

$$(12.12.08 / 1) \quad q_1 = A_s \sqrt{2gh}$$

$$A_s = s \cdot b$$

$$u = \begin{bmatrix} p_{in} \\ F \end{bmatrix}$$

$$y = q_{out}$$

$$\text{Totzeit } \tau = \frac{e}{v} = \frac{2e}{\omega_B \cdot d_B}$$

$$x = \begin{bmatrix} \dot{x} \\ h \end{bmatrix}$$

$$\dot{s} = \omega$$

$$m \cdot \dot{\omega} = F - s \cdot c - d \omega$$

$$\dot{\omega} = \frac{F}{m} - s \frac{c}{m} - \omega \frac{d}{m}$$

$$m \frac{d\omega}{dt} = F - s c$$

$$[q] = \frac{m^2}{s}$$

$$\dot{V} = \dot{h} \cdot A = q_{in} - q_1$$

$$\dot{h} = \frac{q_{in}}{A} - \frac{q_1}{A} = \frac{q_{in}}{A} - s \frac{b \sqrt{2g} \cdot s \cdot \sqrt{h}}{A}$$

$$y = q_{out} = q_1(t - \tau) = s \frac{b \sqrt{2g}}{A} s(t - \tau) \sqrt{h(t - \tau)}$$

$$b) \quad F_R = \text{const}, \quad q_{in,R} = \text{const}$$

$$\omega = 0$$

$$0 = \frac{F_R}{m} - s_R \cdot \frac{c}{m} \rightarrow s_R = \frac{F_R}{c}$$

$$0 = \frac{q_{in,R}}{A} - \frac{b \sqrt{2g}}{A} \cdot \frac{F_R}{c} \cdot \sqrt{h_R} \rightarrow h_R = \left(\frac{q_{in,R} c}{F_R \cdot b \sqrt{2g}} \right)^2$$

$$y = \frac{b \sqrt{2g}}{A} \frac{F_R}{c} \frac{q_{in,R}}{F_R b \sqrt{2g}} = \underline{q_{in,R}}$$

linearisiert

$$B = \frac{df(x, r, u)}{du} =$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 1/m \\ 1/A & 0 \end{bmatrix}$$

$$d=0$$

$$C^T = \frac{d\varphi}{dx} = \left[\sqrt{2g} b \sqrt{h_R} \middle| \frac{d}{dx} \left(\frac{1}{2} \frac{\sqrt{2g} b R}{\sqrt{h_R}} \right) \sqrt{2g} b \sqrt{h(t-r)} r(t-r) \right]$$

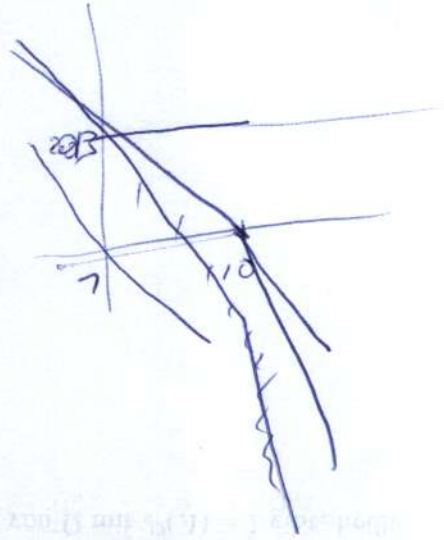
$$A = \frac{\partial f}{\partial x} = \begin{bmatrix} 0 & 1 & 0 \\ -c/m & -d/m & 0 \\ -\frac{b \sqrt{2g} \sqrt{h_R}}{A} & 0 & -\frac{b \sqrt{2g} r_R}{2A \sqrt{h_R}} \end{bmatrix}$$

c) Totzeit

$$G(s) = e^{-sT}$$

e) ϕ_i $\overline{AT_a}$ 12.12.08

1) $G(s) = \frac{1}{\frac{s^2}{100} + \frac{s}{10}} = \frac{10}{s(s/10 + 1)}$



b) $f_r = 0,155$

$\omega_c t_r = 1,5$ $\omega_c = 10$

$PR = 45 = \pi/4$

$\arg(G(s))|_{\omega_c=1} = 0 - \frac{\pi}{2} - \frac{\pi}{4} = -\frac{3\pi}{4} \rightarrow PR = \pi/4 \quad \text{☺}$

$R(s) = V = \sqrt{2}$

$|L(s)|_{\omega_c=1} = 1 = \frac{V \cdot 10}{10(\sqrt{2})} \rightarrow V = \sqrt{2}$

c) $T_{dly} = \frac{G(s)}{1+RG} = \frac{10}{s(s/10+1)} \cdot \frac{1}{1 + \frac{10 \cdot \sqrt{2}}{s(s/10+1)}} = \frac{10}{10\sqrt{2} + s(s/10+1)}$

