

MA201_ASSIGNMENT 5

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1. Three different Gaussian random variables, i.e., X_1, X_2 and X_3 with 0 mean and 1 variance., Compute the covariance matrix of X_1, X_2 and X_3 .

$$\text{Covariance matrix (CV) } CV = \begin{bmatrix} \text{cov}(X_1, X_1) & \text{cov}(X_1, X_2) & \text{cov}(X_1, X_3) \\ \text{cov}(X_2, X_1) & \text{cov}(X_2, X_2) & \text{cov}(X_2, X_3) \\ \text{cov}(X_3, X_1) & \text{cov}(X_3, X_2) & \text{cov}(X_3, X_3) \end{bmatrix}. \text{ Here, } \text{cov}(X, Y) = E[XY] - E[X]E[Y]. \text{ Similarly compute}$$

correlational matrix.

2. Verify the properties of the covariance matrix.

1. Symmetric, i.e., $C_X = C_X^T$.

2. its eigenvalues are greater than equal to zero

3. It is positive semi-definite, i.e., for any real valued vector $a, a^T C_X a \geq 0$

3. Generate covariance matrix of correlated data. Take face images as the data. Show that data and noise are uncorrelated. Take Image files as your data and standard gaussian noise. (Face data is attached in zip file)

Solutions:

```
%matplotlib inline
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
from matplotlib import cm
import matplotlib.image as mpimg
```

Three different Gaussian random variables, i.e., X_1, X_2 and X_3 with 0 mean and 1 variance.

M = 2000

X1 = np.random.normal(0,1,M)

X2 = np.random.normal(100,1,M)

X3 = np.random.normal(10,1,M)

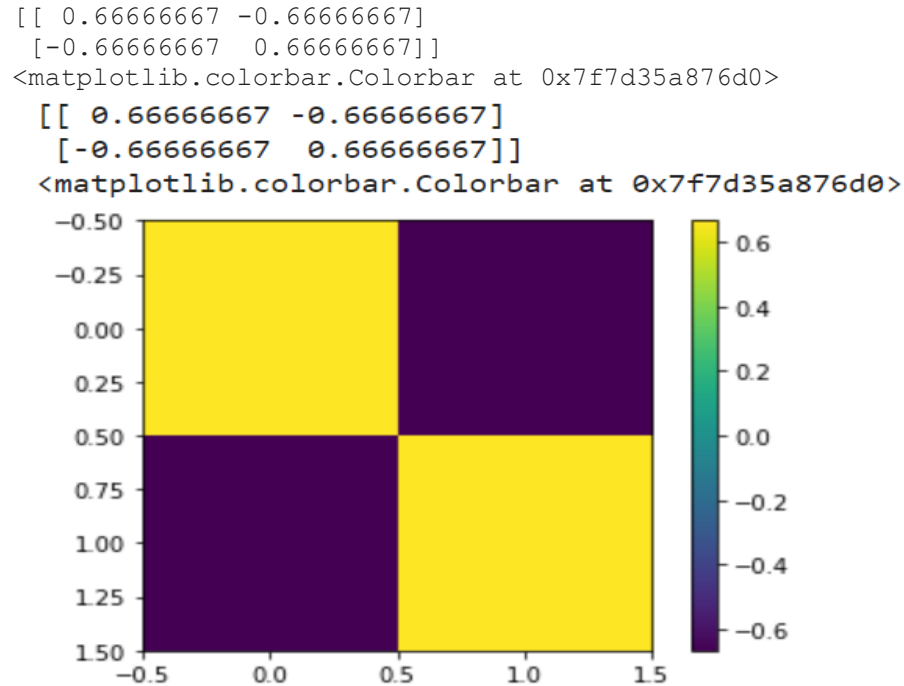
X = np.transpose(np.reshape(np.array([X1,X2,X3]),[3,M]))

Compute the covariance matrix of X_1, X_2 and X_3 . Covariance matrix (CV)

```
def covmat(data_mat):
    [m,n]=np.shape(data_mat)
    CV = np.zeros(shape=(n,n))
    for i in range(n):
        for j in range(n):
            CV[i,j] = np.mean(np.multiply(X[:,i],X[:,j])) -
np.multiply(np.mean(X[:,i]), np.mean(X[:,j]))
    return CV
```

```
#X = np.array([[2.5,2.4],[.5,.7],[2.2,2.9],[1.9,2.2],[3.1,3]])
X = np.array([[0,2],[1,1],[2,0]])
```

```
CV = covmat(X)
print(CV)
fig=plt.figure()
plt.imshow(CV)
plt.colorbar()
```



```
np.cov(X.T,bias=True)
array([[ 0.66666667, -0.66666667], [-0.66666667,  0.66666667]])
```

