

FINITE DIFFERENCE METHOD

Lab Report for Assignment No. 11

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Contents

1 Theory	1
2 Programming	7
3 Results	10

1 Theory

Theory

Date

Finite difference method

→ To Solve 2-Point linear BVP?

Given

$$y''(x) = P(x)y'(x) + Q(x)y(x) + R(x) \quad (1)$$
$$x \in [a, b]$$

Let's start from the Dirichlet conditions.

$$y(a) = \alpha, \quad y(b) = \beta$$

We divide $[a, b]$ in N subintervals corresponding to x_i & the exact value of function = y_i

Now we replace each derivative with the finite difference approximation formula.

$$y''_i(x) = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} + O(h^2)$$

$$y'_i(x) = \frac{y_{i+1} - y_{i-1}}{2h} + O(h^2)$$

So Substituting this in eq (1), we get

$$\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} + O(h^2) = P_i(y_{i+1} - y_{i-1}) + Q_i y_i + R + O(h^2)$$

OR.

$$\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} = \frac{P_i(y_{i+1} - y_{i-1}) + Q_i y_i + R}{2h} \quad (2)$$

To solve these we need two more equations from initial & boundary condition i.e.

$$y(a) = y(x_0) = \alpha, \quad y(b) = y(x_N) = \beta$$

OR we can write the eq(2) as

$$\left(-1 - \frac{h}{2} R_i\right) y_{i-1} + (2 + h^2 Q_i) y_i + \left(-1 + \frac{h}{2} P_i\right) y_{i+1} = -h^2 R_i \quad -(3)$$

As we know $y_0 = \alpha$

Using it we can write.

Putting $i = 1$

$$\left(-1 - \frac{h}{2} P_i\right) y_0 + (2 + h^2 Q_i) y_1 + \left(-1 + \frac{h}{2} P_i\right) y_2 = -h^2 R_i$$

$$\text{OR } \left(-1 - \frac{h}{2} P_i\right) \alpha + (2 + h^2 Q_i) y_1 + \left(-1 + \frac{h}{2} P_i\right) y_2 = -h^2 R_i$$

Similarly we can write the last eq as

$$\left(-1 - \frac{h}{2} P_i\right) y_{i-2} + (2 + h^2 Q_i) y_{i-1} = -h^2 R_i + \left(1 - \frac{h}{2} P_i\right) \beta$$

We can write it in matrix form

$$\begin{bmatrix} d_1 u_1 \\ l_2 d_2 u_2 \\ l_3 d_3 u_3 \\ \vdots \quad \ddots \quad \vdots \\ l_{N-3} d_{N-3} u_{N-3} \\ l_{N-2} d_{N-2} u_{N-2} \\ l_{N-1} d_{N-1} u_{N-1} \end{bmatrix}$$

$$\text{where } d_i = 2 + h^2 Q_i$$

$$u_i = -1 + \frac{h}{2} P_i$$

$$l_i = -1 - \frac{h}{2} P_i$$

with vectors \vec{Y} & \vec{B} as

$$\vec{Y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_{N-2} \\ y_{N-1} \end{bmatrix} \quad \vec{B} = \begin{bmatrix} -h^2 y_1 + (1 + \frac{h}{2} P_1) \alpha \\ -h^2 y_2 \\ \vdots \\ -h^2 y_{N-2} \\ -h^2 y_{N-1} + (1 - \frac{h}{2} P_{N-1}) \beta \end{bmatrix}$$

And thus

$$\vec{Y} = A^{-1} \cdot \vec{B}$$

If we use Newmann OR Robin conditions
we would have.

