g4ntm

Library scope:	global
Named arguments:	supported

Introduction

A library provides control for Telescent Network Topology Management (NTM) robot patch.

Shortcuts

Add · **D**elete · **G**et Connection Info

Keywords

Keyword	Arguments	Documentation
Add	*self*, *dev1*, *intf1*, *dev2*, *intf2*, *direction=bi*, *force=False*	
Delete	*self*, *dev1*, *intf1*, *dev2*, *intf2*, *direction=bi*, *force=False*	Deletes the connection between `dev1:intf1 - dev2:intf2`
Get Connection Info	*self*, *dev*, *intf*	Returns information about the connection by router/interface

Altogether 3 keywords.
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