

# Offline 02: Hill Climbing and Simulated Annealing

Solve the 8-puzzle problem using **steepest ascent hill climbing algorithm** and **simulated annealing algorithm**.

- The successor of each state is found by moving the blank space to *Left, Right, Up* or *Down*.
- Implement the **#misplace-tiles** and **manhattan-distance** as the heuristic cost  $h(n)$  of a state  $n$ .
- Terminate the algorithm when the goal state is reached or after 300 iterations.
- ~~- The memory requirement of your implementation must be  $O(1)$ .~~
- The schedule function of simulated annealing must be such that as  $t$  increases,  $T$  decreases and eventually becomes 0.
- A template code is available [here](#)
- Run hill climbing for sample inputs using **#misplace-tiles** and **manhattan-distance** and **log the results in [this report](#)**. Similarly, run hill climbing for sample input using **#misplace-tiles** and **manhattan-distance** and **log the results in the same report**.

|   |   |   |
|---|---|---|
| 0 | 1 | 2 |
| 3 | 4 | 5 |
| 6 | 7 | 8 |

Goal state (**Assume 0 means blank**)

Sample Input:

| Sample Input            | Sample output   |
|-------------------------|---|
| 3 1 2<br>6 4 5<br>0 7 8 | Neighbor [[3, 1, 2], [0, 4, 5], [6, 7, 8]] $h=2$<br>Neighbor [[0, 1, 2], [3, 4, 5], [6, 7, 8]] $h=0$<br>Neighbor [[1, 0, 2], [3, 4, 5], [6, 7, 8]] $h=2$<br><br>solution [[0, 1, 2], [3, 4, 5], [6, 7, 8]] $h=0$<br>[Note that you need to follow the sample output format but the actual values may be different depending on the heuristic and the algorithm] |
| 3 1 2<br>6 4 0<br>7 8 5 |   |

## Instructions:

- Read the questions very carefully and answer all parts of the question.
- Your output should match the sample output format. Your code will be tested on other inputs not given in the sample input.
- You will get -100% for adopting any unfair means.
- Your marks will fully depend on your viva and understanding.
  - Total 20 marks
    - Heuristics = 2+4 marks
    - Hill climbing = 6 marks (implementation) + 2 marks (report)
    - Simulated annealing = 4 marks (implementation) + 2 marks (report)
- Submit the .ipynb file

# Pseudocodes

## Steepest ascent hill climbing

```
function HILL-CLIMBING(problem) returns a state that is a local maximum  
current  $\leftarrow$  MAKE-NODE(problem.INITIAL-STATE)  
loop do  
    neighbor  $\leftarrow$  a highest-valued successor of current  
    if neighbor.VALUE  $\leq$  current.VALUE then return current.STATE  
    current  $\leftarrow$  neighbor
```

- Memory requirement  $O(1)$
- If you use heuristic cost instead of heuristic value, then you should pick the lowest-cost successor as neighbor and stop when neighbor cost is higher than current cost.

## Simulated annealing

```
function SIMULATED-ANNEALING(problem, schedule) returns a solution state  
inputs: problem, a problem  
        schedule, a mapping from time to “temperature”  
  
current  $\leftarrow$  MAKE-NODE(problem.INITIAL-STATE)  
for  $t = 1$  to  $\infty$  do  
     $T \leftarrow$  schedule( $t$ )  
    if  $T = 0$  then return current  
    next  $\leftarrow$  a randomly selected successor of current  
     $\Delta E \leftarrow$  next.VALUE - current.VALUE  
    if  $\Delta E > 0$  then current  $\leftarrow$  next  
    else current  $\leftarrow$  next only with probability  $e^{\Delta E/T}$ 
```

