

30.4.2010

$$X = \begin{pmatrix} u_c \\ i_L \end{pmatrix}, u = u_e$$

a) $i_c \cdot \frac{du_c}{dt} = i_L - i_D$

$$u_c = L \cdot \frac{di_L}{dt} = u_e - u_c - i_L \cdot R$$

$$\begin{cases} \dot{i}_L = \frac{u_e}{L} - \frac{u_c}{L} - i_L \frac{R}{L} \\ \dot{u}_c = \frac{i_L}{C} - \frac{h(u_c)}{C} \end{cases}$$

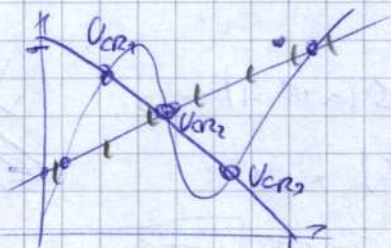
b) $0 = \frac{u_{cr}}{L} - \frac{u_{cr}}{L} - i_{LR} \frac{R}{L}$

$$0 = i_{LR} - h(u_{cr}) \rightarrow i_{LR} = h(u_{cr})$$

$$u_{cr} = u_e - R \cdot h(u_{cr})$$

$$h(u_{cr}) = \frac{u_e - u_{cr}}{R} = i_{LR}$$

→ Ruhelage maximal



$$h(u_{cr}) = 1 \text{ mA} - \frac{u_{cr}}{1000}$$

c) $b = \begin{pmatrix} 0 & 1/L \end{pmatrix}$

$$A = \begin{pmatrix} -\frac{\partial h(u_c)}{\partial u_c} \frac{1}{C} & + \frac{1}{L} \\ -\frac{1}{L} & -\frac{R}{L} \end{pmatrix}$$

ist dann ein HW-Pkt,
wenn $\dot{h} > -\frac{1}{R} = -10^{-3}$
und $\dot{h} > -\frac{R}{L}$
→ genau eine stabile
Ruhelage $u_{cr2} + u_{cr3}$

d) $\frac{R}{L} \dot{h}(u_{cr}) + \frac{1}{L} = 0$

$$(1 + \dot{h} \frac{R}{L}) (1 + \frac{R}{L}) + \frac{1}{L} = \lambda^2 + \lambda \left(\frac{\dot{h}}{C} + \frac{R}{L} \right) + \frac{\dot{h} R}{L} + \frac{1}{L} = 0$$

20) nein, weil p.m., da Nullstelle bei 1

$$e) \lim_{s \rightarrow 0} h(s) = \lim_{s \rightarrow 0} \frac{s^k(1-s)}{(1+s)^2} = \lim_{s \rightarrow 0} \frac{-s^k + s^{k+1}}{s^2+2s+1} \stackrel{!}{=} -1$$

$$\lim_{s \rightarrow 0} h(s) = \lim_{s \rightarrow 0} \frac{s(1-s)}{(1+s)^2} = \lim_{s \rightarrow 0} \frac{-s^2 + s}{s^2+2s+1} = \lim_{s \rightarrow 0} \frac{1 - \frac{1}{s}}{1 + \frac{2}{s} + \frac{1}{s^2}} = -1$$

$$= \lim_{s \rightarrow \infty} \frac{(1-s)}{s^2+2s+1} = 0$$

$$\lim_{s \rightarrow 0} \frac{1-s}{(1+s)^2} = 1$$



$$e) |G(j\omega)| = \frac{\sqrt{\omega^2+1}}{(\omega^2+1)}$$

$$\arg(G(j\omega)) = \arg(-\omega) - 2\arg(\omega) + \arg\left(\frac{\sin \omega T}{\cos \omega T}\right)$$

