



modification

1 message

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Tue, Feb 7, 2012 at 5:26 PM

To: Juan Rojas <rojas70@gmail.com>

Controller/IOserver/robot/HRP3STEP2/bin/ArmParam:/home/harada/src/OpenHRP3.0-HIRO/

Controller/IOserver/robot/HRP3STEP2/calib.dat

Controller/IOserver/robot/HRP3STEP2/script/work.py:sys.path.append('/home/harada/src/OpenHRP3.0-

HIRO/Controller/IOserver/robot/HRP3STEP2/script')

bin/unix/OpenHRPpy:. /home/harada/src/OpenHRP3.0-HIRO/bin/unix/config.sh

bin/unix/OpenHRPpv:java -Dpvthon.home=\$JYTHON HOME -classpath

\$JYTHON JAR:/home/harada/src/OpenHRP3.0-HIRO/Common/corba/openhrpstubskel.jar:\$HRP STUB

PATH

-DNS_OPT="\$NS_OPT" org.python.util.jython \$@

sample/forceSensorPlugin/server/hiroArm.cpp: std::string

data dir = "/home/harada/src/OpenHRP3.0-HIRO/sample/forceSensorPlugin/data/";

sample/forceSensorPlugin/server/forceSensorPlugin impl.cpp: std::string

f name = "/home/harada/src/OpenHRP3.0-HIRO/sample/forceSensorPlugin/data/mc.dat";

sample/forceSensorPlugin/server/forceSensorPlugin impl.cpp~: std::string

f name = "/home/harada/src/OpenHRP3.0-HIRO/sample/forceSensorPlugin/data/mc.dat";

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