

TRESC数学

$$(G \cdot P) V (G \cdot P)$$

$$= I_2 P_x V P_x + I_2 P_y V P_y + I_2 P_z V P_z \\ + i G_z (P_x V P_y - P_y V P_x) \\ + i G_y (P_x V P_z - P_z V P_x) \\ + i G_x (P_y V P_z - P_z V P_y)$$

$$\sqrt{\frac{\epsilon_i \epsilon_j}{\epsilon_k}} (G \cdot P) V \sqrt{\frac{\epsilon_i \epsilon_j}{\epsilon_k}} (G \cdot P) \quad V \text{ 的两边对称, 算符厄米}$$

$$= I_2 \sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x V \sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x + I_2 \sqrt{\frac{\epsilon_x \epsilon_z}{\epsilon_y}} P_y V \sqrt{\frac{\epsilon_x \epsilon_z}{\epsilon_y}} P_y + I_2 \sqrt{\frac{\epsilon_x \epsilon_y}{\epsilon_z}} P_z V \sqrt{\frac{\epsilon_x \epsilon_y}{\epsilon_z}} P_z \\ + i G_z \left(\sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x V \sqrt{\frac{\epsilon_x \epsilon_z}{\epsilon_y}} P_y - \sqrt{\frac{\epsilon_x \epsilon_z}{\epsilon_y}} P_y V \sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x \right) \\ + i G_y \left(\sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x V \sqrt{\frac{\epsilon_x \epsilon_y}{\epsilon_z}} P_z - \sqrt{\frac{\epsilon_x \epsilon_y}{\epsilon_z}} P_z V \sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x \right) \\ + i G_x \left(\sqrt{\frac{\epsilon_x \epsilon_z}{\epsilon_y}} P_y V \sqrt{\frac{\epsilon_x \epsilon_y}{\epsilon_z}} P_z - \sqrt{\frac{\epsilon_x \epsilon_y}{\epsilon_z}} P_z V \sqrt{\frac{\epsilon_x \epsilon_z}{\epsilon_y}} P_y \right)$$

$$\epsilon_x = \frac{1}{\sqrt{1 - \frac{c^2}{\epsilon^2} P_x^2}} = 1 + \frac{P_x^2}{2c^2} \quad (\text{到 } c^{-2} \text{ 阶})$$

$$\therefore \sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} = 1 + \frac{P_y^2}{4c^2} + \frac{P_z^2}{4c^2} - \frac{P_x^2}{4c^2} = 1 + \frac{1}{4c^2} (P^2 - 2P_x^2) \quad (\text{到 } c^{-2} \text{ 阶})$$

以 $\sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x V \sqrt{\frac{\epsilon_y \epsilon_z}{\epsilon_x}} P_x$ 为例, 化为:

$$\left[1 + \frac{1}{4c^2} (P^2 - 2P_x^2) \right] P_x V \left[1 + \frac{1}{4c^2} (P^2 - 2P_x^2) \right] P_x$$

$$\begin{aligned}
 & \left[1 + \frac{1}{4c^2}(P^2 - 2P_x^2) \right] P_x V \left[1 + \frac{1}{4c^2}(P^2 - 2P_x^2) \right] P_x \\
 &= P_x V P_x + \frac{1}{4c^2}(P^2 - 2P_x^2) P_x V P_x + \frac{1}{4c^2} P_x V P_x (P^2 - 2P_x^2) \quad (\text{到 } c^{-2} \text{ 阶}) \\
 &= P_x V P_x + \frac{1}{4c^2} P^2 P_x V P_x + \frac{1}{4c^2} P_x V P_x P^2 \\
 &\quad - \frac{1}{2c^2} P_x^2 P_x V P_x - \frac{1}{2c^2} P_x V P_x^2 P_x
 \end{aligned}$$

P^2 用 $\langle p^2 \rangle$ 本征空间描述.

所以要算的有:

$$P_x V P_x, P_y V P_y, P_z V P_z, P_x^3 V P_x, P_x V P_x^3, P_y^3 V P_y, P_y V P_y^3, P_z^3 V P_z, P_z V P_z^3$$

$$P_x V P_y, P_y V P_x, P_x^3 V P_y, P_x V P_y^3, P_y^3 V P_x, P_y V P_x^3$$

$$P_x V P_z, P_z V P_x, P_x^3 V P_z, P_x V P_z^3, P_z^3 V P_x, P_z V P_x^3$$

$$P_z V P_y, P_y V P_z, P_z^3 V P_y, P_z V P_y^3, P_y^3 V P_z, P_y V P_z^3$$

共 **27** 个 PVP 矩阵元! 这些矩阵元之间不可约分.

$$(\langle X_i | P_x V P_z | X_j \rangle)^{\dagger} \stackrel{\text{实}}{=} P_x V P_z |ij$$

$$= \langle X_j | P_z V P_x | X_i \rangle$$

$$= P_z V P_x |ji$$

$$(\langle X_i | P_x^3 V P_z | X_j \rangle)^{\dagger} \stackrel{\text{实}}{=} P_x^3 V P_z |ij$$

$$= \langle X_j | P_z V P_x^3 | X_i \rangle$$

$$= P_z V P_x^3 |ji$$

PVP 和 P^3VP , PVP^3
都是非对称实矩阵
但都只需算半对角.

$$\begin{aligned}
& \langle X_i | P_x V P_z | X_j \rangle \\
&= \langle X_i | (-i\partial_x)^\dagger V (-i\partial_z) | X_j \rangle \\
&= \langle X_i | -i\partial_x V (-i\partial_z) | X_j \rangle \\
&= -\langle X_i | \partial_x V \partial_z | X_j \rangle
\end{aligned}$$