$$A = \begin{bmatrix} a_{11} & a_{12} & & & & \\ l_1 & c_l & u_1 & & & \\ l_2 & c_l & u_2 & & & \\ \ddots & \ddots & \ddots & \ddots & & \\ l_{N-1} & c_{N-1} & u_{N-1} & & & \\ & d_{N+1} & q_{N+1, N+1} & & & \end{bmatrix}$$

$$\vec{B} = \begin{bmatrix} b_1 \\ -h^2 b_1 \\ -h^2 b_2 \\ \vdots \\ \vdots \\ -h^2 b_{N-1} \\ b_{N+1} \end{bmatrix}$$

where

$$d_i = 2 + h^2 \alpha_i$$

$$u_i = -\frac{b+h}{2} p_i, \quad l_i = -\frac{1-h}{2} p_i$$

2

$$a_{11} = \begin{cases} 1 & \text{Dirichlet B.C.} \\ cb & \text{Newmann} \\ cl_0 + 2hb \frac{\alpha_1}{\alpha_2} & \text{Robin.} \end{cases}$$

$$a_{12} = \begin{cases} 0 & \text{Dirichlet} \\ -2 & \text{otherwise} \end{cases}$$

$$a_{N+1, N+1} = \begin{cases} 1 & \text{Dirichlet} \\ cl_N & \text{newmann} \\ cl_N - 2hu_N \frac{\beta_1}{\beta_2} & \text{Robin} \end{cases}$$

$$b_1 = \begin{cases} \alpha & \text{Dirichlet} \\ -h^2 \gamma_0 + 2hb_0 \alpha_2 & \text{Newmann} \\ -h^2 \gamma_0 + 2hb_0 \frac{\alpha_3}{\alpha_2} & \text{Robin} \end{cases}$$

$$b_{N+1} = \begin{cases} \beta & \text{Dirichlet} \\ -h^2 \gamma_N - 2hu_N \beta & \text{Newmann} \\ -h^2 \gamma_N - 2hu_N \frac{\beta_3}{\beta_2} & \text{Robin} \end{cases}$$

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(b) Eq. $-y'' + \pi^2 y = 2\pi^2 \sin(\pi x)$, $x \in [0, 1]$

$$p(x) = 0 = \rho_i$$

$$q(x) = \pi^2 = q_i$$

$$r(x) = -2\pi^2 \sin(\pi x)$$

$$h = \frac{1-0}{N}$$

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ -1 & 2 + (\pi/4)^2 & -1 & 0 & 0 \\ 0 & -1 & 2 + (\pi/4)^2 & -1 & 0 \\ 0 & 0 & -1 & 2 + (\pi/4)^2 & -1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 \\ \pi^2/16 \\ 2(\pi/4)^2 \\ \pi^2/16 \\ 0 \end{bmatrix} \quad \& \quad X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}$$