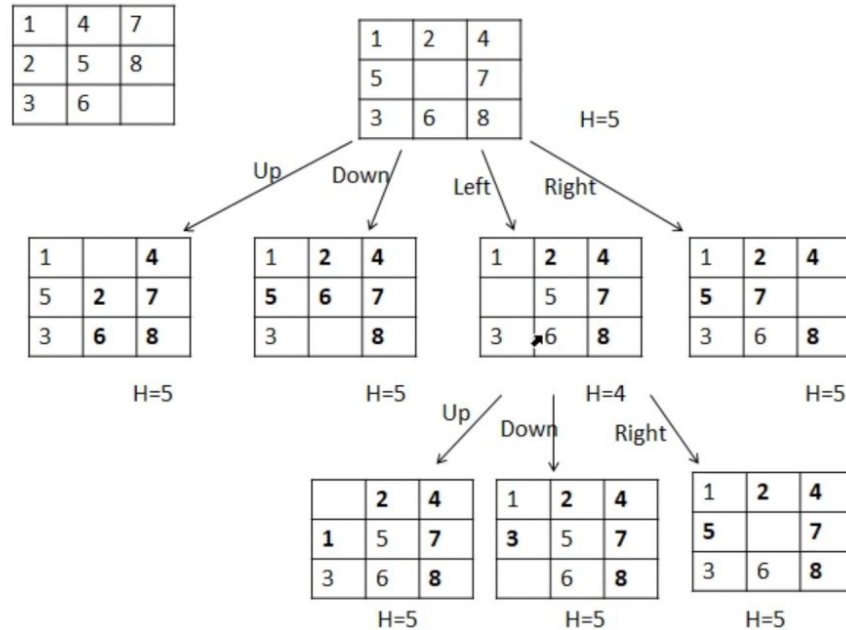
- Memory requirement  $O(1)$
- If you use heuristic cost instead of heuristic value, then  $\Delta E$  should be *current*.cost - *next*.cost.

# Class Lecture:

Heuristic cost and value

Good move and bad move

## 8-puzzle



## Sorting an array

Sort a given array in descending order using **steepest ascent hill climbing** and using **simulated annealing**.

- The value of a state =  $\sum_i \text{number of elements smaller than } A[i] \text{ in index } j > i$   
e.g. value of the state [2 5 -1 4]: 1+2+0+0=3
- The successor of a state is found by swapping a pair of numbers for all possible pairs
  - Successor of state [2 5 -1 4]
    - [5 2 -1 4] value: 3+1+0+0=4
    - [-1 5 2 4]
    - [4 5 -1 2]
    - [2 -1 5 4]

- [ 2 4 -1 5 ]
- [ 2 5 4 -1 ]

## Hill climbing

- No bad moves allowed
- No side away moves allowed

## Simulated Annealing

- Sometimes allows bad moves
- Sometimes allows side away moves
- Simulated annealing maintains a temperature
  - Initially the temperature is high
  - Slowly the temperature decreases
  - When the temperature is high
    - The probability of bad moves is high
  - When the temperature is low
    - The probability of bad move decreases
  - $e^{(-1/500)} = 0.998$
  - $e^{(-1/250)} = 0.996$
  - So, with the decrease of temperature,  $e^{\Delta E/T}$  is decreasing

## Scheduling function

- [A Comparison of Cooling Schedules for Simulated Annealing \(Artificial Intelligence\)](#)
- [Investigation of a Simulated Annealing Cooling Schedule used to Optimize the Estimation of the Fiber Diameter Distribution in a](#)

1. **Exponential Decay**  $T_k = \alpha T_{k-1} \quad 0 < \alpha < 1$

Suppose  $T_0 = 100$  and  $\alpha = 0.9$

Then  $T_1 = 0.9 * 100 = 90$

$T_2 = 0.9 * 90 = 81$

.....

2. **Logarithmic Decay**  $T(t) = \frac{c}{\log(t+d)}$

3. **Linear Decay**  $T_k = T_{k-1} - \text{linear factor}$

*Table 11 Summary of the Best Performing Schedules in Each Category*

|  | Exponential | Logarithmic | Linear | LinEx    | Adaptive |
|--|-------------|-------------|--------|----------|----------|
| Starting Temp                              | 10          | 0.001       | 0.1    | 10       | 10       |
| Number of Transitions per Temperature Step | 500         | 500         | 500    | 500      | 500      |
| Number of Temperature Steps                | 133         | 150         | 200    | 56       | 80       |
| Cooling Ratio                              | 0.9         | N/A         | N/A    | Variable | Variable |
| Decrement Factor                           | N/A         | N/A         | 0.0005 | Variable | N/A      |
| C Value (if applicable)                    | N/A         | 0.001       | N/A    | N/A      | N/A      |
| Stopping Temperature                       | 1.00E-05    | 1.66E-04    | 0      | 1.00E-05 | 1.00E-05 |
| Final Error                                | 0.2104      | 0.2216      | 0.2236 | 0.22     | 0.218    |