P^2, PVP 要取负

$$\begin{aligned}
& \langle X_i | P_x^3 V P_z | X_j \rangle \\
&= \langle X_i | (-i\partial_x)^{\dagger 3} V (-i\partial_z) | X_j \rangle \\
&= \langle X_i | -i(-\partial_x^3) V (-i\partial_z) | X_j \rangle \\
&= \langle X_i | \partial_x^3 V \partial_z | X_j \rangle
\end{aligned}$$

P^3VP, PVP^3 不取负

注意:

$$\begin{aligned}
\langle X_i | \partial_x^\dagger \partial_x | X_j \rangle &= \int dx \langle X_i | \partial_x^\dagger | x \rangle \langle x | \partial_x | X_j \rangle \\
&= \int dx \left(\frac{\partial}{\partial x} X_i(x) \right) \left(\frac{\partial}{\partial x} X_j(x) \right) \\
\langle X_i | \partial_x \partial_x^\dagger | X_j \rangle &= \int dx \langle X_i | x \rangle \langle x | \frac{\partial^2}{\partial x^2} | X_j \rangle \\
&= \int dx X_i(x) \frac{\partial^2}{\partial x^2} X_j(x) \\
&= \int dx \left(\frac{\partial}{\partial x} X_j(x) \right) X_i(x) \\
&= X_i(x) \frac{\partial}{\partial x} X_j(x) \Big|_{-\infty}^{+\infty} - \int dx \frac{\partial}{\partial x} X_j(x) \frac{\partial}{\partial x} X_i(x) \\
&\stackrel{\text{边界}}{=} - \int dx \frac{\partial}{\partial x} X_j(x) \frac{\partial}{\partial x} X_i(x) \\
&= -\langle X_i | \partial_x^\dagger \partial_x | X_j \rangle
\end{aligned}$$

所以用两边作用方式计算的其实正是 $-\nabla^2$ 阵, 不用再取负.

故: $\langle X_i | P_x V P_z | X_j \rangle = -\langle X_i | \partial_x V \partial_z | X_j \rangle = \langle X_i | \partial_x^\dagger V \partial_z | X_j \rangle$ P^2, PVP 不取负

$\langle X_i | P_x^3 V P_z | X_j \rangle = \langle X_i | \partial_x^3 V \partial_z | X_j \rangle = -\langle X_i | \partial_x^{\dagger 3} V \partial_z | X_j \rangle$ P^3VP, PVP^3 要取负

$x_i \rightarrow x_j$ transfer formula:

$$I_x(n_i, n_j) = I_x(n_i+1, n_j-1) + (x_i - x_j) I_x(n_i, n_j-1)$$

$$I_x(n_i, n_j-1) = I_x(n_i+1, n_j-2) + (x_i - x_j) I_x(n_i, n_j-2)$$

\vdots

$$I_x(n_i, 1) = I_x(n_i+1, 0) + (x_i - x_j) I_x(n_i, 0)$$

$$\therefore I_x(n_i, n_j) = I_x(n_i+2, n_j-2) + 2(x_i - x_j) I_x(n_i+1, n_j-2) \\ + (x_i - x_j)^2 I_x(n_i, n_j-2)$$

$$= I_x(n_i+3, n_j-3) + 3(x_i - x_j) I_x(n_i+2, n_j-3)$$

$$+ 3(x_i - x_j)^2 I_x(n_i+1, n_j-3) + (x_i - x_j)^3 I_x(n_i, n_j-3)$$

$$= I_x(n_i+4, n_j-4) + 4(x_i - x_j) I_x(n_i+3, n_j-4)$$

$$+ 6(x_i - x_j)^2 I_x(n_i+2, n_j-4) + 4(x_i - x_j)^3 I_x(n_i+1, n_j-4)$$

$$+ (x_i - x_j)^4 I_x(n_i, n_j-4) \quad \uparrow \text{binomial coefficient.}$$

\vdots

$$I_x(n_i, n_j) = \sum_{k=0}^{n_j} C_{n_j}^k (x_i - x_j)^k I_x(n_i + n_j - k, 0)$$

j 分量

\nearrow 不是 k 分量

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$$\int_{-\infty}^{+\infty} e^{-b(x-x_0)^2} dx = \sqrt{\frac{\pi}{b}}$$

Gaussian Production Rule.

$$e^{-b_1(x-x_1)^2} e^{-b_2(x-x_2)^2} = e^{-(b_1+b_2)(x-x_p)^2} e^{-\left(\frac{x_1-x_2}{\frac{1}{b_1}+\frac{1}{b_2}}\right)^2}$$

s-shell χ_i

$$x_p = \frac{x_2 \frac{1}{b_1} + x_1 \frac{1}{b_2}}{\frac{1}{b_1} + \frac{1}{b_2}} = \frac{x_2 b_2 + x_1 b_1}{b_1 + b_2}$$

$$\frac{2}{\sqrt{\pi}} \int_0^\infty du \int_{-\infty}^\infty dx e^{-b_i(x-x_i)^2} e^{-b_j(x-x_j)^2} e^{-b_k(x'-x_k)^2} e^{-b_l(x'-x_l)^2} e^{-u^2(x_i-x_l)^2}$$

$$= \frac{2}{\sqrt{\pi}} e^{-Gx} \int_0^\infty du \int_{-\infty}^\infty dx e^{-A(x-x_A)^2} e^{-B(x'-x_B)^2} e^{-u^2(x-x')^2}$$

for x :

$$= \frac{2}{\sqrt{\pi}} e^{-Gx} \int_0^\infty du \int_{-\infty}^\infty dx' \sqrt{\frac{\pi}{A+u^2}} e^{-\frac{Au^2}{A+u^2}(x'-x_A)^2} e^{-B(x'-x_B)^2}$$

for x' :

$$= \frac{2}{\sqrt{\pi}} e^{-Gx} \int_0^\infty du \sqrt{\frac{\pi}{A+u^2}} \sqrt{\frac{\pi}{\frac{Au^2}{A+u^2} + B}} e^{-\frac{u^2 AB}{AB + u^2 A + u^2 B}(x_A^2 - x_B^2)}$$