Solution :: $Ax = B$
 $x = A^{-1}B$

$$x = \begin{bmatrix} 0 \\ 0.725371 \\ 1.0259 \\ 0.725470 \\ 0 \end{bmatrix}$$

2 Programming

```
1 #KABIR SETHI ;2020PHY1097
2 #PAWANPREET KAUR ;2020PHY1092
3 import numpy as np
4 import pandas as pd
5 import matplotlib.pyplot as plt
6
7 print("KABIR SETHI ;2020PHY1097")
8 print("PAWANPREET KAUR ;2020PHY1092")
9
10 def solve(l,d,u,B):
11     #l = Lower Diagnol , d = Main Diagnol , u = Upper Diagnol , B = solution vector
12     n = len(B)
13     w = np.zeros(n-1)
14     g = np.zeros(n)
15     x = np.zeros(n)
16     w[0] = u[0]/d[0]
17     g[0] = B[0]/d[0]
18     for i in range(1,n-1):
19         w[i] = u[i]/(d[i] - l[i-1]*w[i-1])
20     for i in range(1,n):
21         g[i] = (B[i] - l[i-1]*g[i-1])/(d[i] - l[i-1]*w[i-1])
22     x[n-1] = g[n-1]
23     for i in range(n-1,0,-1):
24         x[i-1] = g[i-1] - w[i-1]*x[i]
25     return x
26
27 def FiniteDifference(a,b, , ,N,p,q,r,y,key,c1,c2):
28     h = (b-a)/N #size of each subinterval
29     x = []
30     W = []
31     Y = []
32     l=[]
33     err = []
34     for i in range(0,N+1):
35         x.append(a + i*h)
36     if c1 == 'd':
37         B = [  [0]]
38         d = [1]
39         u = [0]
40     elif c1 == 'n':
41         B = [-h*h*r(x[0]) + 2*h*(-1-h*p(x[0])/2)*(  [0])]
42         d = [2+h*h*q(x[0])]
43         u = [-2]
44     elif c1 == 'r':
45         B = [-h*h*r(x[0]) + 2*h*(-1-h*p(x[0])/2)*(  [2]/  [1])]
46         d = [2+h*h*q(x[0]) + 2*h*(-1-h*p(x[0])/2)*(  [0]/  [1])]
47         u = [-2]
48     for i in range(1,N):
49         d.append(2+h*h*q(x[i]))
50         u.append(-1+h*p(x[i])/2)
51         l.append(-1-h*p(x[i])/2)
52         B.append(-h*h*r(x[i]))
53     if c2 == 'd':
54         B.append( [0])
55         d.append(1)
56         l.append(0)
57     elif c2 == 'n':
58         B.append(-h*h*r(x[N]) - 2*h*(-1+h*p(x[N])/2)*(  [0]))
59         d.append(2+h*h*q(x[N]))
60         l.append(-2)
```

```

61 elif c2 == 'r':
62     B.append(-h*h*r(x[N]) - 2*h*(-1+h*p(x[N])/2)*( [2]/ [1]))
63     d.append(2+h*h*q(x[N]) - 2*h*(-1+h*p(x[N])/2)*( [0]/ [1]))
64     l.append(-2)
65 W = solve(l,d,u,B)
66 Y = []
67 err = []
68 for i in range(0, N+1):
69     Y.append(y(x[i]))
70     err.append(abs(Y[i]-W[i]))
71 if key==1:
72     print(f"Analysis for N={N}")
73     data = {"x" : x, "w" : W, "y" : Y, "Error" : err}
74     table = pd.DataFrame(data)
75     print(table)
76 return W, max(err), x
77
78 def Analysis(Ns, name):
79     max_err_for_N = []
80     err_ratio = [ " "]
81     for i in range(0,8):
82         W, err, x = FiniteDifference(a,b, , ,Ns[i],p,q,r,y,0,c1,c2)
83         max_err_for_N.append(err)
84         plt.plot(x,W,label=f"N = {Ns[i]}")
85         if i!=0:
86             err_ratio.append(max_err_for_N[i-1]/max_err_for_N[i])
87 x = np.linspace(a,b,1000)
88 Y = []
89 for i in range(0,len(x)):
90     Y.append(y(x[i]))
91 plt.plot(x,Y,label="Analytic",color="black")
92 plt.xlabel("x")
93 plt.ylabel("y")
94 plt.title("Variation of solution with N")
95 plt.legend()
96 plt.grid()
97 plt.savefig(f"Solution_{name}.pdf")
98 plt.show()
99 data1 = {"N" : Ns, "max abs err" : max_err_for_N, "err ratio" : err_ratio}
100 table1 = pd.DataFrame(data1)
101 print(table1)
102 plt.scatter(Ns,max_err_for_N)
103 plt.xlabel("No. of subintervals")
104 plt.ylabel("Max. absolute error")
105 plt.title("N vs Max abs error")
106 plt.xscale("log")
107 plt.yscale("log")
108 plt.grid()
109 plt.savefig(f"Analysis_{name}.pdf")
110 plt.show()
111
112 #Q1
113 print("Eqn 1")
114 a = 0
115 b = 1
116 = [0]
117 = [0]
118 c1 = 'd'
119 c2 = 'd'
120 name = "Q1"
121 p = lambda x : 0
122 q = lambda x : np.pi*np.pi

```

```

123 r = lambda x : -2*np.pi*np.pi*np.sin(np.pi*x)
124 y = lambda x : np.sin(np.pi*x)
125
126 W, err, x = FiniteDifference(a,b, , 3,p,q,r,y,1,c1,c2)
127 W, err, x = FiniteDifference(a,b, , 8,p,q,r,y,1,c1,c2)
128
129 Ns = []
130 for i in range(2,10):
131     Ns.append(pow(2,i))
132
133 Analysis(Ns, name)
134 print("-----")
135 #Q2
136 print("Eqn 2")
137 a = 0
138 b = np.pi/2
139 = [1,1,-1]
140 = [1]
141 c1 = 'r'
142 c2 = 'n'
143 name = "Q2"
144 p = lambda x : 0
145 q = lambda x : -1
146 r = lambda x : np.sin(3*x)
147 y = lambda x : -1*np.cos(x) + (3/8)*np.sin(x) - (1/8)*np.sin(3*x)
148
149 W, ErrArr, x = FiniteDifference(a,b, , 3,p,q,r,y,1,c1,c2)
150 W, ErrArr, x = FiniteDifference(a,b, , 8,p,q,r,y,1,c1,c2)
151
152 Ns = []
153 for i in range(2,10):
154     Ns.append(pow(2,i))
155
156 Analysis(Ns, name)

