

# g4ntm

Library scope: global  
Named arguments: supported

## Introduction

A library provides control for Telescent Network Topology Management (NTM) robot patch.

## Shortcuts

Add · Delete · Get Connection Info

## Keywords

Keyword	Arguments	Documentation
Add	self, dev1, intf1, dev2, intf2, direction=bi, force=False	
Delete	self, dev1, intf1, dev2, intf2, direction=bi, force=False	Deletes the connection between dev1:intf1 - dev2:intf2
Get Connection Info	self, dev, intf	Returns information about the connection by router/interface

Altogether 3 keywords.  
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