$u \rightarrow t$

xy 都有

$$= 2 e^{-Gx} \sqrt{\frac{P}{\pi}} \int_0^1 dt \left(\frac{1}{1-t^2}\right)^{\frac{3}{2}} \frac{\pi}{NAB} \sqrt{1-t^2} e^{-D_x t^2}$$

$$= 2 e^{-Gx} \sqrt{\frac{P}{\pi}} \int_0^1 dt \frac{\pi}{NAB} e^{-D_x t^2}$$

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Hess的RI算法是否靠谱?

假设基组 $|x_i\rangle$ 完备, 经 Ω 作用得到 p^2 空间本征态.

$$\Omega|x_i\rangle = |p_i\rangle, \quad \langle p_i | \hat{p}^2 | p_j \rangle = p_i^2 \delta_{ij}$$

考虑到基组 $|x_i\rangle$ 不是归一化的, 所以我们只能保证 $|p_i\rangle$ 是归一化的(但可以保证正交), 故多出重叠积分项 $\langle p_i | p_j \rangle = \delta_{ij}$

厄米算符不同本征值的本征态正交.

对于任意算符矩阵 $\langle p_i | \hat{A} | p_j \rangle$, 有:

$$\langle p_i | \hat{A} | p_j \rangle = \langle x_i | \Omega^\dagger \hat{A} \Omega | x_j \rangle = \iint dx_1 dx_2 \langle x_i | x_1 \rangle \Omega^\dagger \langle x_1 | \hat{A} | x_2 \rangle \Omega \langle x_2 | x_j \rangle = \int dx \langle x_i | x \rangle \Omega^\dagger \langle x | \hat{A} | x \rangle \Omega \langle x | x_j \rangle$$

并非对 $|x\rangle$ 的正变换

现在我们希望向复合算符矩阵中插入Identity:

$$\hat{I}|\psi\rangle = \hat{I} \sum_n f_n |p_n\rangle = \sum_m f_m |p_m\rangle \langle p_m | p_n \rangle = \sum_n f_n |p_n\rangle \neq |\psi\rangle$$

所以我们必须将Identity算符修正为:

$$\hat{I} = \sum_m \frac{1}{s_m} |p_m\rangle \langle p_m| \quad \text{----- ①}$$

故对复合算符矩阵的简单化操作为:

$$\langle p_i | \hat{A} \hat{B} | p_j \rangle = \sum_m \langle p_i | \hat{A} | p_m \rangle \langle p_m | \hat{B} | p_j \rangle / s_m \quad \text{----- ②}$$

另外一种更常见的场景是, 我们首先算算符 \hat{A} 在基组下矩阵 $\langle x_i | \hat{A} | x_j \rangle$, 然后再得之对角化(求本征矢), 这样得到的实际上并不是算符 \hat{A} 本征空间表示, 很容易证明对于酉变换 Ω :

$$\langle x_j | \Omega^\dagger \hat{A} \Omega | x_i \rangle = \langle x_j | \sum_{j=1}^N c_{j\mu} \hat{A} \sum_{i=1}^N c_{\nu i} | x_i \rangle \neq \sum_{j=1}^N \sum_{i=1}^N c_{\mu j} \langle x_j | \hat{A} | x_i \rangle c_{\nu i} = \Omega^\dagger \langle x_j | \hat{A} | x_i \rangle \Omega$$

而且对于非正交基 $\langle x_i | x_j \rangle \neq \delta_{ij}$, 无法通过酉变换使之成为Hermitian算符本征矢(酉变换是保内积的), 这明显与 $\Omega^\dagger \langle x_i | \hat{A} | x_j \rangle \Omega$ 可以实现对角化相悖. 但是, 这种“外对角化”的操作也确实可以简化复杂算符矩阵的计算, 如DKH Hamiltonian中对 p^2 矩阵元的外对角化。

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外对归化插入的Identity可以表示为 $|X_m\rangle\Omega \neq \Omega|X_m\rangle$, 区别于本征矢的Identity.

$$\hat{I}|\psi\rangle = \hat{I} \sum_n f_n |X_n\rangle = \sum_{mn} f_n \frac{|X_m\rangle\Omega\Omega^\dagger\langle X_m|}{S_{mm}} |X_n\rangle = \sum_n f_n \left(\sum_m \frac{S_{mn}|X_m\rangle}{S_{mm}} \right) \approx \sum_n f_n |X_n\rangle = |\psi\rangle$$

$$\therefore \hat{I} = \sum_m \frac{1}{S_m} |X_m\rangle\langle X_m|, S_m = \langle X_m|X_m\rangle \dots\dots\dots (3)$$

所以仍然可以通过②式对复合算符矩阵元简单化, 这样操作前提是接受基组不正交引起的误差.

