

g4ntm

Library scope: global
Named arguments: supported

Introduction

A library provides control for Telescent Network Topology Management (NTM) robot patch.

Shortcuts

Add · **Delete** · **Get Connection Info**

Keywords

| Keyword | Arguments | Documentation |
|----------------------------|--|--|
| Add | <i>self, dev1, intf1, dev2, intf2, direction=bi, force=False</i> | |
| Delete | <i>self, dev1, intf1, dev2, intf2, direction=bi, force=False</i> | Deletes the connection between dev1:intf1 - dev2:intf2 |
| Get Connection Info | <i>self, dev, intf</i> | Returns information about the connection by router/interface |

Altogether 3 keywords.

Generated by [Libdoc](#) on 2018-08-01 21:53:01.