1) $\phi(s) = \frac{0,25}{s}$

$\lim_{s \rightarrow 0} \frac{0,25 \cdot 10}{\sqrt{2} + s(s/10+1)} = \frac{2,5}{\sqrt{2}}$

2) $|G(s)|_{s=55} = \frac{10}{\sqrt{(10\sqrt{2} - \frac{25}{10})^2 + 5^2}} = K$

$\arg(G(s))|_{s=55} = -\arctan\left(\frac{5}{10\sqrt{2} - \frac{25}{10}}\right)$

$$2d) i) R(s) = \frac{s-1}{s} \quad G(s) = \frac{s+3}{s^2+s-2}$$

$$T_{r,y} = \frac{R \cdot G}{1 + R \cdot G} = \frac{\frac{s-1}{s} \frac{s+3}{s^2+s-2}}{1 + \frac{s-1}{s} \frac{s+3}{s^2+s-2}} = \frac{(s-1)(s+3)}{(s-1)(s+3) + s(s^2+s-2)}$$

$$= \frac{s^2 - 3 + 2s}{s^2 - 3 + 2s + s^3 + s^2 - 2s} = \frac{s^2 - 3 + 2s}{s^3 + 2s^2 + 0s - 3}$$

kein Hurwitzpolynom \rightarrow nicht BWS

ii) nein, da $G(s)$ nicht stabil ist

3)

$$a) \begin{cases} \dot{x} = t + 2x + u \\ y = x \end{cases} \quad \left. \begin{array}{l} \text{und} \\ \text{nicht linear, aber zeitvariant} \end{array} \right\}$$

$$b) \begin{cases} \dot{x} = 2tx + u \\ y = x \end{cases} \quad \left. \begin{array}{l} \text{nicht linear,} \\ \text{zeitvariant} \end{array} \right\}$$

$$c) \det(E - A) = 0$$

$$\begin{vmatrix} 1 & 0 & 3 \\ 0 & \lambda + 2 & 0 \\ -\alpha & 0 & \lambda + \alpha + 3 \end{vmatrix} = \lambda(\lambda - \alpha + 2)(\lambda + \alpha + 3) + \alpha 3(\lambda - \alpha + 2) = 0$$

$$= (\lambda - \alpha + 2)(\lambda^2 + \lambda(\alpha + 3) + \alpha 3) = 0$$

$$\lambda_1 = \alpha - 2$$

$$\lambda_2 = -\frac{\alpha + 3}{2} \pm \sqrt{\frac{(\alpha + 3)^2}{4} - \alpha 3}$$

$$1.) \alpha < 2, \lambda > 0$$

$$WC: \frac{(\alpha + 3)^2}{4} - \alpha 3 > 0$$

$$\alpha^2 + 6\alpha + 9 - 12\alpha > 0$$

$$\alpha^2 - 6\alpha + 9 > 0$$

$$\alpha^2 - 6\alpha + 9 = (\alpha - 3)^2 > 0$$

$$= -\frac{\alpha + 3}{2} \pm \frac{(\alpha - 3)}{2} < 0$$

$$(-\alpha - 3) \pm (\alpha - 3) < 0$$

$$-\alpha - 3 + \alpha - 3 < 0$$

$$-\alpha - 3 - \alpha + 3 < 0$$

$$4) a) w_1^T A = d_1 w_1^T$$

$$A^T w = d_1 w$$

$$\begin{vmatrix} d-2 & -1 \\ 0 & d-1 \end{vmatrix} = (d-2)(d-1) = 0$$

$$d^2 - 3d + 2 = 0$$

$$d_1 = 2 \quad n = 1$$

$$d_1 = 1 \quad n = 1$$

$$d=2 \quad \begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 2w_1 \\ 2w_2 \end{pmatrix}$$

w_1 beliebig

$$w_1 + w_2 = 2w_2$$

$$w_1 = w_2$$

$$w_{(2)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$d=1$$

$$\begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$$

$$2w_1 = w_1 \quad w_1 = 0$$

$$w_1 + w_2 = w_2$$

$$w_1 = 0, w_2 \text{ beliebig}$$

Prüf: $w_1^T b \neq 0 \quad \forall w_1$
erreichte, w_1

$$(1 \ 1) \begin{pmatrix} 1 \\ 2 \end{pmatrix} \neq 0 \quad \checkmark$$

$$(0 \ 1) \begin{pmatrix} 1 \\ 2 \end{pmatrix} \neq 0 \quad \checkmark$$

b)

