boxed{\text{Time statistics} = \text{Ensemble statistics}}$$

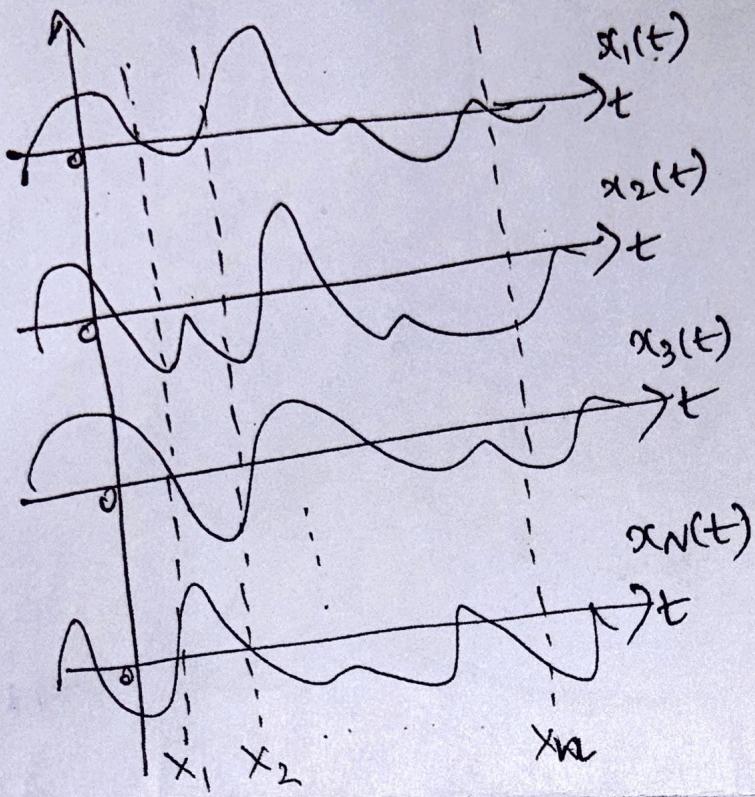
Means: only one sample function is sufficient
 to determine characteristics of entire RP.



"white" colour contains all the colours, equally.

Similarly, "white noise" contains equal power (Uniform PSD) at all frequencies.

Gaussian process: x_1, x_2, \dots, x_N .



Remember,
 $n=1$ first order PDF
 $n=2$ second order
(Two at a time)
joint PDF

for any n

$n=1$
 $n=2$
⋮

the joint PDF will be
Gaussian density fun. at every n .

∴ The process is called
" Gaussian process".

white Gaussian Random process (WGN)

If PSD of $N(t)$ is comes out to be flat (Uniform) i.e., $R_N(\tau)$ an impulse.

Joint PDF at any n is Gaussian PDF.

⇒ Go back to
first slide
"Types of R.P."