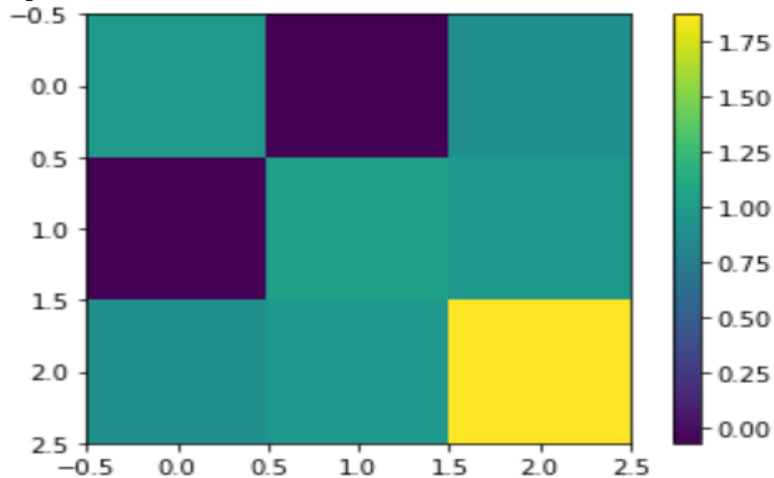
```
np.var(np.array([0,1,2]))
0.6666666666666666
```

Generating three random variables as X1, X2 and X1+X2. Compute the covariance matrix

```
X1 =np.random.normal(0,1,M)
X2 =np.random.normal(0,1,M)
X3 = X1+X2
X = np.transpose(np.reshape(np.array([X1,X2,X3]),[3,M]))
CV = covmat(X)
print(CV)
fig=plt.figure()
plt.imshow(CV)
```

```
plt.colorbar()
```

```
[[ 0.97630072 -0.06816225  0.90813847]
 [-0.06816225  1.03335961  0.96519736]
 [ 0.90813847  0.96519736  1.87333583]]
<matplotlib.colorbar.Colorbar at 0x7fdc7dbed6d8>
```



Generating covariance matrix of correlated data. Taking face images as the data.

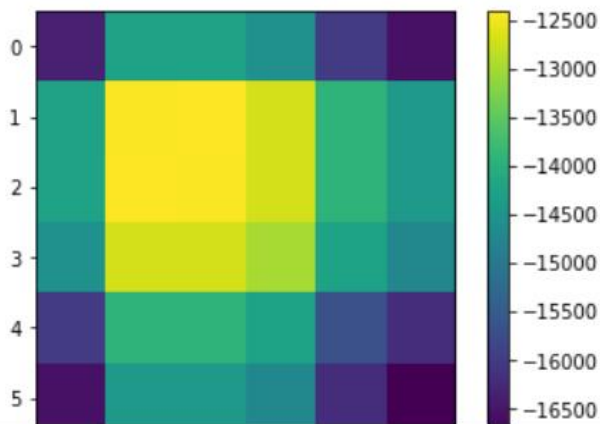
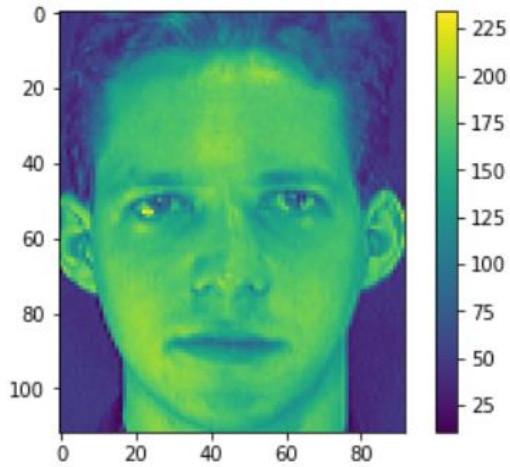
```
X1 = mpimg.imread('f1.pgm')
plt.imshow(X1)
plt.colorbar()
[m,n]=np.shape(X1)
X1 = X1.flatten()
X2 = mpimg.imread('f2.pgm').flatten()
X3 = mpimg.imread('f3.pgm').flatten()
X4 = mpimg.imread('f4.pgm').flatten()
X5 = mpimg.imread('f5.pgm').flatten()
X6 = mpimg.imread('f6.pgm').flatten()

X = np.transpose(np.reshape(np.array([X1,X2,X3,X4,X5,X6]),[6,m*n]))
CV = covmat(X)
print(CV)
fig=plt.figure()
plt.imshow(CV)
plt.colorbar()
[[-16354.60012522 -14246.51604614 -14245.30647319 -14557.76122766
  -15987.5130235  -16533.85277879]
 [-14246.51604614 -12438.46267815 -12414.67478852 -12688.2016277
  -13937.5356198  -14412.66278925]
 [-14245.30647319 -12414.67478852 -12432.98480126 -12686.65473454
  -13933.34908939 -14409.73408491]
 [-14557.76122766 -12688.2016277  -12686.65473454 -12986.96458123
  -14241.61305505 -14728.08677508]]
```

```

[-15987.5130235  -13937.5356198  -13933.34908939 -14241.61305505
 -15669.1158713  -16174.92234759]
[-16533.85277879 -14412.66278925 -14409.73408491 -14728.08677508
 -16174.92234759 -16748.9134148 ]]
<matplotlib.colorbar.Colorbar at 0x7fdc7da78ef0>