$$v_1^T = e_3 R^{-1}$$

$$R = (\Gamma, \Phi \Gamma) = \begin{pmatrix} 1 & 4 \\ 2 & 2 \end{pmatrix}$$

$$v_1^T = [-2 \ 1] \cdot \frac{1}{6}$$

$$R^{-1} = \begin{pmatrix} 2 & -4 \\ -2 & 1 \end{pmatrix} \cdot \frac{1}{6}$$

$$k^T = \frac{1}{2}$$

$$(1 - \frac{1}{2}) \cdot (1 - \frac{2}{3}) = 1^2 - \frac{7}{6} + \frac{1}{3}$$

$$-\frac{1}{3} v_1^T + \frac{7}{6} v_1^T \Phi - v_1^T \Phi^T$$

$$k^T = \frac{1}{18} \begin{pmatrix} -2 & 1 \end{pmatrix} = \frac{7}{36} \begin{pmatrix} -4 & -1 \end{pmatrix} + \frac{7}{6} \begin{pmatrix} 8 & 4 \end{pmatrix}$$

$$\begin{array}{cc|cc} 2 & 1 & 2 & 1 \\ 0 & 1 & 0 & 1 \\ -2 & 1 & -4 & -1 \\ \hline & & -8 & -5 \end{array}$$

$$k = \begin{bmatrix} -\frac{2}{18} + \frac{7}{9} - \frac{8}{6} \\ \frac{1}{18} + \frac{7}{36} - \frac{5}{6} \end{bmatrix} = \frac{1}{18} \begin{bmatrix} -12 \\ -21 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} -4 \\ -7 \end{bmatrix}$$

$$\text{ad 4b)} \quad e = \frac{1}{c^T (E - \phi - \Gamma K^T)^{-1} \Gamma}$$

$$E - \phi - \Gamma K^T =$$

$$\begin{bmatrix} -\frac{6}{18} & -\frac{15}{36} \\ \frac{12}{9} & \frac{21}{18} \end{bmatrix}$$

$$\begin{array}{c|cc} & -\frac{12}{18} & -\frac{21}{36} \\ \hline 1 & -\frac{12}{18} & -\frac{21}{36} \\ 2 & -\frac{12}{9} & -\frac{21}{18} \end{array}$$

$$-11^{-1} = \frac{1}{-\frac{6 \cdot 21}{18 \cdot 18} + \frac{15 \cdot 12^2}{36 \cdot 36}} \begin{bmatrix} \frac{21}{18} & \frac{15}{36} \\ -\frac{12}{9} & -\frac{6}{18} \end{bmatrix}$$

$$= \frac{18}{3} \begin{bmatrix} \frac{21}{18} & \frac{15}{36} \\ -\frac{12}{9} & -\frac{6}{18} \end{bmatrix} = \begin{bmatrix} 7 & \frac{5}{2} \\ -8 & -2 \end{bmatrix}$$

$$c^T \cdot (-11^{-1}) = \begin{bmatrix} 7 & \frac{5}{2} \end{bmatrix}$$

$$-11^{-1} \cdot \Gamma = 7 + 5 = 12$$

$$\boxed{e = \frac{1}{12}}$$

$$\text{c)} \quad G(z) = c^T (zE - \phi)^{-1} \Gamma$$

$$\begin{bmatrix} z-2 & -1 \\ 0 & z-1 \end{bmatrix}^{-1} = \begin{bmatrix} z-1 & 1 \\ 0 & z-2 \end{bmatrix} \frac{1}{(z-1)(z-2)} = \begin{bmatrix} \frac{1}{z-2} & \frac{1}{(z-1)(z-2)} \\ 0 & \frac{1}{(z-1)} \end{bmatrix}$$

$$\begin{aligned} G(z) \quad c^T \cdot (-11^{-1}) \Gamma &= \begin{bmatrix} \frac{1}{z-2} & \frac{1}{(z-1)(z-2)} \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \frac{1}{z-2} + \frac{2}{(z-1)(z-2)} \\ &= \frac{(z-1) + 2}{(z-1)(z-2)} = \frac{(z+1)}{(z-1)(z-2)} \end{aligned}$$

$$d) \quad x_{k+2} + 2x_{k+1} + x_k = -u_k$$

$$y_k = x_{k+1} + 3x_k$$

$$z_{k,1} = x_k$$

$$z_{k,2} = x_{k+1}$$

$$z_{k+1,1} = z_{k,2}$$

$$z_{k+1,2} = x_{k+2} = -u_k - x_k - 2x_{k+1} =$$

$$= -u_k - z_{k,1} - 2z_{k,2}$$

$$z_{k+1} = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} z_k + \begin{bmatrix} 0 \\ -1 \end{bmatrix} u_k$$

$$y_k = \begin{bmatrix} 3 & 1 \end{bmatrix} z_k$$