```

3 Results

Equation 1

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Eqn 1

Analysis for N=3

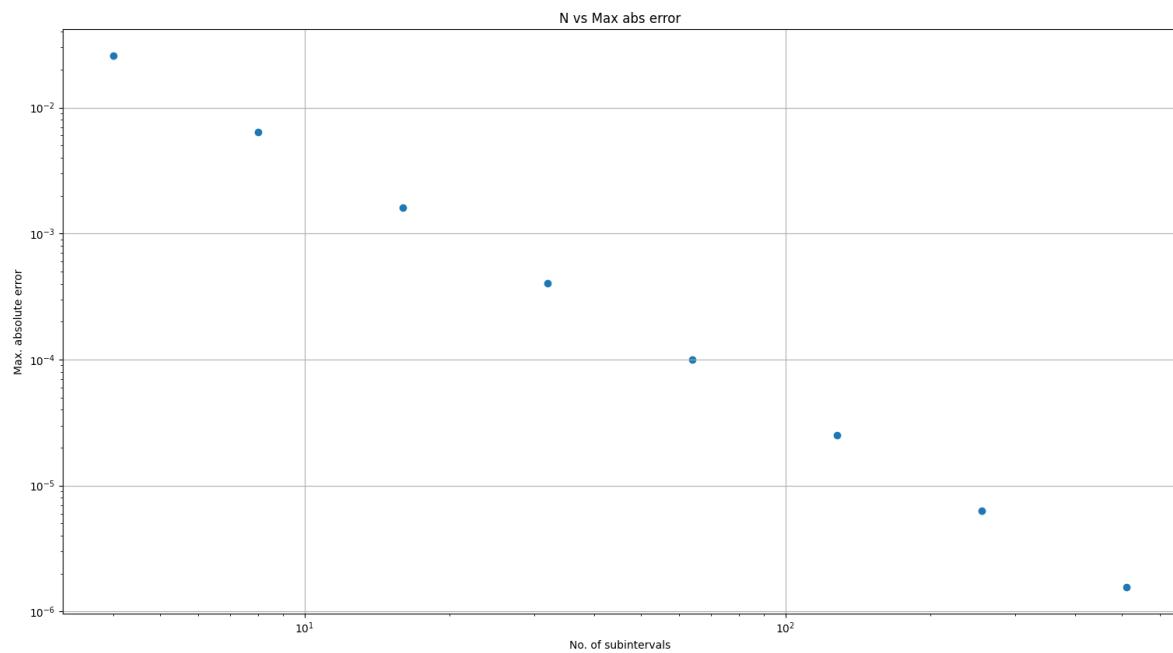
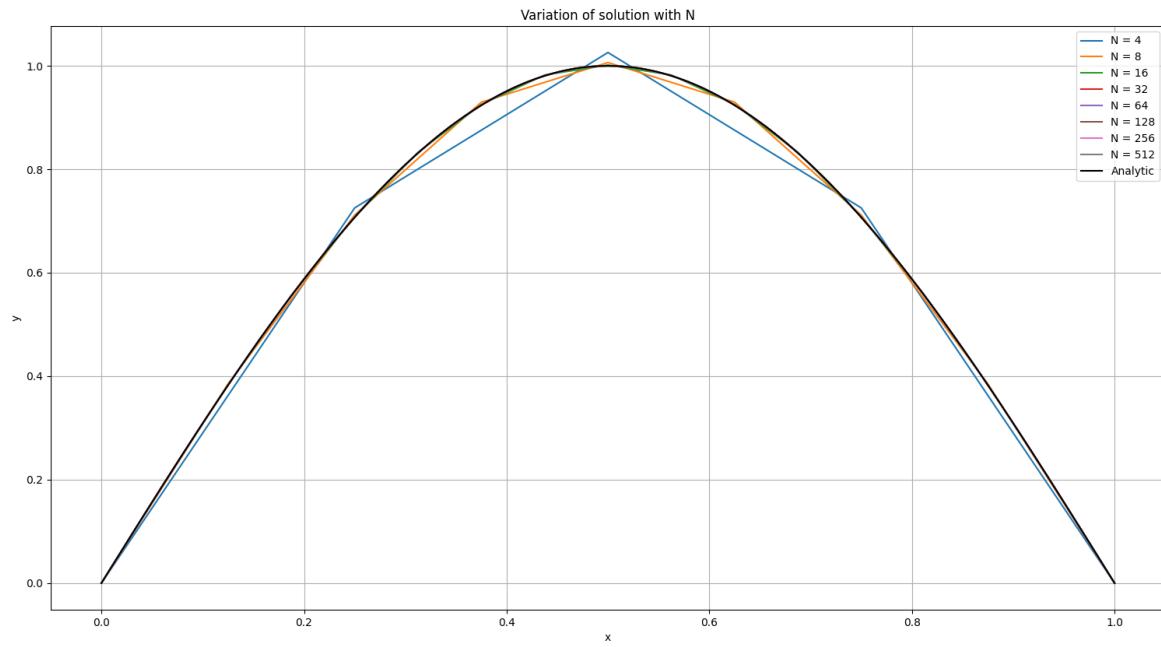
	x	w	y	Err or
0	0.000000	0.000000	0.000000e+00	0.000000e+00
1	0.333333	0.905936	8.660254e-01	3.991072e-02
2	0.666667	0.905936	8.660254e-01	3.991072e-02
3	1.000000	0.000000	1.224647e-16	1.224647e-16