除非我们效仿Hamiltonian的对角化方法, 借助Löwdin矩阵正交化处理 P^2 和其它矩阵, 这样就可插入一个真正的Identity.

$$I = \sum_m |X_m\rangle S^{-\frac{1}{2}} \Omega \Omega^\dagger (S^{-\frac{1}{2}})^\dagger \langle X_m|$$

注意此处 Ω 变成对 $(S^{-\frac{1}{2}})^\dagger \langle P^2 \rangle (S^{-\frac{1}{2}})$ 的对角化矩阵, 而且这样处理后单电子Fock矩阵就不需要再进行

Löwdin正交化操作了. $S^{-\frac{1}{2}}$ 求法: 设 $U^\dagger S U = \Lambda$, $\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$, 则 $\Lambda^{-\frac{1}{2}} = \begin{pmatrix} \lambda_1^{-\frac{1}{2}} & & \\ & \ddots & \\ & & \lambda_n^{-\frac{1}{2}} \end{pmatrix}$, 则有:

$$(U\Lambda^{-\frac{1}{2}}U^\dagger)(U\Lambda^{-\frac{1}{2}}U^\dagger) = U\Lambda^{-1}U^\dagger \stackrel{U^\dagger=U^{-1}}{=} (U\Lambda U^\dagger)^{-1} = S^{-1}$$

因此 $U^\dagger\Lambda^{-\frac{1}{2}}U$ 即所求矩阵.

↑
Löwdin[†]

↑
Löwdin

$S_{0.5}$ 是对称阵.

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复密度矩阵计算

$$\sum_j^{\text{occ}} C_{\sigma j} C_{\lambda j}^* = \sum_j^{\text{occ}} (R_{\sigma j} + i I_{\sigma j}) (R_{\lambda j} - i I_{\lambda j})$$

$$= \sum_j^{\text{occ}} R_{\sigma j} R_{\lambda j} - i I_{\lambda j} R_{\sigma j} + i I_{\sigma j} R_{\lambda j} + I_{\sigma j} I_{\lambda j}$$

$$\sum_j^{\text{occ}} C_{\lambda j} C_{\sigma j}^* = \sum_j^{\text{occ}} R_{\lambda j} R_{\sigma j} + i I_{\lambda j} R_{\sigma j} - i I_{\sigma j} R_{\lambda j} + I_{\lambda j} I_{\sigma j}$$

} 厄米 ✓

$$\sum_j^{\text{occ}} C_{\sigma j} C_{j\lambda}^* = \sum_j^{\text{occ}} (R_{\sigma j} + i I_{\sigma j}) (R_{j\lambda} - i I_{j\lambda})$$

$$= \sum_j^{\text{occ}} R_{\sigma j} R_{j\lambda} - i I_{j\lambda} R_{\sigma j} + i I_{\sigma j} R_{j\lambda} + I_{\sigma j} I_{j\lambda}$$

$$\sum_j^{\text{occ}} C_{\lambda j} C_{j\sigma}^* = \sum_j^{\text{occ}} R_{\lambda j} R_{j\sigma} + i I_{\lambda j} R_{j\sigma} - i I_{j\sigma} R_{\lambda j} + I_{\lambda j} I_{j\sigma}$$

} 不厄米

复密度矩阵下的PG2计算

$$PG2 = \sum_{\mu\nu} \rho_{\mu\nu} G_{\nu\mu} = \dots + \rho_{\mu\nu} G_{\nu\mu} + \dots + \rho_{\nu\mu} G_{\mu\nu} + \dots$$

$$\text{其中 } \rho_{\mu\nu} G_{\nu\mu} + \rho_{\nu\mu} G_{\mu\nu} = (\rho_{\mu\nu}^R + i \rho_{\mu\nu}^I)(G_{\nu\mu}^R + i G_{\nu\mu}^I) + (\rho_{\nu\mu}^R + i \rho_{\nu\mu}^I)(G_{\mu\nu}^R + i G_{\mu\nu}^I)$$

$$\underline{\text{P.G厄米}} \quad (\rho_{\mu\nu}^R + i \rho_{\mu\nu}^I)(G_{\nu\mu}^R + i G_{\nu\mu}^I) + (\rho_{\mu\nu}^R - i \rho_{\mu\nu}^I)(G_{\nu\mu}^R - i G_{\nu\mu}^I)$$

$$= \rho_{\mu\nu}^R G_{\nu\mu}^R - \rho_{\mu\nu}^I G_{\nu\mu}^I + \rho_{\nu\mu}^R G_{\mu\nu}^R - \rho_{\nu\mu}^I G_{\mu\nu}^I$$

实部保留, 虚部抵消.

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开壳层GGA泛函的KS矩阵元计算.

$$\text{已知: } E^{\text{xc}} = \int \varepsilon(\rho_{\alpha}(\vec{r}), \rho_{\beta}(\vec{r}), \nabla \rho_{\alpha}(\vec{r}), \nabla \rho_{\beta}(\vec{r}), \nabla \rho_{\beta\beta}(\vec{r})) d\vec{r}$$

$$\text{其中 } \nabla \rho_{\alpha\beta} = \vec{\nabla} \rho_{\alpha} \cdot \vec{\nabla} \rho_{\beta} \dots$$

$$\text{且有 } V_{\alpha}^{\text{xc}} = \frac{\delta E^{\text{xc}}}{\delta \rho_{\alpha}(\vec{r})}, \quad V_{\beta}^{\text{xc}} = \frac{\delta E^{\text{xc}}}{\delta \rho_{\beta}(\vec{r})}$$

$$F_{\mu\nu}^{\text{xca}} = \int \chi_{\mu} V_{\alpha}^{\text{xc}} \chi_{\nu} d\vec{r}, \quad F_{\mu\nu}^{\text{xcb}} = \int \chi_{\mu} V_{\beta}^{\text{xc}} \chi_{\nu} d\vec{r}$$