$$= \arg(-\omega) - 2\arg(\omega) + \omega T = -\arg(\omega) - \omega T$$

3a) i) $e_{k+1} = A e_k$

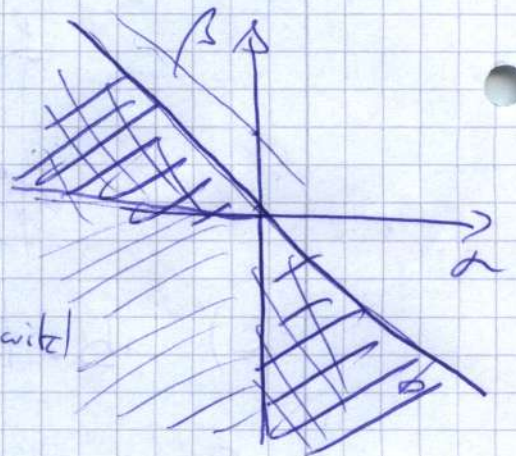
$$(\alpha+\beta-d)/(-2-d) - \alpha\beta(\alpha+\beta-d) = 0$$

$$(\alpha+\beta-d)(d^2+2d-\alpha\beta) = 0$$

$$d_1 = \alpha+\beta, \quad d_{2,3} = -1 \pm \sqrt{1+\alpha\beta}$$

$$\alpha+\beta < 0 \quad +\alpha\beta < 0 \quad (\text{Hurwitz})$$

$$\alpha, \beta < 0$$



$$ii) R = \begin{vmatrix} b_1 & A b_1 & A^2 b_1 \\ b_2 & A b_2 & A^2 b_2 \\ 1 & 0 & \alpha\beta \end{vmatrix} = \begin{vmatrix} 0 & 1 & \alpha+\beta \\ 0 & \beta & -2\beta \\ 1 & 0 & \alpha\beta \end{vmatrix}$$

$$\begin{array}{ccc|cc} & 0 & 1 & & \\ & \beta & \beta & & \\ \hline \alpha+\beta & 0 & 1 & 1 & \alpha+\beta \\ 0 & -2 & \beta & \beta & -2\beta \\ 0 & \alpha & 0 & 0 & \alpha\beta \end{array}$$

$$\det R \neq 0 = -2\beta - \beta(\alpha+\beta)$$

$$\boxed{\alpha+\beta \neq -2}$$

$$iii) \mathcal{O}(C^T A)$$

$$\begin{array}{ccc|ccc} \alpha+\beta & 0 & 1 & \alpha+\beta & 0 & 1 \\ 0 & -2\beta & & 0 & -2\beta & \\ 0 & \alpha & 0 & 0 & \alpha & 0 \\ \hline 1 & 0 & 0 & \alpha+\beta & 0 & 1 \\ & & & (\alpha+\beta)^2 & \alpha & \alpha+\beta \end{array}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ \alpha+\beta & 0 & 1 \\ (\alpha+\beta)^2 & \alpha & \alpha+\beta \end{bmatrix}$$

$$\alpha \neq 0$$

iv)

$$G(s) = C^T (sE - A)^{-1} b =$$

$$= C^T \begin{pmatrix} s-(\alpha+\beta) & 0 & -1 \\ 0 & s+2 & -\beta \\ 0 & -\alpha & s \end{pmatrix}^{-1} b = \frac{\alpha - (s+2)}{(s+\beta)(s+(\alpha+\beta)) - \alpha\beta(s-\alpha+\beta)}$$

$$= \frac{-(s+2)}{(s-(\alpha+\beta))(s^2 + 2s - \alpha\beta)}$$

A) wenn $\alpha+\beta \neq 2$ ist, ist System
stabil 2. Ordnung \rightarrow erreichbar

$$\left(\begin{array}{c} (s^2 + 2s - \alpha\beta) : (s+2) = s \\ 0 \quad 0 \quad -\alpha\beta \end{array} \right) \quad B) \text{ nur, wenn } \alpha\beta \neq 0 \text{ stabil}$$

$$\begin{array}{ccc} A & & B \\ v_i & \longleftrightarrow & v_i \\ n_i & \longleftrightarrow & e^{t+\tau} a \end{array}$$

$$v) \lambda_i = \alpha_i + j\omega_i \rightarrow \omega_i \neq \frac{e\pi}{T_R} \quad \rho = \pm 1, \pm 2, \pm 3$$

