

# g4ntm

**Library scope:** global  
**Named arguments:** supported

## Introduction

A library provides control for Telescent Network Topology Management (NTM) robot patch.

## Shortcuts

**Add** · **Delete** · **Get Connection Info**

## Keywords

Keyword	Arguments	Documentation
<b>Add</b>	<i>self, dev1, intf1, dev2, intf2, direction=bi, force=False</i>	
<b>Delete</b>	<i>self, dev1, intf1, dev2, intf2, direction=bi, force=False</i>	Deletes the connection between dev1:intf1 - dev2:intf2
<b>Get Connection Info</b>	<i>self, dev, intf</i>	Returns information about the connection by router/interface

Altogether 3 keywords.  
Generated by [Libdoc](#) on 2018-11-30 13:34:58.