以计算 V_{α}^{xc} 为例, 对 ρ_{α} 施加微小扰动 $\delta \rho_{\alpha}$, 导致 $\nabla \rho_{\alpha}$, $\nabla \rho_{\alpha\beta}$, $\nabla \rho_{\beta\beta}$ 变

化为:

$$\delta \nabla \rho_{\alpha} = 2 \vec{\nabla} \rho_{\alpha} \cdot \vec{\nabla}(\delta \rho_{\alpha}) \quad \delta \nabla \rho_{\alpha\beta} = \vec{\nabla} \rho_{\beta} \cdot \vec{\nabla}(\delta \rho_{\alpha}) \quad \delta \nabla \rho_{\beta\beta} = 0$$

则有:

$$\delta E_{\alpha}^{\text{xc}} = \int d\vec{r} \left[\frac{\partial \varepsilon}{\partial \rho_{\alpha}} \delta \rho_{\alpha} + 2 \frac{\partial \varepsilon}{\partial \nabla \rho_{\alpha}} \vec{\nabla} \rho_{\alpha} \cdot \vec{\nabla}(\delta \rho_{\alpha}) + \frac{\partial \varepsilon}{\partial \nabla \rho_{\alpha\beta}} \vec{\nabla} \rho_{\beta} \cdot \vec{\nabla}(\delta \rho_{\alpha}) \right]$$

借助关系 $\vec{\nabla} \cdot (f \vec{A}) = f(\vec{\nabla} \cdot \vec{A}) + \vec{A} \cdot (\vec{\nabla} f)$, 有:

$$\int d\vec{r} \left[2 \frac{\partial \varepsilon}{\partial \nabla \rho_{\alpha}} \vec{\nabla} \rho_{\alpha} \cdot \vec{\nabla}(\delta \rho_{\alpha}) \right]$$

$$= \oint d\vec{S} \left[\vec{\nabla} \cdot (\delta \rho_{\alpha} 2 \frac{\partial \varepsilon}{\partial \nabla \rho_{\alpha}} \vec{\nabla} \rho_{\alpha}) \right] - \int d\vec{S} \delta \rho_{\alpha} \vec{\nabla} \cdot (2 \frac{\partial \varepsilon}{\partial \nabla \rho_{\alpha}} \vec{\nabla} \rho_{\alpha})$$

$$= - \int d\vec{r} \delta \rho_{\alpha} \vec{\nabla} \cdot (2 \frac{\partial \varepsilon}{\partial \nabla \rho_{\alpha}} \vec{\nabla} \rho_{\alpha})$$

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$$\text{另有 } \int d\vec{r} \left[\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta \cdot \vec{\nabla} (\delta \rho_\alpha) \right]$$

$$= \oint d\vec{s} \left[\vec{\nabla} \cdot (\delta \rho_\alpha \frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta) \right] - \int d\vec{s} \delta \rho_\alpha \vec{\nabla} \cdot (\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta)$$

$$= - \int d\vec{r} \delta \rho_\alpha \vec{\nabla} \cdot (\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta)$$

$$\therefore \frac{\delta E_\alpha^{\text{xc}}}{\delta \rho_\alpha} = \frac{\partial \mathcal{E}}{\partial \rho_\alpha} - \vec{\nabla} \cdot (2 \frac{\partial \mathcal{E}}{\partial \vec{p}_\alpha} \vec{\nabla} \rho_\alpha) - \vec{\nabla} \cdot (\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta)$$

故:

$$F_{\mu\nu}^{\text{xc}\alpha} = \int \chi_\mu V_\alpha^{\text{xc}} \chi_\nu d\vec{r}$$

$$= \int d\vec{r} \left[\frac{\partial \mathcal{E}}{\partial \rho_\alpha} - \vec{\nabla} \cdot (2 \frac{\partial \mathcal{E}}{\partial \vec{p}_\alpha} \vec{\nabla} \rho_\alpha) - \vec{\nabla} \cdot (\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta) \right] \chi_\mu \chi_\nu$$

再次借助关系 $\vec{\nabla} \cdot (f \vec{A}) = f(\vec{\nabla} \cdot \vec{A}) + \vec{A} \cdot (\vec{\nabla} f)$, 有:

$$\int d\vec{r} \left[- \vec{\nabla} \cdot (2 \frac{\partial \mathcal{E}}{\partial \vec{p}_\alpha} \vec{\nabla} \rho_\alpha) \chi_\mu \chi_\nu \right]$$

$$= - \oint d\vec{s} \left[\vec{\nabla} \cdot (\chi_\mu \chi_\nu 2 \frac{\partial \mathcal{E}}{\partial \vec{p}_\alpha} \vec{\nabla} \rho_\alpha) \right] + \int d\vec{r} \left[2 \frac{\partial \mathcal{E}}{\partial \vec{p}_\alpha} \vec{\nabla} \rho_\alpha \cdot \vec{\nabla} (\chi_\mu \chi_\nu) \right]$$

$$= \int d\vec{r} \left[2 \frac{\partial \mathcal{E}}{\partial \vec{p}_\alpha} \vec{\nabla} \rho_\alpha \cdot \vec{\nabla} (\chi_\mu \chi_\nu) \right]$$

$$\text{另有 } \int d\vec{r} \left[- \vec{\nabla} \cdot (\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta) \chi_\mu \chi_\nu \right]$$

$$= - \oint d\vec{s} \left[\vec{\nabla} \cdot (\chi_\mu \chi_\nu \frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta) \right] + \int d\vec{r} \left[\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta \cdot \vec{\nabla} (\chi_\mu \chi_\nu) \right]$$

$$= \int d\vec{r} \left[\frac{\partial \mathcal{E}}{\partial \vec{p}_\beta} \vec{\nabla} \rho_\beta \cdot \vec{\nabla} (\chi_\mu \chi_\nu) \right]$$