```



Showing that data and noise are uncorrelated.

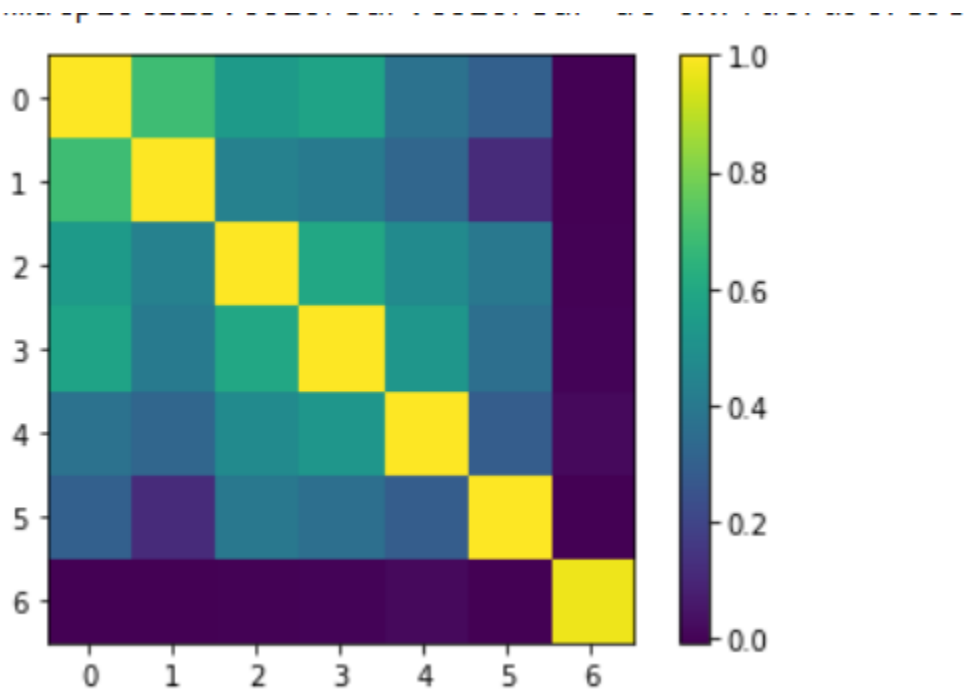
```

X1 = (X1-np.mean(X1))/np.std(X1)
X2 = (X2-np.mean(X2))/np.std(X2)
X3 = (X3-np.mean(X3))/np.std(X3)
X4 = (X4-np.mean(X4))/np.std(X4)
X5 = (X5-np.mean(X5))/np.std(X5)
X6 = (X6-np.mean(X6))/np.std(X6)
m2=np.size(X1)

XN = np.random.normal(0,1,m2)
X = np.transpose(np.reshape(np.array([X1,X2,X3,X4,X5,X6,XN]),[7,m*n]))
CV = covmat(X)
print(CV)
fig=plt.figure()