Analysis for N=8

	x	w	y	Err or
0	0.000	0.000000	0.000000e+00	0.000000e+00
1	0.125	0.385146	3.826834e-01	2.462075e-03
2	0.250	0.711656	7.071068e-01	4.549322e-03
3	0.375	0.929824	9.238795e-01	5.943975e-03
4	0.500	1.006434	1.000000e+00	6.433713e-03
5	0.625	0.929824	9.238795e-01	5.943975e-03
6	0.750	0.711656	7.071068e-01	4.549322e-03
7	0.875	0.385146	3.826834e-01	2.462075e-03
8	1.000	0.000000	1.224647e-16	1.224647e-16

N max abs err err ratio

0	4	0.025830	
1	8	0.006434	4.014754
2	16	0.001607	4.003814
3	32	0.000402	4.000961
4	64	0.000100	4.000241
5	128	0.000025	4.00006
6	256	0.000006	4.000015
7	512	0.000002	4.0



Equation 2

Eqn 2

Analysis for N=3

	x	w	y	E _{rr} tot
0	0.000000	-1.042963	-1.000000	0.042963
1	0.523599	-0.877501	-0.803525	0.073975
2	1.047198	-0.197311	-0.175240	0.022070
3	1.570796	0.536973	0.500000	0.036973

Analysis for N=8

	x	w	y	E _{rr} tot
0	0.000000	-1.005803	-1.000000	0.005803
1	0.196350	-0.985275	-0.977073	0.008202
2	0.392699	-0.905343	-0.895858	0.009485
3	0.589049	-0.754888	-0.745729	0.009159
4	0.785398	-0.537518	-0.530330	0.007188
5	0.981748	-0.272164	-0.268155	0.004008
6	1.178097	0.011205	0.011607	0.000402
7	1.374447	0.279388	0.276638	0.002750
8	1.570796	0.504744	0.500000	0.004744

N max abs err err ratio

0	4	0.039587	
1	8	0.009485	4.173755
2	16	0.002359	4.021065
3	32	0.000590	3.998218
4	64	0.000147	4.002605
5	128	0.000037	3.999585
6	256	0.000009	4.000162
7	512	0.000002	4.000031