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$$F_{\mu\nu}^{xc\alpha} = \int d\vec{r} \left[\frac{\partial \mathcal{E}}{\partial \rho_\alpha} \chi_\mu \chi_\nu + \left(2 \frac{\partial \mathcal{E}}{\partial \chi_{\mu\alpha}} \vec{\nabla} \rho_\alpha + \frac{\partial \mathcal{E}}{\partial \chi_{\nu\beta}} \vec{\nabla} \rho_\beta \right) \cdot \vec{\nabla} (\chi_\mu \chi_\nu) \right]$$

$$F_{\mu\nu}^{xc\beta} = \int d\vec{r} \left[\frac{\partial \mathcal{E}}{\partial \rho_\beta} \chi_\mu \chi_\nu + \left(2 \frac{\partial \mathcal{E}}{\partial \chi_{\mu\beta}} \vec{\nabla} \rho_\beta + \frac{\partial \mathcal{E}}{\partial \chi_{\nu\alpha}} \vec{\nabla} \rho_\alpha \right) \cdot \vec{\nabla} (\chi_\mu \chi_\nu) \right]$$

日期: / /
不同基组初猜波函数投影:

$$|\psi_i^B\rangle = \sum_{\mu} C_{\mu i}^B |\chi_{\mu}^B\rangle$$

$$|\psi_i^A\rangle = \sum_{\nu} C_{\nu i}^A |\chi_{\nu}^A\rangle$$

$$|\psi_i^B\rangle \approx |\psi_i^A\rangle$$

$$\sum_{\mu} C_{\mu i}^B |\chi_{\mu}^B\rangle \approx \sum_{\nu} C_{\nu i}^A |\chi_{\nu}^A\rangle$$

$$\sum_{\mu} C_{\mu i}^B \langle \chi_{\lambda}^B | \chi_{\mu}^B \rangle \approx \sum_{\nu} C_{\nu i}^A \langle \chi_{\lambda}^B | \chi_{\nu}^A \rangle$$

$$C_B S_{BB} \approx C_A S_{BA}$$

正交归一性:

$$C_B^T S_{BB} C_B = C_A^T S_{AB} S_{BB}^{-1} S_{BB} S_{BB}^{-1} S_{BA} C_A$$

$$= C_A^T S_{AB} S_{BB}^{-1} S_{BA} C_A$$

$$\neq I$$

因此投影后的轨道需要正交化, 即对初猜 MO 做正交化:

$$X^T C_B^T S_{BB} C_B X = I$$

这跟对重叠矩阵(CAO)正交化不同, 后者是 $X S_{BB} X^T = I$, 只有当 $C_B^T C_B = I$ 时二者才等价, 如果是 SCF 时通过 Fock 对角化得到的 MO, 满足 $C_B^T C_B = I$, 所以只要对 S 对角化, 向上面投影得到的 MO 并不满足此关系。

这个正交化就用对称正交化(Löwdin 方法), 因为我认为已收敛的 MO 满足 Pauli 反对称, 不太可能出现 2 条 MO 几乎相同使 X 不满秩 (即线性相关问题)。

日期: /

Hartree-Fock 与 Kohn-Sham 的 Fock/KS 矩阵与电子能

① Hartree-Fock:

$$F_{\text{ock}} = h + (J - K)$$

$$E_{\text{ele}} = h + \frac{1}{2} \sum_{\text{orb}}^{\text{SO}} (J - K) = \sum_{\text{orb}}^{\text{SO}} E_{\text{orb}} - \frac{1}{2} \sum_{\text{orb}}^{\text{SO}} (J - K)$$

② Kohn-Sham

$$F_{\text{ock}} = h + J - xK + (1-x)X + C$$

$$E_{\text{ele}} = h + \frac{1}{2} \sum_{\text{orb}}^{\text{SO}} J - \frac{1}{2} x \sum_{\text{orb}}^{\text{SO}} K + (1-x)X + C$$

$$= h + \sum_{\text{orb}}^{\text{SO}} J - \frac{1}{2} \sum_{\text{orb}}^{\text{SO}} J - x \sum_{\text{orb}}^{\text{SO}} K + \frac{1}{2} x \sum_{\text{orb}}^{\text{SO}} K + (1-x)X + C$$

$$= \sum_{\text{orb}}^{\text{SO}} E_{\text{orb}} - \frac{1}{2} \sum_{\text{orb}}^{\text{SO}} (J - xK)$$

经验证, 上式计算得到的 E_{ele} 与实际电子能不符; 就是说实际上, x 能量不具备轨道的加和性质, 它不与轨道直接关联而是与整体波函数(密度)关联。KS 电子能唯一算法是 $E_{\text{ele}} = h + \frac{1}{2} \sum_{\text{orb}}^{\text{SO}} J - \frac{1}{2} x \sum_{\text{orb}}^{\text{SO}} K + (1-x)X + C$

DFT 计算不能仅靠分析轨道得出结论, 分子的性质不是仅由轨道决定。

日期: /

高速运动系下二分量MO坐标与自旋的观测值。

已知静止系的可观测量,求运动系的可观测量,必须经历Lorentz变换;