```

```
plt.imshow(CV)
plt.colorbar()
[[ 1.00000000e+00  6.86364063e-01  5.43393694e-01  5.76192802e-01
   3.72836320e-01  3.00766740e-01 -6.02690863e-03]
 [ 6.86364063e-01  1.00000000e+00  4.36424961e-01  4.08870995e-01
   3.26988068e-01  1.18513726e-01 -4.89635869e-03]
 [ 5.43393694e-01  4.36424961e-01  1.00000000e+00  5.98566612e-01
   4.73639113e-01  3.97086330e-01  4.08574266e-04]
 [ 5.76192802e-01  4.08870995e-01  5.98566612e-01  1.00000000e+00
   5.21458256e-01  3.60153830e-01  2.77972855e-03]
 [ 3.72836320e-01  3.26988068e-01  4.73639113e-01  5.21458256e-01
   1.00000000e+00  2.89964477e-01  2.11497280e-02]
 [ 3.00766740e-01  1.18513726e-01  3.97086330e-01  3.60153830e-01
   2.89964477e-01  1.00000000e+00 -5.08956923e-03]
 [-6.02690863e-03 -4.89635869e-03  4.08574266e-04  2.77972855e-03
   2.11497280e-02 -5.08956923e-03  9.76184233e-01]]
<matplotlib.colorbar.Colorbar at 0x7fdc7d9c7898>
```

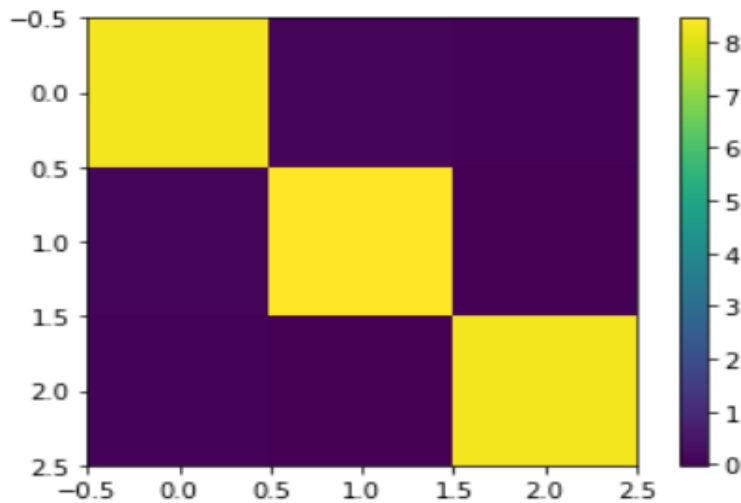


Considering X_1, X_2 and X_3 uniform random variables:

```
M = 2000
X1 = np.random.uniform(0, 10, M)
X2 = np.random.uniform(5, 15, M)
X3 = np.random.uniform(10, 20, M)
X = np.transpose(np.reshape(np.array([X1, X2, X3]), [3, M]))
CV = covmat(X)
print(CV)
fig=plt.figure()
plt.imshow(CV)
```

```
plt.colorbar()
```

```
[[ 8.30369847  0.09571767  0.06347771]
 [ 0.09571767  8.45631545 -0.01710792]
 [ 0.06347771 -0.01710792  8.29650242]]
<matplotlib.colorbar.Colorbar at 0x7fdc7d95fd30>
```



Verifying the properties of the covariance matrix.

a) Symmetric, i.e., $Cx = C^T x$.

```
print(CV - np.transpose(CV))
output:
[[0. 0. 0.]
 [0. 0. 0.]
 [0. 0. 0.]]
```

b) Its eigenvalues are greater than equal to zero

```
from numpy import linalg as LA
[E,U]=LA.eig(CV)
print(U)
output:
[[-0.44813336 -0.73264155  0.51226249]
 [-0.89168562  0.32541693 -0.31464359]
 [-0.06382208  0.59777938  0.79911611]]
```

c) It is positive semi-definite, i.e., for any real valued vector a , $a^T C x a \geq 0$

```
a = np.random.rand(np.size(CV,0),1)
print(np.matmul(np.matmul(np.transpose(a),CV),a))

output:
[[2.6879199]]
```

5. Compute correlation coefficient matrix.

```
def corr(data_mat):  
    [m,n]=np.shape(data_mat)  
    X = data_mat-np.mean(data_mat,axis=0)  
    CV = covmat(X)  
    CR = CV/np.prod(np.std(data_mat,axis=0))  
    return CR  
CR = corr(X)  
print(CR)  
fig=plt.figure()  
plt.imshow(CR)  
plt.colorbar()  
[[ 0.34403108  0.00396569  0.00262995]  
 [ 0.00396569  0.35035416 -0.0007088 ]  
 [ 0.00262995 -0.0007088   0.34373294]]  
<matplotlib.colorbar.Colorbar at 0x7fdc7d8825c0>
```