$$\text{wenn } \alpha/\beta < -1 \rightarrow \omega_i = \sqrt{-1+\alpha\beta} \neq \frac{e\pi}{T_R} \\ = \sqrt{-(1+\alpha\beta)}$$

$$T_R + \frac{e\pi}{\sqrt{-(1+\alpha\beta)}}$$

$$a) G^{\#}(q) - \frac{y}{u} = \frac{q^2 - 2}{q^2 - 8q + 12}$$

nicht sprungfähig, wenn Nst bei $\Omega_0 = \frac{2}{T_a}$

$$(q-2)(q+6) \rightarrow \underline{\underline{T_a \neq 1/2}}$$

nicht realisierbar, wenn Pol bei $\Omega_0 = \frac{2}{T_a}$

$$q^2 - 8q + 12 = (q-6)(q-2) \quad T_a \neq 1, \neq \frac{1}{3}$$

$$b) \Omega_0 = \frac{2}{T_a} \tanh\left(\frac{\varphi_a}{2}\right) / \left(\frac{T_a}{2} \omega\right)$$

in $|G^{\#}(j\Omega_0)|$ und aus $|G^{\#}(j\Omega_0)|$

$$4) a) h_k \rightarrow \Delta$$

$$g_k = (0, \frac{1}{2}, -1, \frac{3}{2}, 0, \dots)$$

$$x_{\max} = (0, 1, 0, 1, 0, \dots) \rightarrow y_{\max} = 2$$

b) Eigenwerte von $\phi \rightarrow$ Eigenwerte von $\psi \rightarrow e^{j\omega T_a}$

$$x_{k+1} = \phi \cdot x_k$$

$$x_k = \psi(k) \cdot x_0$$

$$x_k = \phi^k x_0 \quad \left| \begin{array}{l} x_1 = 2^k x_0 \\ x_2 = x_0 \\ x_3 = (-1)^k x_0 \end{array} \right.$$

$$x_1 = \cancel{2^k} x_0$$

$$x_1 = e^{j\omega T_a} x_0$$

$$x_4 = (-0.5)^k x_0$$

$$\text{mit } x_0 = 1$$



$$c) -40 \log \sqrt{2f} = 14 \text{ dB}$$

$$= 20 \log 2f =$$

$$2f = \frac{10^{-14/20}}{2} = \frac{1}{2 \cdot 2.52} \approx 0.1$$

$$i) T_{yr}(s) = \frac{0.99}{1 + 2.5 \frac{s}{10} + \left(\frac{s}{10}\right)^2}$$

$$ii) e_{\infty} = 0.01 = \frac{1}{1+V} \rightarrow V = 99$$

$$L = R(s) Q(s) \rightarrow R(s) = \frac{(s+1) \cdot V}{1 + 2.5 \frac{s}{10} + \left(\frac{s}{10}\right)^2}$$

$$T_{xy} = \frac{\frac{V}{s}}{1 + \frac{V}{s}} = \frac{V}{s+V} = 0.99$$

$$T_{yr} = \frac{R}{1+RQ} \rightarrow T_{yr} + RQ T_{yr} = RQ$$

$$R = \frac{T_{yr}}{Q(1-T_{yr})} = \frac{0.99(s+1)}{1 + 2.5 \frac{s}{10} + \left(\frac{s}{10}\right)^2 - 0.99}$$

$$= \frac{99(s+1)}{1 + 2.5s + s^2}$$

$$|G(j\omega_c)| = 1 = \frac{99}{1+\omega_c^2} \rightarrow \omega_c = \sqrt{98}$$

$$iii) T_R = \frac{1.5s}{\omega_c} = \frac{1.5s}{\sqrt{98}}$$

$$\tilde{\omega} + PR = 70$$

$$\tilde{\omega} \approx 70\%$$

$$= \frac{99(s+1)}{(s+1)^2} \stackrel{\text{mit } s=1}{=} \boxed{\frac{99}{(s+1)} = PR(s)}$$

$$\varphi = -2. \text{ also } \omega_c = -2.52$$

$$\hookrightarrow PR = 2.52 \approx 2.5$$