其中的关键是,必须以运动系的“同时”($\Delta t = 0$)为前提,即:

$$X_{\text{rest}} = \Lambda(X_{\text{motion}})|_{\Delta t=0}$$

这必须对Lorentz矩阵的空间部分(3×3)求逆,先列出正向变换的空间

部分可写作:

$$\begin{aligned} L &= I + \frac{\gamma-1}{\beta^2} (\vec{\beta} \vec{\beta}^T) \\ &= I + kM \end{aligned}$$

根据Sherman公式:

$$\begin{aligned} (I + kM)^{-1} &= I - \frac{kM}{1 + k \text{tr}(M)} \\ &= I - \frac{\frac{\gamma-1}{\beta^2} \beta \beta^T}{1 + \frac{\gamma-1}{\beta^2} \beta^2} \\ &= I - \frac{\gamma}{\gamma+1} \beta \beta^T = L^{-1} \end{aligned}$$

此式可方便地求出运动系的波函数空间部分,但自旋部分更复杂,

涉及非线性的Imitative变换,直接求逆不容易;反之,可利用其拟向性质,

对于静止系中只有z轴不为0的 $\vec{s}_z(0,0,s)$,变换后方向必然相等子:

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$$\vec{s}_2' = \vec{s}_2 - \frac{Y}{Y+1} \beta_3 s \vec{P}$$

其模方为:

$$\begin{aligned}\vec{s}_2'^2 &= \frac{Y^2}{(Y+1)^2} \beta_3^2 s^2 \beta_1^2 + \frac{Y^2}{(Y+1)^2} \beta_3^2 s^2 \beta_2^2 + \left(s - \frac{Y}{Y+1} \beta_3^2 s\right)^2 \\&= s^2 \left[\frac{Y^2}{(Y+1)^2} \beta_3^2 \beta_1^2 + \frac{Y^2}{(Y+1)^2} \beta_3^2 \beta_2^2 + \left(1 - 2\frac{Y}{Y+1} \beta_3^2 + \frac{Y^2}{(Y+1)^2} \beta_3^4\right) \right] \\&= s^2 \left[\frac{Y^2}{(Y+1)^2} \beta_3^2 \beta^2 + 1 - \frac{2Y}{Y+1} \beta_3^2 \right]\end{aligned}$$

考虑到 $\frac{Y^2}{Y+1} = \frac{Y-1}{\beta^2}$

$$\begin{aligned}\therefore \vec{s}_2'^2 &= s^2 \left[\frac{Y-1}{Y+1} \beta_3^2 + 1 - \frac{2Y}{Y+1} \beta_3^2 \right] \\&= s^2 [1 - \beta_3^2]\end{aligned}$$

故考虑 Imitative 变换后的 \vec{s}_2 为:

$$s_2' = \frac{1 - \frac{Y}{Y+1} \beta_3^2}{\sqrt{1 - \beta_3^2}} s$$

考虑系数的取值:

$$\left(1 - \frac{Y}{Y+1} \beta_3^2\right)^2 \leq 1 - \beta_3^2$$

$$1 - \frac{2Y}{Y+1} \beta_3^2 + \frac{Y^2}{(Y+1)^2} \beta_3^4 \leq 1 - \beta_3^2$$

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$$-\frac{2V}{V+1} + \frac{V^2}{(V+1)^2} \beta_3^2 \leq -1$$

$$-2V^2 - 2V + V^2 \beta_3^2 \leq -V^2 - 2V - 1$$

$$1 - V^2 + V^2 \beta_3^2 \leq 0$$

$$1 - \beta^2 \leq 1 - \beta_3^2$$

此式恒成立,当且仅当 $\beta = \beta_3$ 时取等,这与Lorentz变换定义相符。这一不等式关系表明运动系下自旋态趋于平均化,偏离 $\pm \frac{1}{2}$,当运动系趋近光速时,即 $\lim_{\beta \rightarrow 0} s_z' = \lim_{\beta \rightarrow 0} \sqrt{1 - \beta_3^2} s = 0$,此时电子自旋行为趋近玻色子。

用于反映TRS破缺程度的kappa参数计算:

$$K = \|MM^* + I\| = \left[\sum_{ij} (M_{ij} M_{ij}^* + \delta_{ij})^2 \right]^{\frac{1}{2}} \quad \text{其中 } M_{ij} = \langle \psi_i | 1 - i\gamma_5 | \psi_j \rangle$$

标量计算中 $K = \sqrt{N_\alpha - N_\beta}$, 二阶量时对该值的偏差可视为SOC导致的对TRS的偏离。

日期:

二分量波函数的旋转群积分 (Rotation Group Integration, RGI)

把 $S_{\alpha\beta}$ 作用到任一旋量轨道 $\begin{pmatrix} S_a \\ S_b \end{pmatrix}$

$$P_{MK}^S = \frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin\beta \int_0^{2\pi} d\gamma D_{MK}^{S*} \cdot e^{-\frac{i}{2}\alpha\sigma_z} e^{-\frac{i}{2}\beta\sigma_y} e^{-\frac{i}{2}\gamma\sigma_z} \begin{pmatrix} S_a \\ S_b \end{pmatrix}$$

$$= \frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin\beta \int_0^{2\pi} d\gamma e^{im\alpha} d_{MK}^S e^{ik\gamma} \begin{pmatrix} e^{-\frac{i}{2}(\alpha+\gamma)} \cos\frac{\beta}{2} S_a - e^{-\frac{i}{2}(\alpha-\gamma)} \sin\frac{\beta}{2} S_b \\ e^{\frac{i}{2}(\alpha-\gamma)} \sin\frac{\beta}{2} S_a + e^{\frac{i}{2}(\alpha+\gamma)} \cos\frac{\beta}{2} S_b \end{pmatrix}$$

上旋量 =

$$\frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin\beta \int_0^{2\pi} d\gamma e^{im\alpha} d_{MK}^S e^{ik\gamma} \left[e^{-\frac{i}{2}(\alpha+\gamma)} \cos\frac{\beta}{2} S_a - e^{-\frac{i}{2}(\alpha-\gamma)} \sin\frac{\beta}{2} S_b \right]$$

$$= \frac{(2S+1)S_a}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin\beta \int_0^{2\pi} d\gamma e^{i(m-\frac{1}{2})\alpha} d_{MK}^S e^{i(k-\frac{1}{2})\gamma} \cos\frac{\beta}{2}$$

$$- \frac{(2S+1)S_b}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin\beta \int_0^{2\pi} d\gamma e^{i(m-\frac{1}{2})\alpha} d_{MK}^S e^{i(k+\frac{1}{2})\gamma} \sin\frac{\beta}{2}$$

$$= \frac{(2S+1)S_a}{8\pi^2} \int_0^{2\pi} d\alpha e^{i(m-\frac{1}{2})\alpha} \int_0^\pi d\beta d_{MK}^S \sin\beta \cos\frac{\beta}{2} \int_0^{2\pi} d\gamma e^{i(k-\frac{1}{2})\gamma}$$

$$- \frac{(2S+1)S_b}{8\pi^2} \int_0^{2\pi} d\alpha e^{i(m-\frac{1}{2})\alpha} \int_0^\pi d\beta d_{MK}^S \sin\beta \sin\frac{\beta}{2} \int_0^{2\pi} d\gamma e^{i(k+\frac{1}{2})\gamma}$$

明显这种情况在 $M = \frac{3}{2}, \frac{5}{2}, \dots$ 时积分值为0, 意味着永远不可能投影出

$M = \frac{3}{2}, \frac{5}{2}, \dots$ 的态, 这不合理。原因在于 P_{MK}^S 应作用于整体的多电子态 $|S, M\rangle$, 而非依次

作用到轨道上。

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把 $S_{\alpha\beta}$ 作用到旋量态 $|\Psi\rangle$ 上并将投影态与 Ψ 内积:

$$\langle \bar{\Psi} | P_{MK}^S | \bar{\Psi} \rangle = \frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \int_0^{2\pi} d\gamma \sin\beta D_{MK}^{S*} \cdot \langle \bar{\Psi} | \hat{U}_{S\alpha\beta} | \Psi \rangle$$

令旋转后 $\hat{U}_{S\alpha\beta} |\Psi\rangle(\alpha, \beta, \gamma) = |\Phi\rangle(\alpha, \beta, \gamma)$

$$\text{且 } |\bar{\Psi}\rangle = \frac{1}{N N!} \det \begin{pmatrix} \psi_1(\alpha_1) & \dots & \psi_1(\alpha_N) \\ \vdots & \ddots & \vdots \\ \psi_N(\alpha_1) & \dots & \psi_N(\alpha_N) \end{pmatrix} \quad |\Phi\rangle = \frac{1}{N N!} \det \begin{pmatrix} \phi_1(\alpha_1) & \dots & \phi_1(\alpha_N) \\ \vdots & \ddots & \vdots \\ \phi_N(\alpha_1) & \dots & \phi_N(\alpha_N) \end{pmatrix}$$

$$\begin{aligned} \text{则 } \langle \bar{\Psi} | P_{MK}^S | \bar{\Psi} \rangle &= \frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \int_0^{2\pi} d\gamma \sin\beta D_{MK}^{S*}(\alpha, \beta, \gamma) \cdot \langle \bar{\Psi} | \Phi \rangle(\alpha, \beta, \gamma) \\ &= \frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \int_0^{2\pi} d\gamma \sin\beta D_{MK}^{S*}(\alpha, \beta, \gamma) \cdot \det(\langle \phi | \psi \rangle) \\ &= \frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \int_0^{2\pi} d\gamma \sin\beta D_{MK}^{S*}(\alpha, \beta, \gamma) \det(\text{oper}_3^\dagger \text{oper}_3) \\ &\quad (\text{oper}_3 \text{ 是正交归一基上的正交归一轨道}) \end{aligned}$$

对于二分量单行列式态, 要构造 S^2 和 S_z 的纯态, 首先要从被投影态 $|\Psi\rangle$ 中提取相同 S_z 的成分, 然后旋转投影: 对于具有相同 S^2 但不同 S_z 的分量, 使用 Wigner D 矩阵 D_{MK}^S 将其转换为相同 S_z 会导致子态间相互污染。因此, 需要对所有可能的 M 令 $K=M$ 。

$$\langle \bar{\Psi} | P_{MK}^S | \bar{\Psi} \rangle = \frac{2S+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \int_0^{2\pi} d\gamma \sin\beta e^{iM\alpha} e^{iM\gamma} d_{MK}^S(\beta) \cdot \det(\text{oper}_3^\dagger \text{oper}_3)$$

由于 Wigner-Eckart 定理, 只有 $|\Delta S| \leq 1$ 且 $|\Delta S_z| \leq 1$ 的态之间会发生耦合 (只有 SOC 的情形), 因此在确定了 basic configuration 后, 需要考虑的自旋纯态是有限的:

